

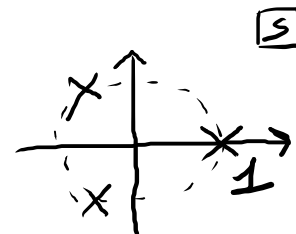
$$\begin{cases} \dot{x}_1 = x_3 + \alpha^2 u \\ \dot{x}_2 = x_1 + 2\alpha u \\ \dot{x}_3 = x_2 + u \\ y = x_3 \end{cases} \quad A = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \quad B = \begin{bmatrix} \alpha^2 \\ 2\alpha \\ 1 \end{bmatrix}$$

$$C = \begin{bmatrix} 0 & 0 & 1 \end{bmatrix}$$

a) $\varphi(s) = \det(sI - A) = \det \begin{bmatrix} s & 0 & -1 \\ -1 & s & 0 \\ 0 & -1 & s \end{bmatrix} = s \cdot s^2 - 1 \cdot 1 = s^3 - 1$

$$\varphi(s) = 0 \Leftrightarrow s^3 - 1 = 0 \Leftrightarrow s^3 = 1$$

NOTA: gli autovalori sono le 3 radici cubiche dell'unità nel campo dei numeri complessi



$$\varphi(s) = (s-1)(s^2 + as + b) = s^3 - 1$$

$$s^3 + as^2 + bs - s^2 - as - b = s^3 - 1$$

$$s^3 + (a-1)s^2 + (b-a)s - b = s^3 - 1 \quad \Leftrightarrow \quad \begin{cases} a = 1 \\ b = 1 \end{cases}$$

$$\varphi(s) = (s-1)(s^2 + s + 1)$$

$$\begin{aligned}
 G(s) &= C(sI-A)^{-1}B = \frac{1}{\varphi(s)} C \operatorname{Adj}(sI-A) B = \\
 &= \frac{1}{(s-1)(s^2+s+1)} [0 \ 0 \ 1] \begin{bmatrix} s^2 & 1 & s \\ s & s^2 & 1 \\ 1 & s & s^2 \end{bmatrix} \begin{bmatrix} \alpha^2 \\ 2\alpha \\ 1 \end{bmatrix} \\
 &= \frac{1}{(s-1)(s^2+s+1)} [1 \ s \ s^2] \begin{bmatrix} \alpha^2 \\ 2\alpha \\ 1 \end{bmatrix} = \frac{1}{(s-1)(s^2+s+1)} (\alpha^2 + s \cdot 2\alpha + s^2) \\
 &= \frac{s^2 + 2\alpha s + \alpha^2}{(s-1)(s^2+s+1)} = \frac{(s+\alpha)^2}{(s-1)(s^2+s+1)}
 \end{aligned}$$

Devo vedere per quali α ho semplificazioni

$$\alpha = -1 \quad G(s) = \frac{(s-1)^2}{(\cancel{s-1})(s^2+s+1)} = \frac{s-1}{s^2+s+1}$$

$\alpha \neq -1$ non ci sono semplificazioni

$$a(s) = s^2 + s + 1$$

$$\varphi_R(s) = s - 1$$

$$a(s) = \varphi(s)$$

$$\varphi_R(s) = 1$$

b) problema ben posto $\Leftrightarrow \varphi_R(s)$ ha tutte radici con $\text{Re} < 0$

$$\alpha = -1 \quad \varphi_R(s) = s - 1 \quad \text{autovalore } \lambda_1 = 1 \text{ nascosto}$$

\Rightarrow problema mal posto

$$\alpha \neq -1 \quad \varphi_R(s) = 1 \quad \Rightarrow \text{problema ben posto}$$

c) $\alpha = 2$ studiare stabilità in ciclo chiuso al variare di K

$$\begin{aligned} \varphi^*(s) &= \varphi_R(s) [a_c(s) + K b(s)] = s^3 - 1 + K(s+2)^2 \\ &= s^3 - 1 + K(s^2 + 4s + 4) = s^3 + Ks^2 + 4Ks + 4K - 1 \end{aligned}$$

