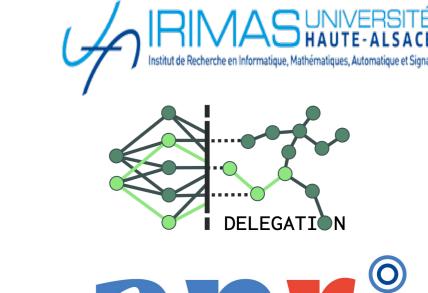
Weighted Average of Human Motion Sequences for Improving Rehabilitation Assessment

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Abstract

Context:

- The specific task of assessing rehabilitation motion is difficult due to the lack of annotated data
- Traditional augmentation techniques often produce meaningless human motion sequences, particularly in the context of rehabilitation
- In rehabilitation assessment, labels are continuous values representing movement quality, making it difficult to assign labels to augmented data

Contribution:

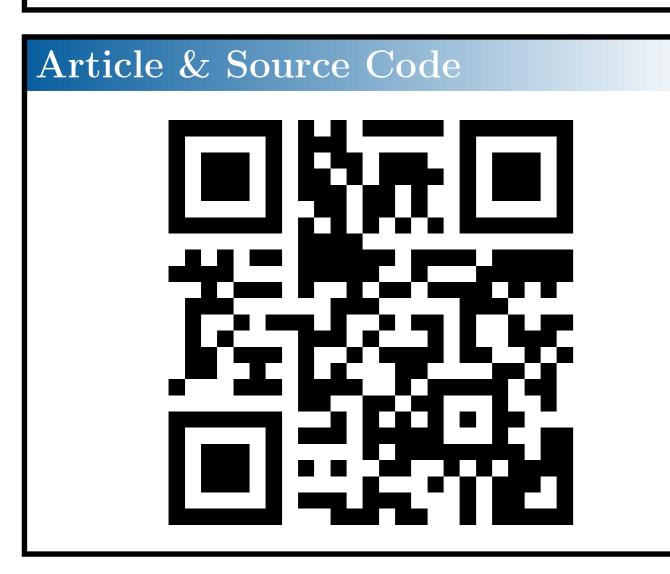
- We investigate the use of ShapeDBA [4] for human skeleton sequences to generate average rehabilitation movements
- We extend the averaging method by a weighting strategy [3, 2] that allows generating more various but yet coherent sequences
- We leverage the weighting strategy for associating meaningful continuous labels to synthetic rehabilitation sequences
- We consider the proposed method for extending a small real-world rehabilitation dataset [1] and evaluate it on an extrinsic regression task

