

**WEEK 6-2017**

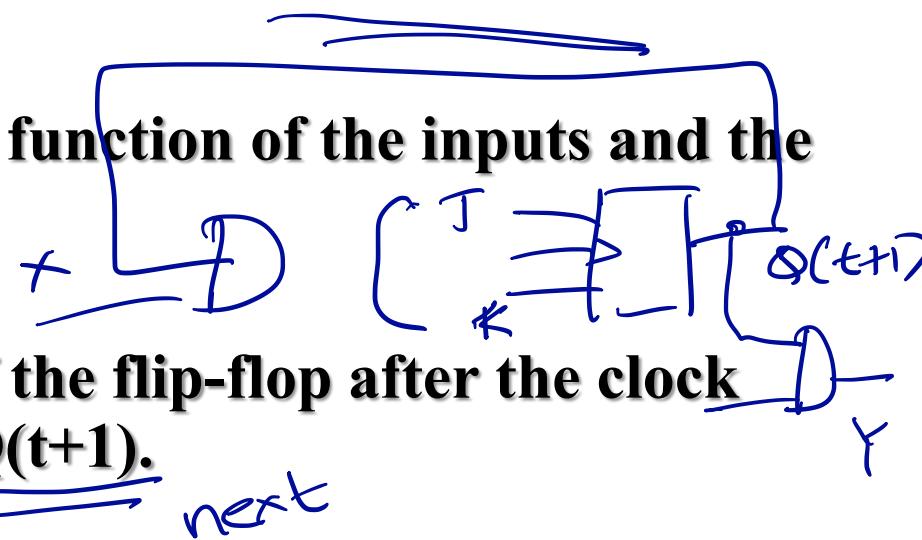
# Synchronous Sequential Circuit II



# Characteristic Tables

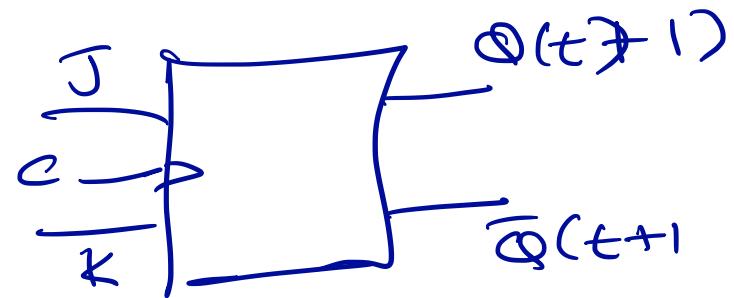
JK  
D  
T

- A characteristic table defines the logical properties of a flip-flop by describing its operation in tabular form.
- It defines the next state as a function of the inputs and the presents state.
- The next state is the state of the flip-flop after the clock transition and denoted by  $\underline{\underline{Q(t+1)}}$ .
- The present state is the state of the flip-flop immediately before the clock edge and denoted by  $\underline{\underline{Q(t)}}$ .

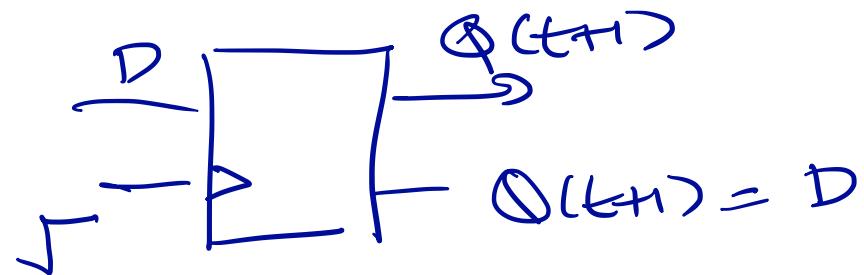


# Characteristic Tables

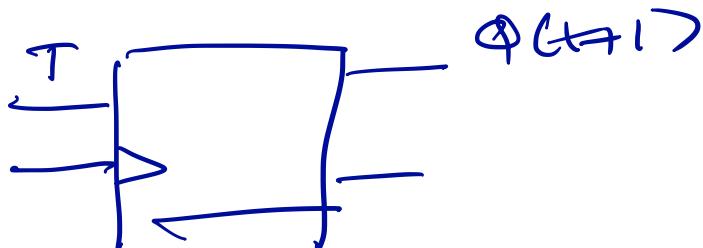
J	K	$Q(t+1)$	
0	0	$Q(t)$	unchanged
0	1	0	Reset
1	0	1	Set
1	1	$\bar{Q}(t)$	complement



D	$Q(t+1)$	
0	0	reset
1	1	set



T	$Q(t+1)$	
0	$Q(t)$	unchanged
1	$\bar{Q}(t)$	complemented



# Characteristic Equations

Q	J	K	Q (t+1)
0	0	0	0
0	0	1	0
0	1	0	1
0	1	1	1
1	0	0	1
1	0	1	0
1	1	0	1
1	1	1	0

$Q(t+1)$ :

