

Mathematics and numerics for data assimilation and state estimation – Lecture 2



Summer semester 2020

Overview

1 Summary of lecture 1

2 Discrete random variables

- Independence of random variables and events
- Expected value and moments

On ubungs, presentation and lectures

- 10:30-12:00 on most Fridays.
- Structure: 5-10 questions, which I will put up in pdf form on course webpage and on Moodle. Roughly 30 minutes work in groups or alone, where I will be present for discussions, thereafter solutions in plenary by me and/or you.
- No hand-ins, unless you want to (i.e., only for feedback, which does not affect grade).
- The only “graded” part of the course, in the form of bonus points, is the presentation early July, and, of course, the final exam.
- Presentations can be done alone or in groups of maximum 2 people.
- Lectures after July 17th moved to first week of June.

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Measurable spaces and probability measures

- introduced a probability space $(\Omega, \mathcal{F}, \mathbb{P})$
- discrete random variable $X : \Omega \rightarrow A = \{a_1, a_2, \dots\}$ satisfies the event constraints

$$X^{-1}(a) = \{\omega \in \Omega \mid X(\omega) = a\} \in \mathcal{F} \quad \text{for all } a \in A.$$

- X can be represented by a simple function

$$X(\omega) = \sum_{a \in A} a \mathbb{1}_{X=a}(\omega). \quad \text{where } \mathbb{1}_{X=a}(\omega) := \begin{cases} 1 & \text{if } X(\omega) = a \\ 0 & \text{otherwise} \end{cases}$$

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Discrete random variables 2

Example 1 (Coin toss, $X \sim \text{Bernoulli}(p)$)

- image-space outcomes $A = \{0, 1\}$,

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$$\Omega = \{Heads, Tails\}, \quad \mathcal{F} = \{\emptyset, \{Heads\}, \{Tails\}, \Omega\}$$

- $X(Heads) = 1$ and $X(Tails) = 0$ and

$$\mathbb{P}(X = 1) = \mathbb{P}(X^{-1}(1)) = \mathbb{P}(Heads) = p, \quad \mathbb{P}(X = 0) = \mathbb{P}(Tails) = 1 - p.$$

Comment from last lecture: image-outcomes $\{a_1, a_2, \dots\}$ may not be associated uniquely to (probability-space) outcomes in Ω .

Larger set of outcomes in Ω than in A

Alternative, and admittedly confusing, probability space for the same rv as in the preceding example:

Example 2 (Coin toss, $X \sim \text{Bernoulli}(p)$)

- image-space outcomes $A = \{0, 1\} \subset \mathbb{R}$,
- $\Omega = \{Heads, Tails, \text{Nose}\}$ and

$$\mathcal{F} = \{\emptyset, \{Nose\}, \{Heads\}, \{Tails\}, \{Nose, Heads\}, \\ \{Nose, Tails\}, \{Heads, Tails\}, \Omega\}$$

- $X^{-1}(1) = \{Heads, Nose\}$ and $X^{-1}(0) = \{Tails\}$ and

$$\mathbb{P}(X = 1) = \mathbb{P}(X^{-1}(1)) = \mathbb{P}(\{Heads, Nose\}) = p, \\ \mathbb{P}(X = 0) = \mathbb{P}(\{Tails\}) = 1 - p.$$

Motivation: if, for instance, you want to represent both a coin toss and a three-sided-die toss in the same probability space.

Joint rv

If $X : \Omega \rightarrow A$ and $Y : \Omega \rightarrow B = \{b_1, b_2, \dots\}$ are two discrete rv on the same probability space, then

- $(X, Y) : \Omega \rightarrow A \times B$ is also a discrete rv with countable set of outcomes

$$A \times B = \{(a, b) \mid a \in A, b \in B\}.$$

- with joint distribution:

$$\mathbb{P}_{(X,Y)}((a, b)) = \mathbb{P}(X = a, Y = b).$$

- Question: why is $\mathbb{P}(X = a, Y = b)$ defined? Answer: when we say X and Y are defined on the same probability space, this entails that

$$\{X = a\}, \{Y = b\} \in \mathcal{F} \quad \underbrace{\implies}_{\text{since } \mathcal{F} \text{ is } \sigma\text{-algebra}} \quad \{X = a\} \cap \{Y = b\} \in \mathcal{F},$$

and

$$\mathbb{P}(X = a, Y = b) = \mathbb{P}(\{X = a\} \cap \{Y = b\}).$$

Definition 3 (Independence of two rv)

If $X : \Omega \rightarrow A$ and $Y : \Omega \rightarrow B = \{b_1, b_2, \dots\}$ are two discrete rv on the same probability space^a are said to be independent random variables if

$$\mathbb{P}(X = a, Y = b) = \mathbb{P}(X = a)\mathbb{P}(Y = b), \quad \forall a \in A \quad b \in B.$$

Notation: $X \perp Y$.

