

a

```
BA3: bus access standard_bus <-> camera_sensor.BA1;  
BA4: bus access standard_bus <-> standard_memory.BA1;  
BA5: bus access standard_bus <-> core2.BA1;  
BA6: bus access standard_bus <-> core3.BA1;  
BA7: bus access standard_bus <-> core4.BA1;  
BA8: bus access standard_bus <-> haptic_sensor.BA1;  
BA9: bus access standard_bus <-> infocscreen.BA1;  
BA10: bus access standard_bus <-> camera1_sensor.BA1;  
BA11: bus access standard_bus <-> stwheel.BA1;
```

```
flows  
etelateny1:end to end flow camera_sensor.f1 -> DC1 -> detection_app.f1 -> DC2 -> brake.f1 {  
    Latency => 70ms .. 120 ms;;
```

```
properties  
Actual_Processor_Binding => (reference (core1) ) applies to detection_app.camera_cmd_data;  
Actual_Processor_Binding => (reference (core1) ) applies to pedestrian_app.camera_proc_data1;  
Actual_Processor_Binding => (reference (core2) ) applies to detection_app.camera_proc_data;  
Actual_Processor_Binding => (reference (core2) ) applies to lanedetection_app.camera_proc_data;  
Actual_Processor_Binding => (reference (core2) ) applies to lanedetection_app.camera_kalman_data;  
Actual_Processor_Binding => (reference (core3) ) applies to pedestrian_app.camera_cmd_data1;
```

- Package Public mapping_public
 - System Adas
 - System Impl Adas.detection_test
 - End to End Flow etelateny1
 - Access Connection BA1
 - Access Connection BA2
 - Access Connection BA3
 - Access Connection BA4
 - Access Connection BA5
 - Access Connection BA6
 - Access Connection BA7
 - Access Connection BA8
 - Access Connection BA9
 - Access Connection BA10
 - Connected Element
 - Connected Element
 - Access Connection BA11
 - Port Connection DC1
 - Port Connection DC2

b

