

RSDK Toolchain User Guide

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RSDK Toolchain User Guide for Release 1.5.6p2
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Chapter 1 RSDK

The Realtek Software Development Kit (RSDK) is a chain of software tools that empowers end-users to develop embedded applications that run on Realtek's in-house processor cores. The set of tools in RSDK can be divided into three groups, compilers, binary utilities, and C libraries. The tools in the first two groups are derived from the GNU compiler collection (GCC) and binutils respectively. The C libraries are based on newlib and uClibc.

The lists of changes and enhancements to the original GNU compiler collection and binutils are summarized in the following chapters. For the detailed usage of GNU compiler collection and binutils, please refer to the GNU website at http://www.gnu.org.

Version Numbering

The format of RSDK version number is shown as follows:

GNU version . RLX version . Patch level - pSub-patch Level

The current release version is 1.5.6p2. Each version contains four numbers, GNU version, RLX version, Patch level, and sub-patch level. The GNU version number is mapped to a set of GNU tools which RSDK is based on. The RLX version number corresponds to the processor cores supported by the RSDK. The patch level and sub-patch numbers represent the number of updates in a RSDK branch. It is usually that the higher the numbers the less the bugs.

The RSDK version number will be appended to that of the original GNU tools during the building of RSDK toolchain. To check the RSDK version number as well as the original GNU version numbers, users can issue version display commands shown in program 1.

Example 1: RSDK Version number

```
% rsdk-elf-gcc -v
Using built-in specs.
Target: mips-elf
Configured with: RSDK Builder release 1.5
Thread model: single
gcc version 4.4.6 (Realtek RSDK-1.5.6)
```

Table 1.1 shows the list of GNU tools supported in 1.5.6p2 and table 1.2 shows the list of RLX processor core supported in 1.5.6p2.

Software Component

The list of software components and their version numbers is summarized in table 1.1.

Table 1.1: Software Components

Software	Original Version
gcc	4.4.6
binutils	2.19
insight	6.6
newlib	1.17.0
uclibc	0.9.30.3

Table 1.2: Supported LX/RLX CPU cores

Processor Core	RTL Release Version	MIPS1	MIPS16	RADIAX
LX4180	4.0.2	Yes	Yes	No
LX5280	1.3	Yes	Yes	Yes
RLX4181	1.5	Yes	Yes	No
RLX5181	1.6	Yes	Yes	Yes
RLX4281	1.2	Yes	Yes	No
RLX5281	1.2	Yes	Yes	Yes

Supported Processor Cores

The list of supported processor cores is summarized in table 1.2.

Supported Platform

The list of supported platforms is summarized in table 1.3.

Table 1.3: Supported RSDK platforms

Platform	Version	Package name
Linux RedHat 7.3 and above		rsdk-1.5.6p2 -linux.tar.gz
Cygwin	Cygwin 1.5.10 and above	rsdk-1.5.6p2 -cygwin.tar.gz

NOTE: The C library shipped with RedHat Linux may differ from the one the RSDK toolchain was built against. To ensure maximal compability, the following two packages are recommended if the RedHat Linux version is newer than 7.3.

compat-glibc-7.x-2.2.4.32.6 compat-libstdc++-7.3-2.96.128

NOTE: The Cygwin platform itself is not a stable environment for software development. Users might encounter various problems which are not directly related to the RSDK toolchains. To ensure maximal stability, users are advised to develop applications on Linux platforms whenever possible.

Supported C Libraries

The list of supported C libraries is summarized in table 1.4.

Table 1.4: Supported C Libraries

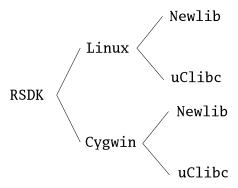
Library	Version
Newlib	1.17.0
uClibc	0.9.30

Installation

The RSDK packages are available as four tarballs, one for each platform and each C library. These toolchains are completely independent. Users should only need to download the desired RSDK toolchain and point the executable path to where it is installed. The tarballs are as follows:

```
rsdk-1.5.6p2 -newlib-linux.tar.gz
rsdk-1.5.6p2 -uclibc-linux.tar.gz
rsdk-1.5.6p2 -newlib-cygwin.tar.gz
rsdk-1.5.6p2 -uclibc-cygwin.tar.gz
```

The structure of the RSDK tarball is shown as follows:



The installation procedure is shown in program 2. The list of supported libraries and their versions is summarized in table 1.4.

Example 2: RSDK installation procedure

```
step 1: cd TARGET_DIR
step 2: bzip2 -cd rsdk-{VERSION}-{LIBRARY}-{PLATFORM}.tar.bz2 | tar xvf -
step 3: ln -s rsdk-{VERSION}/{PLATFORM}/{LIBRARY} rsdk
step 4: set path=(TARGET_DIR/rsdk/bin $path)
```

Chapter 2 GCC

GCC is the GNU Compiler Collection, which includes front ends for multiple languages such as C, C++, Objective-C, Fortran, Java, and Ada, as well as libraries for these languages (libstdc++, libgcj,...).

In RSDK 1.5.6p2, gcc has been upgraded to 4.4 for performance improvement and bug fixes. The list of changes is summarized in the following subsections.

General Changes

Relative path search

GCC search certain paths for binaries, libraries, and includes files during compilation. In RSDK, to ensure maximal portability, GCC has been patched to search paths relative to the GCC binary.

Default options

The following options, listed in table 2.1, are enabled by default.

Table 2.1: Default compiler options

Options	Description
-msoft-float	Enable software floating point support
-meb	Enable big-endian
-march=4180	Set default target to LX4180 if none is specified

Machine-dependent options

-march|mtune|mcpu=4180|4181|5181|5280

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Specify target processor core

Status: Current Version: 1.2.0+ Description:

The marchimtunelmcpu option sets the target processor core to the one specified in the option.

If none of the -march, -mtune, and -mcpu options is specified, compiler will automatically add -march=4180 to the option list.

-mt0-t3

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Expand function parameter registers from four to eight

Dependency: None Status: Current Version: 1.2.0+ Description:

By MIPS ABI convention, only four registers, a0, a1, a2, and a3, are used to pass function parameters. When calling a function with more than four parameters, extra parameters are pushed into and popped out of the stack before and after entering the callee. There are two major drawbacks for this approach. First, incremented number of memory accesses for loading and storing these parameters will certainly degrade the performance. Second, loading data from memory has the load delay penalty and may incur cache miss, which makes things even worse. Therefore, it is beneficial to expand the number of function parameter passing registers from four to eight at the cost of breaching ABI compatibility. When -mt0-t3 option is specified, compiler will use four additional registers, t0, t1, t2, and t3, for passing function parameters. The total number of registers that are reserved for passing parameters is increased from four to eight.

NOTE: this option is not ABI compatible. If this option is used, it should be applied to all the source files in the application.

NOTE: When using inline assembly with this option enabled, users must take caution not to destroy the extra registers, t0-t4. These extra registers should be saved first if they will be used in the inline assembly codes and should be restored after use.

-msimd

Architecture: RLX5181, LX5280

Summary: Expand single instruction multiple data support

Dependency: -mradiax

Status: Current Version: 1.2.0+ Description:

RLX5181 and LX5280 support Single Instruction Multiple Data (SIMD) instructions. A SIMD instruction operates on multiple values contained in a single register at the same time.

Table 2.2: Built-in data type for SIMD instructions

Type	Definition	Internal Type
v2hi	typedef int v2hiattribute((mode(V2HI))	VNB

For multa2, mulna2, madda2, and msuba2, there are three different forms for their builtin functions. The three different forms are internal1, internal2, and internal3. For internal1, the destination register is the upper 32-bit HI of the accumulator. For internal2, the destination register is the lower 32-bit LO of the accumulator. For internal3, the destination register is the entire 64-bit accumulator, HI and LO.