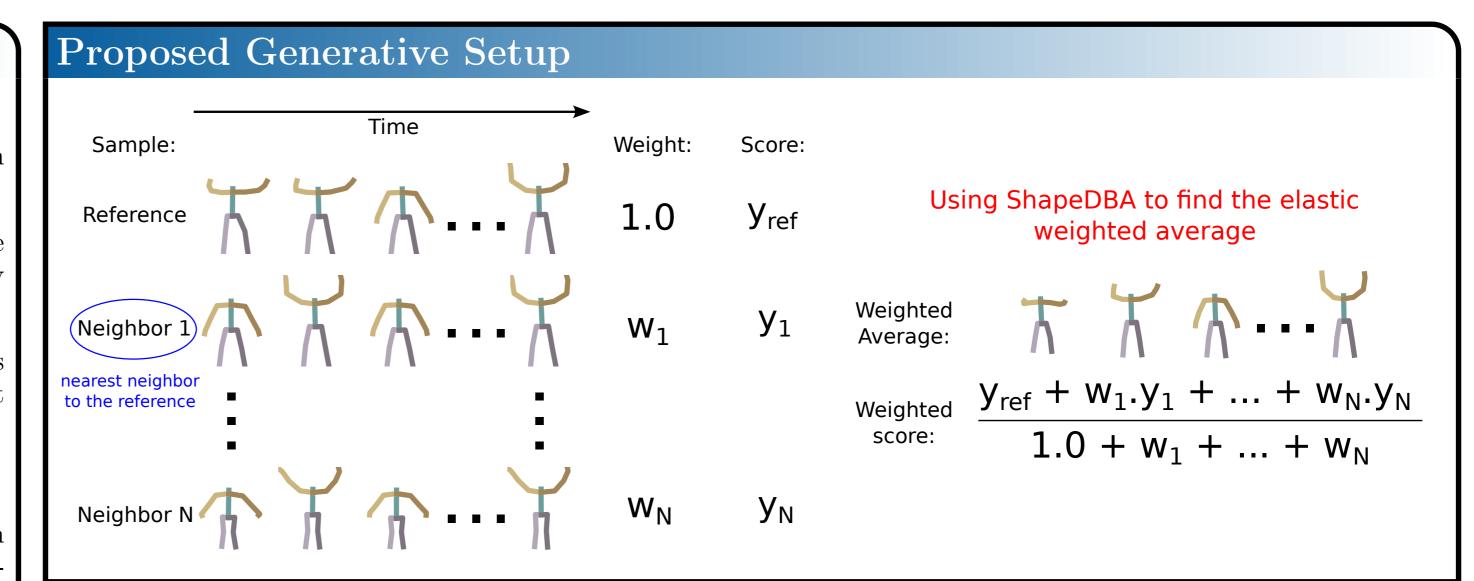
References

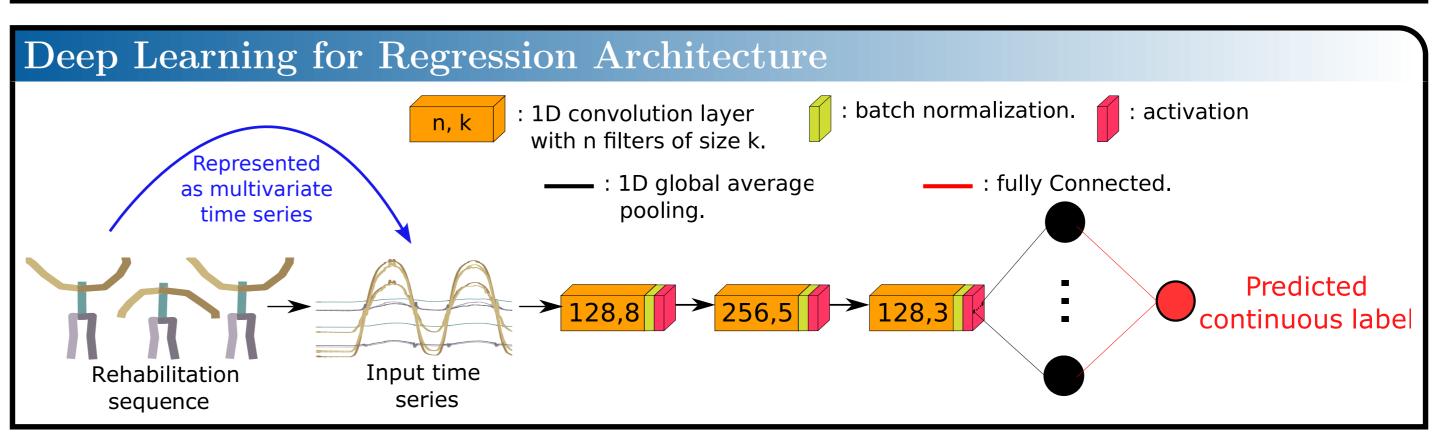
- [1] Marianna Capecci, Maria Gabriella Ceravolo, Francesco Ferracuti, Sabrina Iarlori, Andrea Monteriu, Luca Romeo, and Federica Verdini. The kimore dataset: Kinematic assessment of movement and clinical scores for remote monitoring of physical rehabilitation. *IEEE Transactions on Neural Systems and Rehabilitation Engineering*, 27(7):1436–1448, 2019.
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Acknowledgments

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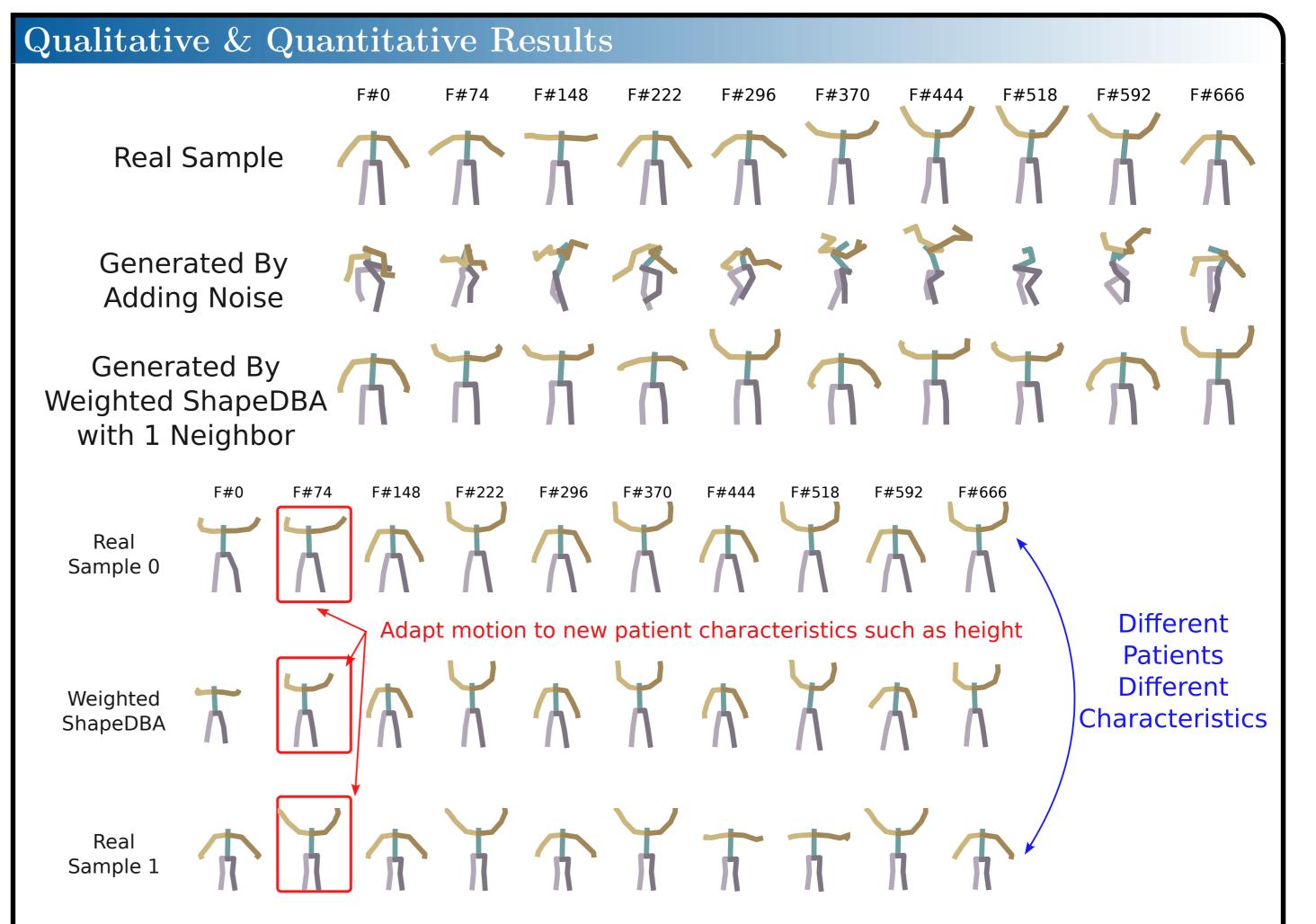


