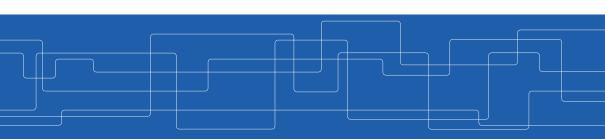
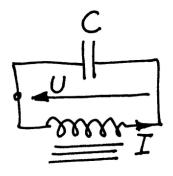


Mästarprov 13: Strömkretsen

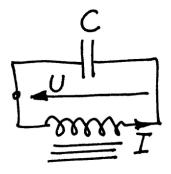
Hassan Al Noori





LC-circuit

▶ What is an LC-circuit?









Electronic article surveillance



▶ What is the current in the circuit?



- ▶ What is the current in the circuit?
- ▶ How is the current affected by the voltage?



- ▶ What is the current in the circuit?
- ▶ How is the current affected by the voltage?
- ▶ Prove E(t) is constant



- ▶ What is the current in the circuit?
- ▶ How is the current affected by the voltage?
- ▶ Prove E(t) is constant
- ▶ How big is the error?



- ▶ What is the current in the circuit?
- ▶ How is the current affected by the voltage?
- ightharpoonup Prove E(t) is constant
- ▶ How big is the error?
- ► Fourier transform



- ▶ What is the current in the circuit?
- ▶ How is the current affected by the voltage?
- ightharpoonup Prove E(t) is constant
- ▶ How big is the error?
- ► Fourier transform
- ► Voluntary part

$$L = \frac{L_0}{1 + I^2} \qquad U = L \frac{dI}{dt}$$

$$I = -C \frac{dU}{dt} \qquad t = 0, \quad I = 0, \quad \frac{dI}{dt} = \frac{U_0}{L_0}$$

$$\frac{d^2I}{dt^2} = \frac{2I}{1+I^2} \left(\frac{dI}{dt}\right)^2 - \frac{I\left(1+I^2\right)}{L_0C}$$

$$\tilde{y}'(t) = \begin{bmatrix} y_1'(t) \\ y_2'(t) \end{bmatrix} = \begin{bmatrix} y_2(t) \\ \frac{2y_1(t)y_2^2(t)}{1+y_1(t)^2} - \frac{1+y_1(t)^2}{L_0C} \end{bmatrix}$$

$$E(t) = U(t)^{2} - \log(1 + I(t)^{2})$$



$$\frac{dE}{dt} = \frac{d}{dt} \left(U(t)^2 - \log(1 + I(t)^2) \right)$$



$$= \frac{d}{dt} \left(\left(\frac{L_0 \frac{dI}{dt}}{1 + I(t)^2} \right) \right)^2 - \log \left(1 + I(t)^2 \right) \right)$$



$$= \frac{d}{dt} \left(\frac{L_0 \frac{dI}{dt}}{1 + I(t)^2} \right)^2 - \frac{d}{dt} \left(log \left(1 + I(t)^2 \right) \right)$$



 $= \dots$



$$=2\left(\frac{\frac{dI}{dt}\left(1+I(t)^2\left(\frac{d^2I}{dt^2}\right)-2I(t)\left(\frac{dI}{dt}\right)^2\right)}{\left(1+I(t)^2\right)^3}-\frac{I(t)\left(\frac{dI}{dt}\right)}{\left(1+I(t)^2\right)}\right)$$



$$=2\left(\frac{\frac{dI}{dt}}{1+I(t)^2}\right)\left(\frac{1+I(t)^2\left(\frac{d^2I}{dt^2}\right)-2I(t)\left(\frac{dI}{dt}\right)^2}{\left(1+I(t)^2\right)^2}-\frac{I(t)}{1}\right)$$

$$\frac{dE}{dt} = 0 \quad \forall \quad t \in \mathbb{R} \quad \Longleftrightarrow \frac{d}{dt}I(0) = 0 \quad \text{or} \quad I(0) = 0 \quad \because$$

$$\frac{dE}{dt} = 0 \Longrightarrow \frac{d^2I}{dt^2} = \left(\frac{2I(t)\frac{dI}{dt}}{1 + I(t)^2} + \frac{4\left(\frac{dI}{dt}\right)^3I(t)}{\left(1 + I(t)^2\right)^3}\right)\frac{(1 + I(t)^2)^2}{2\left(\frac{dI}{dt}\right)}$$

Which by definition is a second order autonomous ODE. Thus, If I = c is a specific solution, then its phase line is independent of the time at which initial conditions are applied. Hence

$$\frac{d^2I}{dt^2} = 0, \quad I_0 = 0 \quad \therefore \quad \frac{dE}{dt} = 0$$



