

Practical Lab: First-Order System Analysis

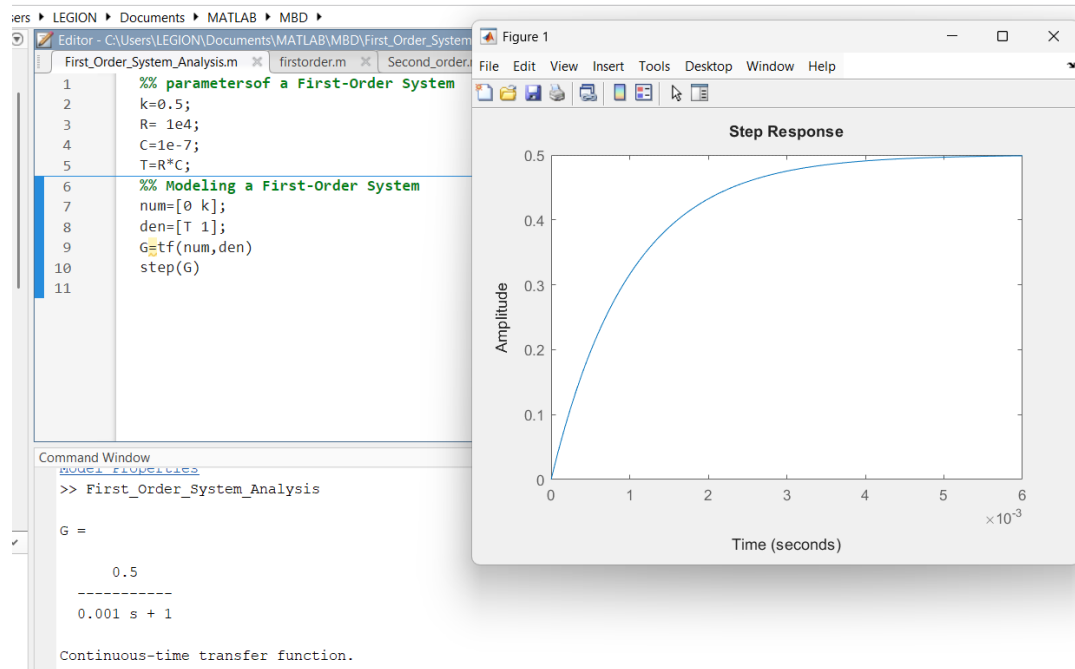
OS-Academy

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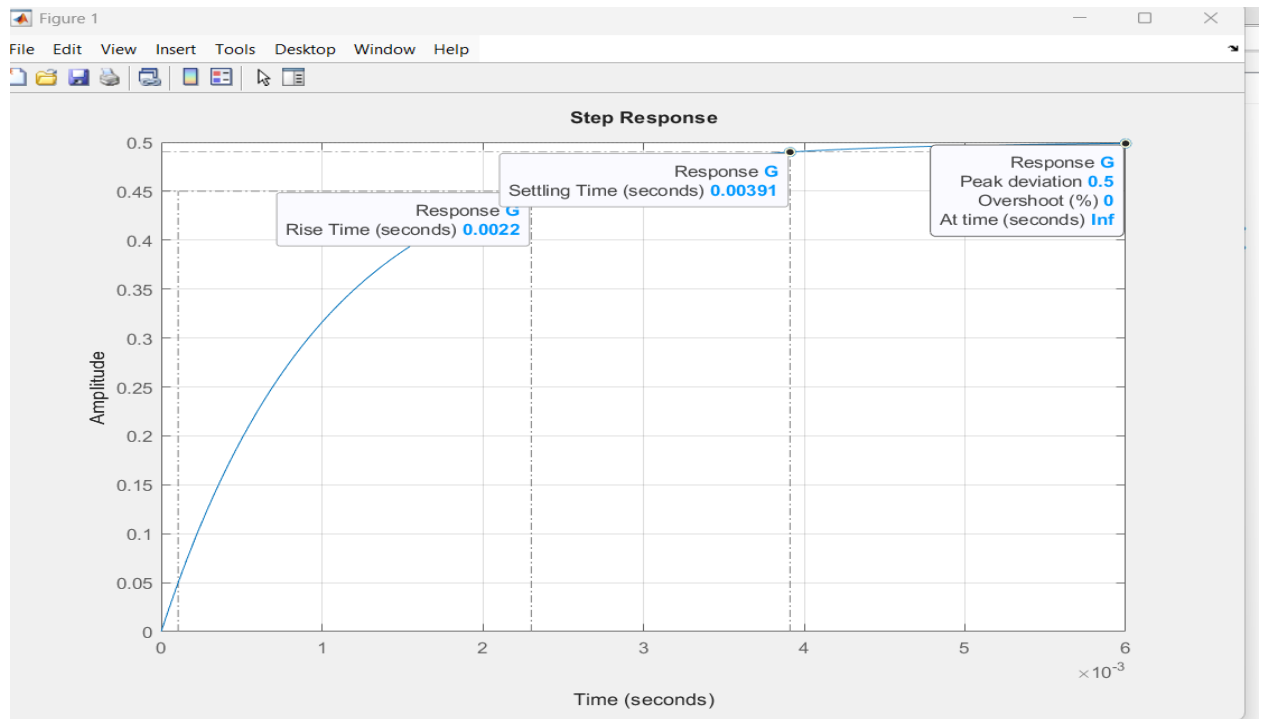
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1. Modeling a First-Order System:



2. Analyzing the System Response:

- Observe the response characteristics, such as rise time, settling time, and overshoot, on the plot. (NO Overshoot for the 1st order system)



