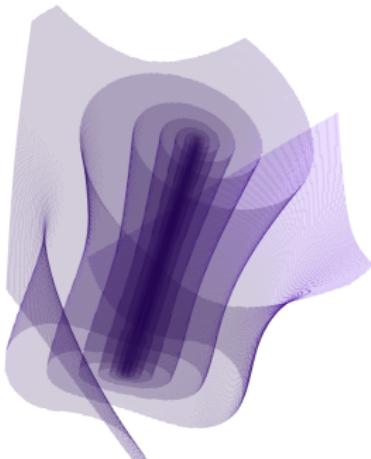


A deep-learning approach for nonequilibrium trajectories

or Geometrical Minimum Action Method revisited

Eric Simonnet

CNRS, INPHYNI, UMR 7010



Outline

- Motivation
- Basics: instantons and the geometrical action
- Neural network formulation
- SDEs
- SPDEs
- Beyond the Freidlin-Wentzell regime: crisis, intermittency.
- Perspective

Motivation

Rare events: **physical space** versus **phase space** $\partial_t u = \mathcal{F}(u, \nabla_{\mathbf{x}} u, \Delta_{\mathbf{x}} u, \dots) + \text{noise}, \mathbf{x} \in \mathbb{R}^d$.

Phase space, Galerkin truncation: #d.o.fs = $O(\text{precision}^{-d})$.

$$u(\mathbf{x}) = \sum_k u_k \mathbf{e}_k(\mathbf{x}),$$

- One is looking for (pointwise) estimates of the **Committor** = "Probability to first hit set **a** before another set **b**, given a present state". Solution of backward Kolmogorov operator in phase space: $\epsilon \Delta_{u_1, \dots, u_n} C + \mathbf{F} \cdot \nabla_{u_1, \dots, u_n} C = 0, C(a) = 0, C(b) = 1, a \cap b = \emptyset$.

Strategies

- AMS.** Selection-mutation on trajectories using many \sim short-time integrations of the SDE system $du_k = \mathcal{F}_k(u_1, \dots, u_n) dt + \sqrt{\epsilon} dW_k$.
- Dimension reduction/coarse-graining**, e.g. collective variables $O(100^d) \rightarrow O(10\text{-}100)$
 - ▶ Neural Network parametrisation (*Khoo et al. 2019; Q.Li et al. 2019; H.Li et al. 2021*).
 - ▶ Simulation/Data-based approaches (analogues) \rightarrow loop AMS (*D.Lucente et al. 2019, 2021*).
- Issues** Rare events: noise amplitude $\epsilon \ll 1 \rightarrow$ AMS strong "apparent bias" due to nonoptimal reaction coordinate. Committor estimate very challenging (large deviations). Not enough data.

Motivation

Rare events: **physical space** versus **phase space** $\partial_t u = \mathcal{F}(u, \nabla_{\mathbf{x}} u, \Delta_{\mathbf{x}} u, \dots) + \text{noise}$, $\mathbf{x} \in \mathbb{R}^d$.

Physical space, NN parametrisation: #d.o.fs = $\text{Polynomial}(d, \text{precision}^{-1})$ (A.Jentzen theorems).

$$u(t, \mathbf{x}; \theta) = \mathcal{N}_{\text{out}} \circ \mathcal{N}_L \circ \dots \circ \mathcal{N}_1 \circ \mathcal{N}_{\text{in}}((t, \mathbf{x})), \quad \mathcal{N}_k(\mathbf{y}) = \sigma_k(W_k \mathbf{y} + \mathbf{b}_k), \quad \theta = (W_k, \mathbf{b}_k).$$

- **AMS**: Selection-mutation on trajectories in neural network space θ . NO PDE-integrators !
Physics-informed, Deep Galerkin not good enough. Maybe with FNO/DeepONet approaches
(AnandKumar, Karnadiakis) ? ... and there are still issues with the reaction coordinate.
- **Instanton**: Minimizing the Freidlin-Wentzell action \mathcal{A} (additive noise) between two attractive sets a, b :

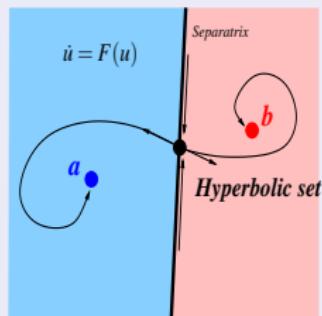
$$\lim_{T \rightarrow \infty} \min_{u \in V} \int_0^T \|\partial_t u - \mathcal{F}(u)\|^2 dt, \quad V = \{u(0) = a, u(T) = b\}.$$

- **Advantages:** rare events regime $\varepsilon \rightarrow 0$. Small dimension.
- **Issues:** one needs a relevant action (Freidlin-Wentzell regime). Cost functional might be difficult to minimize.