studio la stabilità costruendo la tabella di Routh

$$\begin{array}{c|cc} 3 & 1 & 4K & 0 \\ 2 & K & 4K-1 & 0 \\ 1 & E_{11} & 0 & \\ 0 & 4K-1 & & \end{array} \quad E_{11} = -\frac{1}{K} \det \begin{bmatrix} 1 & 4K \\ K & 4K-1 \end{bmatrix} = -\frac{1}{K} (4K-1 - 4K^2)$$
$$= \frac{4K^2 - 4K + 1}{K}$$

$$\begin{array}{c|c} 3 & 1 & 4k \\ 2 & k & 4k-1 \\ 1 & \frac{4k^2-4k+1}{k} & \\ 0 & 4k-1 & \end{array}$$

tutte radici con $\text{Re} < 0$



tutti elementi della prima colonna $\neq 0$
e con segno concorde



$$\left\{ \begin{array}{l} k > 0 \\ \frac{4k^2 - 4k + 1}{k} > 0 \\ 4k - 1 > 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} k > 0 \\ 4k^2 - 4k + 1 > 0 \\ k > \frac{1}{4} \end{array} \right.$$



$$\left\{ \begin{array}{l} k > \frac{1}{4} \\ (2k-1)^2 > 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} k > \frac{1}{4} \\ k \neq \frac{1}{2} \end{array} \right.$$

stabilit  asintotica in ciclo chiuso $\Leftrightarrow k > \frac{1}{4}$ e $k \neq \frac{1}{2}$

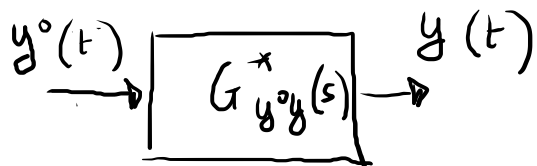
d) Prendo ad esempio $k = \frac{1}{3}$

$$G_{y^o y}^*(s) = \frac{b(s)}{a(s) + k b(s)} H = \frac{s^2 + 4s + 4}{s^3 + ks^2 + 4ks + 4k - 1} H = \frac{s^2 + 4s + 4}{s^3 + \frac{s^2}{3} + \frac{4s}{3} + \frac{1}{3}} H$$

$$G_{y^o y}^*(0) = \frac{4}{1/3} H = 12 H$$

$$G_{y^o y}^*(0) = 1 \quad \Leftrightarrow \quad H = \frac{1}{12}$$

e) $y^o(t) = 5 \cdot \sin(t) \cdot 1(t)$ regime permanente?



$G_{y^o y}^*(s)$ stabile \Rightarrow posso applicare il teorema delle risposte in frequenza

$$y^{r^o}(t) = 5 \left[\operatorname{Re} \{ G_{y^o y}^*(j\omega_0) \} \sin(\omega_0 t) + \operatorname{Im} \{ G_{y^o y}^*(j\omega_0) \} \cos(\omega_0 t) \right] 1(t)$$

$$y^{ro}(t) = 5 \left[\operatorname{Re} \{ G_{y^o y}^*(j\omega_0) \} \sin(\omega_0 t) + \operatorname{Im} \{ G_{y^o y}^*(j\omega_0) \} \cos(\omega_0 t) \right] 1(t)$$

$\omega_0 = 1$

$$G_{y^o y}^*(s) = \frac{s^2 + 4s + 4}{s^3 + \frac{s^2}{3} + \frac{4}{3}s + \frac{1}{3}} \cdot \frac{1}{12}$$

$$G_{y^o y}^*(j) = \frac{(j)^2 + 4j + 4}{(j)^3 + \frac{j^2}{3} + \frac{4}{3}j + \frac{1}{3}} \cdot \frac{1}{12} = \frac{-1 + 4j + 4}{-j - \frac{1}{3} + \frac{4}{3}j + \frac{1}{3}} \cdot \frac{1}{12} = \frac{3 + 4j}{\frac{1}{3}j} \cdot \frac{1}{12}$$

$$= \frac{9j - 12}{-1} \cdot \frac{1}{12} = \frac{12 - 9j}{12} = 1 - \frac{3}{4}j$$

$$y^{ro}(t) = 5 \left[\sin(t) - \frac{3}{4} \cos(t) \right] 1(t)$$