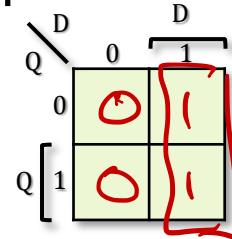
JK \ Q	00	01	11	10
Q	0	0	1	1
Q	1	0	0	1

$$Q(t+1) = \bar{J}\bar{Q} + \bar{K}Q$$

# Characteristic Equations

$Q$	$D$	$Q(t+1)$
0	0	0
0	1	1
1	0	0
1	1	1

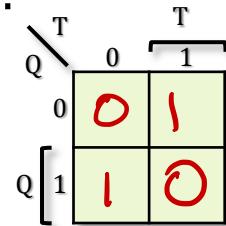
$Q(t+1):$



$$Q(t+1) = D$$

$Q$	$T$	$Q(t+1)$
0	0	0
0	1	1
1	0	1
1	1	0

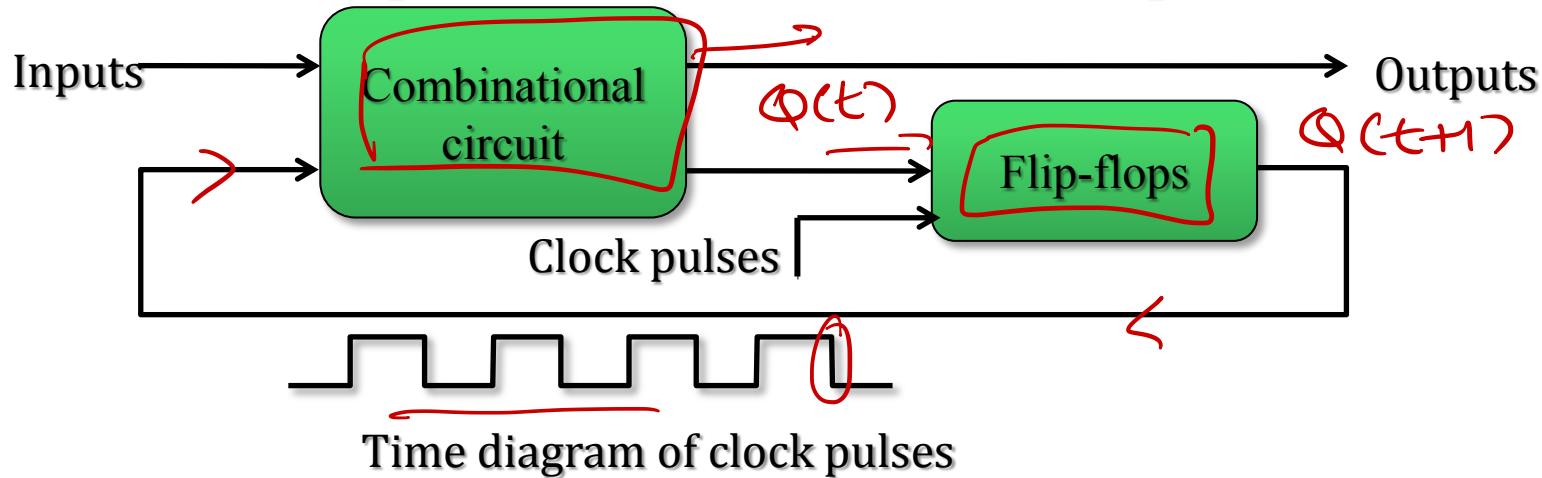
$Q(t+1):$



$$\begin{aligned} Q(t+1) &= \bar{Q}T \\ &\quad + Q\bar{T} \\ &= T \oplus Q \end{aligned}$$

# Analysis of clocked Sequential Circuit

- The behavior of a clocked sequential circuit is determined from the inputs, internal states and outputs.



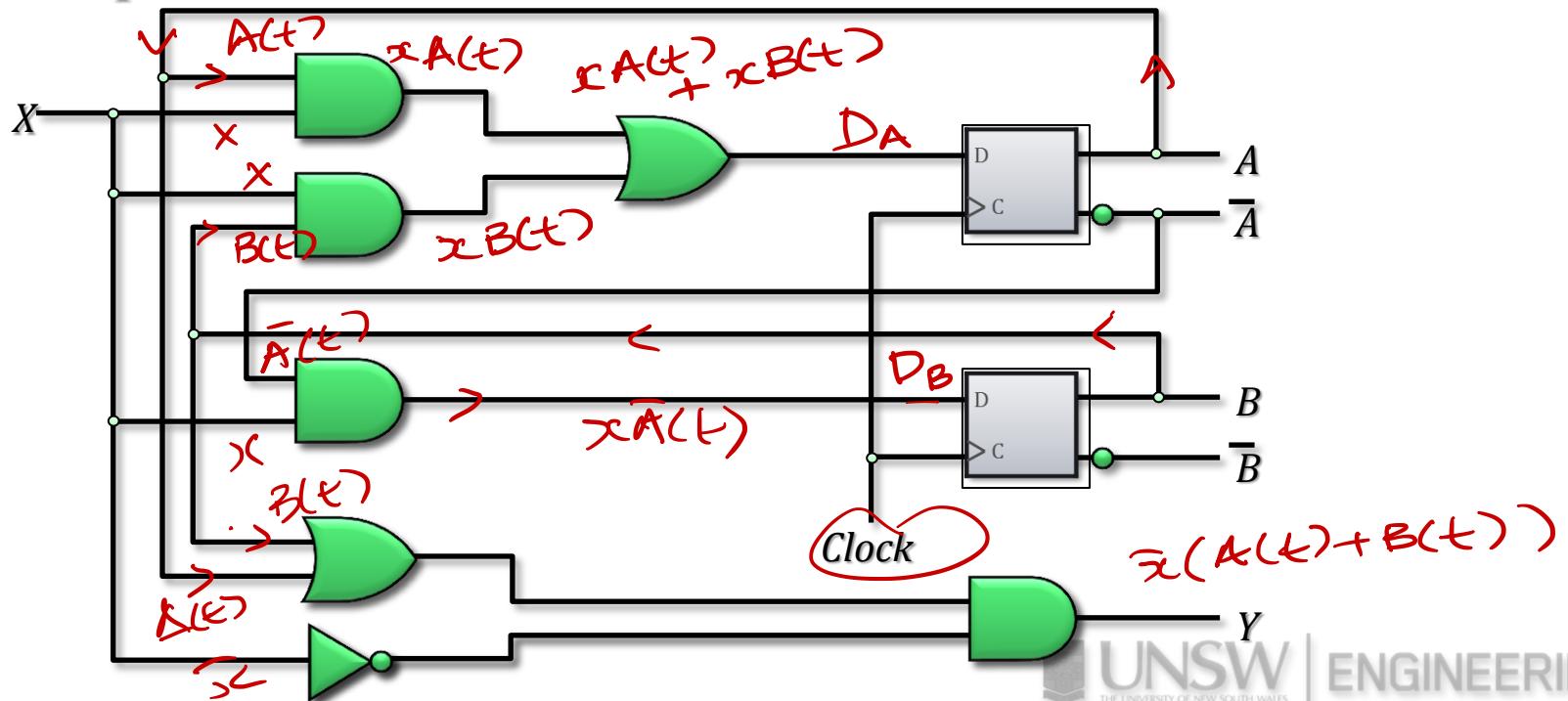
- The outputs and the next state are both the function of the inputs and the present state.
- Analysis of sequential circuit consists of obtaining a table or a diagram for the time sequence of inputs, internal states and outputs.
- Boolean expressions can be used to describe the behavior of the sequential circuit. In this case, it should include the necessary time sequence

