Basic RL.6

Judy Tutorial

Softmax (Multiclass Logistic) Regression &

Neural Networks

MNIST dataset

[LeCun 1998]

Multiple Labels $y \in \{0,1,2,...,9\}$



Hypothesis function

$h_k(\boldsymbol{\theta}) = g(\boldsymbol{\theta}_k^{\mathrm{T}} \boldsymbol{X})$ parameters

Activation function

$$g(z_k) = \frac{e^{z_k}}{\sum_{l=1}^K e^{z_l}}$$
 softmax

Objective function

$$J(\theta) = -\frac{1}{N} \sum_{i=1}^{N} \sum_{l=1}^{K} y_l^{(i)} \log h_l(\theta)^{(i)}$$

Cross entropy loss

Hypothesis function

hesis function
$$h(\boldsymbol{\theta}) = \begin{bmatrix} g(\boldsymbol{\theta}_{k=1}^{T} \boldsymbol{X}) \\ g(\boldsymbol{\theta}_{k=2}^{T} \boldsymbol{X}) \\ g(\boldsymbol{\theta}_{k=3}^{T} \boldsymbol{X}) \\ \vdots \\ g(\boldsymbol{\theta}_{k=K}^{T} \boldsymbol{X}) \end{bmatrix} = \begin{bmatrix} \frac{\exp \boldsymbol{\theta}_{k=1}^{T} \boldsymbol{X}}{\sum_{l=1}^{K} \exp \boldsymbol{\theta}_{l}^{T} \boldsymbol{X}} \\ \frac{\exp \boldsymbol{\theta}_{k=2}^{T} \boldsymbol{X}}{\sum_{l=1}^{K} \exp \boldsymbol{\theta}_{l}^{T} \boldsymbol{X}} \\ \frac{\exp \boldsymbol{\theta}_{k=3}^{T} \boldsymbol{X}}{\sum_{l=1}^{K} \exp \boldsymbol{\theta}_{l}^{T} \boldsymbol{X}} \\ \vdots \\ \frac{\exp \boldsymbol{\theta}_{k=K}^{T} \boldsymbol{X}}{\sum_{l=1}^{K} \exp \boldsymbol{\theta}_{l}^{T} \boldsymbol{X}} \end{bmatrix}$$

Objective function

$$J(\theta) = -\frac{1}{N} \sum_{i=1}^{N} \sum_{l=1}^{K} y_l^{(i)} \log h_l(\theta)^{(i)}$$



Negative Log-Likelihood of Multinomial distribution

Multinomial Distribution



Wiki:

 the Multinomial distribution gives the probability of any particular combination of numbers of successes for the various categories

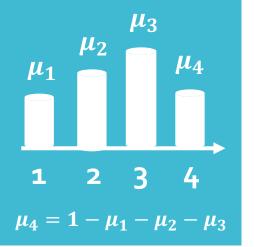
Example:

- Repeat rolling a dice for many times
- Suppose we roll a dice 5 times, what's the probability of the appearances of two 3s and three 4s?

•
$$p(34344|\mu) = \frac{5!}{2!3!} \left(\frac{1}{6}\right)^2 \left(\frac{1}{6}\right)^3$$

Parameter vector for dice probability where $\mu_k = \frac{1}{6}$, K = 6

Multinomial Distribution



- x_k the number of repeatition of a specific outcome when conducting some events
- μ_k the probability of each event

#events
$$Mult(x_1, x_2, ..., x_K | \mu, N) = C_N^{x_1 x_2 ... x_K} \prod_{k=1}^K \mu_k^{x_k}$$

distribution parameter vector

•
$$0 \le \mu_k \le 1, \sum_{k=1}^K \mu_k = 1$$

$$\cdot \sum_{k=1}^{K} x_k = N$$

•
$$C_N^{x_1 x_2 \dots x_K} = \frac{N!}{x_1! x_2! \dots x_K!}$$

$$Mult(x_1, x_2, \dots, x_K | \boldsymbol{\mu}) \propto \prod_{k=1}^K \mu_k^{x_k}$$