^aFrom now on, it will be implicitly assumed that all rv are defined on the same probability space, unless otherwise stated.

Example 4

Given independent coin tosses $X_k \sim \text{Bernoulli}(1/2)$ for $k = 1, 2$, describe the smallest possible σ -algebra on which the rv (X_1, X_2) is defined.

Solution:

Example 5 (one coin toss and one three-sided-die toss)

- Consider $X : \Omega \rightarrow \{0, 1\}$ and $Y : \Omega \rightarrow \{1, 2, 3\}$ both defined on the probability space from Example 2.
- Recall that $X^{-1}(1) = \{Heads, Nose\}$ and $X^{-1}(0) = \{Tails\}$ and let us assume that

$$\mathbb{P}(X = 1) = 1/2, \quad \mathbb{P}(X = 0) = 1/2$$

and that $Y^{-1}(1) = \{Heads\}$, $Y^{-1}(2) = \{Nose\}$ and $Y^{-1}(3) = \{Tails\}$.

- Question: For $p = 1/2$, what is

$$\mathbb{P}(X = 0, Y \in \{1, 2\}) = ?$$

- Question: Are X and Y independent?



Independence of multiple rv

Definition 6

Let $X_k : \Omega \rightarrow A_k$ for $k = 1, 2, \dots, N$, be a finite sequence of discrete rv. Then X_1, X_2, \dots, X_N are independent provided

$$\mathbb{P}(X_1 = a_1, X_2 = a_2, \dots, X_N = a_N) = \prod_{k=1}^N \mathbb{P}(X_k = a_k) \quad (1)$$

for all $a_1 \in A_1, a_2 \in A_2, \dots, a_n \in A_N$.

Extension: A **countable** sequence of discrete rv X_1, X_2, \dots are independent provided every finite subsequence $\{X_{k_j}\}_j$ satisfies (1).

Example 7

Let $X_i \sim \text{Bernoulli}(p)$ for $i = 1, \dots, N$ with joint distribution

$$\mathbb{P}(X_1 = a_1, X_2 = a_2, \dots, X_N = a_N) = p^{\sum_{k=1}^N a_k} (1 - p)^{N - \sum_{k=1}^N a_k}$$

for any $a_1, \dots, a_N \in \{0, 1\}$. Then X_1, X_2, \dots are independent and identically distributed (iid).

Example 8 (Functions of joint discrete rv are also discrete rv)

Let $X_i \sim \text{Bernoulli}(p)$ be independent for $i = 1, 2, \dots, N$ and

$$S_N = f(X_1, \dots, X_N) := \sum_{i=1}^N X_i.$$

Then

$$\mathbb{P}(S_N = k) = \binom{N}{k} (1-p)^{N-k} p^k$$

S_N is called the **Binomial distribution** with degrees of freedom N and p , and we write $S_N \sim B(N, p)$.

Comment: the number of different ways the event $\{S_N = k\}$ when flipping N independent coins once equals **factor** in the $k + 1$ -th summand of

$$((1-p) + p)^N = (1-p)^N + \binom{N}{1} p(1-p)^{N-1} + \dots + \binom{N}{k} p^k (1-p)^{N-k} + \dots$$

Independence of events

Equation (1) is on the form:

$$\mathbb{P}\left(\bigcap_{k=1}^N \{X_k = a_k\}\right) = \mathbb{P}(\text{intersection of events}) = \text{Product of } [\mathbb{P}(\text{each event})]$$

Definition 9

A finite sequence of events H_1, H_2, \dots, H_N that belongs to \mathcal{F} are independent provided

$$\mathbb{P}\left(\bigcap_{k=1}^N H_k\right) = \prod_{k=1}^N \mathbb{P}(H_k) \quad (2)$$

A **countable** sequence of events A_1, A_2, \dots belonging to \mathcal{F} are independent provided finite subsequence $\{A_{k_j}\}_j$ satisfies (2).

