

## Oct 24, 2023 (Due: 08:00 Oct 31, 2023)

1. Let  $A \in \mathbb{C}^{n \times n}$ ,  $x \in \mathbb{C}^n$ . Suppose that  $X = [x, Ax, \dots, A^{n-1}x]$  is nonsingular. Show that  $X^{-1}AX$  is upper Hessenberg.

2. Let  $A_0 \in \mathbb{C}^{n \times n}$ ,  $\mu_0, \mu_1, \dots, \mu_m \in \mathbb{C}$ . Define  $A_1, A_2, \dots, A_{m+1}$  by

$$A_k - \mu_k I = Q_k R_k, \quad A_{k+1} = R_k Q_k + \mu_k I,$$

for  $k \in \{0, 1, \dots, m\}$ , where  $Q_k$ 's are unitary matrices. Show that

$$(A_0 - \mu_0 I)(A_0 - \mu_1 I) \cdots (A_0 - \mu_m I) = (Q_0 Q_1 \cdots Q_m)(R_m \cdots R_1 R_0).$$

3. Let

$$A = \begin{bmatrix} a & c \\ 0 & b \end{bmatrix} \in \mathbb{R}^{2 \times 2}.$$

Design an algorithm to compute an orthogonal matrix  $Q \in \mathbb{R}^{2 \times 2}$  such that

$$Q^T A Q = \begin{bmatrix} b & c \\ 0 & a \end{bmatrix}.$$

(H) What happens if the matrix  $A$  is complex?

4. Let

$$A = \begin{bmatrix} a_1 & b_1 & & & \\ c_2 & a_2 & b_2 & & \\ & \ddots & \ddots & \ddots & \\ & & c_{n-1} & a_{n-1} & b_{n-1} \\ & & & c_n & a_n \end{bmatrix} \in \mathbb{R}^{n \times n},$$

with  $b_i c_{i+1} > 0$  for  $i \in \{1, 2, \dots, n-1\}$ . Show that  $A$  is diagonalizable, and has real spectrum.

5. Implement the following algorithms for Hessenberg reduction:

- (a) using Householder reflections;
  - (b) using Arnoldi process based on modified Gram-Schmidt orthogonalization.
- Randomly generate a few matrices and compute the corresponding Hessenberg decomposition  $A = Q H Q^T$ . Check the accuracy in terms of  $\|Q^* A Q - H\|_F$  and  $\|Q^* Q - I\|_F$  for your Hessenberg reduction implementations. What do you observe?

(optional) Perturb the matrix  $A$  a little bit. How do  $Q$  and  $H$  change accordingly?

6. (optional) Let

$$A = \begin{bmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ & a_{2,2} & a_{2,3} \\ & a_{3,2} & a_{3,3} \end{bmatrix} \in \mathbb{R}^{3 \times 3}.$$

Design an algorithm to compute an orthogonal matrix  $Q \in \mathbb{R}^{3 \times 3}$  such that  $Q^\top A Q$  is of the form

$$Q^\top A Q = \begin{bmatrix} b_{1,1} & b_{1,2} & b_{1,3} \\ b_{2,1} & b_{2,2} & b_{2,3} \\ & & a_{1,1} \end{bmatrix}.$$