Multinomial Likelihood

#data

$$\mathcal{L}(\boldsymbol{\theta}) = \prod_{l=1}^{N} \prod_{l=1}^{K} h_l(\boldsymbol{\theta})^{(i)} y_l^{(i)} - \text{classification label}$$

 $g(\boldsymbol{\theta}_{k}^{T}\boldsymbol{X})$

$$0 \le h_k(\boldsymbol{\theta}) \le 1$$
$$\sum_{l}^{K} h_l(\boldsymbol{\theta}) = 1$$

 $y_l^{(i)} = \mathbf{1}_{y=k} = \begin{cases} \mathbf{1}, & \text{if } y = k \\ \mathbf{0}, & \text{if } y \neq k \end{cases}$

MLE for Softmax Regression

$$\max_{\boldsymbol{\theta}} \log \mathcal{L}(\boldsymbol{\theta}) = \sum_{i=1}^{N} \sum_{l=1}^{K} y_l^{(i)} \log h_l(\boldsymbol{\theta})^{(i)}$$

$$\min_{\boldsymbol{\theta}} J(\boldsymbol{\theta}) = -\frac{1}{N} \sum_{i=1}^{N} \sum_{l=1}^{K} y_l^{(i)} \log h_l(\boldsymbol{\theta})^{(i)}$$

Cross entropy loss

Objective function

$$\min_{\boldsymbol{\theta}} J(\boldsymbol{\theta}) = -\frac{1}{N} \sum_{i=1}^{N} \sum_{l=1}^{K} y_l^{(i)} \log h_l(\boldsymbol{\theta})^{(i)}$$

Batch Gradient

$$\nabla_{\theta_{j}} J(\theta_{j}) = \nabla_{\theta_{j}} - \frac{1}{N} \sum_{i=1}^{N} \sum_{l=1}^{K} y_{l}^{(i)} \log h_{l}(\theta)^{(i)}$$

$$= -\frac{1}{N} \sum_{i=1}^{N} \sum_{l=1}^{K} \frac{y_{l}^{(i)}}{h_{l}(\theta_{j})^{(i)}} \nabla_{\theta_{j}} h(\theta_{j})^{(i)}$$

$$= \frac{1}{N} \sum_{i=1}^{N} \sum_{l=1}^{K} \left[h(\theta_{j})^{(i)} - y_{l}^{(i)} \right] x^{(i)}$$
Element-wise

Matrix-wise
$$= \frac{1}{N} X [h(\theta) - Y]^T$$

same as linear/logistic regression related to Exponential Family and Generalized Linear Model

Gradient Descent

$$\boldsymbol{\theta}_{t+1} \leftarrow \boldsymbol{\theta}_t - \alpha \nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta})$$

Batch

Mini Batch

&

Stochastic Gradient Descent

Require a batch/entire dataset

$$\nabla_{\theta_j} J(\theta_j) = \frac{1}{N} \sum_{i=1}^N \left[h(\theta_j)^{(i)} - y^{(i)} \right] x^{(i)}$$

