Sep 5, 2023 (Due: 08:00 Sep 12, 2023)

- 1. Let \hat{x} be an approximation to x. In practice it is often much easier to estimate $\tilde{E}_{\rm rel}(\hat{x}) = |x \hat{x}|/|\hat{x}|$ compared to $E_{\rm rel}(\hat{x}) = |x \hat{x}|/|x|$. What is the relationship between $E_{\rm rel}$ and $\tilde{E}_{\rm rel}$?
- **2.** How to evaluate $f(x) = \tan x \sin x$ for $x \approx 0$ such that numerical cancellation is avoided?
- **3.** You are given $A \in \mathbb{R}^{m \times n}$ and $x \in \mathbb{R}^n$, both already stored in floating-point format. Show that there exists a "small" matrix $E \in \mathbb{R}^{m \times n}$ such that fl(Ax) = (A + E)x. Try to bound the entries of E as tight as you can. You may assume that there is no overflow or (gradual) underflow in the calculation.
- **4.** Let $L \in \mathbb{R}^{n \times n}$ be lower triangular and nonsingular. Provide two different implementations for solving the linear system Lx = b, where $b \in \mathbb{R}^n$ is a given vector.
- 5. Implement Gaussian elimination for solving nonsingular linear systems. You may assume that no divide-by-zero error is encountered. Measure the execution time of your program in terms of matrix dimensions and visualize the result by a log-log scale plot. (You may generate your test matrices with with normally distributed random elements.)
- **6.** (optional) Analyze the rounding error for complex arithmetic. You may assume that there is no overflow or (gradual) underflow in the calculation.