-msave-restore-mmd

Architecture: RLX5181, LX5280 **Summary:** Preserve MMD state

Dependency: -mradiax

Status: Current Version: 1.2.0+ Description:

Table 2.3: Built-in functions defined for SIMD instructions

Function	Argument 0	Argument 1	Return Type
builtin_lx5280_addr2	V2HI	V2HI	V2HI
builtin_lx5280_subr2	V2HI	V2HI	V2HI
builtin_lx5280_min2	V2HI	V2HI	V2HI
builtin_lx5280_max2	V2HI	V2HI	V2HI
builtin_lx5280_multa2_internal1	V2HI	V2HI	V2HI
builtin_lx5280_multa2_internal2	V2HI	V2HI	V2HI
builtin_lx5280_multa2_internal3	V2HI	V2HI	DI (long long)
builtin_lx5280_mulna2_internal1	V2HI	V2HI	V2HI
builtin_lx5280_mulna2_internal2	V2HI	V2HI	V2HI
builtin_lx5280_mulna2_internal3	V2HI	V2HI	DI (long long)
builtin_lx5280_madda2_internal1	V2HI	V2HI	V2HI
builtin_lx5280_madda2_internal2	V2HI	V2HI	V2HI
builtin_lx5280_madda2_internal3	V2HI	V2HI	DI (long long)
builtin_lx5280_msuba2_internal1	V2HI	V2HI	V2HI
builtin_lx5280_msuba2_internal2	V2HI	V2HI	V2HI
builtin_lx5280_msuba2_internal3	V2HI	V2HI	DI (long long)
builtin_lx5280_sltr2	V2HI	SI (int)	V2HI
builtin_lx5280_sllv2	V2HI	SI (int)	V2HI
builtin_lx5280_srlv2	V2HI	SI (int)	V2HI
builtin_lx5280_srav2	V2HI	SI (int)	V2HI
builtin_lx5280_absr2	V2HI	V2HI	V2HI

MMD is a special register that is shared among many RADIAX instructions. The state of this MMD register is crucial for two reasons: First, compiler depends on the state of this MMD register to emit the right RADIAX instruction. Second, sequence of RADIAX instructions rely on the state of this MMD register to operate correctly. During compilation, the compiler keeps track of the state of MMD register carefully. However, if users change the state of the MMD register manually, for example, loading data into the MMD register in inline assembly codes, the result might be unpredictable. The -msave-restore-mmd is provided to add a safe net under this situation. When -msave-restore-mmd is specified, compiler will automatically emit instructions that save the state of MMD register before the operation that changes its state and emit instructions that restore the state of MMD register after the operation result is retrieved.

-mfpga

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Add an extra nop for FPGA boards

Dependency: None **Status:** Obsoleted **Version:** –

Description:

Setting the MMD register requires a delay slot before the data can be used. By default, only a single NOP will be emitted. However, on some FPGA boards, it may take two NOPs to get the data ready. When -mfpga is used, two NOPs will be emitted after setting the MMD register. This option is obsoleted.

Example 3: Example of using built-in functions

```
int func2()
    return i > 0 ? i : -i;
int func1()
    v2hi data[32];
    v2hi sumv1, sumv2;
    long long sumv3;
    int sumv0 = 0;
    int i;
    for (i = 0; i < 32; i++)
        data[i] = \underline{\quad builtin_lx5280_addr2((v2hi) i, (v2hi) i);}
    for (i = 0; i < 32; i++) {
        sumv1 = __builtin_lx5280_madda2_internal1(data[i], data[i]);
        sumv2 = __builtin_lx5280_madda2_internal2(data[i], data[i]);
        sumv3 = builtin lx5280 madda2 internal3(sumv2, data[i]);
    }
    shift_num = func2(-6);
    sumv2 = __builtin_lx5280_srav2(sumv2, shift_num);
    sumv0 = value & 0xffffffff;
    return (int) __builtin_lx5280_subr2(sumv2, (v2hi) sumv0);
```

-mradiax

Architecture: RLX5181, LX5280

Summary: Enable RADIAX support for RLX5181 and LX5280

Dependency: None Status: Current Version: 1.2.0+ Description:

The -mradiax option enables the RADIAX support for RLX5181 and LX5280. The RADIAX instruction extensions include MAC operations, vector-addressing, and enhanced extensions to the MIPS-I ALU instructions. For RLX5181 and LX5280, -mradiax automatically implies -mmac by default.

-mmac

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Enable optional Multiply/Divide/Accumulator support

Dependency: None Status: Current Version: 1.2.0+ Description:

All the LX/RLX processor cores support an optional Multiply/Divide/Accumulate module (MAC-DIV) which further enhances mathematical operations. This MAC-DIV module is configurable using the lconfig utility. When -mmac option is specified, compiler will emit the instructions listed in table 2.4 whenever possible. It is users' responsibilities to ensure the MAC-DIV module exists in the target processor core.

The list of instructions for the optional MAC-DIV module is summarized as follows:

For RLX5181 and LX5280, -mradiax automatically implies -mmac by default.

Table 2.4: Optional MAC-DIV instructions

Mnemonic	Operation	Latency	Repeat Delay	Description
MTHI	HI <- Rs	-	-	pre-load accumulator, or restore saved HI
MTLO	LO <- Rs	-	-	pre-load accumulator, or restore saved LO
MFHI	Rd <- HI	1	-	read accumulator, or part of 64-bit result
MFLO	Rd <- LO	1	-	read accumulator, or part of 64-bit result
MULT	HI,LO <- Rs*Rt	5	-	32x32 signed multiply 64-bit result
MULTU	HI,LO <- Rs*Rt	5	-	32x32 unsigned multiply 64-bit result
MADH	HI <- HI+Rs[15:0]*Rt[15:0]	3	0	16x16 signed multiply, with 32-bit signed add to accum
MADL	LO <- LO+Rs[15:0]*Rt[15:0]	3	0	16x16 signed multiply, with 32-bit signed add to accum
MAZH	HI <- 0+Rs[15:0]*Rt[15:0]	3	0	16x16 signed multiply, add to pre-zeroed 32-bit accum
MAZL	LO <- 0+Rs[15:0]*Rt[15:0]	3	0	16x16 signed multiply, add to pre-zeroed 32-bit accum
MSBH	HI <- HI-Rs[15:0]*Rt[15:0]	3	0	16x16 signed multiply, with 32-bit signed sub from accum
MSBL	LO <- LO-Rs[15:0]*Rt[15:0]	3	0	16x16 signed multiply, with 32-bit signed sub from accum
MSZH	HI <- 0-Rs[15:0]*Rt[15:0]	3	0	16x16 signed multiply, sub from pre-zeroed 32-bit accum
MSZL	LO <- 0-Rs[15:0]*Rt[15:0]	3	0	16x16 signed multiply, sub from pre-zeroed 32-bit accum
DIV	HI <- Rs%Rt; LO<-Rs/Rt	35	-	32 by 32 signed divide with reminder
DIVU	HI <- Rs%Rt; LO<-Rs/Rt	35	-	32 by 32 unsigned divide with reminder

-mcache-profile

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Enable optional Multiply/Divide/Accumulator support

Dependency: None **Status:** Obsoleted

Version: – Description:

In general, profiling functions are placed in the uncacheable memory region to remove effects casted by the memory cache and to achieve more accurate results. The trade-off is the profiling speed because compiler will have to generate more instructions to cope with long jumps and memory access latency is inevitably higher. However, if the profiling speed is a concern, users can force compiler to map the address in the cacheable region by using -mcache-profile option.

-mno-data-in-code

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Separate data and code section

Dependency: None **Status:** New **Version:** 1.3.0+ **Description:**

When specified, the compiler will not emit codes that embed data in the text section, instead, the compiler will allocate data symbols explicitly in the data section. This results in better IMEM/ICACHE utilization by removing data dependency from the text segment. This option is especially useful in MIPS16 mode where code size is critical.

Compiler Options

-finhibit-ltw

Architecture: RLX4181

Summary: Disable load twin-word instruction, ltw

Dependency: None **Status:** Obsoleted **Version:** – **Description:**

Disable load twin-word instruction. When -finhibit-ltw is specified, compiler will emit a sequence of load byte and shift instructions instead of ltw instruction. Itw will trigger exception if the load address is not twin-word aligned i.e. 8-byte aligned. Since RSDK 1.2.0, this option is obsoleted as ltw is disabled by default.

-finhibit-lt -finhibit-st

Architecture: RLX5181, LX5280

Summary: Disable load/store twin-word instruction, lt and st

Dependency: None **Status:** Obsoleted

Version: – Description:

When -finhibit-lt is specified, compiler will emit a sequence of load byte and shift instructions instead of lt instruction. Likewise, when -finhibit-st is specified, compiler will emit a sequence of store byte and shift instructions instead of st instruction. It and st will trigger exception if the load or store address is not twin-word aligned i.e. 8-byte aligned. Since RSDK 1.2.0, these options are obsoleted as lt and st are disabled by default.