Basics

Shortcut: Freidlin-Wentzell is for noise-induced transitions.

- Exit time from a domain. Very few hypothesis to be valid: \mathbf{a} must be isolated.



$$\left\{ \begin{array}{l} d\mathbf{u}_t = F(\mathbf{u}_t)dt + \sqrt{\varepsilon}dW_t, \\ \Pr([\mathbf{u}_t]; \mathbf{u}(0) = \mathbf{a}, \mathbf{u}(T) = \mathbf{b}) \asymp \exp\left(-\frac{\mathcal{A}_T[\mathbf{u}]}{\varepsilon}\right) \\ \mathcal{A}_T[\mathbf{u}] = \frac{1}{2} \int_0^T \|\dot{\mathbf{u}} - F(\mathbf{u})\|^2 dt \end{array} \right.$$

- behavior for large time intervals: *most probable trajectory* or *instanton path* or *nonequilibrium transition* or *maximum likelihood path*: argmin of

$$\inf_T \inf_{\mathbf{u} \in V} \mathcal{A}_T[\mathbf{u}], \quad V = \{\mathbf{u}(0) = \mathbf{a}, \mathbf{u}(T) = \mathbf{b}\}.$$

- Pathological case: non-isolated attractors, e.g. Euler 2-D, AB model: F.Bouchet H.Touchette, J.Stat.Mech 2012.

M.Freidlin, A.Wentzell, *Random perturbations of Dynamical Systems*, Springer, 1984, 1998, 2012.

The geometrical action

- Relevant paths are for $T \rightarrow \infty$, one wishes to simplify the optimisation pb $\inf_T \inf_{\mathbf{u} \in V} \mathcal{A}_T[\mathbf{u}]$. The remarkable idea is to look at instanton arclength parametrisations.
- M.Heymann, E.Vanden-Eijnden, The geometric minimum action method: A least action principle on the space of curves, Comm.Pure Appl. Math, 61, 1052–1117 (2008); see also Olender, Elber, 1997 and FW, 1998.

$$\inf_T \inf_{\mathbf{u} \in V} \mathcal{A}_T[\mathbf{u}] = \inf_{\mathbf{u} \in W} \mathcal{A}_g[\mathbf{u}]$$

$$\mathcal{A}_g[\mathbf{u}] \equiv \int_0^1 (||\dot{\mathbf{u}}|| ||F(\mathbf{u})|| - \langle \dot{\mathbf{u}}, F(\mathbf{u}) \rangle) ds, \quad W = \{\mathbf{u}(0) = \mathbf{a}, \mathbf{u}(1) = \mathbf{b}\}.$$

- short proof: $|a|^2 + |b|^2 \geq 2|a| |b|$, gives $\frac{1}{2} \int_0^T ||\dot{\mathbf{u}} - F(\mathbf{u})||^2 dt \geq \mathcal{A}_g$ and is equal for \mathbf{u} such that $||\dot{\mathbf{u}}|| = ||F(\mathbf{u})||$. In fact all curves can be reparametrized such that $||\dot{\mathbf{u}}|| = ||F(\mathbf{u})||$ and due to the homogeneity of \mathcal{A}_g in time, one can conclude.

Cost functional

- We replace u by some (deep) NN parametrisation: $\mathcal{N} : (s, \mathbf{x}) \in [0, 1] \times \mathbb{R}^d \rightarrow \mathbb{R}^k$, $d \geq 0, k \geq 1$. Of course \mathcal{N} depends also on parameters θ (weight/bias). We do not write them explicitly.
- There is a continuum of possible parametrisations for \mathcal{A}_g , we fix one $\|\dot{\mathcal{N}}\| \approx \text{cst}$.

$$\mathcal{C}_{\text{total}} = \gamma_g \mathcal{A}_g + \gamma_{\text{bv}} \mathcal{C}_{\text{BV}} + \gamma_{\text{bc}} \mathcal{C}_{\text{BC}} + \gamma_a \mathcal{C}_{\text{arc}}, \quad \gamma_a \ll 1$$

$$\mathcal{C}_{\text{arc}} = \int_0^1 \|\dot{\mathcal{N}}\|^2 ds - \left(\int_0^1 \|\dot{\mathcal{N}}\| ds \right)^2$$

- Lift or not Lift ?. BV is for boundary values, we need $\mathcal{N}(0; \mathbf{x}) = \mathbf{a}(\mathbf{x})$ and $\mathcal{N}(1; \mathbf{x}) = \mathbf{b}(\mathbf{x})$. We choose the "naive" lift:

$$\mathbf{u}(s, \mathbf{x}) = (1-s)\mathbf{a}(\mathbf{x}) + s\mathbf{b}(\mathbf{x}) + s(1-s)\mathcal{N}(s, \mathbf{x}), \quad s \in [0, 1].$$

Therefore $\gamma_{\text{bv}} = 0$. *Do not lift if you are looking for gold.*

- \mathcal{C}_{bc} is for boundary conditions in the case of PDEs ($d \geq 1$) on $[0, 1] \times \partial\mathcal{D}$. Note that in the case of periodic domains, periodicity of first-order derivatives is crucial.