- Use the `stepinfo` function in MATLAB to obtain and display numerical values for these response characteristics.

```
11
12 %% Analyzing the System Response:
13 sys=stepinfo(G);
14 disp(sys)
```

Command Window

Continuous-time transfer function.

Model Properties

```
RiseTime: 0.0022
TransientTime: 0.0039
SettlingTime: 0.0039
SettlingMin: 0.4523
SettlingMax: 0.4997
Overshoot: 0
Undershoot: 0
Peak: 0.4997
PeakTime: 0.0073
```

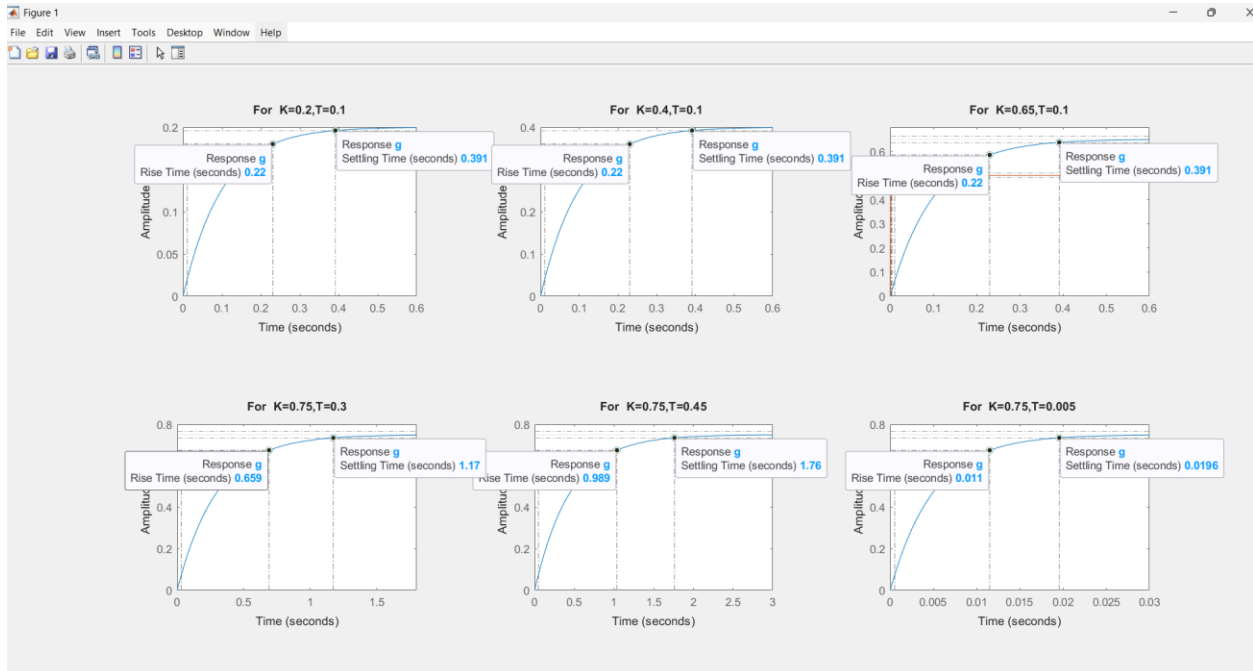
3. Exploring Different Scenarios:

- Change the values of the gain (k) and the time constant (T) and observe how it affects the system's time response.

```
14 %% Exploring Different Scenarios:
15 k=0.75;
16 t=0.005;
17 Num=[0 k];
18 Den=[t 1];
19 g=tf(Num,Den);
20 subplot(2,3,6)
21 step(g)
22 title(['For ' 'K=' num2str(k) ', ' 'T=' num2str(t)])
23 hold on
```

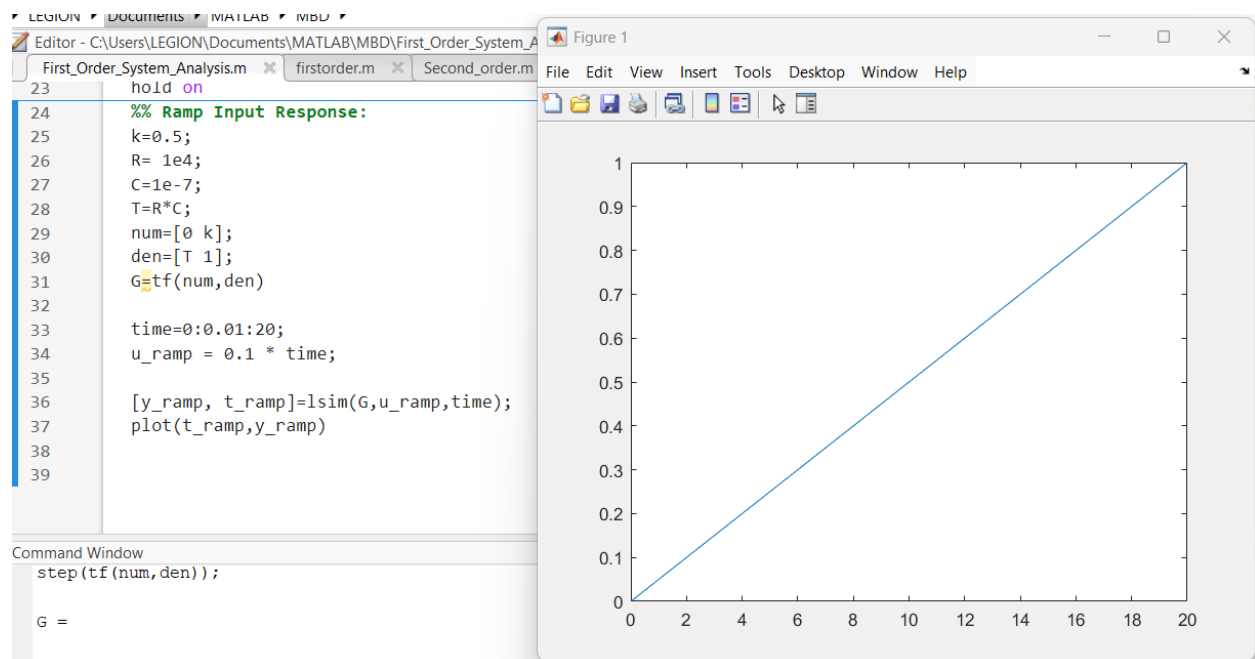
- Plot and analyze the step response for different combinations of gain and time constant values. As the time constant increases (constant gain), T_s increases & the response is slower.