-finhibit-lw -finhibit-sw

Architecture: LX4180, RLX4181, RLX5181, LX5280 **Summary:** Disable load/store word instruction, lw and sw

Status: Obsoleted Version: – Description:

When -finhibit-lw is specified, compiler will emit a sequence of load byte and shift instructions instead of lw instruction. Likewise, when -finhibit-sw is specified, compiler will emit a sequence of store byte and shift instructions instead of sw instruction. lw and sw will trigger exception if the load or store address is not word aligned i.e. 4-byte aligned.

-fltw

Architecture: RLX4181

Summary: Enable load twin-word instruction, ltw

Dependency: None

Status: Obsoleted, use -ftword instead

Version: – Description:

When -fltw is specified, compiler will emit ltw instruction instead of a sequence of load byte and shift instructions whenever possible. This option is added since RSDK 1.2.0 and is merged into -ftword in RSDK 1.2.4.

-flt

-fst

Architecture: RLX5181, LX5280

Summary: Enable load/store twin-word instruction, lt and st

Status: Obsoleted, use -ftword instead

Version: – Description:

When -flt is specified, compiler will emit lt instruction instead of a sequence of load byte and shift instructions whenever possible. Likewise, when -fst is specified, compiler will emit st instruction instead of a sequence of store byte and shift instructions whenever possible. These options are added since RSDK 1.2.0 and are merged into -ftword in RSDK 1.2.4.

-ftword

Architecture: RLX4181, RLX5181, LX5280

Summary: Enable load/store twin-word instruction, ltw or lt/st

Dependency: None Status: Current Version: 1.2.4+ Description:

When -ftword is specified, compiler will emit ltw (RLX4181) instruction or lt (RLX5181/LX5280) instruction instead of a sequence of load byte and shift instructions whenever possible. Likewise, when -ftword is specified, compiler will emit st (RLX5181/LX5280) instruction instead of a sequence of store byte and shift instructions whenever possible. These options are added since RSDK 1.2.4.

-ftword-stack

Architecture: RLX4181, RLX5181, LX5280

Summary: Enable twin-word instructions in function prologue/epilogue

Dependency: None **Status:** Current **Version:** 1.2.4+ **Description:**

When -ftword-stack is specified, compiler will emit lt/ltw instruction instead of a sequence of load byte and shift instructions whenever possible during function calling. This option is added since RSDK 1.2.0.

-frlxgcov

Architecture: LX4180, RLX4181, RLX5181, LX5280 **Summary:** Enable code coverage analysis using RLX library

Dependency: None Status: New Version: 1.2.7+ Description:

When -frlxgcov is specified, compiler will emit codes to do coverage analysis for basic blocks. This option is similar to the combination of '-fprofile-arcs -ftest-coverage' except that it uses the RSDK supplemental library which supports remote file I/O over GDB remote serial protocol.

The coverage analysis codes will be placed in **.rlxgcov** section. Therefore, the linker script must be modified to explicitly allocate the **.rlxgcov** section. This option is added since RSDK 1.2.7.

The '-fprofile-arcs -ftest-coverage' options have been reverted to comply with GNU standard. If specified, the standard GNU code coverage analysis will be used. Please refer to GNU website for more information.

-fdafile-relative

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Enable Linux profiling

Dependency: -fprofile-arcs -ftest-coverage

Status: New Version: 1.2.7+ Description:

By default, GCOV generates .da file in the path where the source files reside. When this option is specified, GCOV will generate .da file in the path where the executable is invoked.

subsection*-fmerge-constants **Architecture:** LX4180, RLX4181, RLX5181, LX5280

Summary: Attempt to merge identical string constants across compilation units

Dependency: -O and above

Status: New Version: 1.3.0+ Description:

If this option is enabled, GCC will attempt to merge identical string literals and float point constants across compilation units by putting string literals and/or floating point constants in dedicate sections .rodata.str1.4 and .rodata.cst4. The benefit is that the code size can be reduced because duplicate constants are removed. For Linux kernel 2.4, the magnitude of reduction in code size and in memory footprint is in the order of mega bytes.

In original GCC version 4, this option is turned on by default for optimized compilation if the assembler and linker support it. This option was enabled at levels -O, -O2, -O3, and -Os. In other words, if optimization is turned on, the compiler will remove duplicate constants by merging them into dedicate sections.

In RSDK 1.4.0, this option is always turned off unless explicitly switched on by specifying -fmerge-constants.

NOTE: If this option is turned on, the linker script must explicitly include the two dedicate sections .rodata.str1.4 and .rodata.cst4 if they are not already dealt with. Example is shown as follows:

```
. . . .
.data :
  _{fdata} = .;
  *(.data)
                               /* merged constant */
  *(.rodata.cst4)
  *(.rodata.str1.4)
                                /* merged string literals */
/* Align the initial ramdisk image (INITRD) on page boundaries. */
 . = ALIGN(4096);
 __rd_start = .;
*(.initrd)
\underline{\phantom{a}}rd_end = .;
 . = ALIGN(4096);
  CONSTRUCTORS
}
```

-fuse-uls

Architecture: RLX4181, RLX5181

Summary: Enable unaligned load/store instructions

Dependency: None **Status:** New **Version:** 1.3.3+ **Description:**

When this option is specified, GCC will generate unaligned load/store instructions whenever possible.

Profiling options

-plinux

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Enable Linux profiling

Dependency: None Status: Current Version: 1.2.0+ Description:

When this option is specified, compiler will emit instructions in functions prologue and epilogue to jump to the predefined profiling functions for Linux profiling.

-pros

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Enable ROS profiling

Dependency: None **Status:** Current **Version:** 1.2.0+ **Description:**

When this option is specified, compiler will emit instructions in functions prologue and epilogue to jump to the predefined profiling functions for ROS profiling.

-pg -p

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Enable general program profiling

Dependency: None Status: Current Version: 1.2.0+ Description:

When this option is specified, compiler will emit instructions in functions prologue and epilogue to jump to the predefined profiling functions for general program profiling, e.g. user applications. These two options are identical.

Attributes

__attribute__((far_call))

Architecture: LX4180, RLX4181, RLX5181, LX5280 **Summary:** Mark the specified function as a long jump

Dependency: None Status: Current Version: 1.2.0+ Description:

By default, the range for a jump instruction is within 256MB. If the jump target is more than 256MB away, then a single jump instruction can not reach the desired target. In this case, the jump instruction must be modified to a load and a jump instructions. The former loads the target address to a specific register and the later does the actual jump to the address stored in that register. By using the far_call attribute, users can explicitly specify certain functions as long jumps and compiler will emit the right instructions when these functions are called.

Program 1: Example of using __attribute__((far_call))

```
int func() __attribute__((far_call))
int func()
{
    ....
}
int myfunc()
{
    ....
    func();
}
```

The purpose of attribute is similar to that of the compiler option -mlong-calls. The difference is that the compiler option, -mlong-calls, applies to all the functions in the application, while __attribute__((far_call)) allows users to do finer control and apply to specific functions only.

```
__attribute__((mips16))
__attribute__((nomips16))
```

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Mark the specified function to be compiled in MIPS16/NONMIPS16 mode

Dependency: None **Status:** New **Version:** 1.2.0+ **Description:**

The __attribute__((mips16)) enables users to insert MIPS16 codes into MIPS1 applications without compiling the entire source as a MIPS16 code. In other words, with this attribute, users can fine control certain functions to be in MIPS16 mode and balance the trade-off between code performance and code size.

Likewise, the __attribute__((nomips16)) enables users to insert MIPS1 codes into MIPS16 applications without compiling the entire source as a MIPS1 code.

The example is shown in program 2.

NOTE: the compilation time will increase as the number of functions with MIPS16 attribute increases. The overhead is introduced by testing and switching between MIPS1 and MIPS16 mode on a per function basis. If the majority of the functions in a C file are MIPS16, users should consider compiling the entire file in MIPS16 mode using the -mips16 compiler option.