# Analysis of clocked Sequential Circuit

- State equation, state table and state diagram will be used to describe the behavior of any clocked sequential circuit.

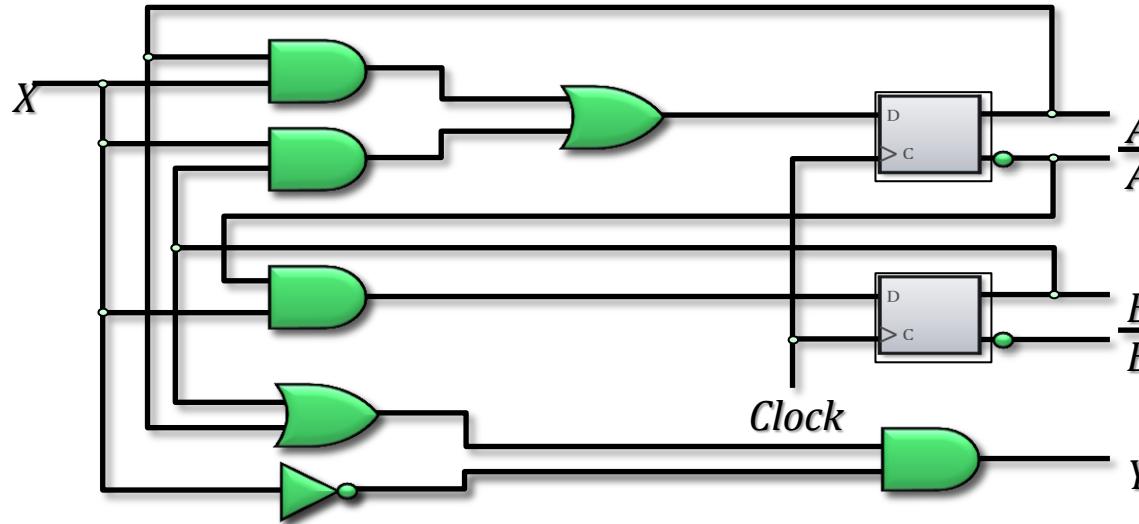
## State Equations (Transition Equation):

- A state equation (transition equation) specifies the next state as a Boolean function of the present state and inputs.



# State Equations

State Equations (Transition Equation):



Since the D input of a flip-flop determines the value of the next state (i.e, the state reached after the clock transition)

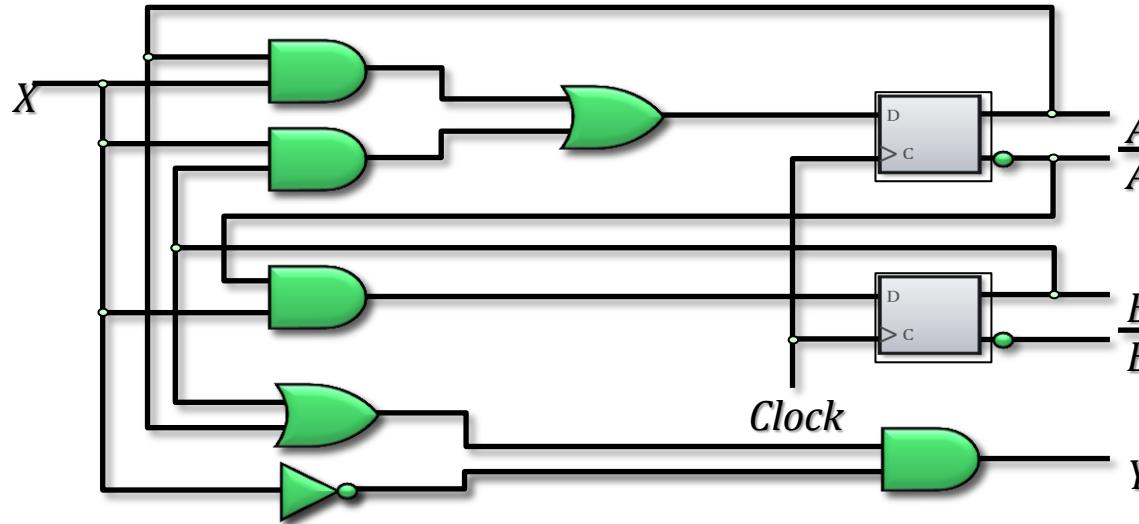
$$\begin{aligned} \overbrace{A(t+1)}^{\rightarrow} &= \overbrace{A(t)x(t)}^{\text{D input}} + \overbrace{B(t)x(t)}^{\text{D input}} \\ \overbrace{B(t+1)}^{\text{underlined}} &= \overbrace{A(t)}^{\text{D input}}x(t) \end{aligned}$$

The present-state value of the output can be expressed algebraically as

$$Y(t) = \overbrace{[A(t) + B(t)]}^{\text{underlined}} \overbrace{x(t)}^{\text{underlined}}$$

# State Equations

State Equations (Transition Equation):



