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図 1 FIGURE

$$x = 1 \tag{1}$$

$$x = 2 \tag{2}$$

$$x = 3 \tag{3}$$

Hello, T<sub>E</sub>X! ⊠ 1, (1), [1]

$$\frac{a_{\mathrm{tt}}^3}{T_{\mathrm{tt}}^2} = G \cdot \frac{m_{\mathrm{tt}} + m_{\mathrm{tt}}}{4\pi^2}$$

## 参考文献

[1] Emmanuel Sin, He Yin, and Murat Arcak. Passivity-based distributed acquisition and station-keeping control of a satellite constellation in areostationary orbit. In *Dynamic Systems and Control Conference*, volume 84287, page V002T30A001. American Society of Mechanical Engineers, 2020.