Preprocessor definitions

-D_m4180|_m4181|_m5181|_m5280

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Define identifier for each processor

Dependency: None **Status:** New **Version:** 1.2.0+ **Description:**

Due to differences among the ISAs of Realtek's processor cores, users may need fine-tune certain code segments for each core, e.g. fine-tune machine-dependent codes using inline assembly. When the target processor is set by

Program 2: Example of using __attribute__((mips16))

```
int __attribute__((mips16)) func1()
{
     ....
}
int func2()
{
     ....
}
int myfunc()
{
     .... /* MIPS32 mode */
     func1(); /* MIPS16 mode */
     func2(); /* MIPS32 mode */
     .... /* MIPS32 mode */
}
```

specifying -marchl-mtunel-mcpu, compiler will automatically add the corresponding preprocessor identifier for users to separate machine-dependent codes in the same segment. The preprocessor identifiers are shown in table 2.5.

Processor Core	Preprocessor definition
-march mtune mcpu=4180	-Dm4180
-marchlmtunelmcpu=4181	-Dm4181
-marchlmtunelmcpu=5181	-Dm5181
-march mtune mcpu=5280	-D m5280

Table 2.5: Preprocessor definition mapping

Deprecated Options

-mgpopt | -mno-gpopt

The -mgpopt switch says to write all of the data declarations before the instructions in the text section, this allows the MIPS assembler to generate one word memory references instead of using two words for short global or static data items. This is on by default if optimization is selected.

Both options, -mgpopt and -mno-gpopt, have been deprecated since GCC 3.3. They have been merged into the -G option.

```
-G num
   Put global and static items less than or equal to num bytes into the
small data or bss section instead of the normal data or bss section.
This allows the data to be accessed using a single instruction.

All modules should be compiled with the same -G num value.

-G 0 ==> -mno-gpopt
```

If the num is 0, gpopt optimization is turned off, otherwise, gpopt will be effective.

Program 3: Example of using preprocessor definitions

```
#ifdef __m4180
   machine-dependent code for 4180
#endif

#ifdef __m4181
   machine-dependent code for 4181
#endif

#ifdef __m5181
   machine-dependent code for 5181
#endif

#ifdef __m5280
   machine-dependent code for 5280
#endif
```

Chapter 3 Binutils

The binutils tool set is based on the GNU binutils package. The binutils tool set includes assembler, linker, and object file manipulation utilities, such as ar, nm, objdump, and objcopy. In RSDK 1.5.6p2, the binutils has been upgraded from version 2.16 to 2.17 to provide a more reliable and a more stable development environment for both MIPS1 and MIPS16 applications.

The list of changes is summarized in the following subsections.

Assembler

-march=4180|4181|5181|5280

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Set the target processor core

Status: Current **Description:**

The -march option sets the target processor core to the one specified in the option.

If none of the -march option is specified, the assembler will automatically add -march=4180 to the option list.

MIPS1 and MIPS16 mix mode

Linking MIPS16 objects into MIPS1 mode is not supported at this moment. Due to the current design in the binutils, the linker cannot handle linking MIPS16 objects within MIPS1 mode, hence causes user application to fail when it tries to access the wrong address. This problem can be worked around by using explicit symbols instead of expressions. The example is shown in program 4.

In RSDK 1.5.6p2, the assembler has been modified to yield an error message on this case and to abort the assembling process.

Objdump

-mmips:4180|4181|5181|5280

Architecture: LX4180, RLX4181, RLX5181, LX5280

Summary: Set the target processor core

Status: Current **Description:**

The -mmips option specifies the target ISA for the objdump utility. The usage is shown in program 5.

Program 4: Example of mixing MIPS1 and MIPS16 objects

```
1:

jalx 1b+18 # should jump to M32 (Fail)
jalx M32 # should jump to M32 (Work)
nop
b fail16
nop
addiu v0, 0x4
addiu v0, 0x8
.set nomips16
add v0, 0x8
M32:
add v0, 0x8
add v0, 0x10
...
```

Program 5: Objdump Example

```
rsdk-elf-objdump -d -m mips:4180 file.o
rsdk-elf-objdump -d -m mips:4181 file.o
rsdk-elf-objdump -d -m mips:5181 file.o
rsdk-elf-objdump -d -m mips:5280 file.o
```

Run-Time OPCODE Table

In RSDK 1.5.6p2, binutils has been patched to support dynamic opcode tables. This is done by storing the opcode table in an external file and by loading the external file during run-time. The Run-Time opcode table mechanism enables a single toolchain to support multiple instruction sets. This feature is useful for projects with custom engines and user defined instructions.

An example of opcode table is shown as follows:

```
/* These instructions appear first so that the disassembler will find
  them first. The assemblers uses a hash table based on the
  instruction name anyhow.
                      match,
                                  mask,
                                              pinfo,
                                                           pinfo2,
                                                                       membership
 name.
           args,
{"pref",
           "k,o(b)", 0xcc000000, 0xfc000000, RD_b,
                                                          Ο,
                                                                       I4|I32|G3},
{"prefx",
           "h,t(b)", 0x4c00000f, 0xfc0007ff, RD_b|RD_t, 0,
                                                                       I4|I33},
                      0x00000000, 0xffffffff, 0,
                                                           INSN2 ALIAS, I1}
{ "nop",
```

Instruction Fields

Each instruction in the opcode table contains seven arguments. They are **name**, **args**, **match**, **mask**, **pinfo**, **pinfo2**, and **membership**. These seven arguments define the mnemonic name and the format, as well as information for encoding and decoding for an instruction. The detail for each argument is explained in the following subsection.

• name:

This field is the name of the instruction.

· args:

This field is a string describing the arguments for this instruction.