Connection between independence of rv and independence of events

Given a probability space $(\Omega, \mathcal{F}, \mathbb{P})$, we can assign an rv to each event $H \in \mathcal{F}$ as follows

$$\mathbb{1}_H(\omega) := \begin{cases} 1 & \omega \in H \\ 0 & \text{otherwise} \end{cases}.$$

Easy consequence of preceding definition: $\mathbb{1}_{H_1}$ and $\mathbb{1}_{H_2}$ are independent if and only if

$$\mathbb{P}(H_1 \cap H_2) = \mathbb{P}(H_1)\mathbb{P}(H_2).$$

Expectation of rv

Definition 10

For a discrete rv $X : \Omega \rightarrow A \subset \mathbb{R}^d$, the expectation X is defined as

$$\mathbb{E}[X] := \int_{\Omega} X(\omega) \mathbb{P}(d\omega) = \sum_{a \in A} a \mathbb{P}(X = a)$$

Motivation of the above integral:

$$\int_{\Omega} X(\omega) \mathbb{P}(d\omega) =$$

- The condition

$$\mathbb{E}[|X|] = \sum_{a \in A} |a| \mathbb{P}(X = a) < \infty$$

is a sufficient condition for $\mathbb{E}[X]$ being defined and bounded.

- Example for $X \sim \text{Bernoulli}(p)$

$$\mathbb{E}[X] = ?$$

Expectation of rv

Definition 11

For a discrete rv $X : \Omega \rightarrow A \subset \mathbb{R}^d$, the expectation X is defined as

$$\mathbb{E}[X] := \int_{\Omega} X(\omega) \mathbb{P}(d\omega) = \sum_{a \in A} a \mathbb{P}(X = a)$$

- The condition

$$\mathbb{E}[|X|] = \sum_{a \in A} |a| \mathbb{P}(X = a) < \infty$$

is a sufficient condition for $\mathbb{E}[X]$ being defined and bounded.

- For mappings $f : \mathbb{R}^d \rightarrow \mathbb{R}^k$ and rv $f(X)$ the above definition readily extends:

$$\mathbb{E}[f(X)] = \sum_{a \in A} f(a) \mathbb{P}(X = a).$$

- Example for $X \sim \text{Bernoulli}(p)$

$$\mathbb{E}[X] =$$

Properties of the expectation

- For mappings $f : \mathbb{R}^d \rightarrow \mathbb{R}^k$ and rv $f(X)$, the expectation becomes

$$\mathbb{E}[f(X)] = \sum_{a \in A} f(a) \mathbb{P}(X = a).$$

- For a pair of rv $X : \Omega \rightarrow A \subset \mathbb{R}^d$ and $Y : \Omega \rightarrow B \subset \mathbb{R}^d$, it holds for any $c \in \mathbb{R}$, that

$$\mathbb{E}[X + cY] = \mathbb{E}[X] + c \mathbb{E}[Y]$$

provided $\mathbb{E}[|X|] + \mathbb{E}[|Y|] < \infty$ (sufficient condition).

Motivation:

Properties of the expectation 2

- Probability of events can be expressed through expectations:

$$\mathbb{P}(H) = \qquad \qquad \qquad = \mathbb{E}[1_H]$$

for any $H \in \mathcal{F}$.

- Expectation of discrete rv of the form $f(X, Y)$ where $X : \Omega \rightarrow A$ and $Y : \Omega \rightarrow B$:

$$\mathbb{E}[f(X, Y)] =$$

Variance of an rv

- For $X : \Omega \rightarrow A \subset \mathbb{R}$

$$F(k) = \mathbb{E}[(X - k)^2]$$

is the squared deviation of X from k in expectation.

- For $\mu := \mathbb{E}[X]$, and provided $\mathbb{E}[X^2] < \infty$, it can be shown that

$$F(\mu) \leq F(k) \quad \text{for all } k \in \mathbb{R},$$

- Which motivates the variance of X :

$$\text{Var}(X) := \mathbb{E}[(X - \mu)^2]$$

- For $X \sim \text{Bernolli}(p)$, $\mu = p$ and

$$\text{Var}(X) =$$

Notation with same meaning

For events $H_1, H_2, \dots \in \mathcal{F}$, the following notation is used interchangeably in the literature

$$\mathbb{P}(H_1 H_2 \dots H_n) = \mathbb{P}(H_1, H_2, \dots, H_n) = \mathbb{P}\left(\bigcap_{j=1}^n H_j\right).$$

And since

$$\mathbb{1}_{\bigcap_{j=1}^n H_j} = \prod_{i=1}^n \mathbb{1}_{H_j}.$$

we have that

$$\mathbb{P}\left(\bigcap_{j=1}^n H_j\right) = \mathbb{E}[\mathbb{1}_{\bigcap_{j=1}^n H_j}] = \mathbb{E}\left[\prod_{i=1}^n \mathbb{1}_{H_j}\right].$$

Next time

- Conditional expectations and probabilities
- Convergence of random variables
- Random walks and discrete time Markov Chains