As gain K increases (constant T), the output increases.



4. Ramp Input Response:

- Plot the system's response to the ramp input.



Let the system be a closed-loop system with unity feedback.

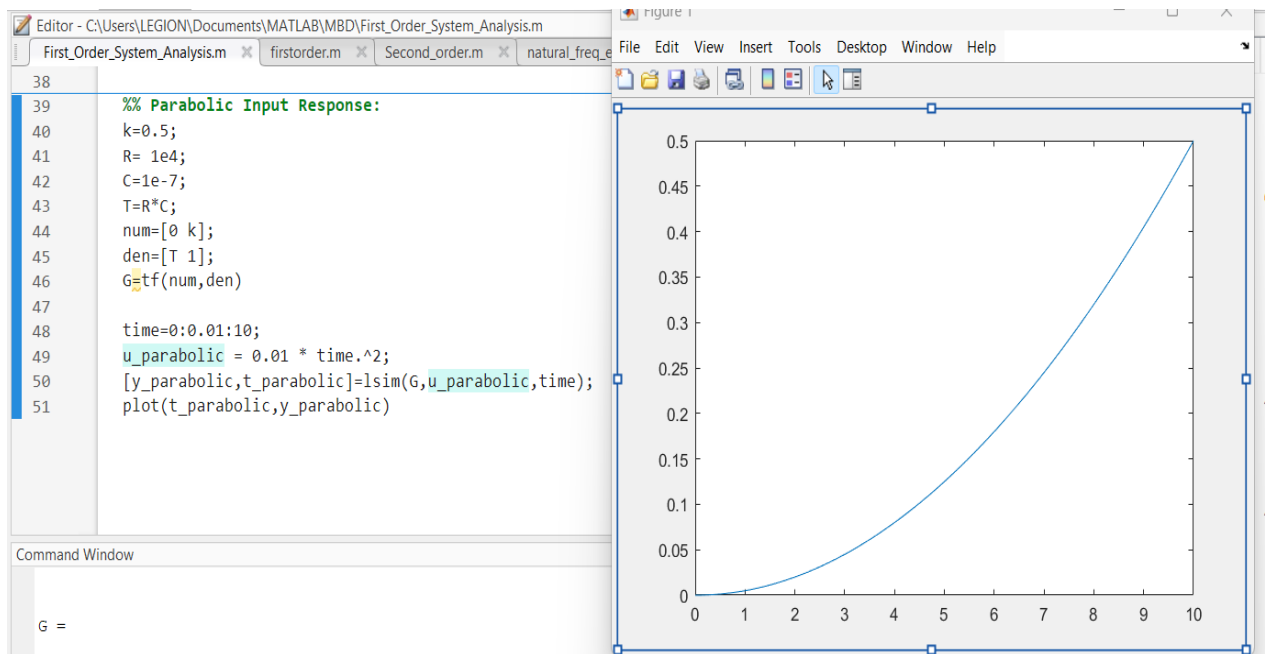
$$K_v = \lim_{s \rightarrow 0} s * G = \text{zero.}$$

K_v : velocity constant & the steady state error = $1/K_v = \infty$

$$G = \frac{0.5}{0.001 s + 1}$$

5. Parabolic Input Response:

- Plot the system's response to the parabolic input.



- Analyze the response and observe how the system reacts to a changing rate of input.

Increasing the rate of the input increases the error between the input and output, because the system cannot track the input fast enough.