These are the characters which may appear in the args field of an instruction. They appear in the order in which the fields appear when the instruction is used. Commas and parentheses in the args string are ignored when assembling, and written into the output when disassembling.

```
"<": 5 bit shift amount (OP * SHAMT)
">": shift amount between 32 and 63, stored after subtracting 32 (OP_*_SHAMT)
"a": 26 bit target address (OP_*_TARGET)
"b": 5 bit base register (OP_*_RS)
"c": 10 bit breakpoint code (OP_*_CODE)
"d": 5 bit destination register specifier (OP_*_RD)
"h": 5 bit prefx hint (OP_*_PREFX)
"i": 16 bit unsigned immediate (OP_*_IMMEDIATE)
"j": 16 bit signed immediate (OP_*_DELTA)
"k": 5 bit cache opcode in target register position (OP_*_CACHE)
      Also used for immediate operands in vr5400 vector insns.
"o": 16 bit signed offset (OP_*_DELTA)
"p": 16 bit PC relative branch target address (OP * DELTA)
"q": 10 bit extra breakpoint code (OP_*_CODE2)
"r": 5 bit same register used as both source and target (OP_*_RS)
"s": 5 bit source register specifier (OP_*_RS)
"t": 5 bit target register (OP_*_RT)
"u": 16 bit upper 16 bits of address (OP_*_IMMEDIATE)
"v": 5 bit same register used as both source and destination (OP_*RS)
"w": 5 bit same register used as both target and destination (OP_*_RT)
"U": 5 bit same destination register in both OP_*RD and OP_*RT
       (used by clo and clz)
"C": 25 bit coprocessor function code (OP_*_COPZ)
"B": 20 bit syscall/breakpoint function code (OP_*_CODE20)
"J": 19 bit wait function code (OP_*_CODE19)
"x": accept and ignore register name
"z": must be zero register
"K": 5 bit Hardware Register (rdhwr instruction) (OP_*_RD)
"+A": 5 bit ins/ext position, which becomes LSB (OP_*_SHAMT).
Enforces: 0 \le pos \le 32.
"+B": 5 bit ins size, which becomes MSB (OP * INSMSB).
Requires that "+A" or "+E" occur first to set position.
Enforces: 0 < (pos+size) <= 32.
"+C": 5 bit ext size, which becomes MSBD (OP_*_EXTMSBD).
Requires that "+A" or "+E" occur first to set position.
Enforces: 0 < (pos+size) <= 32.
(Also used by "dext" w/ different limits, but limits for
that are checked by the M_DEXT macro.)
"+E": 5 bit dins/dext position, which becomes LSB-32 (OP_*_SHAMT).
Enforces: 32 <= pos < 64.
"+F": 5 bit "dinsm" size, which becomes MSB-32 (OP_*_INSMSB).
Requires that "+A" or "+E" occur first to set position.
Enforces: 32 < (pos+size) <= 64.</pre>
"+G": 5 bit "dextm" size, which becomes MSBD-32 (OP_*_EXTMSBD).
Requires that "+A" or "+E" occur first to set position.
Enforces: 32 < (pos+size) <= 64.
"+H": 5 bit "dextu" size, which becomes MSBD (OP_*_EXTMSBD).
Requires that "+A" or "+E" occur first to set position.
Enforces: 32 < (pos+size) <= 64.
   Floating point instructions:
   "D" 5 bit destination register (OP_*_FD)
   "M" 3 bit compare condition code (OP_*_CCC) (only used for mips4 and up)
   "N" 3 bit branch condition code (OP_*_BCC) (only used for mips4 and up)
   "S" 5 bit fs source 1 register (OP_*_FS)
   "T" 5 bit ft source 2 register (OP_*_FT)
   "R" 5 bit fr source 3 register (OP_*_FR)
   "V" 5 bit same register used as floating source and destination (OP_*FS)
```

```
"W" 5 bit same register used as floating target and destination (OP_*_FT)
   Coprocessor instructions:
   "E" 5 bit target register (OP_*_RT)
   "G" 5 bit destination register (OP_*_RD)
   "H" 3 bit sel field for (d)mtc* and (d)mfc* (OP_*_SEL)
   "P" 5 bit performance-monitor register (OP_*_PERFREG)
   "e" 5 bit vector register byte specifier (OP_*_VECBYTE)
   "%" 3 bit immediate vr5400 vector alignment operand (OP_*_VECALIGN)
   see also "k" above
   "+D" Combined destination register ("G") and sel ("H") for CPO ops,
for pretty-printing in disassembly only.
  Macro instructions:
   "A" General 32 bit expression
   "I" 32 bit immediate (value placed in imm_expr).
   "+I" 32 bit immediate (value placed in imm2_expr).
   "F" 64 bit floating point constant in .rdata
   "L" 64 bit floating point constant in .lit8
   "f" 32 bit floating point constant
   "1" 32 bit floating point constant in .lit4
  MDMX instruction operands (note that while these use the FP register
   fields, they accept both $fN and $vN names for the registers):
   "O" MDMX alignment offset (OP_*_ALN)
   "Q" MDMX vector/scalar/immediate source (OP_*_VSEL and OP_*_FT)
   "X" MDMX destination register (OP_*_FD)
   "Y" MDMX source register (OP_*_FS)
   "Z" MDMX source register (OP_*_FT)
   DSP ASE usage:
   "3" 3 bit unsigned immediate (OP_*_SA3)
   "4" 4 bit unsigned immediate (OP_*_SA4)
   "5" 8 bit unsigned immediate (OP_*_IMM8)
   "6" 5 bit unsigned immediate (OP_*_RS)
   "7" 2 bit dsp accumulator register (OP_*_DSPACC)
   "8" 6 bit unsigned immediate (OP_*_WRDSP)
   "9" 2 bit dsp accumulator register (OP_*_DSPACC_S)
   "0" 6 bit signed immediate (OP_*_DSPSFT)
   ":" 7 bit signed immediate (OP_*_DSPSFT_7)
   "'" 6 bit unsigned immediate (OP_*_RDDSP)
   "@" 10 bit signed immediate (OP_*_IMM10)
   MT ASE usage:
   "!" 1 bit immediate at bit 5
   "$" 1 bit immediate at bit 4
   "*" 2 bit dsp/smartmips accumulator register (OP_*_MTACC_T)
   "&" 2 bit dsp/smartmips accumulator register (OP_*_MTACC_D)
   "g" 5 bit coprocessor 1 and 2 destination register (OP_*_RD)
   "+t" 5 bit coprocessor 0 destination register (OP_*_RT)
   "+T" 5 bit coprocessor 0 destination register (OP_*_RT) - disassembly only
   Other:
   "()" parens surrounding optional value
   "," separates operands
   "[]" brackets around index for vector-op scalar operand specifier (vr5400)
   "+" Start of extension sequence.
   Characters used so far, for quick reference when adding more:
   "34567890"
```

```
"%[]<>(),+:'@!$*&"
"ABCDEFGHIJKLMNOPQRSTUVWXYZ"
"abcdefghijklopqrstuvwxz"

Extension character sequences used so far ("+" followed by the following), for quick reference when adding more:
"ABCDEFGHIT"
"t"
```

• match:

The basic opcode for the instruction. When assembling, this opcode is modified by the arguments to produce the actual opcode that is used. If pinfo is INSN_MACRO, then this is 0.

· mask:

If pinfo is not INSN_MACRO, then this is a bit mask for the relevant portions of the opcode when disassembling. If the actual opcode anded with the match field equals the opcode field, then we have found the correct instruction. If pinfo is INSN_MACRO, then this fiend is the macro identifier.

• pinfo:

For a macro, this is INSN_MACRO. Otherwise, it is a collection of bits describing the instruction, notably any relevant hazard information.

These are the bits which may be set in the pinfo field of an instructions, if it is not equal to INSN_MACRO.

```
WR_d: /* Modifies the general purpose register in OP_*_RD.
                                                        * /
WR_t: /* Modifies the general purpose register in OP_*_RT.
WR_31: /* Modifies general purpose register 31. */
WR_D: /* Modifies the floating point register in OP_*_FD.
WR_S: /* Modifies the floating point register in OP_*_FS. */
WR_T: /* Modifies the floating point register in OP_*_FT.
RD_s: /* Reads the general purpose register in OP_*_RS. */
RD_t: /* Reads the general purpose register in OP_*_RT.
RD_S: /* Reads the floating point register in OP_*_FS. */
RD T: /* Reads the floating point register in OP * FT. */
RD_R: /* Reads the floating point register in OP_*_FR.
WR_CC: /* Modifies coprocessor condition code.
RD_CC: /* Reads coprocessor condition code. */
/* TLB operation.
                                 0x00002000
#define INSN_TLB
RD_C0: /* Reads coprocessor register other than floating point register.
RD_C1: /* Reads coprocessor register other than floating point register.
                                                                     * /
RD_C2: /* Reads coprocessor register other than floating point register.
                                                                     */
RD_C3: /* Reads coprocessor register other than floating point register. */
/* Instruction loads value from memory, requiring delay. */
/* Instruction loads value from coprocessor, requiring delay. */
#define INSN LOAD COPROC DELAY 0x00010000
/* Instruction has unconditional branch delay slot. */
#define INSN_UNCOND_BRANCH_DELAY 0x00020000
/* Instruction has conditional branch delay slot. */
#define INSN_COND_BRANCH_DELAY 0x00040000
/* Conditional branch likely: if branch not taken, insn nullified. */
#define INSN_COND_BRANCH_LIKELY 0x00080000
/* Moves to coprocessor register, requiring delay. */
/* Loads coprocessor register from memory, requiring delay. */
#define INSN_COPROC_MEMORY_DELAY 0x00200000
/* Reads the HI register.
```

```
#define INSN_READ_HI 0x00400000
/* Reads the LO register. */
#define INSN_READ_LO 0x00800000
/* Modifies the HI register. */
#define INSN WRITE HI 0x01000000
/* Modifies the LO register. */
#define INSN WRITE LO 0x02000000
/* Takes a trap (easier to keep out of delay slot). */
#define INSN TRAP
/* Instruction stores value into memory. */
#define INSN STORE MEMORY 0x08000000
/* Instruction uses single precision floating point. */
#define FP_S 0x1000000
/* Instruction uses double precision floating point. */
#define FP_D 0x20000000
/* Instruction is part of the tx39's integer multiply family.
                                                          */
#define INSN MULT
                                  0x40000000
/* Instruction synchronize shared memory. */
#define INSN SYNC
                 0x80000000
/* These are the bits which may be set in the pinfo2 field of an
  instruction. */
/* Instruction is a simple alias (I.E. "move" for daddu/addu/or) */
#define INSN2 ALIAS
                     0x0000001
/* Instruction reads MDMX accumulator. */
#define INSN2_READ_MDMX_ACC
                             0x00000002
/* Instruction writes MDMX accumulator. */
/* Instruction is actually a macro. It should be ignored by the
  disassembler, and requires special treatment by the assembler. */
#define INSN_MACRO
                                  0xfffffff
/* Masks used to mark instructions to indicate which MIPS ISA level
  they were introduced in. ISAs, as defined below, are logical
  ORs of these bits, indicating that they support the instructions
  defined at the given level. */
```

• pinfo2:

A collection of additional bits describing the instruction.

• membership:

A collection of bits describing the instruction sets of which this instruction or macro is a member.