Since all variables in the Boolean expressions are a function of the present state, the designation of ( $t$ ) after each variable can be omitted

$$\begin{aligned} \rightarrow A(t+1) &= Ax + Bx \\ \rightarrow B(t+1) &= \bar{A}x \end{aligned}$$

The present-state value of the output can be expressed algebraically as

$$Y(t) = [A + B]\bar{x}$$

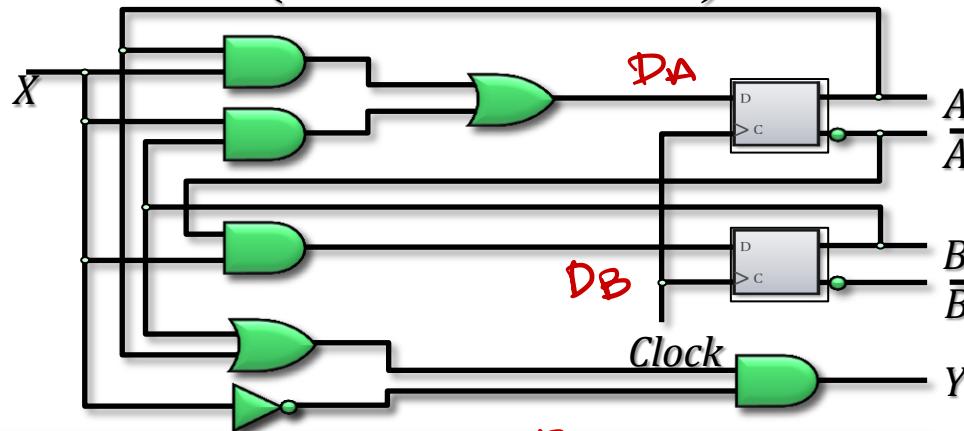
# State table

State table (Transition table):

- It is possible to enumerate the time sequences of inputs, outputs and states of the sequential circuit using state table (transition table)
- The table consists of four sections labelled present state, input, next state and output.  
 $\overbrace{x}^{\text{present state}}$     $\overbrace{A(t) \ B(t)}^{\text{input}}$     $\overbrace{A(t+1) \ B(t+1)}^{\text{next state}}$
- The derivation of a state table requires listing all possible binary combinations of present states and inputs.
- The next-states and the output values are then determined from the logic diagram or state equations for each possible binary combination.

# State table

State table (transition table):



Present state	Input	$D_A$	$D_B$	Next state	Output
A B	X			A B	Y
0 0	0	0	0	0 0	0
0 0	1	0	0	0 1	0
0 1	0	0	0	0 0	1
0 1	1	1	1	1 1	0
1 0	0	0	0	0 0	1
1 0	1	1	1	0 0	0
1 1	0	0	0	0 0	1
1 1	1	1	0	1 0	0

$\downarrow \quad \downarrow \quad \downarrow$

$$A(t+1) = Ax + Bx$$

$$B(t+1) = \bar{A}x$$

$$Y(t) = [A + B]\bar{x}$$

# State table

State table (transition table):

wx

00	-
01	-
10	-
11	-

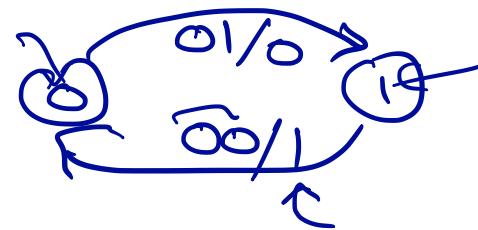
- The state transition may be conveniently expressed in a slightly different form having only three sections: present state, next state and output.

Present state		Next state		Output	
		X=0	X=1	X=0	X=1
A	B	A	B	A	B
0	0	0	0	1	0
0	1	0	0	1	0
1	0	0	0	1	0
1	1	0	0	1	0

Diagram annotations: A blue oval encloses the 'Present state' column. Another blue oval encloses the 'Next state' and 'Output' columns. A blue bracket underlines the 'X=0' and 'X=1' labels in the 'Next state' row. A blue bracket underlines the 'X=0' and 'X=1' labels in the 'Output' row. A blue arrow points from the 'Output' column to the right.

$$\begin{aligned}A(t+1) &= Ax + Bx \\B(t+1) &= \bar{A}x \\Y(t) &= [A + B]\bar{x}\end{aligned}$$

# State diagram

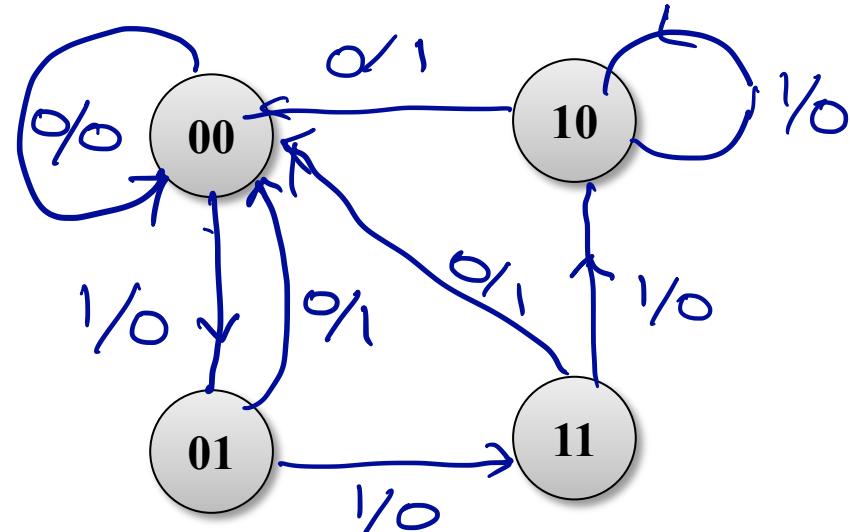


- The information available in state tables can be represented graphically in the form of a state diagram.
- In a state diagram, a state is indicated by a circle and the transitions between the states are represented by directed lines connecting the circles.
- The directed lines are labeled with two binary numbers separated by a slash. The first binary number is for the input value and the second number shows the output value for the given input value during the present state which is represented by a circle from which the directed line emanates.