Table 1: MAE and RMSE errors obtained for all compared approaches on each exercise separately. Best values are emphasized in bold, while second best values are underlined.

Training Set	Exercise 1	Exercise 2	Exercise 3	Exercise 4	Exercise 5
		MAE			
Ref.	0.206 ± 0.069	0.202 ± 0.037	0.204 ± 0.055	0.184 ± 0.068	0.224 ± 0.058
Ref. + Noise	0.186 ± 0.065	0.172 ± 0.040	0.203 ± 0.045	0.185 ± 0.073	0.229 ± 0.069
Ref. + ShapeDBA NN1	$\boxed{\textbf{0.167} \pm \textbf{0.070}}$	0.175 ± 0.030	$\textbf{0.182}\pm\textbf{0.051}$	$\boxed{\textbf{0.141} \pm \textbf{0.062}}$	$ig egin{array}{c} 0.208 \pm 0.079 \end{array}$
Ref. + ShapeDBA NN2	0.169 ± 0.057	0.177 ± 0.041	0.194 ± 0.041	0.168 ± 0.056	0.226 ± 0.066
Ref. + ShapeDBA NN3	0.173 ± 0.063	0.183 ± 0.047	0.199 ± 0.058	0.168 ± 0.083	0.225 ± 0.055
Ref. + ShapeDBA NN4	0.168 ± 0.059	0.179 ± 0.043	0.199 ± 0.043	0.180 ± 0.080	0.231 ± 0.060
Ref. $+$ ShapeDBA NN5	$\boxed{\textbf{0.166} \pm \textbf{0.067}}$	0.185 ± 0.043	0.201 ± 0.050	0.182 ± 0.089	0.226 ± 0.061
		RMSE			
Ref.	0.251 ± 0.083	0.247 ± 0.045	0.248 ± 0.065	0.230 ± 0.083	0.267 ± 0.073
Ref. + Noise	0.203 ± 0.078	0.226 ± 0.043	0.238 ± 0.046	0.227 ± 0.090	0.274 ± 0.092
Ref. + ShapeDBA NN1	0.199 ± 0.087	$\textbf{0.226}\pm\textbf{0.036}$	$\textbf{0.214}\pm\textbf{0.054}$	$\boxed{0.178\pm0.074}$	$oxed{0.251\pm0.094}$
Ref. + ShapeDBA NN2	0.203 ± 0.075	0.232 ± 0.052	0.226 ± 0.044	0.210 ± 0.074	0.268 ± 0.083
Ref. + ShapeDBA NN3	0.205 ± 0.082	0.235 ± 0.050	0.240 ± 0.062	0.214 ± 0.105	0.268 ± 0.066
Ref. + ShapeDBA NN4	$\boxed{0.198\pm0.071}$	0.235 ± 0.050	0.234 ± 0.048	0.230 ± 0.105	0.279 ± 0.070
Ref. + ShapeDBA NN5	0.202 ± 0.079	0.230 ± 0.049	0.244 ± 0.057	0.231 ± 0.109	0.280 ± 0.080