

## Potential Outcome Framework

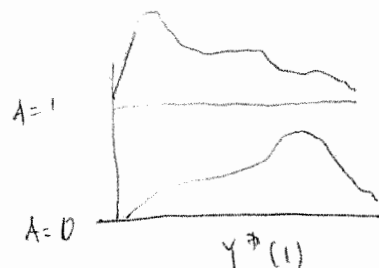
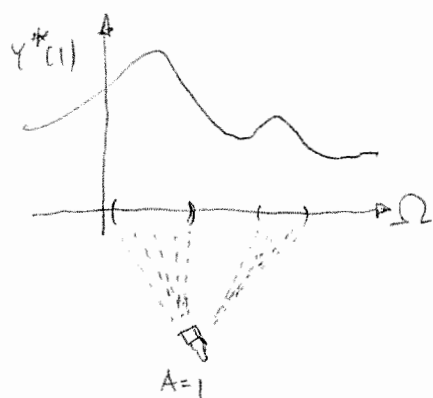
① Observe  $(Y, A)$ . What is the "causal effect of  $A$  on  $Y$ ?"

Postulate potential outcomes  $Y^*(0), Y^*(1), \dots$  for  $A=0, A=1, \dots$  (SUTVA)

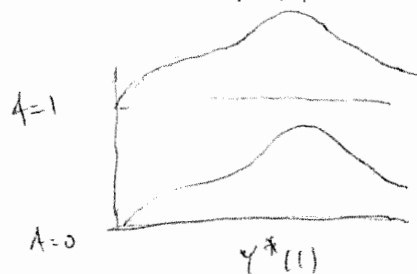
Link to the data:  $Y = AY^*(1) + (1-A)Y^*(0)$  ("consistency")

ATE:  $IE Y^*(1) - IE Y^*(0)$

② Estimation - confounding - formulation as a missing data problem

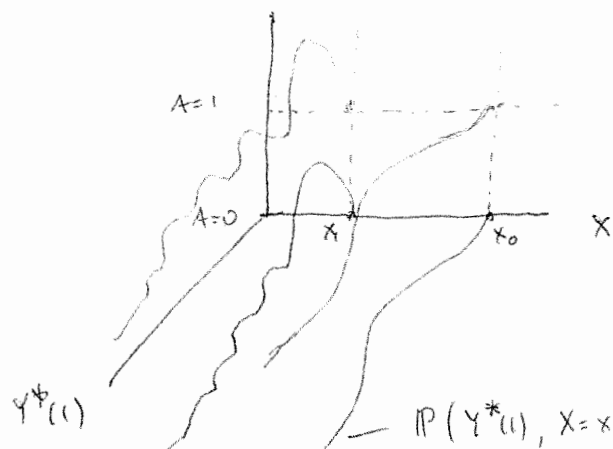


confounding  
 $IE(Y|A=1) \neq IE Y^*(1)$



randomization:  $A \perp Y^*(1)$   
ATE =  $IE(Y|A=1) - IE(Y|A=0)$   
association = causation

Require ~~to solve~~ In absence of randomization, require  $A \perp (Y^*(0), Y^*(1)) | X$



No unmeasured confounders

$$P(Y^*(1), X=x_0, A=0) \propto P(Y^*(1), X=x_0, A=1)$$

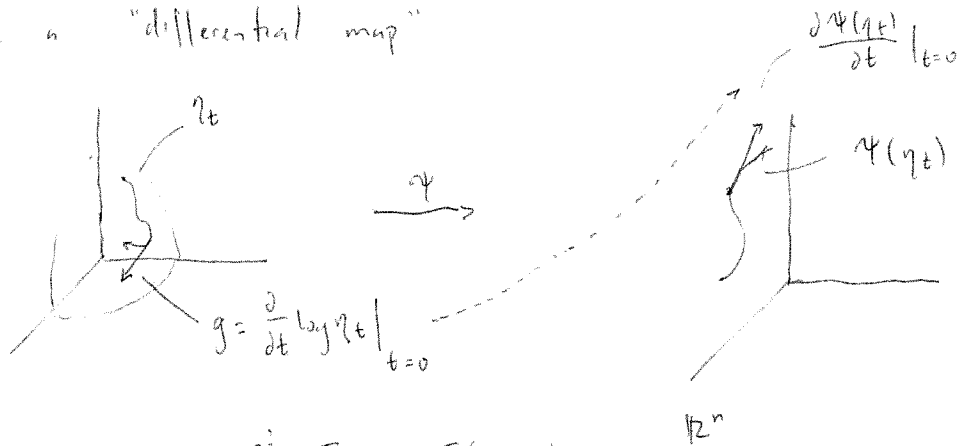
# Semiparametrics

① Problem is to estimate  $\Psi \theta = \mathbb{E} Y^*(1) - \mathbb{E} Y^*(0)$  on observing  $(Y, A, X)$