What we do in the shadows: gMAM versus NN

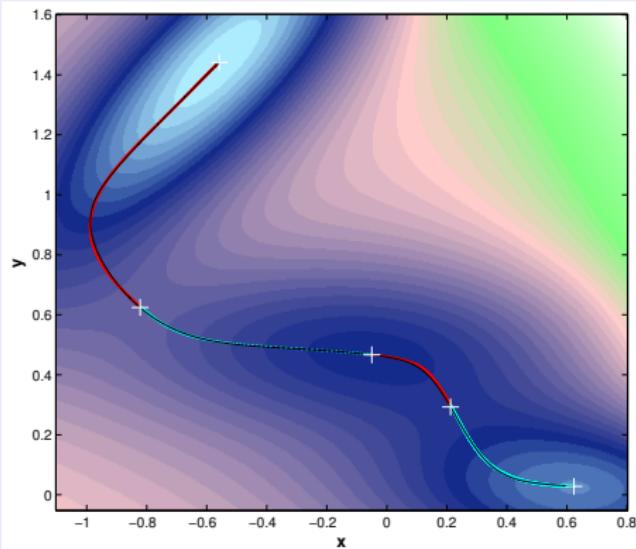
Comparison with the geometrical minimum action method

	gMAM	Deep NN
Discretisation	finite-diff, pseudo-spectral,...	NN parameter θ (exact)
Descent vector	$-\frac{\ F(\mathbf{u})\ }{\ \dot{\mathbf{u}}\ } \times \text{EL, Euler-Lagrange} \equiv \frac{\delta \mathcal{A}_g}{\delta \mathbf{u}}$	$-\nabla_{\theta}(\mathcal{A}_g + \mathcal{C}_{\text{arc}})$
Descent algor.	deterministic: relaxation, CG, L-BFGS	stochastic: ADAM and variants
Renormalisation step	hard constraint $\ \dot{\mathbf{u}}\ = \text{cst}$ (interpolation)	none (soft constraint)
Dim curse ($d \geq 3$)	Yes	No
Non-convexity	Moderate (\sim continuous action)	Wild (NN par.)

gMAM: M.Heymann, E.VdE (Comm. Math., PRL, 2008), G.Poppe,T.Schäfer (J.Physics A, 2018), M.Tao (Physica D 2018). See also MAM, aMAM algorithms, e.g. X.Zhou, W.Ren, W.E (2008).

2-D Müller potential

$$\mathcal{A}_g = 229.1 \text{ (Arrhenius)}, \langle \mathcal{A}_g \rangle = 229.3$$

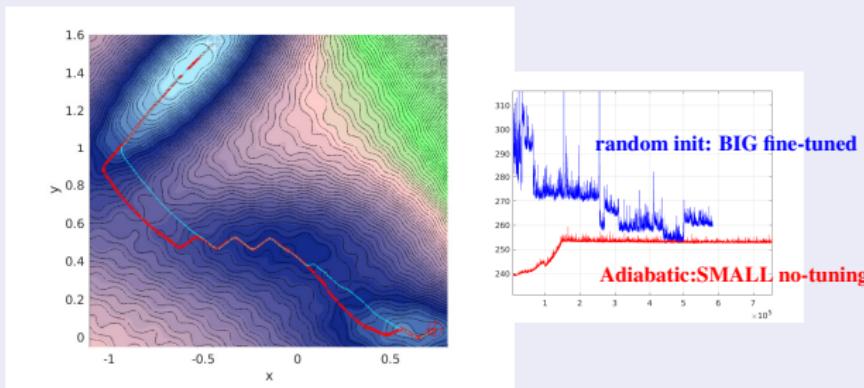


ANY: lifted $\mathcal{N} : [0, 1] \rightarrow \mathbb{R}^2$, 4 hidden layers, 10 neurons/layer, swish, ADAM 10^{-3} , $N = 2048$, random init, $\gamma_{\text{arc}} = 0.01$, $\gamma_{\text{geom}} = 1$, **# params = 482**.