Sample random mini batch from the entire dataset

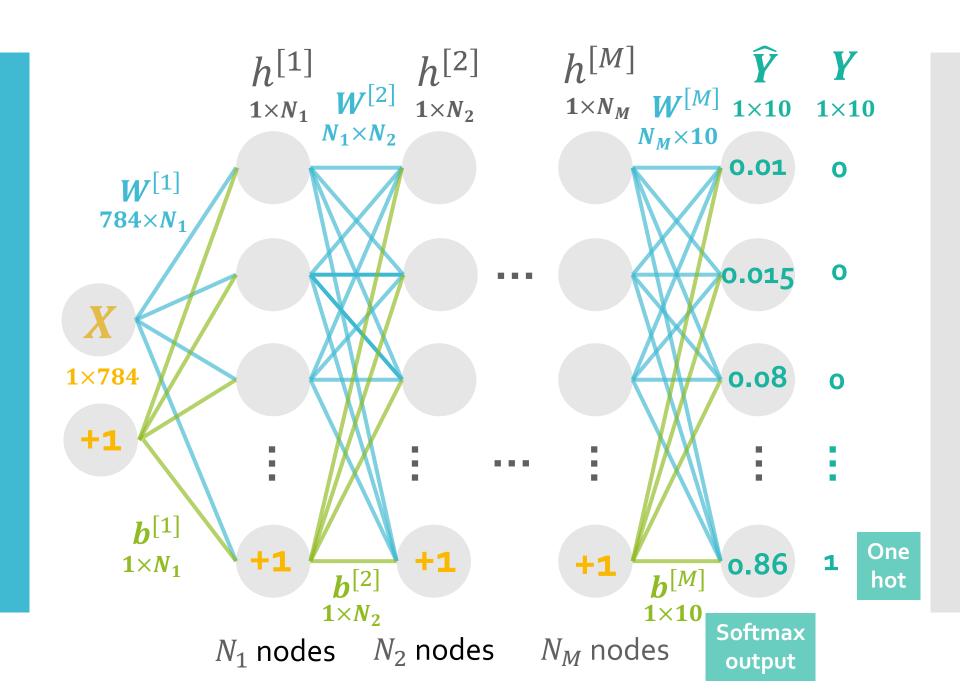
$$\nabla_{\theta_j} J(\theta_j) = \frac{1}{N_{mini}} \sum_{i=1}^{N_{mini}} \left[h(\theta_j)^{(i)} - y^{(i)} \right] x^{(i)}$$

Require only one data point

$$\nabla_{\theta_j} J(\theta_j) = \left[h(\theta_j)^{(i)} - y^{(i)} \right] x^{(i)}$$
Mini batch

batch

Feedforward Neural Networks



Activation functions

$$g(z) = z$$



linear

$$g(z_k) = \frac{e^{z_k}}{\sum_{l=1}^{K} e^{z_l}}$$
 $g(z) = \max(z, 0)$ $g(z) = \max(z, 0.1z)$

A generalized sigmoid

softmax

$$g(z) = \frac{1}{1 + e^{-z}}$$

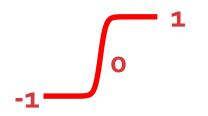


Sigmoid

$$g(z) = \max(z, 0)$$



$$g(z) = \frac{1}{1 + e^{-z}}$$
 $g(z) = \frac{e^{z} - e^{-z}}{e^{z} + e^{-z}}$



tanh

$$g(z) = \max(z, 0.1z)$$



Leaky ReLU

Objective functions

$$\frac{1}{N} \sum_{i=1}^{N} (y_i - \hat{y}_i)^2$$

 $-[y_i \log \hat{y}_i + (1 - y_i) \log(1 - \hat{y}_i)]$

MSE

Binary Cross entropy

$$\frac{1}{N} \sum_{i=1}^{N} |y_i - \hat{y}_i|$$

$$-\frac{1}{N} \sum_{i=1}^{N} y_i \log \hat{y}_i$$

MAE

Multiclass Cross entropy

Optimizers

Batch Gradient

MiniBatch Gradient

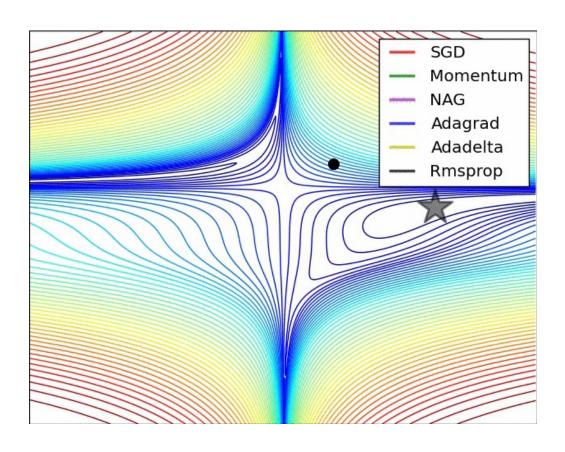
SGD

SGD+momentum

Adam

Adagrad

Rmsprop



https://www.analyticsvidhya.com/blog/2021/10/a-comprehensive-guide-on-deep-learning-optimizers/