Consider RAL estimates  $\sqrt{n}(\hat{\delta}_n - \delta) = n^{-1/2} \sum_{j=1}^n \hat{\Psi}(Y_j, A_j, X_j) + o_{p_n}(1)$

Geometric interpretation of influence function  $\hat{\Psi}$

Given probability model  $\eta \in H$  and a functional  $\Psi: H \rightarrow \mathbb{R}^n$ ,  $\hat{\Psi}$  is like a "differential map"



$$\hat{\Psi}: T(\eta) \rightarrow T(\Psi(\eta))$$

$$\hat{\Psi}g = (\hat{\Psi}, g) = \frac{\partial \Psi(\eta_t)}{\partial t}$$

(semiparametric set-up:  $\eta = (\theta, v)$ ,  $\Psi(\eta) = \theta$ )

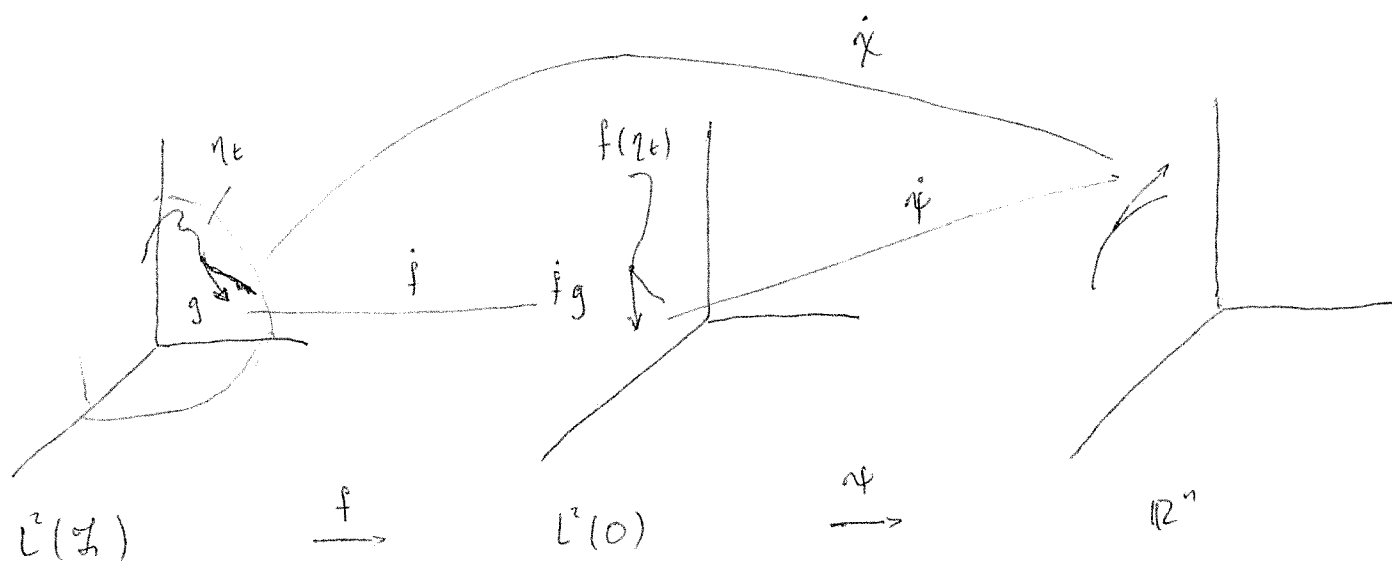
# Semiparametrics

② Coarsening or "information loss model"

$$(Y^*(0), Y^*(1), X) \xrightarrow{f} (Y, A, X) = (AY^*(1) + (1-A)Y^*(0), A, X)$$

"of"                      "O"

We want influence functions of parameter on coarsened data  
from influence functions  $\chi$  on full data



$$\dot{\chi}(g) = (\dot{\chi}, g) = \dot{\psi}(\dot{f}g) = (\dot{\psi}, \dot{f}g) = (\dot{f}^* \dot{\psi}, g)$$

observed data influence function  $\dot{\psi}$  obtained from pre-image  
under  $\dot{f}^*$  of full-data influence function

Thm In information loss model,  $\dot{f}$  is conditioning

$$\dot{f}g = \mathbb{E}(g(Z_1) | 0) = \mathbb{E}(g(Y^*(1), Y^*(0), X) | Y, A, X)$$

$$\dot{f}^* \text{ is reverse conditioning } \dot{f}^*g = \mathbb{E}(g(0) | Z_1)$$