Rugged 2-D Müller potential $+\gamma \sin(10\pi x) \sin(10\pi y)$, $\gamma = 3$

How to bring NNs to relevant states ?

- **Brut force:** fine-tuning with deep NNs (penalty, capacity, depth, training rate, activation function, multi-scaling, etc...) NN converges to solution even with random initialisation (Xavier).
- **Adiabatic descent:** slow change of ad-hoc parameter during stochastic descent → ANY: cheap, light tuning, very efficient !

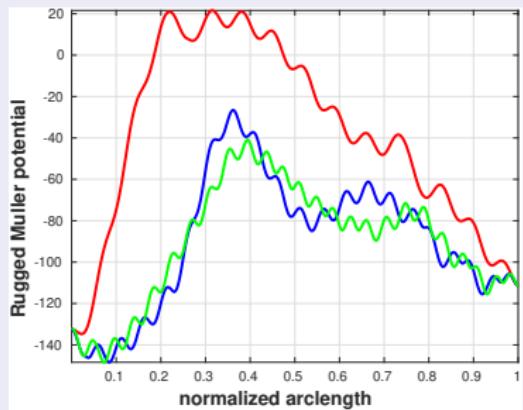
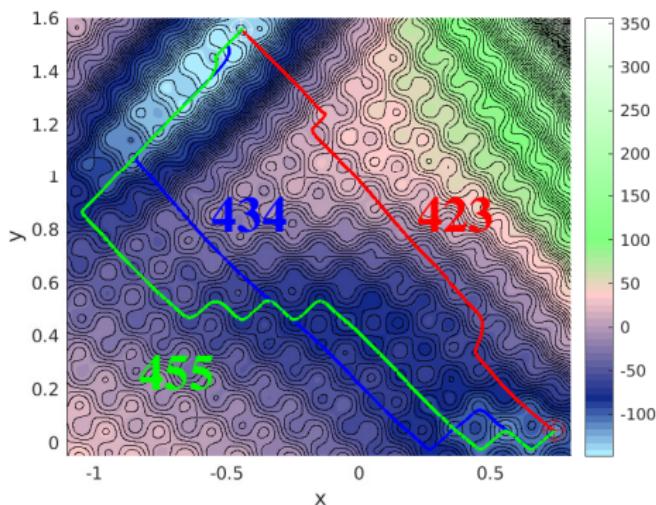


SMALL = e.g. basic feedforward 8 hidd $\times 10$ neur/l, # params = 922.

BIG = Multiscaled 5 \times 20 hidd $\times 10$ neur/l. Skip connections, $N = 128$, ADAM 10^{-3} , # params = 11210

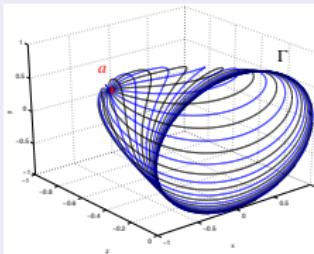
A challenging benchmark: many saddles

Rugged 2-D Müller potential $+\gamma \sin(10\pi x) \sin(10\pi y)$, $\gamma = 9$



A continuum set of instantons

- Separatrix can now contain more complicated *hyperbolic* sets Γ : limit cycles or attractors (e.g. Melancholia states, V.Lucarini).
- Consequence: continuum set of instantons which differ by their length [Tao, 2018]:



- To handle these situations, one must constrain the NN to look for instantons having a prescribed (arc)length L . New term in the cost functional:

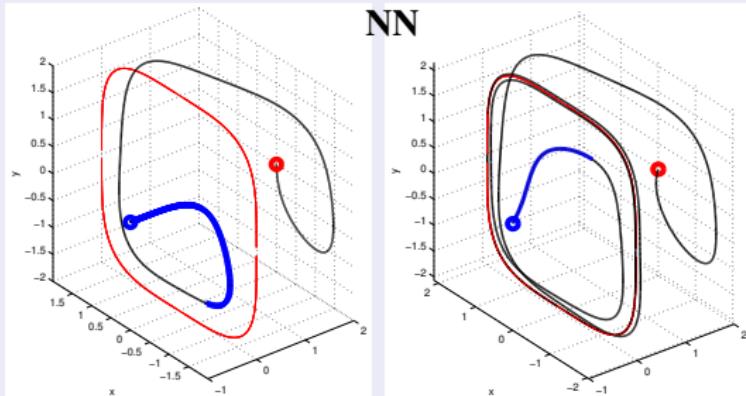
$$C_L = \left(\int_0^1 \|\dot{\mathcal{N}}\| ds - L \right)^2.$$

M.Tao, Hyperbolic periodic orbits in nongradient systems and small-noise-induced metastable transitions, Physica D. 363, 2018.