Backpropagation – chain rule

$$h^{[1]} = g^{[1]}(XW^{[1]} + b^{[1]})$$

$$h^{[2]} = g^{[2]}(h^{[1]}W^{[2]} + b^{[2]})$$

$$\hat{Y} = g^{[3]}(h^{[2]}W^{[3]} + b^{[3]})$$

$$J = -\sum_{i=1}^{N} y_i \log \hat{y}_i \to -\log \hat{y}_i$$

ReLU

ReLU

softmax

Multiclass Cross entropy

$$\frac{\partial J}{\partial W^{[3]}} = \frac{\partial J}{\partial \hat{Y}} \frac{\partial \hat{Y}}{\partial g^{[3]}} \frac{\partial g^{[3]}}{\partial W^{[3]}} \qquad h^{[1]} \qquad \frac{\partial J}{\partial b^{[3]}} = \frac{\partial J}{\partial \hat{Y}} \frac{\partial \hat{Y}}{\partial g^{[3]}} \frac{\partial g^{[3]}}{\partial b^{[3]}} \qquad 1$$

$$\frac{\partial J}{\partial W^{[2]}} = \frac{\partial J}{\partial \hat{Y}} \frac{\partial \hat{Y}}{\partial g^{[3]}} \frac{\partial g^{[3]}}{\partial h^{[2]}} \frac{\partial h^{[2]}}{\partial g^{[2]}} \frac{\partial g^{[2]}}{\partial W^{[2]}} \qquad X \qquad \frac{\partial J}{\partial b^{[2]}} = \frac{\partial J}{\partial \hat{Y}} \frac{\partial \hat{Y}}{\partial g^{[3]}} \frac{\partial g^{[3]}}{\partial h^{[2]}} \frac{\partial h^{[2]}}{\partial g^{[2]}} \frac{\partial g^{[2]}}{\partial b^{[2]}} \qquad 1$$

$$\frac{\partial J}{\partial W^{[1]}} = \frac{\partial J}{\partial \hat{Y}} \frac{\partial \hat{Y}}{\partial g^{[3]}} \frac{\partial g^{[3]}}{\partial h^{[2]}} \frac{\partial h^{[2]}}{\partial g^{[2]}} \frac{\partial g^{[2]}}{\partial h^{[1]}} \frac{\partial h^{[1]}}{\partial g^{[1]}} \frac{\partial g^{[1]}}{\partial W^{[1]}} \qquad \frac{\partial J}{\partial b^{[1]}} = \frac{\partial J}{\partial \hat{Y}} \frac{\partial \hat{Y}}{\partial g^{[3]}} \frac{\partial g^{[3]}}{\partial h^{[2]}} \frac{\partial h^{[1]}}{\partial g^{[2]}} \frac{\partial g^{[1]}}{\partial b^{[1]}} \frac{\partial g^{[1]}}{\partial b^{[1]}} \qquad \frac{\partial J}{\partial b^{[1]}} = \frac{\partial J}{\partial \hat{Y}} \frac{\partial \hat{Y}}{\partial g^{[3]}} \frac{\partial g^{[3]}}{\partial h^{[2]}} \frac{\partial h^{[2]}}{\partial g^{[2]}} \frac{\partial h^{[1]}}{\partial b^{[1]}} \frac{\partial g^{[1]}}{\partial b^{[1]}} \qquad \frac{\partial J}{\partial b^{[1]}} \qquad \frac{\partial J}{\partial b^{[1]}} = \frac{\partial J}{\partial \hat{Y}} \frac{\partial \hat{Y}}{\partial g^{[3]}} \frac{\partial g^{[3]}}{\partial h^{[2]}} \frac{\partial h^{[2]}}{\partial g^{[2]}} \frac{\partial g^{[1]}}{\partial b^{[1]}} \frac{\partial J}{\partial b^{[1]}} \qquad \frac{\partial J}{\partial b^{[1]}} \qquad \frac{\partial J}{\partial b^{[1]}} \qquad \frac{\partial J}{\partial g^{[3]}} \frac{\partial J}{\partial h^{[2]}} \frac{\partial J}{\partial g^{[2]}} \frac{\partial J}{\partial h^{[1]}} \frac{\partial J}{\partial g^{[1]}} \frac{\partial J}{\partial b^{[1]}} \qquad \frac{\partial J}{\partial b^{[1]}} \qquad \frac{\partial J}{\partial b^{[1]}} \frac{\partial J}{\partial g^{[3]}} \frac{\partial J}{\partial h^{[2]}} \frac{\partial J}{\partial g^{[2]}} \frac{\partial J}{\partial h^{[1]}} \frac{\partial J}{\partial g^{[1]}} \frac{\partial J}{\partial b^{[1]}} \frac{\partial J}{\partial b^{[1]}} \qquad \frac{\partial J}{\partial b^{[1]}} \frac{\partial J}{\partial b^{[1]}} \frac{\partial J}{\partial g^{[2]}} \frac{\partial J}{\partial h^{[2]}} \frac{\partial J}{\partial g^{[2]}} \frac{\partial J}{\partial h^{[1]}} \frac{\partial J}{\partial g^{[1]}} \frac{\partial J}{\partial b^{[1]}} \frac{\partial J}{\partial b^$$

