

# Bayesian Statistics: basics and elementary examples

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**Aim:** practical use of general methodology

- ▶ minimum level of formality

**Literature:** Bishop, Ch.M. Pattern recognition and machine learning. Springer, 2006.

**Details:** [scholar.google.com](https://scholar.google.com)

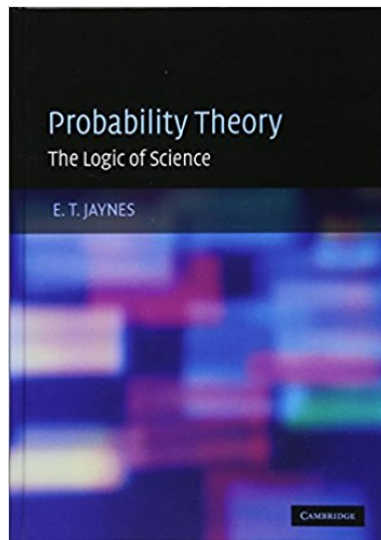
**Marks:** individual assignment

Probability theory as:

- ▶ extension of logic
- ▶ language
- ▶ necessity for making decisions under uncertainty

Alternatives:

- ▶ Dempster Shafer
- ▶ fuzzy logic



## Example

Probability of patients illness:

illness	Dr. #1 likelihood	Dr.#2 likelihood	posterior
brain tumor	99.9%	0%	
concussion	0%	99.9%	
meningitis	0.1%	0.1%	

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Counterintuitive results

1. Is probability theory wrong?

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Counterintuitive results

1. Is probability theory wrong?
2. Is model wrong?

Random variables:

$$X \in \{x_1, \dots, x_M\}$$

$$Y \in \{y_1, \dots, y_L\}$$

Joint probability

$$P(X = x_i, Y = y_j) = \frac{n_{i,j}}{N}$$

where  $N$  ( $N \rightarrow \infty$ ) is the number of realizations and  $n_{i,j}$  is the number of trials where  $X = x_i, Y = y_j$ .

Rules:

1. sum rule

$$P(X = x_i) = \sum_{j=1}^L P(X = x_i, Y = y_j),$$

2. product rule

$$P(X, Y) = p(Y|X)p(X)$$



Random variable:  $X$ , realization  $x$

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Rules:

1. sum rule

$$p(x) = \int p(x, y)dy$$

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Engineering (ML) notation: meaning given by context.

$$p(x|y) = \frac{p(y|x)p(x)}{p(y)}$$

## Toy problem

Noisy observation:

$$d = m + e,$$

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Noise model (likelihood): Gaussian

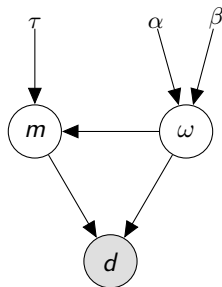
$$p(e_i) = \mathcal{N}(0, \omega^{-1}) = \sqrt{\frac{\omega}{2\pi}} \exp\left(-\frac{1}{2}\omega e^2\right)$$

$$p(d_i) = \mathcal{N}(m, \omega^{-1}) = \sqrt{\frac{\omega}{2\pi}} \exp\left(-\frac{1}{2}\omega(d - m)^2\right)$$

Prior:

$$p(m|\omega) = \mathcal{N}(0, \tau\omega) = \sqrt{\frac{\omega\tau}{2\pi}} \exp\left(-\frac{1}{2}\tau\omega m^2\right)$$

$$p(\omega) = G(\alpha, \beta) = \frac{\beta^\alpha}{\Gamma(\alpha)} \omega^{\alpha-1} \exp(-\beta\omega)$$



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Find:

$$p(m, \omega|d) = ?$$

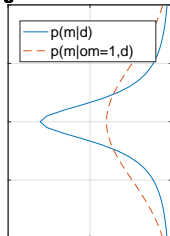
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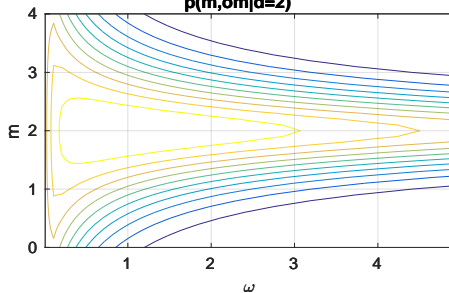
$$p(\omega|d) = ?$$

Results:  $d = 2, \alpha = 0.1, \beta = 0.1, \tau = 0.0001$

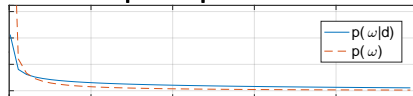
**marginal vs. conditional**



**$p(m, om|d=2)$**



**prior vs. posterior**



# Choices:

Likelihood:

1. Gaussian
2. Other

Prior:

- ▶ informative
- ▶ non-informative

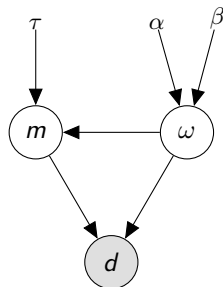
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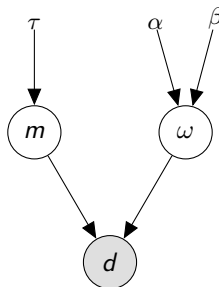
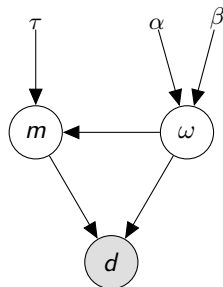
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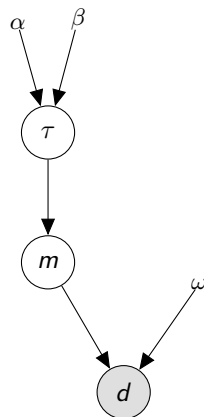
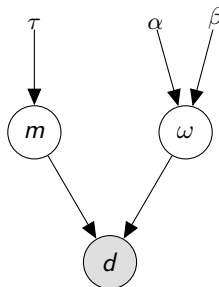
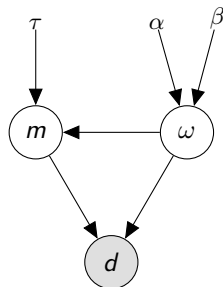
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- ▶  $p(m|\omega) = \int p(d|m, \omega)p(m|\alpha)p(\alpha)d\alpha$
- ▶ graphical model