A continuum set of instantons: example [Tao]

Two stable points $\mathbf{a} = (0, 0, -1)$, $\mathbf{b} = (0, 0, +2)$ and an hyperbolic limit cycle Γ on the separatrix $z = 0$

$$\begin{cases} \dot{x} &= -(z+1)(z-2) \frac{x}{(x^4+y^4)^{1/4}} - x - y^3 \\ \dot{y} &= -(z+1)(z-2) \frac{y}{(x^4+y^4)^{1/4}} + x^3 - y \\ \dot{z} &= -(z+1)(z-2)z \end{cases} .$$



L=17

L=50

Ginzburg-Landau, Allen-Cahn PDE with shear

$$\partial_t u = v \Delta u + u - u^3 + \mathbf{c} \cdot \nabla u, \quad \mathbf{x} \in \mathcal{D} \equiv [0, 1]^d$$

with boundary conditions, either Dirichlet or periodic. It contains a very large set of situations:

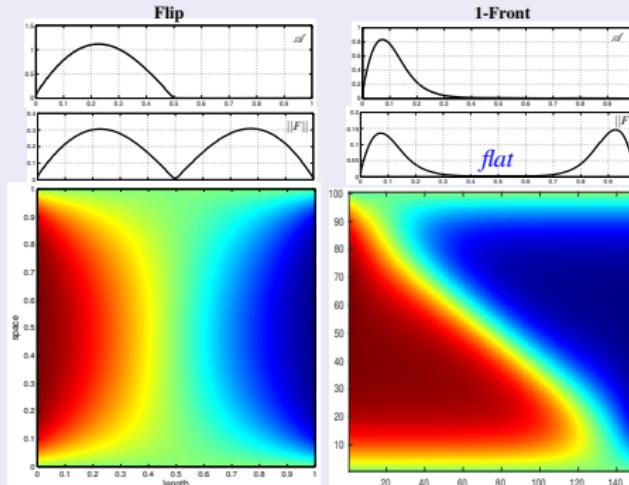
- Gradient PDE $\mathbf{c} = 0$: W.G.Faris, G.Jona-Lasinio, 1982 (LDP: $d = 1$).
- Nongradient with no transverse decomposition: $\|\nabla_{\mathbf{x}} \mathbf{c}\| \neq 0, d \geq 2$ [Tao]
- Separatrix contains many saddle fixed points and hyperbolic limit cycles.
- Many group symmetries and symmetry-breaking scenarii.
- \sim exact estimates of minimum action values in the transverse case are available: [Arrhenius law](#).
- $v \rightarrow 0$ singular limit
- Many exploratory studies, proof of concepts:

W.E, W.Ren, E.VdE, 2004 (MAM), M.Heymann, E.VdE PRL2008 (gMAM), M.Tao 2018 (gMAM), J.Rolland et al. 2016 (AMS), H.Li et al., 2021 (NN, committor).

$d = 1$, Dirichlet boundary conditions, $c = 0$, $v = 5 \cdot 10^{-3}$.

Two stable points $\mathbf{a}(x) = +1, \mathbf{b}(x) = -1$ + boundary-layer corrections, many possible saddles. Periodic BCs: discrete set of orbits for the Hamiltonian $H(x, y) = y^2/2 - \frac{1}{4v}(x^4 - 2x^2)$.

$$\text{Arrhenius law : } \mathcal{A}^{(0)} \sim \frac{1}{2} - \frac{4}{3}\sqrt{2v}, \quad \mathcal{A}^{(n)} \sim \frac{4}{3}n\sqrt{2v}, \quad v \leq \frac{1}{(n+1)^2\pi^2}, n \geq 1.$$



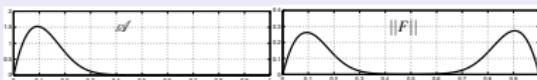
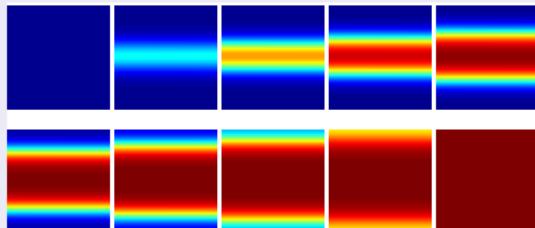
$$L = 1.8, \mathcal{A}_g = 0.36$$

$$L = 3.1, \mathcal{A}_g = 0.13$$

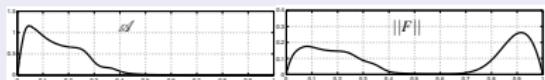
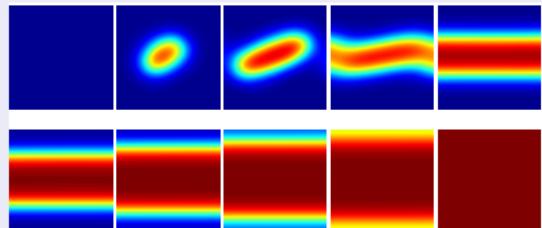
Nongradient 2-d PDE