$$\frac{\partial J}{\partial b^{[3]}} = \frac{\partial J}{\partial \hat{Y}} \frac{\partial \hat{Y}}{\partial g^{[3]}} \frac{\partial g^{[3]}}{\partial b^{[3]}} \qquad \mathbf{1}$$

$$\frac{\partial J}{\partial b^{[2]}} = \frac{\partial J}{\partial \hat{Y}} \frac{\partial \hat{Y}}{\partial g^{[3]}} \frac{\partial g^{[3]}}{\partial h^{[2]}} \frac{\partial h^{[2]}}{\partial g^{[2]}} \frac{\partial g^{[2]}}{\partial b^{[2]}} \qquad \mathbf{1}$$

$$\frac{h^{[1]}}{g^{[1]}} \frac{\partial g^{[1]}}{\partial W^{[1]}} = \frac{\partial J}{\partial \hat{Y}} \frac{\partial \hat{Y}}{\partial g^{[3]}} \frac{\partial g^{[3]}}{\partial h^{[2]}} \frac{\partial h^{[2]}}{\partial g^{[2]}} \frac{\partial h^{[1]}}{\partial h^{[1]}} \frac{\partial g^{[1]}}{\partial g^{[1]}}$$

 $(\widehat{Y} - Y)$ $W^{[3]}$ **0**, **1** $W^{[2]}$ **0**, **1**

Given a training dataset (X, Y)

1. Initialize W, b

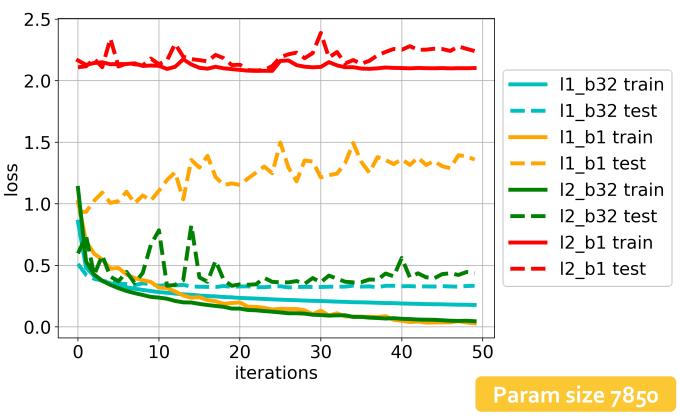
Learning Flow

- 2. Forward: calculate $h^{[1]}, h^{[2]}, \dots, \widehat{Y}, J$
- 3. Backward: calculate $\frac{\partial J}{\partial W}$, $\frac{\partial J}{\partial b}$
- 4. Optimize: e.g. SGD
- 5. Verify with test dataset