For RLX processor cores, the following ISA sets are defined:

- INSN_ISA4180
- INSN_ISA4181
- INSN_ISA5181
- INSN_ISA5280

Custom UDI Instructions

To add custom UDI instructions to the binutils, a text-based UDI instruction table must be constructed. This UDI instruction table is used to encode assembly code and to decode between machine object code.

UDI Instruction File

Example UDI instruction file is shown as follows:

```
/*
 * RLX UDI instruction list.
struct mips_opcode rlx_udi_opcodes[] =
/* Lexra opcode extensions. Register mode */
{"udi0", "d,v,t", 0x00000038, 0xfc0007ff, WR_d|RD_s|RD_t, 0, RLX2 },
{"udi1", "d,v,t", 0x0000003a, 0xfc0007ff, WR_d|RD_s|RD_t, 0, RLX2 },
{"udi2", "d,v,t", 0x0000003b, 0xfc0007ff, WR_d|RD_s|RD_t, 0, RLX2 },
{"udi3", "d,v,t", 0x0000003c, 0xfc0007ff, WR_d|RD_s|RD_t, 0, RLX2 },
{"udi4", "d,v,t", 0x0000003e, 0xfc0007ff, WR_d|RD_s|RD_t, 0, RLX2 },
{"udi5", "d,v,t", 0x0000003f, 0xfc0007ff, WR_d|RD_s|RD_t, 0, RLX2 },
/* Lexra opcode extensions. Immediate mode */
{"udi0i", "t,r,j", 0x60000000, 0xfc000000, WR_t | RD_s, 0, RLX2 },
{"udili", "t,r,j", 0x64000000, 0xfc000000, WR_t | RD_s, 0, RLX2 },
{"udi2i", "t,r,j", 0x68000000, 0xfc000000, WR t | RD s, 0, RLX2 },
{"udi3i", "t,r,j", 0x6c000000, 0xfc000000, WR_t | RD_s, 0, RLX2 },
} ;
```

Instruction File Manipulation

The manipulation of ISA file is done via a utility program, rsdk-elf-opcutil, which is shipped with the RSDK toolchain package.

The usage of rsdk-elf-opcutil is shown as follows:

• -I: the -I option lists the current supported opcode tables. The output includes name, description, number of ISA, and number of UDI instructions of each opcode table. Example is shown as follows:

```
sh% ./rsdk-elf-opcutil -l

RLX Binutils OPCODE Util v1.4

optree[0] = RLX, RLX opcode v1.4 rev 1, num_isa = 1144, num_udi = 10

optree[1] = VENUS, DVR-VENUS opcode v1.4 rev 1, num_isa = 1144, num_udi = 88
optree[2] = MARS, DVR-MARS opcode v1.4 rev 1, num_isa = 1144, num_udi = 250
```

• -d: the -d option shows details of the current opcode table. The output includes the file name, tag, number of ISA, and number of UDI instructions of the opcode table. Example is shown as follows:

```
sh% ./rsdk-elf-opcutil -d

RLX Binutils OPCODE Util v1.4

Filename: ../mips-elf/bin/rlx-isa.bin

TAG: RLX opcode v1.4 rev 1

ISA: 1144 instructions

UDI: 10 instructions
```

• -i: the -i option shows details of the specified opcode file. The output includes the file name, tag, number of ISA, and number of UDI instructions of the opcode table. Example is shown as follows:

```
sh% ./rsdk-elf-opcutil -i rlx-isa.bin

RLX Binutils OPCODE Util v1.4

Filename: rlx-isa.bin

TAG: RLX opcode v1.4 rev 1

ISA: 1144 instructions

UDI: 10 instructions
```

• -r: the -r option replaces the current opcode table file with the specified opcode tag. Users can use -l option to find out the supported opcode tags.

```
sh% ./rsdk-elf-opcutil -1

RLX Binutils OPCODE Util v1.4

optree[0] = RLX, RLX opcode v1.4 rev 1, num_isa = 1144, num_udi = 10
optree[1] = VENUS, DVR-VENUS opcode v1.4 rev 1, num_isa = 1144, num_udi = 88
optree[2] = MARS, DVR-MARS opcode v1.4 rev 1, num_isa = 1144, num_udi = 250

sh% ./rsdk-elf-opcutil -r VENUS

RLX Binutils OPCODE Util v1.4

Changing opcode table to VENUS ...

TAG: VENUS
REV: DVR-VENUS opcode v1.4 rev 1
ISA: 1144 instructions
UDI: 88 instructions
```

Chapter 4 Problem Report

The official website for the processor and platform team is at the following URL:

http://processor.realtek.com.tw

On the official website, latest news, documentation, and releases of RSDK toolchain will be made available as soon as they are ready. The link to the issue tracking system can also be found on the processor website. Through the issue tracking system, any feature request and bug report will be handled in a systematic and timely fashion.

To report a problem, in addition to the detail problem description, please also clearly indicate the platform, the RSDK version, and exact way to reproduce the problem. The more details we have, the faster we can have the problem identified and nailed.

Appendix A RADIAX registers

RADIAX register name translation

For processor cores that support DSP instructions, an additional set of registers are available for programming. The mnemonic names of RADIAX registers are added to: **\${RSDK}/include/regdef.h**

The set of registers are shown as follows:

#define	m0l	\$1
#define	m0h	\$2
#define	m0	\$3
#define	m11	\$5
#define	m1h	\$6
#define	m1	\$7
#define	m21	\$9
#define	m2h	\$10
#define	m2	\$11
#define	m31	\$13
#define	m3h	\$14
#define	m3	\$15
#define	estatus	\$0
#define	ecause	\$1
#define	intvec	\$2
#define	cbs0	\$0
#define	cbs1	\$1
#define	cbs2	\$2
#define	cbe0	\$4
#define	cbe1	\$5
#define	cbe2	\$6
#define	lps0	\$16
#define	lpe0	\$17
#define	lpc0	\$18
#define	mmd	\$24

The RADIAX registers are treated as regular MIPS registers in the way the register name translation is processed.

The register name translation can happen in two places:

• preprocessor:

If preprocessor is applicable and the **regdef.h** header file is included, the preprocessor can do the following translation:

addma.s m0l, m0l, m0l => addma.s \$1, \$1, \$1

• assembler:

When it comes to the assembler, the register names should be prefixed with a \$ character. For example, the

assembler is able to do the translation of the following form:

addma.s \$m0l, \$m0l, \$m0l => addma.s \$1, \$1, \$1

Appendix B Inline Assembly Format

Form 1

The first form of inline assembly is shown as follows:

```
asm("move $6, $8");
```

The above code will be translated literally to the code segment shown below:

```
#APP
move $6, $8
#NO_APP
```

Form 2

The second form of inline assembly is shown as follows:

```
int v1;
int v2;

asm("move %0,%1" : "=d"(v1) : "d"(v2));
```

The above inline assembly code states that: copy the value of variable v2 to variable v1 while storing v1 and v2 in general registers. The compiler will generate the actual assembly code as follows:

```
#APP
move $6, $8
#NO_APP
```

NOTE: the actual register number is determined by compiler during register allocation so the actual register number might be different from the one shown above.

Form 3

The third form of inline assembly is shown as follows:

```
register int v1 asm("8");
int ret;
ret = ret + v1;
```

The compiler supports a special keyword, asm, for variable declaration. The above code forces compiler to allocate register 8 for variable v1. The translated assembly code is shown as follows:

```
#APP
addu $8, $2, $8
#NO_APP
```

There are five alternatives to the above form. The \$8, %8, and #8 are internally supported in the compiler. The name stands for the alias of the register.

```
register int v1 asm("8");
register int v1 asm("$8");
register int v1 asm("%8");
register int v1 asm("#8");
register int v1 asm("name");
```

NOTE: The compiler optimization, -O, has the priority over register number assignment in this form. If -O is turned on, the compiler might assign a different register number than the one specified in the inline assembly code.

Appendix C Porting Linux kernel 2.4 to RSDK 1.4

When Linux Kernel 2.4 was being developed, the main GCC compiler version used was GCC 3.2. However, in RSDK 1.4, the base GCC compiler used is GCC 4.1. GCC 4.1 is a better compiler in terms of strictness of the compiler and performance of the compiled code. There might exist minor incompatibility issues for source codes that are not fully compliant with GCC 4.1 coding standard. The kernel 2.4 has hit some of the traps.