$d = 2$, periodic boundary conditions, $0.1 \sin(2\pi y) \frac{\partial u}{\partial x}$, $v = 5 \cdot 10^{-3}$.

Two stable points $a(x) = -1, b(x) = +1$, same saddles than for $c = 0$, in addition: presence of hyperbolic limit cycles.



$$L = 2.9, \mathcal{A} = 0.26$$

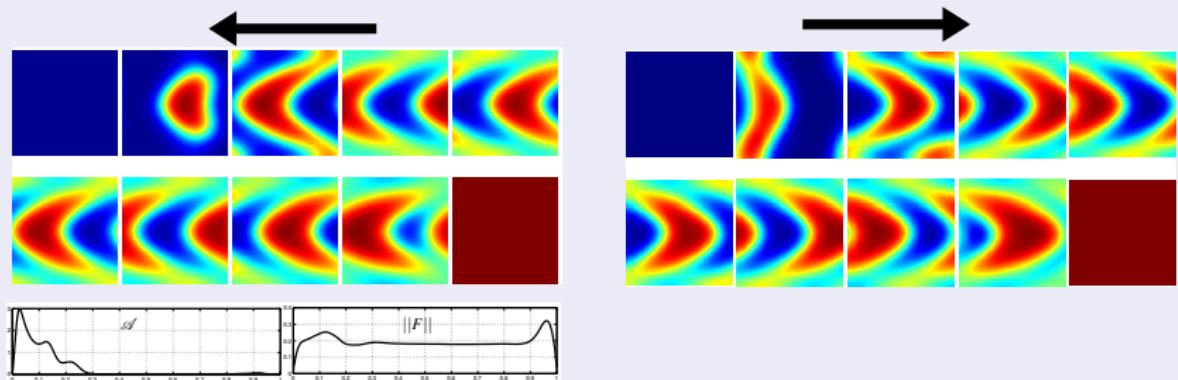


$$L = 3.3, \mathcal{A} = 0.248$$

- shear-facilitated nucleation: first obtained by M.Heynmann, E.VdE (PRL2008) using gMAM.
- goes through the same saddle ! transverse decomposition cannot hold [Tao, 2018].
- Here: NN initial conditions are *random* + **symmetry breaker**: $\left(\int_0^1 \|\partial_x \mathcal{N}\|^2 ds - cst\right)^2$.

$d = 2$, periodic boundary conditions, $0.1 \sin(2\pi y) \frac{\partial u}{\partial x}$, $v = 5 \cdot 10^{-3}$.

Arrow⁺, Arrow⁻ hyperbolic limit cycles

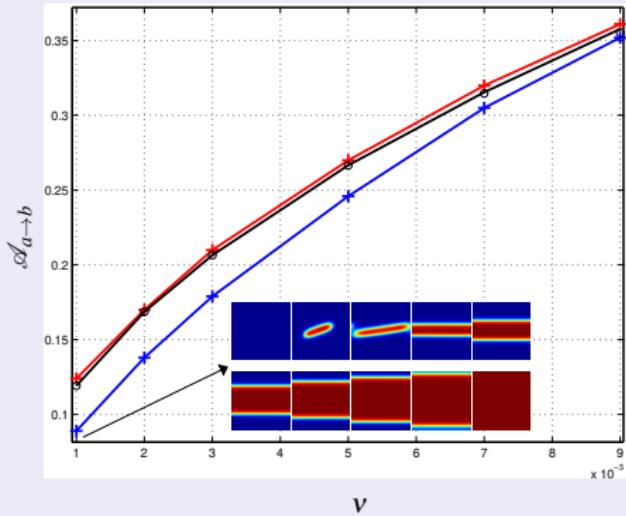


$$L = 10, \mathcal{A} = 0.35$$

- undocumented: symmetry-breaking of Tao's snake?

