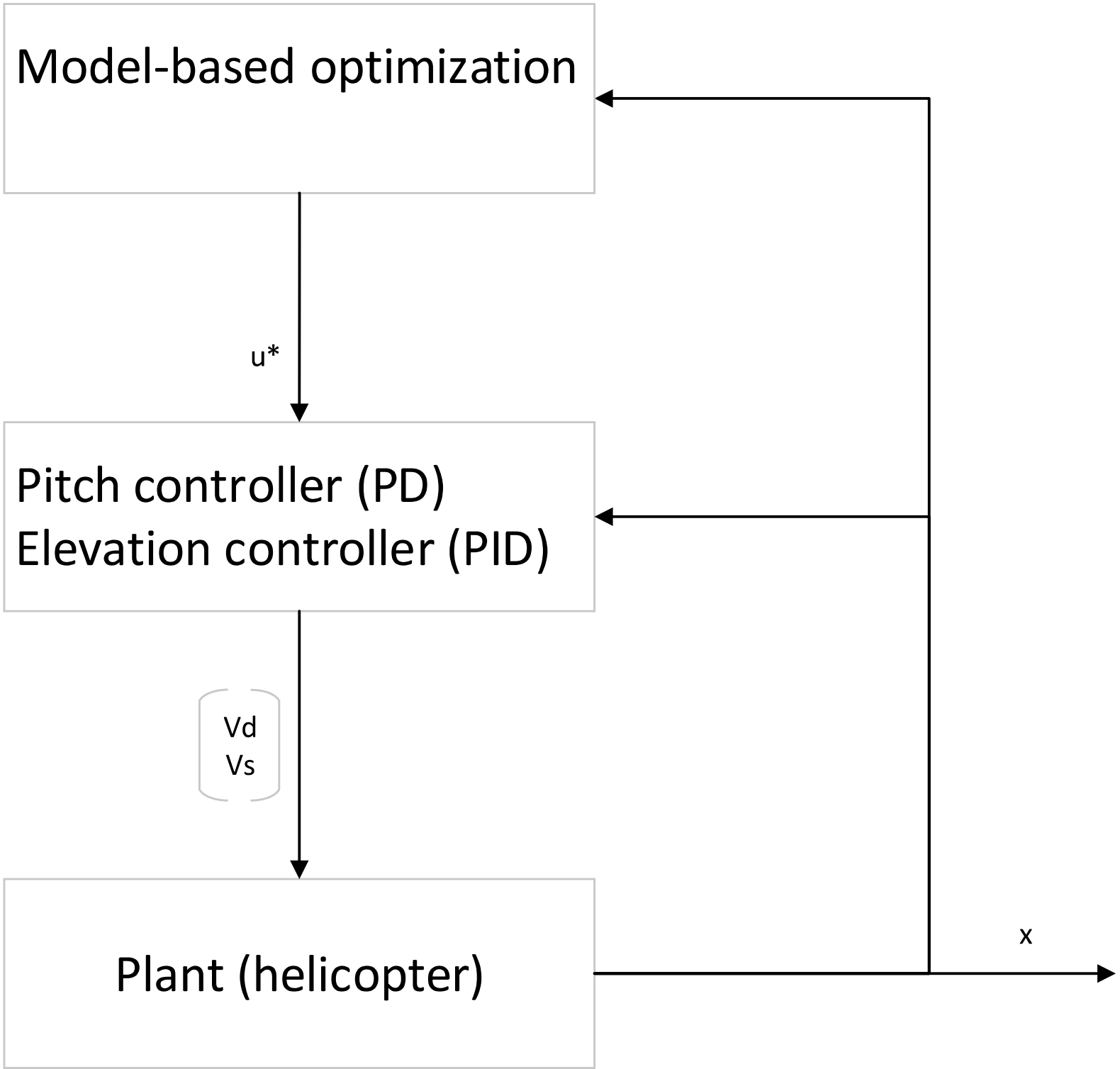
Model-based optimization
u*
Pitch controller (PD)
Elevation controller (PID)
Vd
Vs
Plant (helicopter)
x