# State diagram

- The state diagram for the following state table can be drawn as:

Present state		Next state		Output	
A	B	X=0	X=1	X=0	X=1
0	0	0	0	0	0
0	1	0	0	1	0
1	0	0	0	1	0
1	1	0	0	1	0



- The same information is conveyed by both state diagram and state table.
- State diagrams provides pictorial representation that is easier for human representation.

# State and output time sequence

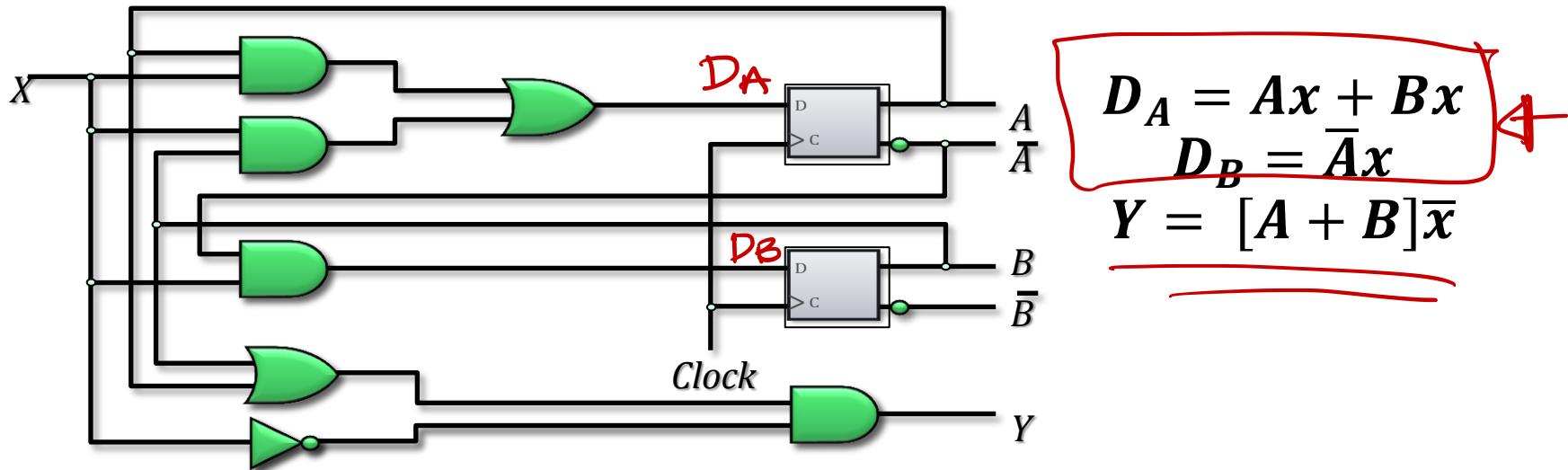
- Find state and output time sequence for input sequence of 010100110 assuming the sequential is initially in state 00

Clk	0	1	0	1	0	0	1	1	0	0
X	0	1	0	1	0	0	1	1	0	0
A	0	0	0	0	0	0	0	0	1	0
B	0	0	1	0	0	1	0	0	1	0
Y	0	0	1	0	1	0	0	0	1	0

Present state	Next state		Output	
	X=0	X=1	X=0	X=1
A B	A	B	A	B
0 0	0	0	0	1
0 1	0	0	1	1
1 0	0	0	1	0
1 1	0	0	1	0

# Flip-flop input equations

- The set of Boolean functions that describes the part of the sequential circuit that generates the inputs to flip-flops.

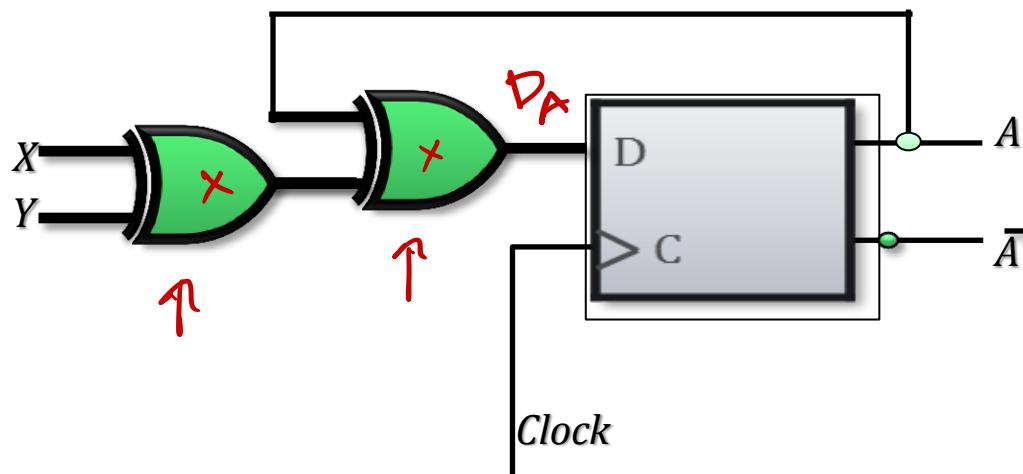


- The three equations provide the necessary information for drawing the logic diagram of the sequential circuit.
- The symbol  $D_A$  specifies a D flip-flop labeled A and  $D_B$  is for another D flip-flop labeled B.
- The flip-flop equations specify the combination circuit that drives the flip-flops and the type of flip-flops used.