$d = 2$, periodic boundary conditions, $0.1 \sin(2\pi y) \frac{\partial u}{\partial x}$

$v \rightarrow 0$ using adiabatic descent

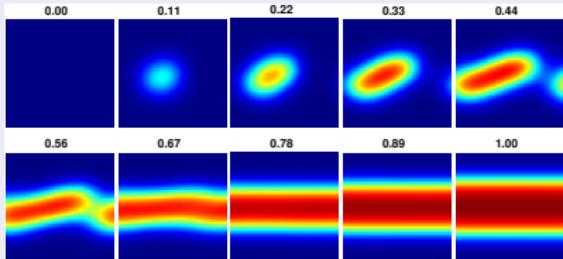


$d = 3$, periodic boundary conditions, $\nu = 5 \cdot 10^{-3}$.

$$\partial_t u = \nu \Delta u + u - u^3 + 0.1 \sin 2\pi y (\partial_x u + \partial_z u)$$

z=0.5

y

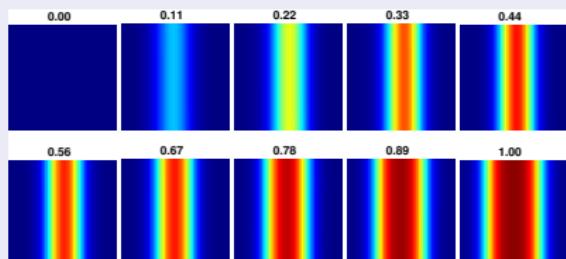


x

$$\mathcal{A} = 0.24$$

x=0.5

z



y

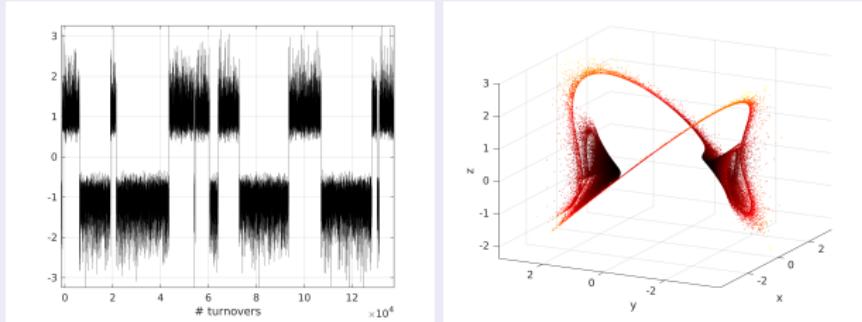
7 hidden layers, 10 neurons/layer, swish, tensorial batch: 16×32 using two symmetry breakers in x and z .

- converge with a very small # of parameters ! Here 1662, to be compared to $O(10M)$ with classical methods.
- no codim-2 nucleations ?

Bistability in deterministic systems

- One does not need noise to observe bistability: **Crisis-induced intermittency**: Grebogi, Ott, York (1982). Basin of attractions can touch/overlap —> Chaos is doing the job...
- Even more generic with group symmetry: road to crisis. P.Chossat, M.Golubitsky, *Symmetry-increasing bifurcation of chaotic attractors*, Physica D, 1988 . Double-gyre circulation, Kuroshio bimodality, atmospheric jet transitions in Phillips models.
- Rare event is "intermittency with a timescale separation" !
- Example Dynamo reversal: C.Gissinger, E.Dormy, S.Fauve EPL 2010

$$\dot{x} = \mu x - yz, \dot{y} = -vy + xz, \dot{z} = -z + xy + \Gamma$$



$$\mu = 0.1192805, v = 0.1, \Gamma = 0.9$$

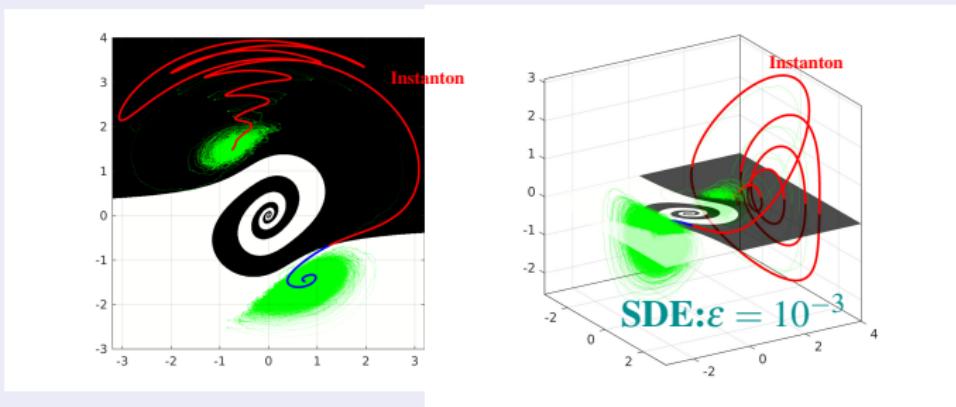
Freidlin-Wentzell action

- **No large deviations** for $\mu > \mu_c$! The *mean waiting time* follows a power law:
 $\tau \sim (\mu_c - \mu)^{-\gamma}$, $\gamma \sim \frac{1}{2}$ in the dynamo model. Here $\mu_c \approx 0.1192805$. The exponent depends on the type of crisis tangency.
- **FW minimizers have zero action !**

Which strategy to use if one does not know (stochastic versus deterministic) ?