# ATE estimation strategy

## Strategy

- 1) find full-data influence functions ("X")
- 2) find observed data influence functions
  - a) solve  $E(h(Y, A, X) | \mathcal{F}_1) = \phi^F(\mathcal{F}_1)$  for  $h$ , where  $\phi^F(\mathcal{F}_1) \in \Lambda_F^\perp$  is an unnormalized influence function
  - b) solve  $E(h(Y, A, X) | \mathcal{F}_1) = 0$  for  $h$  — "augmentation space"
- 3) find efficient influence function, derive doubly robust estimator

- 1) Non-parametric model for  $\mathcal{F} = (Y^*(0), Y^*(1), X)$ , just a single influence function

$$\hat{\Psi}_n = \frac{1}{n} \sum_{j=1}^n (Y_j^*(1) - Y_j^*(0)), \quad \Psi = Y^*(1) - Y^*(0) - \Psi_0$$

Then

$$2a) \quad E[h(Y, A, X) | Y^*(0), Y^*(1), X] = Y^*(1) - Y^*(0) - \Psi_0$$

$$\Rightarrow h(Y, A, X) = \frac{AY}{\pi(X)} - \frac{(1-A)Y}{1-\pi(X)} - \Psi_0$$

~~$$E\left[\frac{AY}{\pi(X)} \mid Y^*(0), Y^*(1), X\right] = E\left[\frac{AY^*(1)}{\pi(X)} \mid X\right] = Y^*(1)$$~~

$$E\left(\frac{AY}{\pi(X)} \mid Y^*(0), Y^*(1), X\right) = \pi^{-1}(X) E(AY^*(1) | \dots) = Y^*(1) \dots$$

$$2b) \quad \mathbb{E}(h(Y, A, X) \mid Y^*(0), Y^*(1), X) = 0$$

$$= \mathbb{E}(A h(Y, 1, X) + (1-A) h(Y, 0, X) \mid Y^*(0), Y^*(1), X)$$

$$= \mathbb{E}(A h(Y^*(1), 1, X) + (1-A) h(Y^*(0), 0, X) \mid Y^*(0), Y^*(1), X)$$

$$= h(Y^*(1), 1, X) \pi(x) + h(Y^*(0), 0, X) (1 - \pi(x))$$

$$h(Y^*(1), 1, X) \pi(x) = -h(Y^*(0), 0, X) (1 - \pi(x))$$

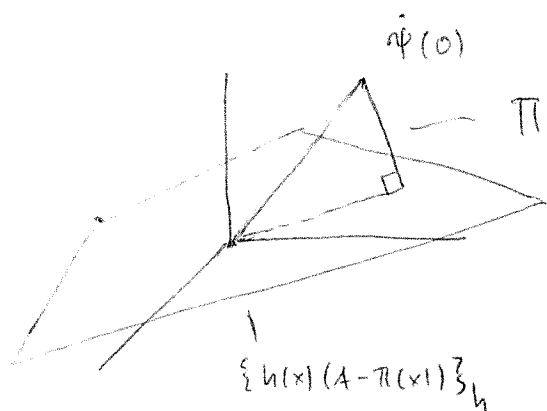
$$\Rightarrow h(Y, A, X) = h(A, X) = A h(1, X) - (1-A) \frac{\pi(x)}{1-\pi(x)} h(1, X)$$

$$= h(1, X) \frac{A - \pi(x)}{1 - \pi(x)} = h'(x) (A - \pi(x)) \quad * \text{ score for } \pi_t(x)$$

3) Observed data influence functions are

$$\frac{AY}{\pi(x)} - \frac{(1-A)Y}{1-\pi(x)} + h(x) (A - \pi(x)) - \psi_0, \quad h \in L^2(x)$$

minimize norm (variance) at the residual



linearize in  $A$  and use

$$\pi(A f(Y, X) \mid (A - \pi(x)) h(x)) = (A - \pi(x)) \mathbb{E}(f \mid A=1, X)$$

$$\psi_{\text{eff}}(Y, A, X) = \frac{AY}{\pi(x)} - \frac{(A - \pi(x)) \mathbb{E}(Y \mid A=1, X)}{\pi(x)}$$

$$- \frac{(1-A)Y}{1-\pi(x)} - \frac{(A - \pi(x)) \mathbb{E}(Y \mid A=0, X)}{1-\pi(x)} - \psi_0$$

~~$$\psi_{\text{eff}}(Y, A, X) = \frac{AY}{\pi(x)} - \frac{(A - \pi(x)) \mathbb{E}(Y \mid A=1, X)}{\pi(x)} - \frac{(1-A)Y}{1-\pi(x)} - \frac{(A - \pi(x)) \mathbb{E}(Y \mid A=0, X)}{1-\pi(x)} - \psi_0$$~~