There are a number of changes that need to be applied on kernel 2.4 for the kernel to work with GCC 4.1. The list of incompatibilities is summarized as follows and is explained in details in the following subsections:

- __FUNCTION__ GCC extension
- save_static_function macro
- · kernel linker script

__FUNCTION__ extension

The __FUNCTION__ is a GCC extension that does does string catenation with the current function name. This extension has been changed since GCC 4.1 and might be removed completely in future releases. Therefore, the kernel source needs to be modified accordingly.

save_static_function

In kernel 2.4, save_static_function is a macro that save additional registers before falling through the next function. It is usually invoked as follows:

```
save_static_function(sys_sigsuspend);
static_unused int _sys_sigsuspend(struct pt_regs regs)
{
    ......
}
```

While it used to work in GCC 3.2 (RSDK 1.2), it is not working in GCC 4.1 (RSDK 1.3) due to the dead code elimination and function reordering in GCC 4.1 optimization phase. The result is a unusable kernel binary.

There are a number of patches, which can be found on google, for the save_static_function to built with GCC 4.1. One of the patches, from http://osdir.com/ml/ports.mips.general/2004-12/msg00039.html, is shown as follows:

```
traps.o ptrace.o reset.o semaphore.o setup.o syscall.o \
                  sysmips.o ipc.o scall_o32.o time.o unaligned.o
+ check_gcc = \$(shell if \$(CC) \$(1) -S -o /dev/null -xc /dev/null > /dev/null
2>&1; then echo "$(1)"; else echo "$(2)"; fi)
+ syscall.o signal.o : override CFLAGS += $(call check_gcc,
-fno-unit-at-a-time,)
 obj-$(CONFIG_MODULES)
                       += mips_ksyms.o
 obj-$(CONFIG_CPU_R3000)
                                     += r2300_fpu.o r2300_switch.o
Index: kernel/signal.c
______
RCS file: /linux/linux/arch/mips/kernel/signal.c,v
retrieving revision 1.1.1.2
diff -c -p -r1.1.1.2 signal.c
*** kernel/signal.c 1 Dec 2004 21:50:39 -0000 1.1.1.2
--- kernel/signal.c
                     3 Dec 2004 03:00:44 -0000
******
*** 18,23 ****
--- 18,24 ----
  #include <linux/errno.h>
  #include <linux/wait.h>
  #include <linux/unistd.h>
+ #include <linux/compiler.h>
  #include <asm/asm.h>
  #include <asm/bitops.h>
******** int copy_siginfo_to_user(siginfo_t *to,
*** 76,82 ****
   * Atomically swap in the new signal mask, and wait for a signal.
  */
 save_static_function(sys_sigsuspend);
! static_unused int _sys_sigsuspend(struct pt_regs regs)
  {
       sigset_t *uset, saveset, newset;
--- 77,84 ----
   * Atomically swap in the new signal mask, and wait for a signal.
 save_static_function(sys_sigsuspend);
! __attribute_used__ static int
! _sys_sigsuspend(struct pt_regs regs)
 {
       sigset_t *uset, saveset, newset;
******* static_unused int _sys_sigsuspend(struct
*** 102,108 ****
 }
 save_static_function(sys_rt_sigsuspend);
! static_unused int _sys_rt_sigsuspend(struct pt_regs regs)
  {
       sigset_t *unewset, saveset, newset;
         size_t sigsetsize;
--- 104,111 ----
 }
  save_static_function(sys_rt_sigsuspend);
```

```
! __attribute_used__ static int
! _sys_rt_sigsuspend(struct pt_regs regs)
       sigset_t *unewset, saveset, newset;
         size t sigsetsize;
Index: kernel/syscall.c
______
RCS file: /linux/linux/arch/mips/kernel/syscall.c,v
retrieving revision 1.1.1.2
diff -c -p -r1.1.1.2 syscall.c
1.1.1.2
--- kernel/syscall.c 3 Dec 2004 03:00:44 -0000
*****
*** 25,30 ****
--- 25,31 ----
 #include <linux/slab.h>
 #include <linux/utsname.h>
 #include <linux/unistd.h>
+ #include <linux/compiler.h>
 #include <asm/branch.h>
 #include <asm/offset.h>
 #include <asm/ptrace.h>
******* sys_mmap2(unsigned long addr, unsigned l
*** 158,164 ****
 save_static_function(sys_fork);
! static unused int sys fork(struct pt regs regs)
 {
       int res;
--- 159,166 ----
 }
 save_static_function(sys_fork);
! __attribute_used__ static int
! _sys_fork(struct pt_regs regs)
 {
       int res;
******* static_unused int _sys_fork(struct pt_re
*** 168,174 ****
 save static function(sys clone);
! static_unused int _sys_clone(struct pt_regs regs)
 {
       unsigned long clone_flags;
       unsigned long newsp;
--- 170,177 ----
 save_static_function(sys_clone);
! __attribute_used__ static int
! _sys_clone(struct pt_regs regs)
       unsigned long clone flags;
       unsigned long newsp;
```

Kernel 2.4 linker script

If -fmerge-constants compiler option is enabled, the linux kernel linker script, **arch/mips/ld.script.in** and/or **arch/mips/ld.script** must be modified to accommodate the two extra sections, **.rodata.cst4** and **.rodat.str1.4**. The modified linker script for kernel 2.4 is shown as follows:

```
OUTPUT_ARCH(mips)
ENTRY(kernel_entry)
SECTIONS
  /* Read-only sections, merged into text segment: */
  /*. = @@LOADADDR@@;*/
  . = 0x80000000;
  .init
                  : { *(.init) } =0
  .text
             :
    _{ftext} = .;
    *(.text)
    *(.rodata)
    *(.rodata1)
    /* .gnu.warning sections are handled specially by elf32.em. */
    *(.gnu.warning)
  =0
  .kstrtab : { *(.kstrtab) }
  . = ALIGN(16); /* Exception table */
  \_start\_ex\_table = .;
  __ex_table : { *(__ex_table) }
  \__stop\__ex_table = .;
  start dbe table = .; /* Exception table for data bus errors */
  __dbe_table : { *(__dbe_table) }
  __stop___dbe_table = .;
  __start___ksymtab = .; /* Kernel symbol table */
  __ksymtab : { *(__ksymtab) }
  \underline{\phantom{a}}stop\underline{\phantom{a}}ksymtab = .;
  _{\text{etext}} = .;
  . = ALIGN(8192);
  .data.init_task : { *(.data.init_task) }
  /* Startup code */
  . = ALIGN(4096);
  \underline{\phantom{a}} init_begin = .;
  .text.init : { *(.text.init) }
  .data.init : { *(.data.init) }
  \cdot = ALIGN(16);
  __setup_start = .;
  .setup.init : { *(.setup.init) }
  \_setup_end = .;
  __initcall_start = .;
  .initcall.init : { *(.initcall.init) }
  __initcall_end = .;
  . = ALIGN(4096); /* Align double page for init_task_union */
  \underline{\phantom{a}} init_end = .;
  . = ALIGN(4096);
```

```
.data.page_aligned : { *(.data.idt) }
. = ALIGN(32);
.data.cacheline_aligned : { *(.data.cacheline_aligned) }
         : { *(.fini)
                        } =0
.reginfo : { *(.reginfo) }
/* Adjust the address for the data segment. We want to adjust up to
   the same address within the page on the next page up. It would
   be more correct to do this:
   The current expression does not correctly handle the case of a
   text segment ending precisely at the end of a page; it causes the
   data segment to skip a page. The above expression does not have
   this problem, but it will currently (2/95) cause BFD to allocate
   a single segment, combining both text and data, for this case.
   This will prevent the text segment from being shared among
  multiple executions of the program; I think that is more
   important than losing a page of the virtual address space (note
   that no actual memory is lost; the page which is skipped can not
  be referenced). */
. = .;
.data
  _fdata = . ;
  *(.data)
  *(.rodata.cst4)
  *(.rodata.str1.4)
 /* Align the initial ramdisk image (INITRD) on page boundaries. */
 . = ALIGN(4096);
 \underline{\phantom{a}}rd_start = .;
 *(.initrd)
 _{\rm rd\_end} = .;
 . = ALIGN(4096);
  CONSTRUCTORS
}
.data1 : { *(.data1) }
_{gp} = . + 0x8000;
.lit8 : { *(.lit8) }
.lit4 : { *(.lit4) }
.ctors
           : { *(.ctors) }
.dtors
              : { *(.dtors) }
              : { *(.got.plt) *(.got) }
.got
.dynamic : { *(.dynamic) }
/* We want the small data sections together, so single-instruction offsets
   can access them all, and initialized data all before uninitialized, so
   we can shorten the on-disk segment size. */
         : { *(.sdata) }
.sdata
\cdot = ALIGN(4);
\_edata = .;
PROVIDE (edata = .);
\__bss\_start = .;
fbss = .;
.sbss
          : { *(.sbss) *(.scommon) }
.bss
```

```
*(.dynbss)
 *(.bss)
 *(COMMON)
\cdot = ALIGN(4);
\_end = . ;
PROVIDE (end = .);
/* Sections to be discarded */
/DISCARD/ :
      *(.text.exit)
      *(.data.exit)
      *(.exitcall.exit)
}
/* This is the MIPS specific mdebug section. */
.mdebug : { *(.mdebug) }
/* These are needed for ELF backends which have not yet been
   converted to the new style linker. */
.stab 0 : { *(.stab) }
.stabstr 0 : { *(.stabstr) }
/* DWARF debug sections.
   Symbols in the .debug DWARF section are relative to the beginning of the
   section so we begin .debug at 0. It's not clear yet what needs to happen
   for the others. */
.debug
              0 : { *(.debug) }
.debug_srcinfo 0 : { *(.debug_srcinfo) }
.debug_aranges 0 : { *(.debug_aranges) }
.debug_pubnames 0 : { *(.debug_pubnames) }
.debug_sfnames 0 : { *(.debug_sfnames) }
                0 : { *(.line) }
/* These must appear regardless of . */
.gptab.sdata : { *(.gptab.data) *(.gptab.sdata) }
.gptab.sbss : { *(.gptab.bss) *(.gptab.sbss) }
.comment : { *(.comment) }
.note : { *(.note) }
```