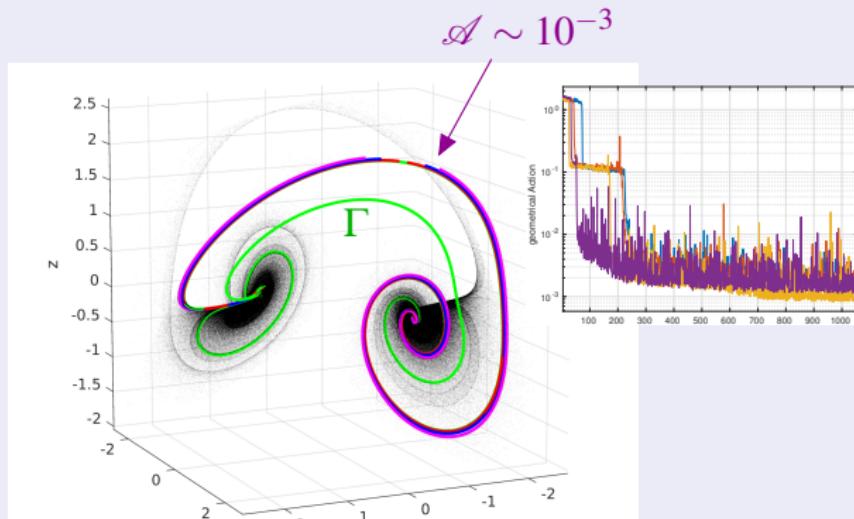
- **Direct simulation:** in the rare event regime (e.g. $|\mu - \mu_c| \ll 1$), one must integrate for a very long time some uninteresting dynamics. This is what we want to avoid.
- **AMS:** solve this problem by selections, mutations in the space of trajectories. Still the issue of reaction coordinate when ϵ is too small: poor estimates due to \exists of large tails (bias on probability *and ensemble*).
- **Geometrical action:** it looks like direct simulation with reparametrisation of time...

FW regime



- One saddle $O = (0, 0, \Gamma)$, two stable (damped oscillations) points: $(\pm\sqrt{v + \Gamma\sqrt{\frac{v}{\mu}}}, -\pm\sqrt{\mu + \Gamma\sqrt{\frac{\mu}{v}}}, -\sqrt{\mu v})$
- $\dim W^u(O) = 2$ (oscillatory).
- noisy precursor of crisis ? Silchenko et al., Fluctuational transitions across different kinds of fractal basin boundaries, PRE 2005. See also Maier, Stein, Luchinsky, Kraut, Grebogi, Demaeyer...
- Very different from Lorenz63: X.Zhou, W.E, Study of noise-induced transitions in the Lorenz system using the minimum action method, Comm.Math.Sci, 2010.

A waiting time killer ?



- **Bad guy:** initial conditions a are important. Do like in AMS: DNS sampling of $\mu_{eq}^{hit}\{\partial C\}$ where C contains a . Note that the transition path Γ is still correct up to a scaling factor in phase space (i.e $\exists \gamma > 0, \gamma \Gamma$ close to crisis path).

CONCLUSION

Advantages

- Natural stochastic extension of classical gMAM in the context of deep learning.
- Simple to implement, possibility to add algorithmic constraints without extra work
- NNs are most often able to find ad-hoc solutions without help (stochastic gradient descent).
- Possibility to work as well in the context of deterministic chaotic systems: "**waiting time filtering**".
- Hard to compete with in dimension $3 + 1$ and more (curse dimensionality).

Drawbacks

- Hyperparameters tuning: mostly penalty parameters, sometimes tricky...
- Chaotic systems (e.g. eddy-resolving models): one needs to consider more powerfull NN structures : *how far can we go ?*
- Pathological situations: barotropic QG with additive noise (Eulerian limit).
- Cannot be used for understanding finite-noise effects (see triple-well potential).

Perspectives

- intermediate-complexity deterministic models having crisis (ODEs, 1-D PDEs ?)
- challenge: baroclinic QG 2-layer model (Phillips) with atmospheric jet transitions.
- Room for algorithmic improvments: e.g. coupling with time integrators, multiscaled architectures...