in python keras

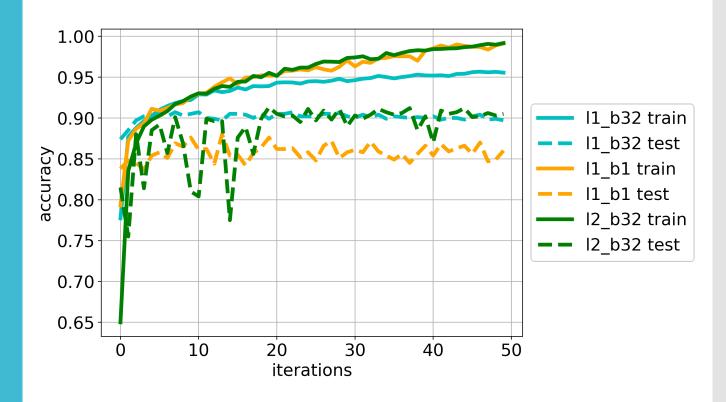
```
x_train,y_train,x_test,y_test=process_data()
model=Sequential()
model.add(Dense(10,input dim=784,activation='relu'))
model.add(Dense(10,activation='softmax'))
                                                          Build model
model.compile(optimizer=SGD(lr=0.1),
              loss='categorical_crossentropy',
              metrics=['categorical accuracy'])
traj=model.fit(x_train,
               y_train,
               epochs=50,
                                                      Training
               batch_size=32,
               validation data=(x test, y test),
               shuffle=True, verbose=0)
plt.plot(traj.history['loss'], linewidth=4, label='loss')
plt.plot(traj.history['categorical accuracy'],linewidth=4,label='accuracy')
plt.legend()
                                                        Plot results
                                               1.0
  x_train: (5000,784)
                                               8.0
  y_train: (5000,10) - one hot
                                               0.6
  x_test: (1000,784)
                                               0.4
                                               0.2
  y_test: (1000,10) – one hot
                                               0.0
                                                     10
                                                         20
                                                             30
```

Learning behaviors [layers,batchsize]

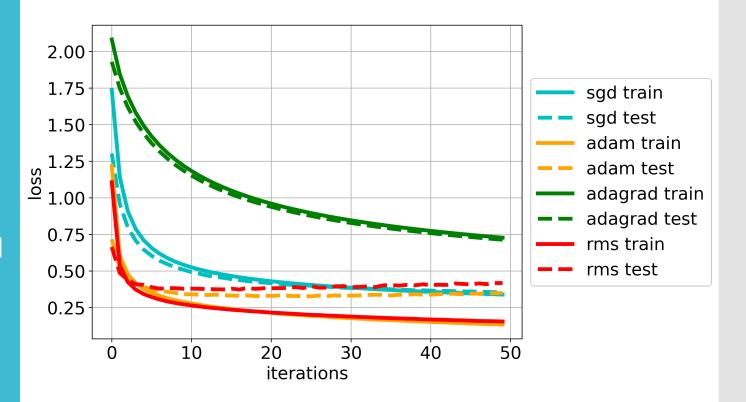


- l1_b32: one layer, batch size 32 <=> Softmax regression
- l1_b1: one layer, batch size 1 <=> Softmax regression
- L2_b32: two layers, batch size 32
 Param size 7960
- L2_b1: two layers, batch size 1 SGD

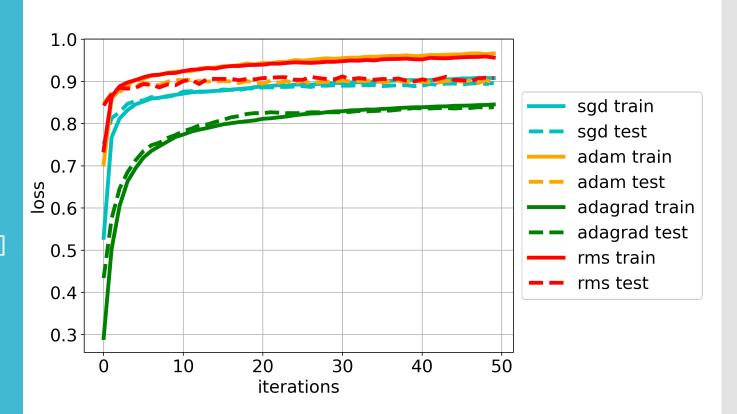
Learning behaviors [layers,batchsize]



Behaviors of different optimizers [layer:1, batch:32]



Behaviors of different optimizers [layer:1, batch:32]



Weights visualization for softmax regression (one-layer mlp)

