Řešíme numericky Riccatiho rovnici (1) na intervalu [0.25, 0.45] Rungeovými-Kuttovými metodami. Známe její analytické řešení: $u(t) = (\frac{1}{\sqrt{2}t} \tan{(\sqrt{2}(c-\frac{1}{t}))} - \frac{1}{2t})e^t$, kde klademe c=1.

$$\dot{u}(t) = t^{-4}e^{t} + u(t) + 2e^{-t}u^{2}(t) = f(t, u),$$

$$u(0.25) = -31, 1844.$$
(1)

Označíme $\tau = integrationTimeStep$, $u_0 = u(t_0)$. Použijeme metody:

I. Euler:

$$k_1(\tau) = \tau \cdot f(t_0, u_0),$$

 $u(t_0 + \tau) = u(t) + k_1(\tau).$

II. Runge-Kutta 2. řádu:

$$k_1(\tau) = \tau \cdot f(t_0, u_0),$$

$$k_2(\tau) = \tau \cdot f(t_0 + \tau, u_0 + k_1(\tau)),$$

$$u(t_0 + \tau) = u(t) + \frac{1}{2}k_1(\tau) + \frac{1}{2}k_2(\tau).$$

III. Runge-Kutta-Merson:

$$\begin{split} k_1(\tau) &= \tau \cdot f(t_0, u_0), \\ k_2(\tau) &= \tau \cdot f(t_0 + \frac{1}{3}\tau, u_0 + \frac{1}{3}k_1), \\ k_3(\tau) &= \tau \cdot f(t_0 + \frac{1}{3}\tau, u_0 + \frac{1}{6}k_1 + \frac{1}{6}k_2), \\ k_4(\tau) &= \tau \cdot f(t_0 + \frac{1}{2}\tau, u_0 + \frac{1}{8}k_1 + \frac{3}{8}k_3), \\ k_5(\tau) &= \tau \cdot f(t_0 + \tau, u_0 + \frac{1}{2}k_1 - \frac{3}{2}k_3 + 2k_4), \\ u(t_0 + \tau) &= y_0 + \frac{1}{6}k_1 + \frac{2}{3}k_4 + \frac{1}{6}k_5. \end{split}$$

Rozebereme podrobněji metodu (II):

- (a) Výsledný graf v porovnání s průběhem analytického řešení:
- (b) Implementace:

```
template < typename Problem >
class RungeKutta: public IntegratorBase
 public:
  RungeKutta ( Problem & problem )
       this ->k1 = new double[ problem.getDegreesOfFreedom() ];
       this ->k2 = new double[ problem.getDegreesOfFreedom() ];
       this ->aux = new double[ problem.getDegreesOfFreedom() ];
  }
  bool solve ( Problem& problem,
               double* u )
       const int dofs = problem.getDegreesOfFreedom();
       double tau = std::min( this->integrationTimeStep, this->stopTime - this->time );
       long int iteration( 0 );
       while ( this -> time < this -> stopTime )
         * Compute k1
         problem.getRightHandSide( this->time, u, k1 );
```

```
/* ***
            * Compute k2
            for(int i = 0; i < dofs; i++)
             aux[i] = u[i] + tau * k1[i];
            problem.getRightHandSide(\ \ \textbf{this} \ -\!\!\!> \ time \ + \ tau\ ,\ aux\ ,\ k2\ );
            /* ** */
           for(int i = 0; i < dofs; i++)
             u[ i ] += ( tau / 2.0 ) * ( k1[ i ] + k2[ i ] );
            this -> time += tau;
            iteration++;
            if ( iteration > 100000 )
              std::cerr << "The_solver_has_reached_the_maximum_number_of_iteratoins._"
                           << std::endl;
              return false;
           tau = std::min( tau, this->stopTime - this->time );
std::cout << "ITER:" << iteration << "_\t_tau_=_" << tau
                           << "_\t_time=_" << time << "____\r_" << std :: flush;</pre>
         std::cout << std::endl;</pre>
         return true;
   }
   ~RungeKutta()
         delete[] k1;
         \boldsymbol{delete}\,[\,]\ k2\,;
         delete[] aux;
  protected:
   \textbf{double} \ *k1 \ , \ *k2 \ , \ *aux \ ;
};
```