# Heart Monitor (Demo 1)

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## GITHUB REPO:

https://github.com/habibagamal/EmbeddedProject\_HeartMonitor

#### Current Progress in Embedded Application

- ADC samples ECG signals
- Sampling frequency of ADC is determined by timer 3 (Timer 3 triggers ADC start of conversion)
- Timer 2 is used to count 1 minute (Used in "Collect 1 minute worth of data" command)
- The UART supports the receipt of the 3 required commands

#### Current Progress in Python Application

- Python application is developed through which user can send commands and receive data from microcontroller through UART
- Python application plots the ECG signals in real-time
- Python application allows user to set the COM port and the baud rate

#### To-do (Embedded Application)

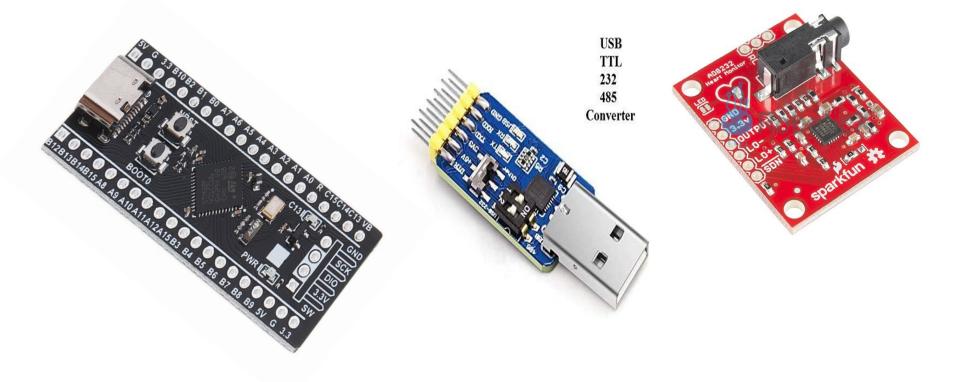
- Calculate heart rate (bpm)
- Increase the #of digits of sampling frequency to 7 (to support up to the maximum sampling frequency of the ADC of 1MSPS)

(will not attempt this point as Dr. Shalan pointed to me that 1 kHz is a practical maximum sampling frequency for this application)

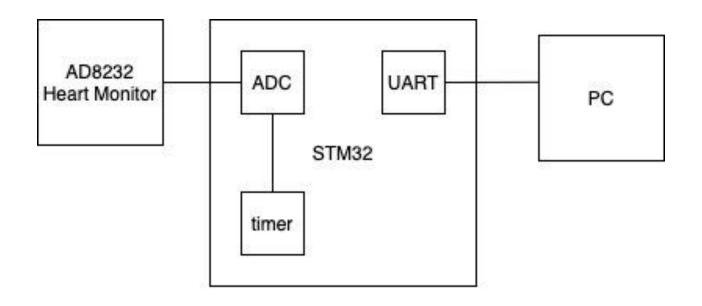
#### To-do (Python Application)

- Auto-concatenate white spaces to the short commands (Now, it needs to be done manually when inputting the command)
- Example:
  - The longest command is the one used to set the sampling rate. It is composed of 6 characters "f=xxxx"
  - only. Right now the user needs to send the command "bpm" which is made of 3 characters only. Right now the user needs to enter bmp followed by any 3 characters.
  - To start collecting 1-min worth of data, the user needs to send the command "start" which is 5 characters so the user needs to transmits any extra character
- For the final submission: the python application will auto-concatenate white spaces to short commands

### **Used Components**

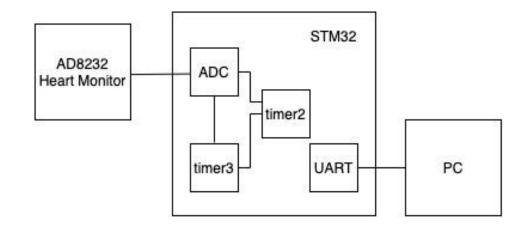


#### Block Diagram In Proposal



#### Updated Block Diagram

 When developing the application, I realized I need 2 timers. Timer 2 is used to count 1 minute, timer 3 is used to trigger ADC conversion.



#### Design Details of Embedded Application

- UART receive generates an interrupt.
- If one of the three supported commands is received, its operation starts
- If "start" command is sent, the ADC, timer2 and timer3 are started. At the end
  of each ADC conversion, the ADC converted value is read and sent through
  UART.
- The python application uses this value to plot the real-time graph

#### Design Details of Embedded Application (Cont'd)

- If "f=xxxx" is sent, the program reads "xxxx", converts it to integer, then computes the period that corresponds to this frequency.
- The period of timer3 (which triggers the start of conversion of the ADC) is changes to match the computed period.
- The next "start" command will use this new frequency

#### Design Details of Embedded Application (Cont'd)

- If "bpm" command is sent, currently the "report" is sent through UART to indicate that the command is received
- In my to-do list, the "bpm" command will compute the bpm and then report it to the use through transmission over UART
- If none of the 3 commands is received, the UART transmits "no command" to indicate that it received unsupported command
- The python application will prevent this last case from happening, through checking the commands inputted by the user before sending them to the microcontroller

#### Design Details of Python Application

- Multi-threaded application
- Producer-Consumer architecture
- Thread 1 (Producer Thread)
  - Reads command line input
  - Waits until it is consumed
- Thread 2 (Consumer Thread)
  - Consumes read user input
  - Send this data to the microcontroller

#### Design Details of Python Application (Cont'd)

- Thread 3 (Printing thread)
  - Reads data from the microcontroller
  - Prints received data to the user
- Main thread
  - Plots the real-time ECG signals

#### **UART** baud rate

- I increased the baud rate to 402000
- 1 kHz is practically the maximum sampling rate of the application
- To transmit 1k samples per second, each sample is made up of 4 digits and each digit is transmitted in 10 bits.
- In 1 second, 400000 bits need to be transmitted