Appendix D RELEASE NOTE

RSDK Release 1.5

We are pleased to announce the release of RSDK version 1.5 on March 31, 2010. RSDK stands for Realtek Software Development Kit. It is the software development kit for Realtek's in-house processor cores. Version 1.5.0 is the first stable release for branch 1.5.

What's new in release 1.5:

1. gcc-4.4.2

The major version of gcc has come to 4.4. At this moment the note is made, it reached 4.4.2 with less bugs and more stability. 4.4.2 is the version recruited in this release. Here is a brief list of notable technique items that are added or enhanced since 4.2.

GCC has much more significant improvements from 4.3 to 4.4 on the quality and the size of its code generation.

- 4.3) The gcc middle-end has been integrated with the MPFR library, resulting consistent correct codes regardless of the math library implementation or floating point precision of the host platform.
- 4.3) A new forward propagation pass on RTL was added, resulting in compile-time improvements as well as better code generation in some cases.
- 4.3) Improved mips16/32 mixed-mode code generation. The support of mips16 in previous RSDK versions, such as -mno-data-in-code, are ported to base on it. Other features also get revised and bug-fixed (small-data allocation).
- 4.4) A new register allocator called integrated register allocator (IRA) has been introduced to replace the old one.
- 4.4) A new instruction scheduler and software pipeliner, based on the selective scheduling approach, has been added.
- 4.4) MIPS16 o32 PIC mode is now supported.

Other changes/new features can be found at official gcc release notes.

Along with the porting of our previous work on gcc to 4.4.2, we provide further improvements:

RTK) Optimized support of existent processors as well as the newly added Taroko series (RX4281 and RX5281).

2. uClibc-0.9.30

The uClibc C library has been upgraded 0.9.30. The memcpy and memset functions in uClibc 0.9.30 have also been patched for RLX/LX processor cores to improve performance by using word copy whenever possible and to support processor cores with and without unsupported unaligned load/store instructions.

RSDK wrapper is fully supported on RSDK 1.5. Customized wrappers for specific Linux and uClibc versions can be generated upon request.

3. RSDK Supplementary Library Module

A supplementary library module has been added to enrich RSDK's capability in functional profiling, performance tuning, and remote debugging. The supplementary library includes following modules:

- a. CP3 library CP3 performance counter
- b. Profiler library function-level profiling support
- c. GDB I/O remote I/O via GDB remote serial protocol
- d. RLXCOV RLX code coverage analysis library
- e. RLXULS RLX unaligned load/store library

CPUs supported by RSDK release 1.5

- 1. LX4180:
- All versions
- 2. RLX4181
- All versions
- 3. LX5280
- All versions
- 4. RLX5181
- All versions
- 5. RLX4281
- All versions
- 6. RLX5281
- All versions

Appendix E Change Log

```
version 1.5.6
    * Upgrade to GCC 4.4.6
    * Support CEF 1.0
    * Change GCC and binutils to GNU ones
    * Change newlib to CodeSourcery-based
    * Add Lexra register name for inline assembly (ex: m0h, lps0)
    * Port newlib assembly libraries
    * Fix GCC inline-assembly bug
   * Fix GCC alignment bug
    * Fix objdump option (1.5.6p1)
    * Fix BFD bug for addr2line (1.5.6p1)
    * Fix GCC mips16 bug in BLKmode (1.5.6p1)
    * Fix CEF bug (1.5.6p1)
    * Auto detect solib path for gdb (1.5.6p1)
    * Fix binutils subsection alignment bug (1.5.6p2)
   * Fix bug in setting default bfd machine (1.5.6p2)
    * Change C++ exception handling method as dwarf-2 (1.5.6p2)
    * Fix CEF bug (1.5.6p2)
    * Fix newlib 'signal' bug (1.5.6p2)
version 1.5.5
    * Upgrade to GCC 4.4.5
    * Upgrade uClibc to uClibc 0.9.30.3
    * Enable TLS for uClibc toolchain
    * Disable TLS for libstdc++
    * libmath wrapper to libstdc++_pic.a
    * Fix binutils opcode bug
    * Fix gcc 20090518-1.c
    * Fix profiling bug in GCC (1.5.5p1)
   * Add mips16 profiling support (1.5.5p1)
   * Fix branch delay slot filling (1.5.5p1)
    * Add -ffix-bdsl to work around Taroko pre-v1.3 bug (1.5.5p1)
    * Fix LOAD-USE and BACK-to-BACK DMP CEI warning bug (1.5.5p2)
    * Add LXCO register names for Taroko (1.5.5p2)
    * Fix error LXCP0 TLPTR ID $29 -> $8 (1.5.5p2)
    * Fix bugs in TLS support (1.5.5p2)
    * Fix BFD debug section bug (1.5.5p2)
    * CEF - compilation option collection (1.5.5p2)
    * Add -pg support (1.5.5p2)
    * Add -Wpossible-load-use to detect possible load-use in branch delay slot (1.5.5p3)
    * Modify -ffix-bdsl to work around mips16 bug found in Taroko version <= 1.1.2 (1.5.5p4)
version 1.5.4
```

* Support CEF (Compilation Engineering Framework)
* Enable customer enginer instructions on RLX5181

* Fix gcc mipscop-3.c

- * Fix gcc \$ra problem (1.5.4p1)
- * Add back-to-back warning for DMP CEI (1.5.4p2)
- * Fix stp/swp/shp/sbp load-use detection (1.5.4p2)
- * Fix tcl/tk bugs under cygwin 1.7.x (1.5.4p2)

version 1.5.3

- * Add load-use detection for RLX processors
- * Sync mcount/ecount processing with the original MIPS porting
- * Fix gcc pr42559 (1.5.3p1)
- * Fix sim/mips configuration for RLX (1.5.3p1)

version 1.5.2

- * Update to GCC 4.4.4
- * Fix mmd register sp offset
- * Fix RLX4081 load delay slot use in strlen
- * Fix depcreated contraint "h" (1.5.2p1)
- * Fix -fuse-uls control (1.5.2p2)
- * Disable -fstrict-overflow by default (1.5.2p3)
- * Remove the usage of ctc3 instruction in -pg (1.5.2p4)

version 1.5.1

- * Add RLX4081 support
- * Disable progolue/epilogue scheduling

version 1.5.0

- * Initial version of RSDK toolchain branch 1.5
- * Update gcc from 4.1.2 to 4.4.2
- * Upgrade binutils from 2.17 to 2.19
- * Upgrade uclibc from 0.9.28 to 0.9.30
- * Upgrade newlib from 1.15.0 to 1.17.0
- * Upgrade insight/gdb from 6.4 to 6.6