Numerical Methods - Runge Kutta 4

$$K_{1} = hf(x_{n}, y_{n})$$

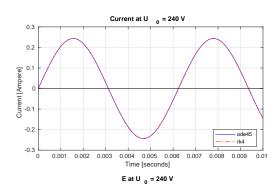
$$K_{2} = hf(x_{n} + \frac{h}{2}, y_{n} + \frac{k_{1}}{2})$$

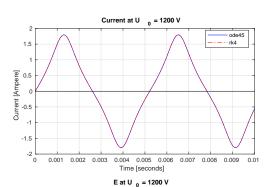
$$K_{3} = hf(x_{n} + \frac{h}{2}, y_{n} + \frac{k_{2}}{2})$$

$$K_{4} = hf(x_{n} + h, y_{n} + k_{3})$$

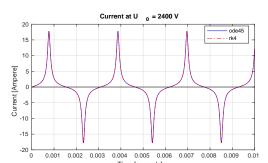
$$y_{n+1} = y_{n} + \frac{1}{6}(K_{1} + 2K_{2} + 2K_{3} + K_{4}) + O(h^{5})$$

0.057600000000001





1 44



Fourier analysis

$$I(t) = a_1 sin(\omega t) + a_2 sin(2\omega t) + a_3 sin(3\omega t) + \cdots, \qquad \omega = 2\pi/T$$

$$a_k = \frac{2}{T} \int_0^T I(t) \sin(k\omega t) dt, \quad k = 1, 2, 3....$$

Fourier analysis

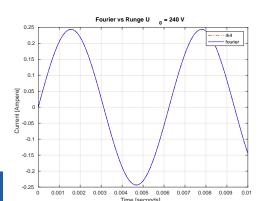
▶ Trapezoidal integration for periodic functions

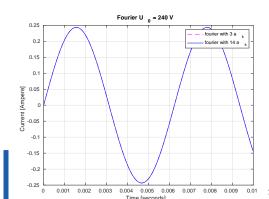


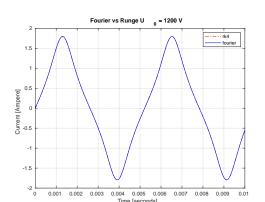
Fourier analysis

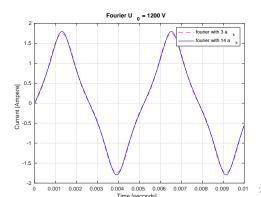
► Trapezoidal integration for periodic functions

$$I = T(h) - \frac{f'(b) - f'(a)}{12}h^2 + \frac{f'''(b) - f'''(a)}{720}h^4 - \frac{f^{(5)}(b) - f^{(5)}(a)}{30240}h^6 + O(h^8)$$



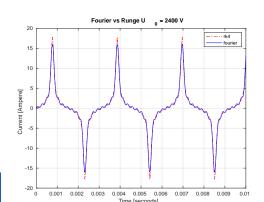


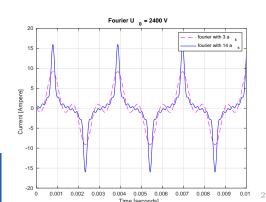




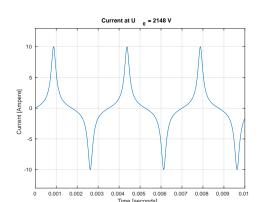


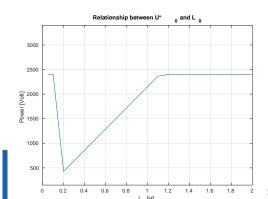
$U_0 = 2400V$





Voluntary part 1

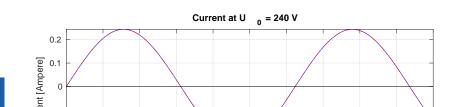




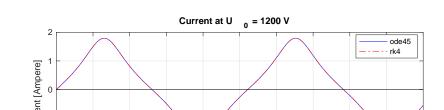
$$U = L\frac{dI}{dt} \qquad I = -C\frac{dU}{dt} \qquad L = \frac{L_0}{1 + I^2}$$

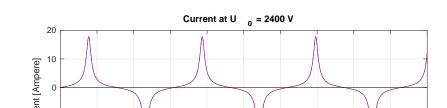
$$\tilde{y}' = \begin{bmatrix} \frac{dI}{dt} \\ \frac{dU}{dt} \end{bmatrix} = \begin{bmatrix} \frac{1+I^2}{L_0}U \\ \frac{dI}{dt} \end{bmatrix}$$

Voluntary part 2



Voluntary part 2







Thanks

github - haaln

mail - hassanan@kth.se