# Analysis with D flip-flops

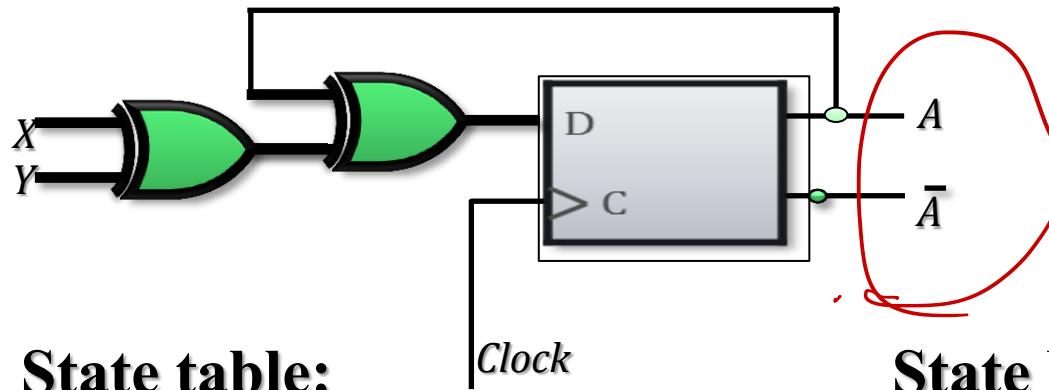
- Steps in analyzing clocked sequential circuits with D flip-flops:
  - Find the flip-flop input equations.
  - The state equations are the same as the flip-flop input equations for D flip-flops.
  - Derive the state table from the state equations.
  - Draw the state diagram from the state table

Example:



$$\begin{aligned}D_A &= X \oplus Y \oplus A \\A(t+1) &= D_A \\&= X \oplus Y \oplus A\end{aligned}$$

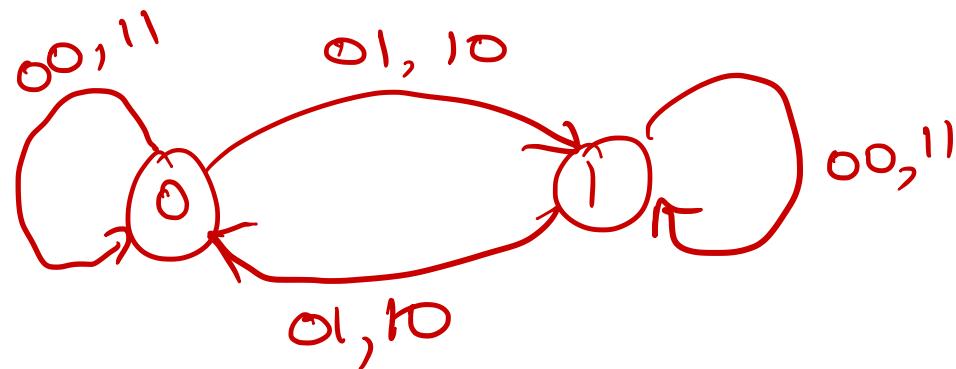
# Analysis with D flip-flops



- State table:

Present state	Input		Next state
A	X	Y	A
0	0	0	0
	0	1	1
	1	0	1
	1	1	0
1	0	0	1
	0	1	0
	1	0	0
	1	1	1

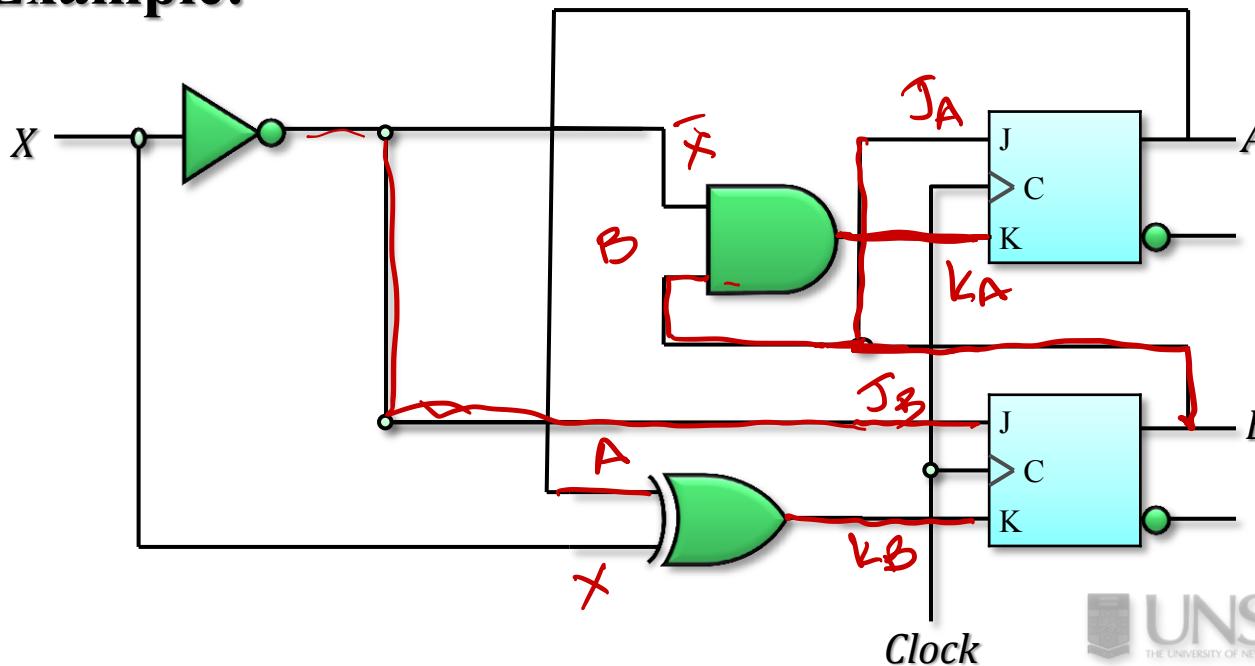
State Diagram:



# Analysis with JK flip-flops

- Steps in analyzing clocked sequential circuits with JK flip-flops:
  - Find the flip-flop input equations in terms of present state and inputs.
  - List the binary values of each input equation.
  - Use the JK flip-flop characteristic table to determine the next states in the state table.
  - Use K-map to obtain minimized state equations

Example:



$$\begin{aligned}J_A &= B \\K_A &= B\bar{X} \\J_B &= \bar{X} \\K_B &= A \oplus X\end{aligned}$$

# Analysis with JK flip-flops

- Flip-flop input equations:

$$J_A = \underline{B}$$

$$J_B = \underline{\bar{x}}$$

$$K_A = \underline{\bar{B}x}$$

$$K_B = \underline{A \oplus x}$$

$$Q(t+1) = J\bar{Q} + \bar{K}Q$$

$$A(t+1) = J_A \bar{Q} + \bar{K}_A Q$$

Present state	Input	Next state		Flip-Flop inputs			
		A	B	$J_A$	$K_A$	$J_B$	$K_B$
0 0	0	0	1	0	0	1	0
0 0	0	0	0	0	0	0	1
0 1	0	1	1	1	0	1	0
0 1	1	1	0	1	0	0	1
1 0	0	1	1	0	0	1	1
1 0	0	1	0	0	0	0	0
1 1	0	0	0	1	1	1	1
1 1	1	1	1	1	0	0	0

Handwritten notes:

$$A(t+1) = \bar{B}x$$

$$Q(t+1) = 00 \quad 01 \quad 11 \quad 10$$

$$Q(t) = 00 \quad 01 \quad 11 \quad 10$$

$$A(t) = 0 \quad 1 \quad 1 \quad 0$$

$$A(t+1) = \bar{A}\bar{B}$$

$$+ A\bar{B}x + Ax\bar{C}$$

Handwritten notes:

$$B(t+1) = \bar{B}x + \bar{A}\bar{x} + Ax\bar{B}$$

$$Q(t+1) = 00 \quad 01 \quad 11 \quad 10$$

$$Q(t) = 00 \quad 01 \quad 11 \quad 10$$

$$A(t) = 0 \quad 1 \quad 1 \quad 0$$

# Analysis with JK flip-flops

- Steps in analyzing clocked sequential circuits with JK flip-flops:
  - Find the flip-flop input equations in terms of present state and inputs.
  - Substitute the input equations into the flip-flop characteristic equation to obtain the state equations.
  - Use the corresponding state equations to determine the next-values in the state table and state diagrams

For previous example:

$$J_A = B$$

$$K_A = B\bar{X}$$

$$J_B = \bar{X}$$

$$K_B = \overline{A \oplus x}$$

Characteristic equation for JK flip-flop:

$$A(t+1) = J_A \bar{A} + \overline{K_A} A$$

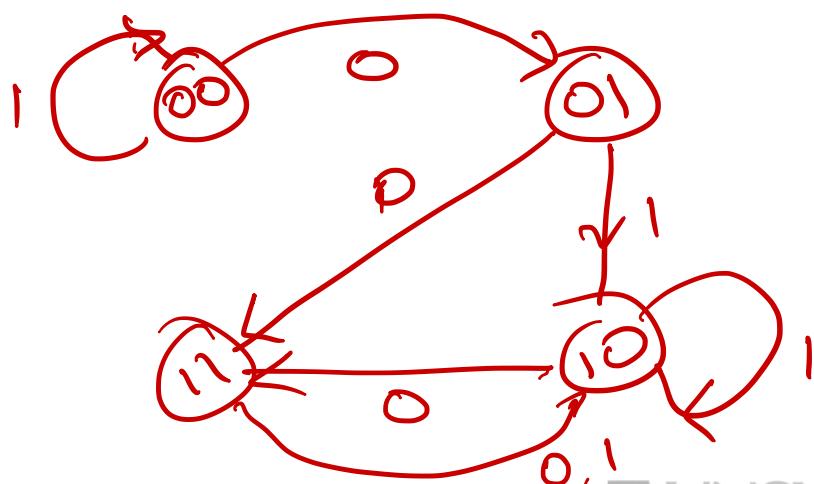
$$B(t+1) = J_B \bar{B} + \overline{K_B} B$$

# Analysis with JK flip-flops

State Table:

Present state		Next State			
		X=0		X=1	
A	B	A	B	A	B
0	0	0	1	0	0
0	1	1	1	1	0
1	0	1	1	1	0
1	1	1	0	1	0

State Diagram:



# Analysis with T flip-flops

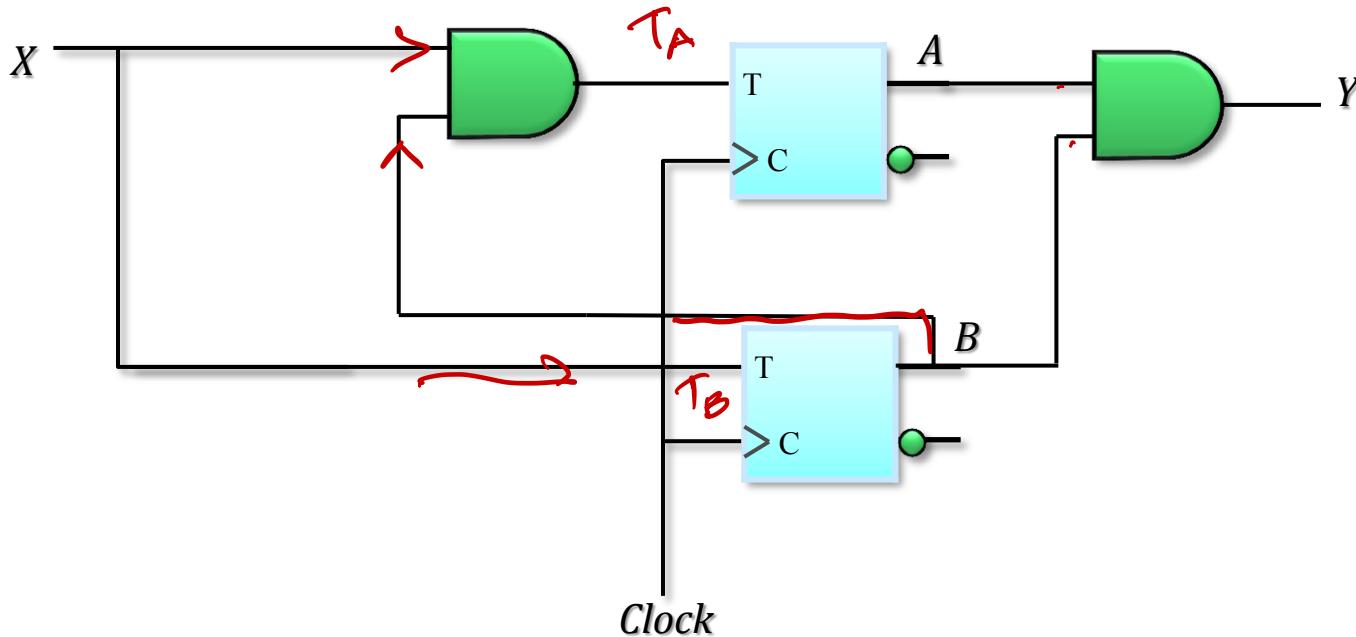
- The same procedure as JK flip-flop is to be followed:
  - Find the flip-flop input equations in terms of present state and inputs.
  - List the binary values of each input equation.
  - Use the T flip-flop characteristic table to determine the next states in the state table.
  - Use K-map to obtain minimized state equations

OR

- Find the flip-flop input equations in terms of present state and inputs.
- Substitute the input equations into the flip-flop characteristic equation to obtain the state equations.
- Use the corresponding state equations to determine the next-values in the state table and state diagrams

# Analysis with T flip-flops

Example:



$$\begin{array}{ll} T=0 & Q(t+1) \\ & = Q(t) \\ T=1 & Q(t+1) \\ & = \overline{Q(t)} \end{array}$$

Flip-flop input equations:

$$T_A = \overline{B} \cdot C$$

$$T_B = X$$

Output equation:

$$Y = AB$$

# Analysis with T flip-flops

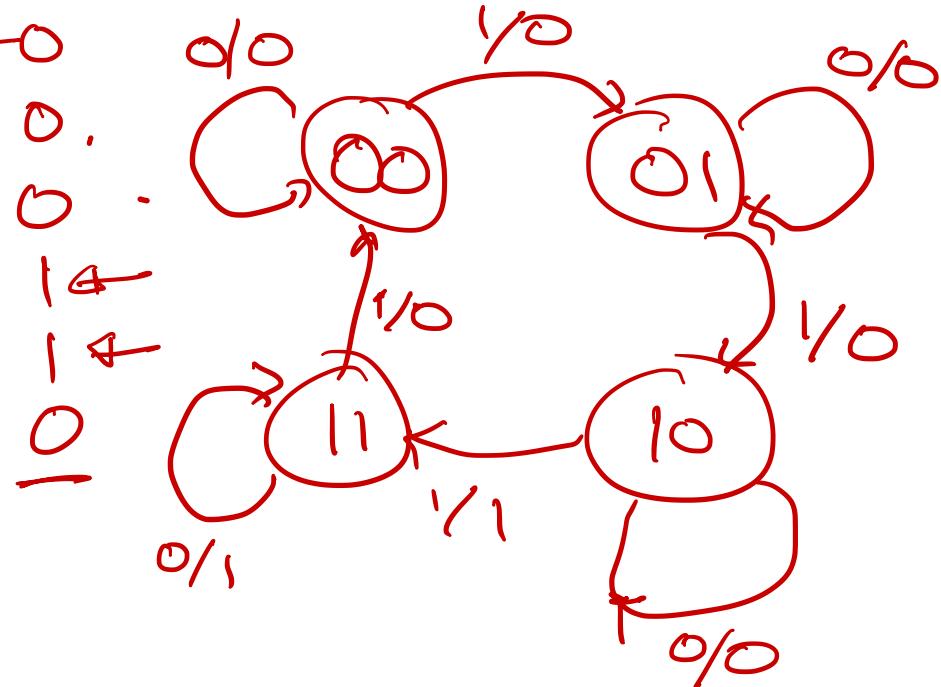
$$\begin{array}{ll} \textcircled{Q} & \\ T=0 & Q(t+1) = Q(t) \\ =1 & Q(t+1) = \bar{Q}(t) \end{array}$$

Present state	Input	Next state		Flip-Flop inputs	
A B	X	A	B	<u><math>T_A</math></u>	<u><math>T_B</math></u>
0 0	0	0	0	0	0
0 0	1	0	1	0	1
0 1	0	0	1	0	0
0 1	1	1	0	1	1
1 0	0	1	0	0	0
1 0	1	1	1	0	0
1 1	0	0	0	0	1
1 1	1	0	0	1	1

$$T_A = XB$$

$$T_B = X$$

$$Y = \underline{AB}$$



# Analysis with T flip-flops

For previous example:

$$T_A = \cancel{x_B}$$

~~$x_{A,B,C,D}$~~

$$T_B = \cancel{x_C}$$

Characteristic equation for T flip-flop:

$$A(t+1) = \cancel{T_A} \oplus A$$

$$B(t+1) = \cancel{T_B} \oplus B$$

# Analysis with T flip-flops

State Table:

Present state		Next State				Output state	
		X=0		X=1		X=0	X=1
A	B	A	B	A	B	Y	Y
0	0	0	0	0	1	0	0
0	1	0	1	1	0	0	0
1	0	1	0	1	1	0	0
1	1	1	1	0	0	1	1



State Diagram: