



# Extreme Events in Complex Systems via Large Deviation Theory

Tobias Grafke

## Rogue waves:

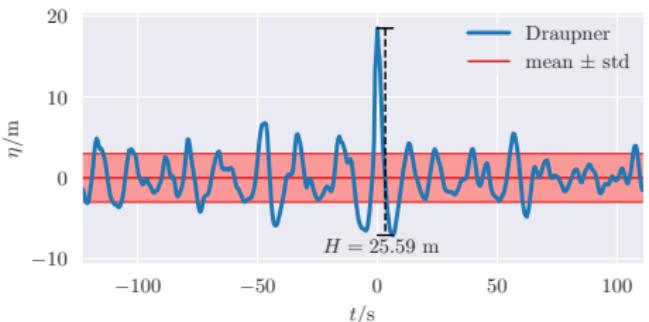
Events of extreme ocean surface elevation.

- Mechanism not fully understood
- Probably caused by **nonlinear amplification** (*modulational instability*) out of a background of (smaller) waves
- Probability density function unknown.

Goal: Estimate **tails** of the distribution

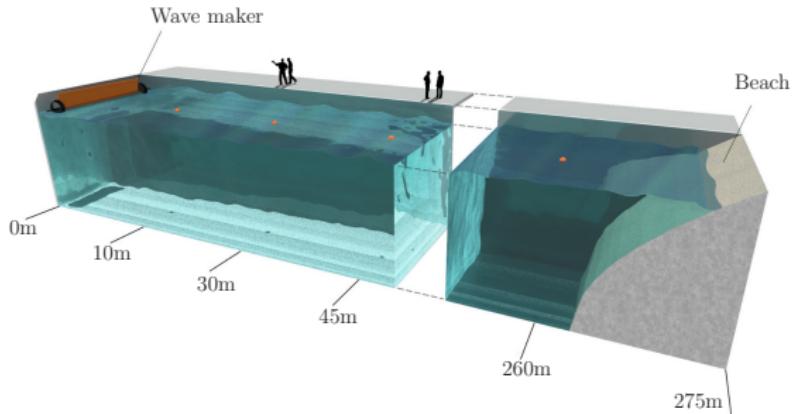


Tanker "Stolt Surf" in 1977, New York Times



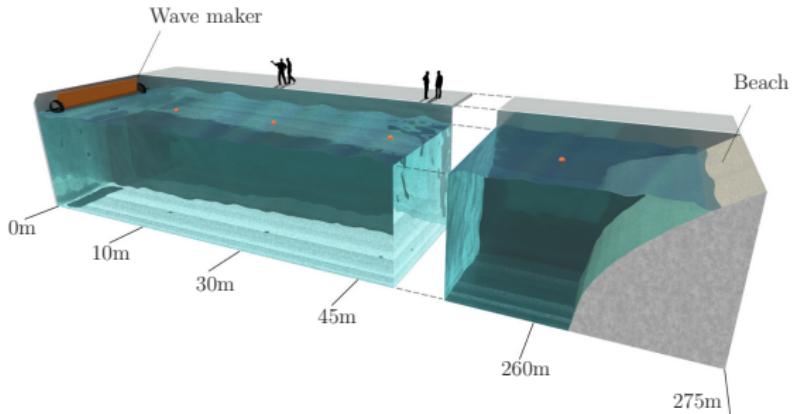
"Draupner Wave", Jan 1, 1995

# Experimental Setup

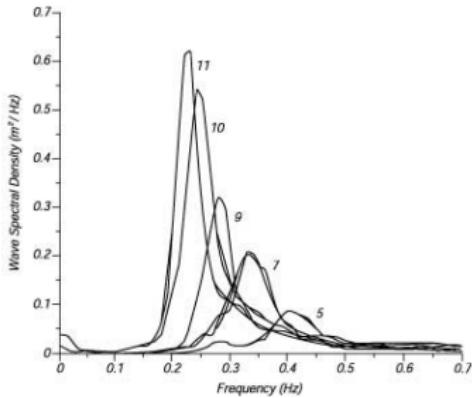


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- Wave maker generates **random signal**
- Planar wave **propagates** along the flume
- 19 probes record **elevation signal**  $\eta(t)$

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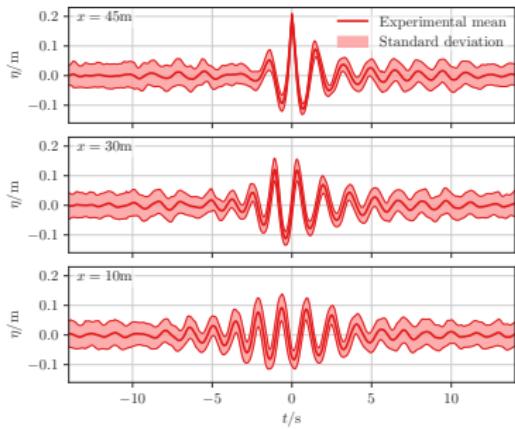
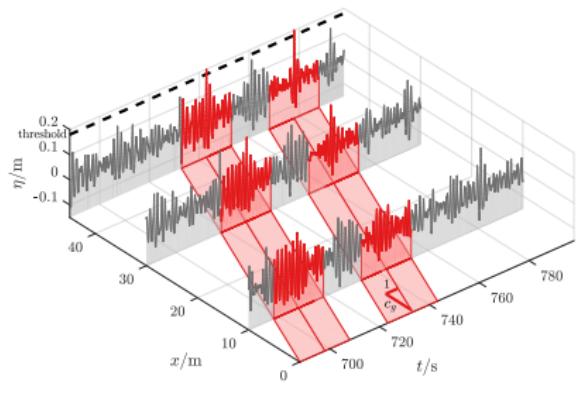


Input signal: JONSWAP observational spectrum

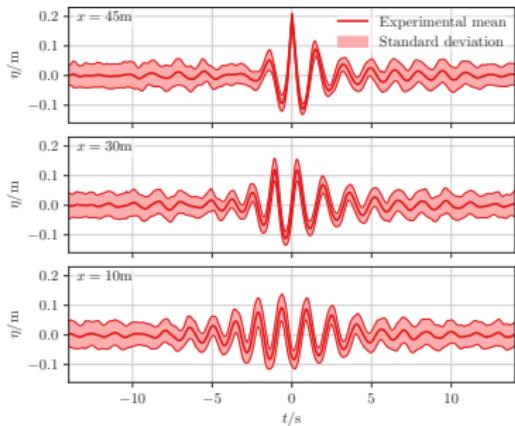
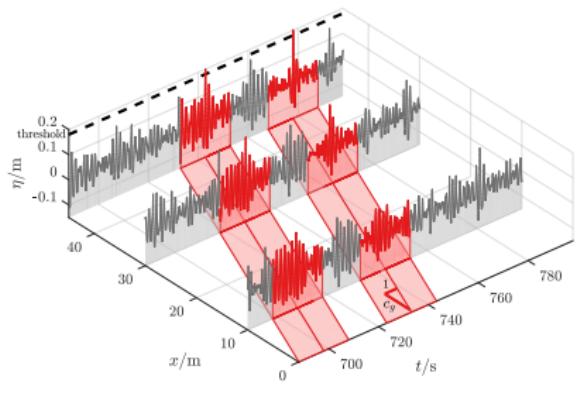
Defined by 2 Parameters:

- $H_s$ : sign. wave height
- BFI: degree of nonlinearity

# Extreme Event Filtering



- At fixed location  $x$  along flume, measure events that exceed threshold  $z$
- Track wave packet backwards in space, using  $c_g$
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**Claim:** Rogue Waves can be described via Large Deviations

# Large Deviations in Random Dynamical Systems

Consider **dynamical system**  $x \in \Omega$ , with **random parameters** and **random initial conditions**,

$$\dot{x} = b(x, \theta), \quad x(t=0) = x_0(\theta), \quad \theta \sim \mu(\theta)$$

and some **observable**  $f : \Omega \mapsto \mathbb{R}$ , then

$$P_T(z) = \mathcal{P}(f(x(T)) \geq z) = \mu(\Omega(z))$$

where  $\Omega(z) = \{\theta \in \Omega \mid f(x(T; \theta)) \geq z\}$ .

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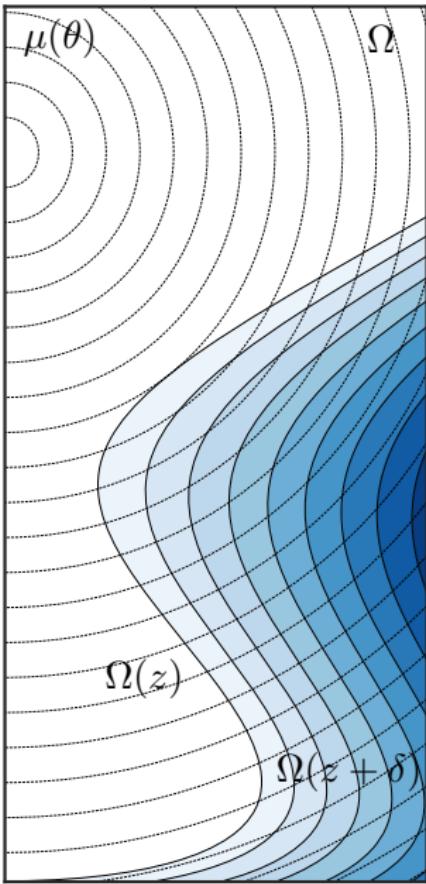
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$\Omega$ : Space of random parameters  $\theta$

$\mu$ : Random measure of  $\theta$  on  $\Omega$

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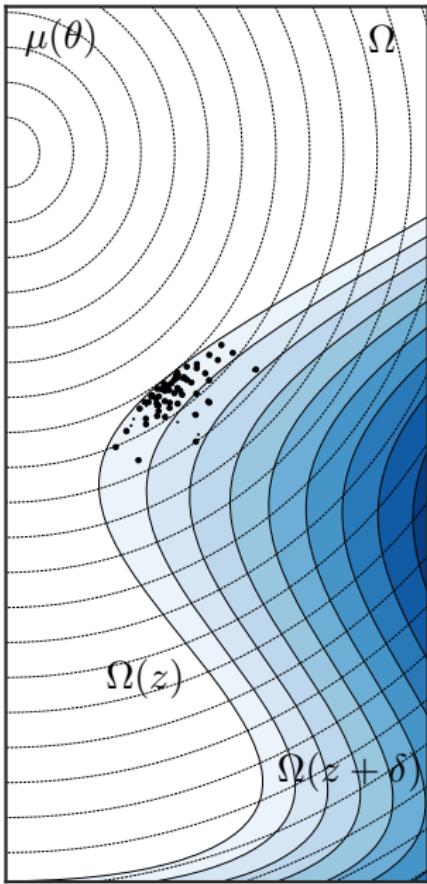
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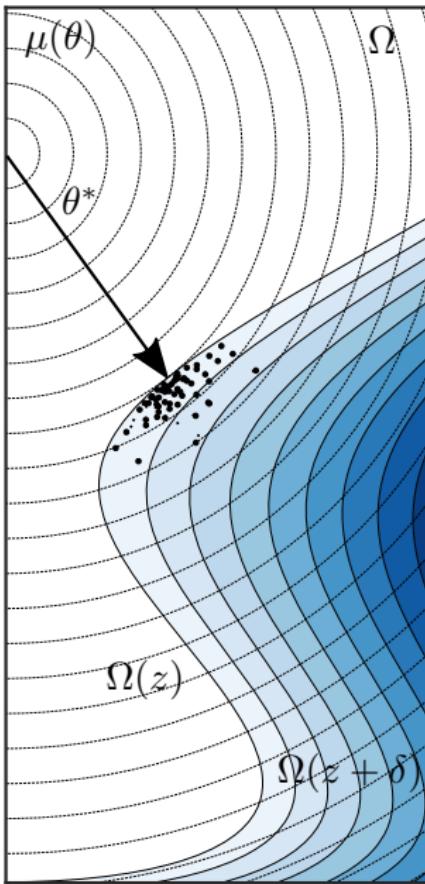
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## Intuition

We can replace the **integral over  $\Omega(z)$**  by its **most likely point** (dominating point, instanton)  $\theta^*(z)$ , i.e. the most likely random parameters that still lead to the rare event.

This transforms a **difficult sampling problem** into an **constrained optimization problem**



Then **large deviation principle** (LDP) says

$$P_T(z) \asymp \exp \left( - \min_{\theta \in \Omega(z)} I(\theta) \right)$$

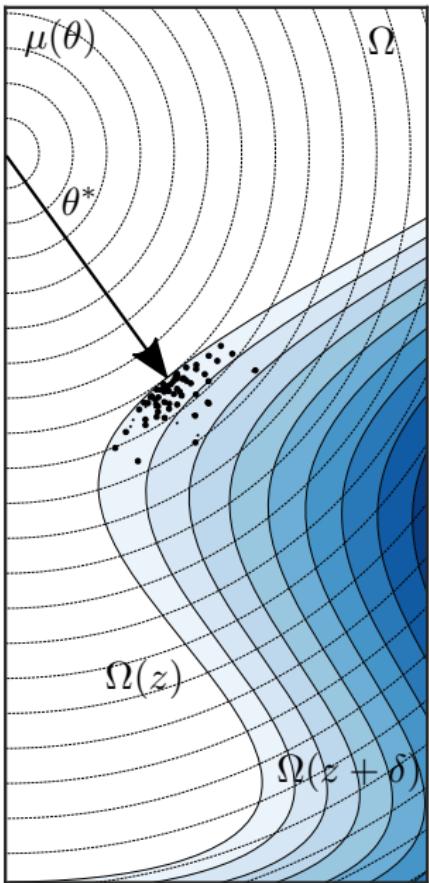
with rate function  $I(\theta) = \max_{\eta} \{ \langle \eta, \theta \rangle - S(\eta) \}$

and cumulant generating function

$$S(\eta) = \log \mathbb{E} e^{\langle \eta, \theta \rangle}$$

Dominated for  $z \rightarrow \infty$  by **instanton** or **minimizer**

$$\theta^*(z) = \operatorname{argmin}_{\theta \in \Omega(z)} I(\theta)$$



# Rogue waves in MNLS

Evolution of a narrow-banded, uni-directional **wave envelope**  $\psi(t, x)$  on the surface of a fluid with **infinite depth**:

*nonlinear Schrödinger equation* (NLS)

$$\partial_x \psi + 2\frac{k_0}{\omega_0} \partial_t \psi + i\frac{k_0}{\omega_0^2} \partial_t^2 \psi + 2ik_0^3 |\psi|^2 \psi = 0, \quad \psi(x=0) = \psi_0$$

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## Instanton computation

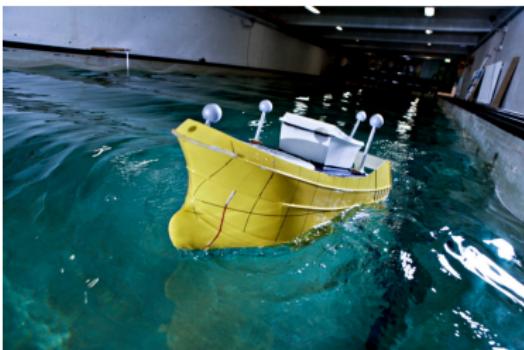
We have the above LDT for

$$\begin{cases} b(\psi) = \text{NLS} \\ \psi_0 \sim \mu = \text{JONSWAP} \\ f(\psi(L)) = \max_{t \in \Omega} |\psi(X, t)| \end{cases}$$

and find numerically

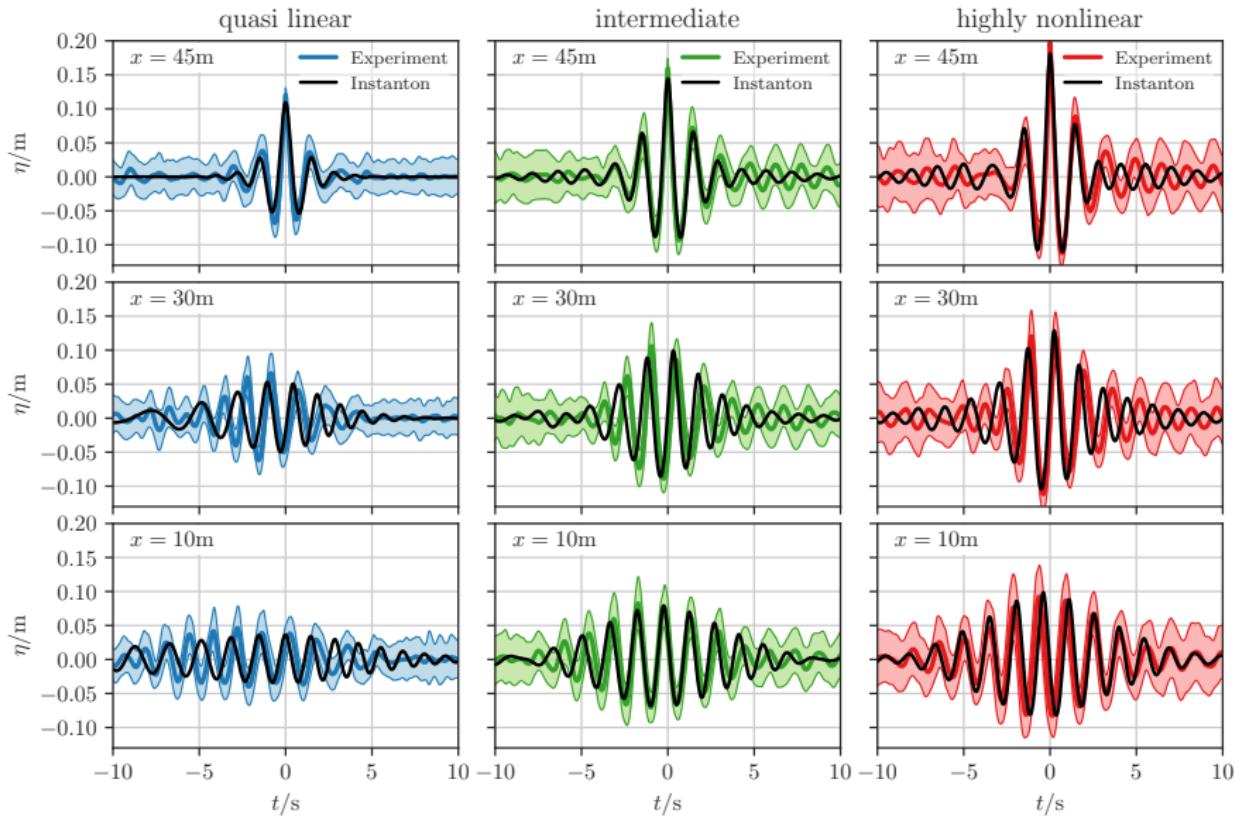
$$P(z) = \mathcal{P}(f(\psi(L)) > z) \sim \exp(-S(\psi_0^*))$$

by computing instanton  $\psi^*$ .



Compare  $\psi^*$  to experiment!

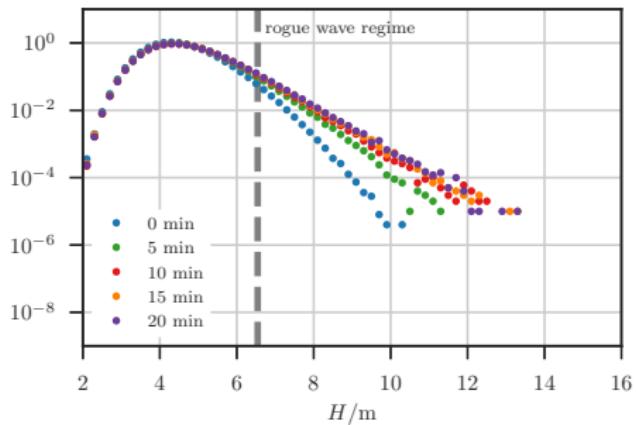
# Comparison: Experiment vs Instanton



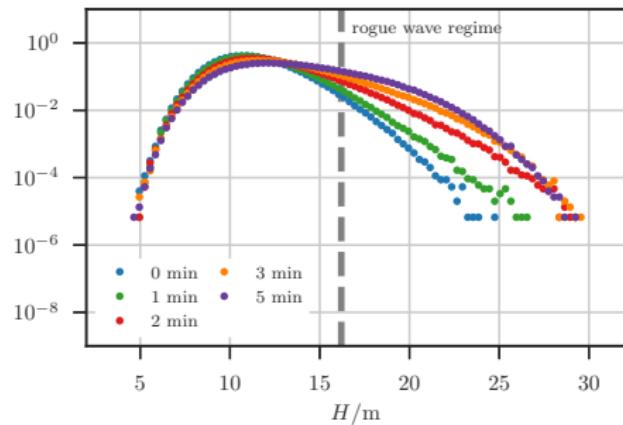
Giovanni Dematteis, Tobias Grafke, Miguel Onorato, and Eric Vanden-Eijnden. In: *Physical Review X* 9.4 (Dec. 2019). doi: 10.1103/PhysRevX.9.041057

# Probabilities

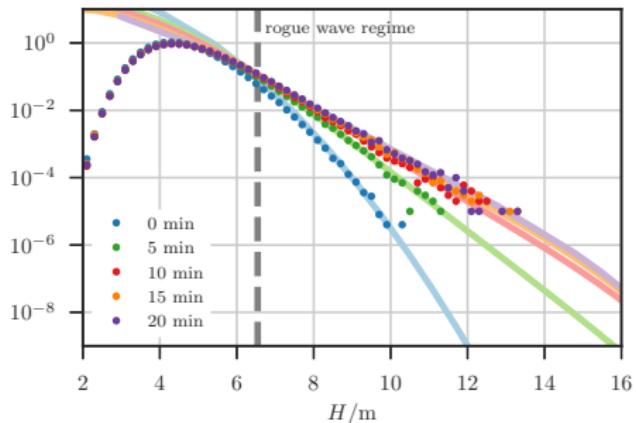
*rough sea* ( $H_s = 3.3\text{m}$ , BFI = 0.34)



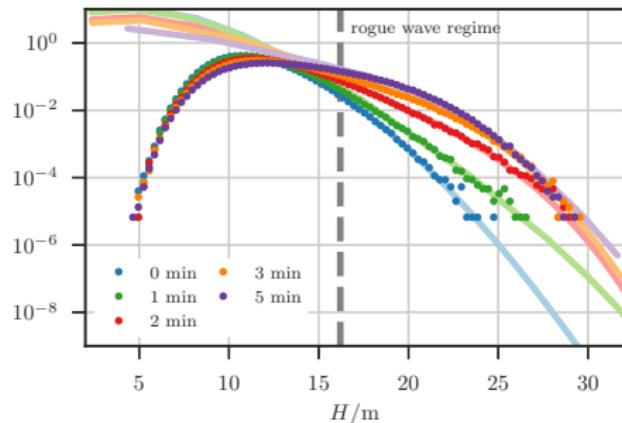
*high sea* ( $H_s = 8.2\text{m}$ , BFI = 0.85)



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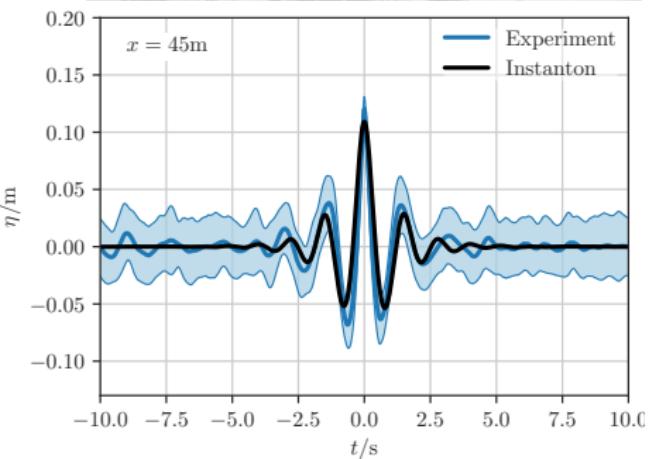
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Comparison between **Monte Carlo** (dots) and **LDT** (lines):

LDT is able to **predict tails of rogue wave** distribution.

- Experimental evidence of **hydrodynamic instanton**
- Each **Rogue Wave** event in **Wave Flume** experiment closely resembles **Instanton** solution
- Contains **linear theory** as limiting case
- Contains **Peregrine soliton** in nonlinear limit
- Offers **unified description** of Rogue waves



Giovanni Dematteis, Tobias Grafke, and Eric Vanden-Eijnden. In: *Proceedings of the National Academy of Sciences* 115.5 (Jan. 2018). doi: [10.1073/pnas.1710670115](https://doi.org/10.1073/pnas.1710670115)

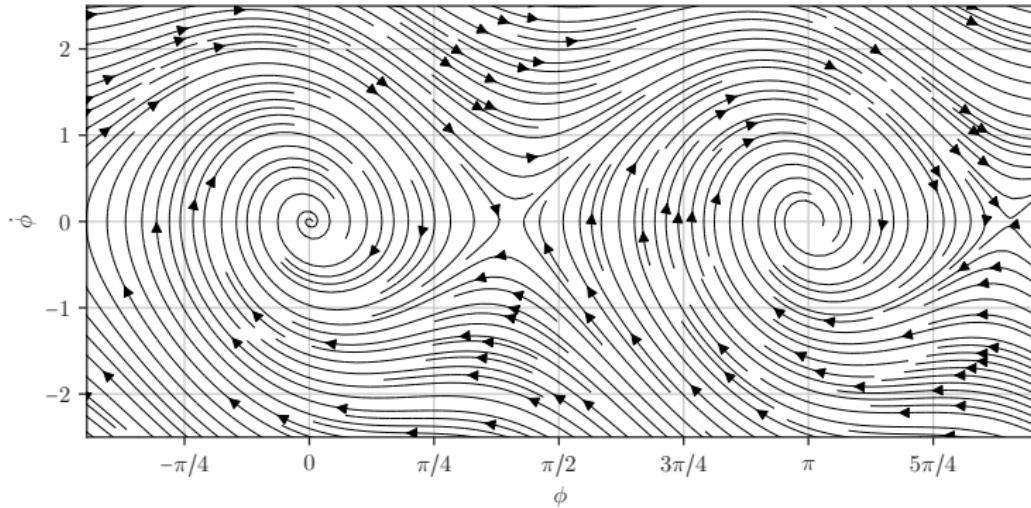
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Extreme Events in Complex Systems

## Large Deviation Theory

The way rare events occur is often predictable — it is dominated by the *least unlikely* scenario — which is the essence of LDT

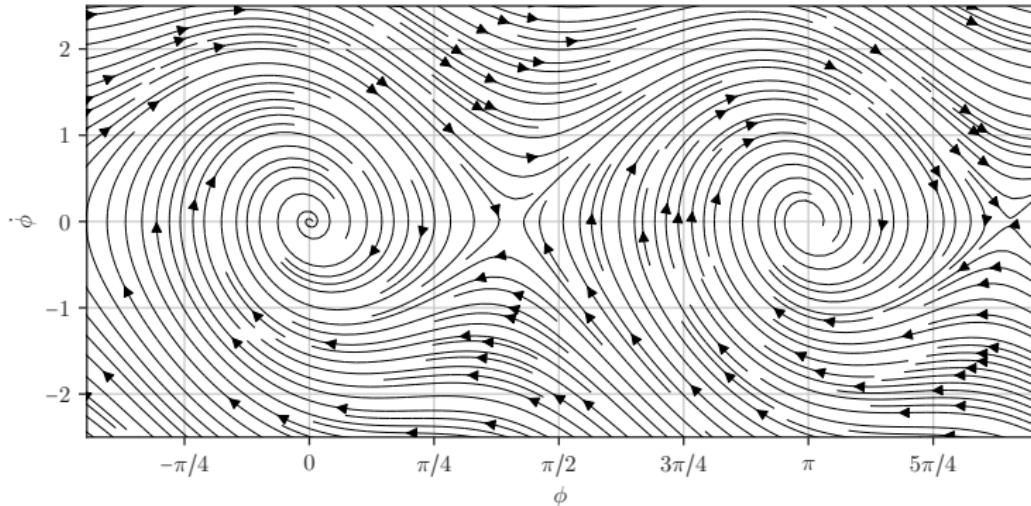
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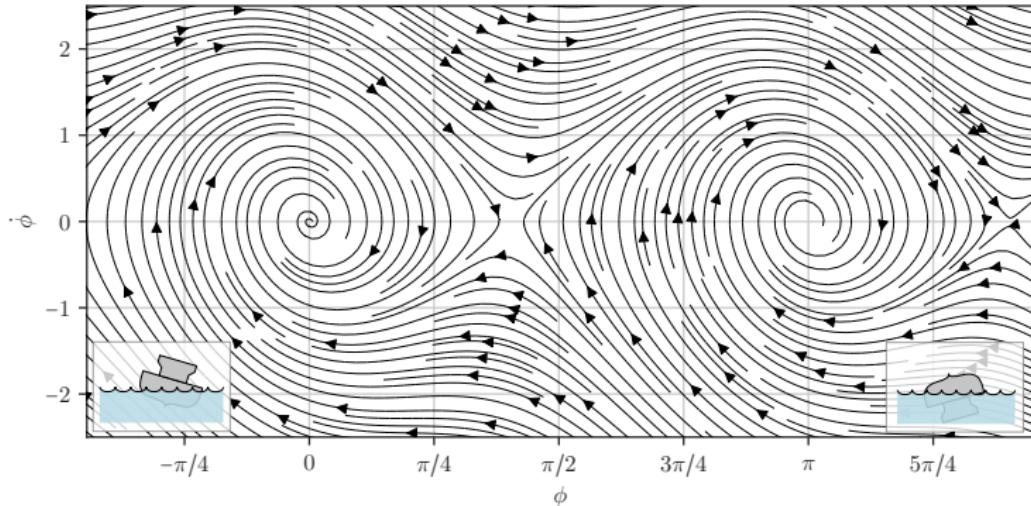


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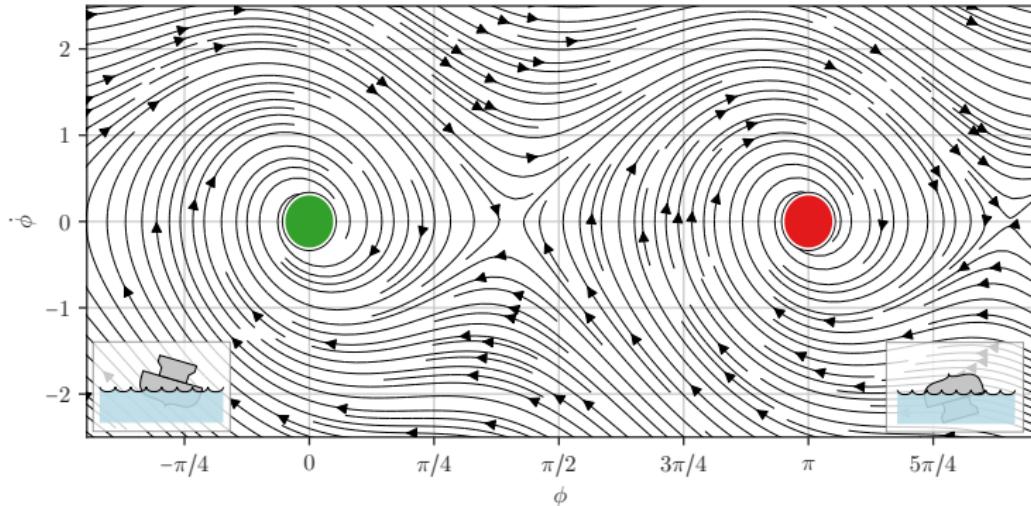


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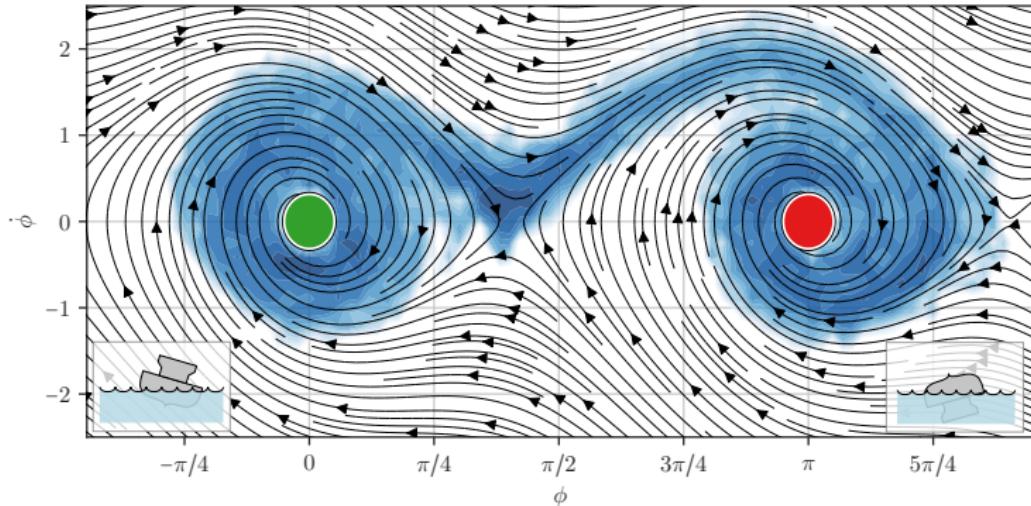


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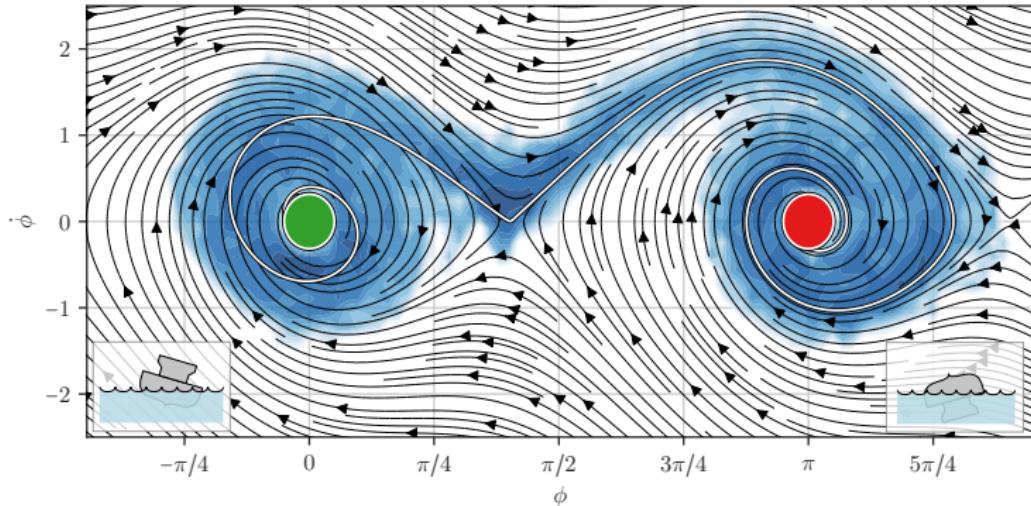
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## Large deviation theory for stochastic processes

A family of stochastic processes  $\{X_t^\varepsilon\}_{t \in [0, T]}$  with smallness-parameter  $\varepsilon$  (e.g.  $\varepsilon = 1/N$ , or  $\varepsilon = k_B T$ , etc) fulfills **large deviation principle**:

The probability that  $\{X^\varepsilon(t)\}_{t \in [0, T]}$  is close to a path  $\{\phi(t)\}_{t \in [0, T]}$  is

$$\forall \delta > 0 \quad \mathcal{P}^\varepsilon \left\{ \sup_{0 \leq t \leq T} |X^\varepsilon(t) - \phi(t)| < \delta \right\} \asymp \exp(-\varepsilon^{-1} S_T(\phi)) \text{ for } \varepsilon \rightarrow 0$$

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Here,  $\asymp$  is log-asymptotic equivalence, i.e.

$$\lim_{\varepsilon \rightarrow 0} \varepsilon \log \mathcal{P}^\varepsilon = - \inf_{\phi \in \mathcal{C}_x^y} S_T(\phi) \text{ with e.g. } \mathcal{C}_x^y = \{\phi \mid \phi(0) = x, \phi(T) = y\}$$

We also call the **minimizer**  $\phi^*(t) = \operatorname{argmin}_{\phi \in \mathcal{C}_x^y} S_T(\phi)$  the **instanton**

In particular consider SDE (diffusion) for  $X_t^\varepsilon \in \mathbb{R}^n$ ,

$$dX_t^\varepsilon = b(X_t^\varepsilon) dt + \sqrt{\varepsilon} \sigma dW_t,$$

with “drift”  $b : \mathbb{R}^n \rightarrow \mathbb{R}^n$  and “noise” with covariance  $\chi = \sigma\sigma^T$ , we have

$$S_T(\phi) = \frac{1}{2} \int_0^T |\dot{\phi} - b(\phi)|_\chi^2 dt = \int_0^T L(\phi, \dot{\phi}) dt,$$

for **Lagrangian**  $L(\phi, \dot{\phi})$  (follows by contraction from Schilder’s theorem).

We are interested in

$$\phi^* = \operatorname{argmin}_{\phi \in \mathcal{C}} \int_0^T L(\phi, \dot{\phi}) dt$$

which is the **maximum likelihood pathway** or **instanton**, which fulfills the corresponding Hamilton’s equations ( $H(\phi, \theta) = \min_{\dot{\phi}} \{\dot{\phi} \cdot \theta - L(\phi, \dot{\phi})\}$ ):

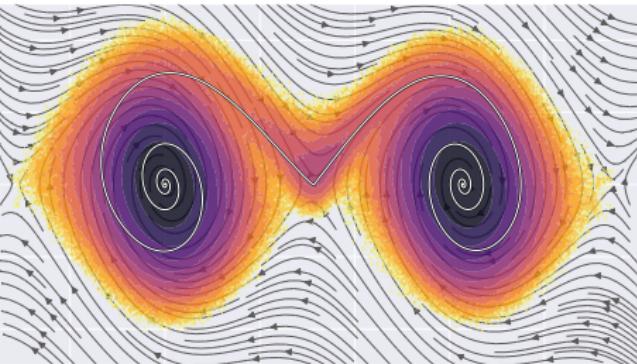
$$\begin{cases} \dot{\phi} &= b(\phi) + \chi \theta \\ \dot{\theta} &= (-\nabla b)^\top \theta \end{cases} \quad \text{with appropriate boundary conditions.}$$

## Main Problem

Find the **instanton**  $\phi^*$  such that

$$S_T(\phi^*) = \inf_{\phi \in \mathcal{C}_x^y} S_T(\phi)$$

where  $\mathcal{C}_x^y$  is the set of trajectories that transition  $x \rightarrow y$



Knowledge of the optimal trajectory gives us

1. **Probability** of event,  $\mathcal{P} \sim \exp(-\varepsilon^{-1} S_T(\phi^*))$
2. Most likely **occurrence**,  $\phi^*$  itself  
(allows for prediction, exploring causes, etc.)
3. Most effective way to force event (optimal control),  
**optimal fluctuation**

# Example: Ornstein-Uhlenbeck

## Ornstein-Uhlenbeck process

$$du = -\gamma u dt + \sqrt{\varepsilon} dW, \quad \gamma > 0.$$

Consider events with  $u(T) \geq z$

The **instanton** is

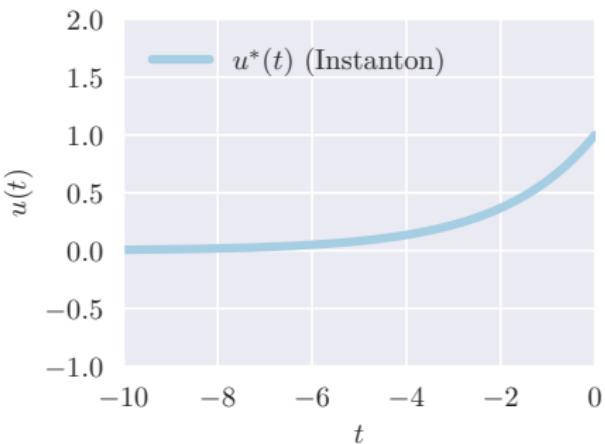
$$u^*(t) = ze^{\gamma(t-T)} \left( \frac{1 - e^{-2\gamma t}}{1 - e^{-2\gamma T}} \right),$$

obtained from **constrained optimization**

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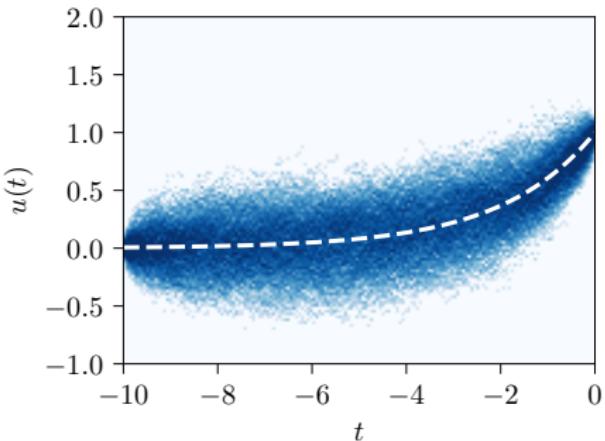
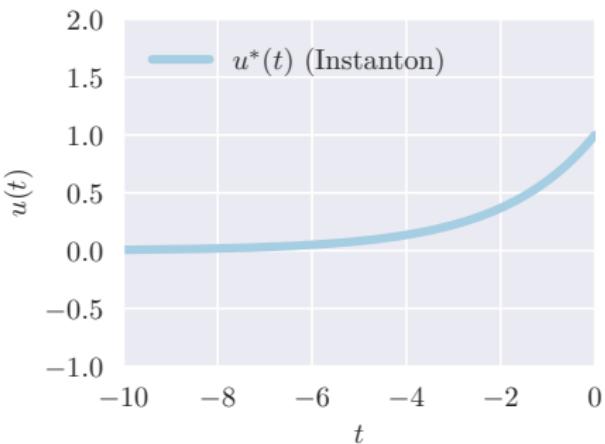
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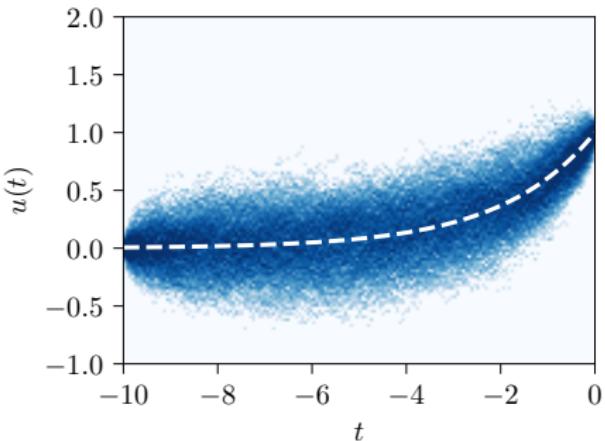
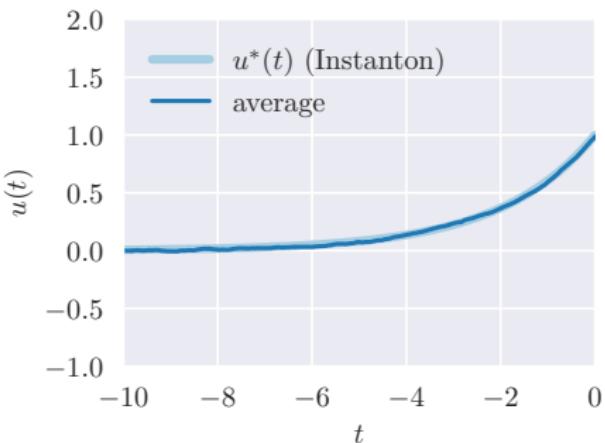
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### 3D Navier-Stokes equation

$$\begin{cases} \partial_t u + u \cdot \nabla u = -\nabla p + \Delta u + \sqrt{\varepsilon} \eta, \\ \nabla \cdot u = 0, \\ \mathbb{E}(\eta(x, t)\eta(x', t')) = \chi(x - x')\delta(t - t'). \end{cases}$$

We want to find the **most likely** extreme event that realizes an extreme **vorticity** or **strain**:

$$\omega_z(0, 0) \geq a \quad \text{or} \quad \partial_z u_z(0, 0) \geq a.$$

The corresponding **instanton** is the solution of the equations

$$\begin{cases} \partial_t u_I + \mathbb{P}[(u_I \cdot \nabla) u_I] - \Delta u_I = \chi * p_I, \\ \partial_t p_I + \mathbb{P}[(u_I \cdot \nabla) p_I + (\nabla p_I)^\top u_I] + \Delta p_I = 0, \end{cases}$$

(for the Leray-projector  $\mathbb{P} = \text{Id} - \nabla \Delta^{-1} \nabla \cdot$ )

# Instantons for the 3D Navier-Stokes equation

Observable: **Vorticity**

$$\omega_z \geq a$$

Compare **conditional average** from stochastic DNS against **instanton** from optimization problem.

This is a **large** problem ( $\approx 128^3 \times 1000$  dofs).

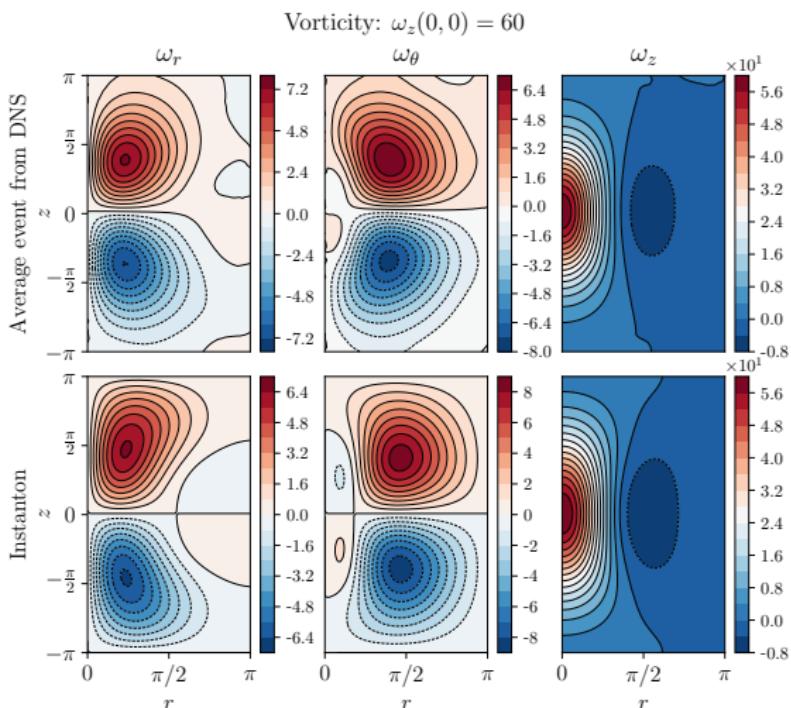
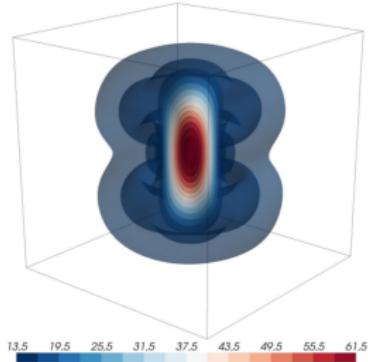
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## Spontaneous Symmetry Breaking

While the **observable** is symmetric, and the **action** is symmetric, the **minimizer** need not be symmetric.

# Spontaneous Symmetry Breaking in the Navier-Stokes equation

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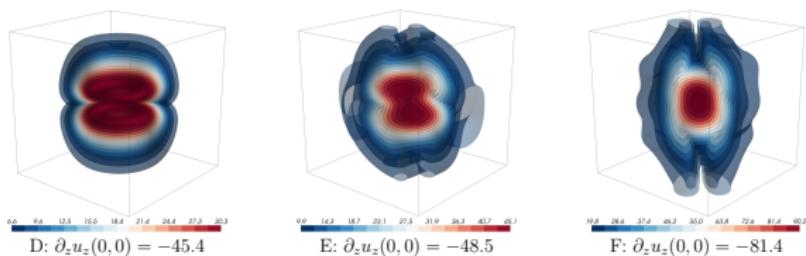
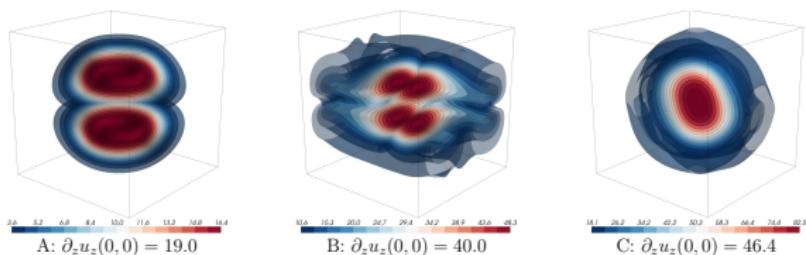
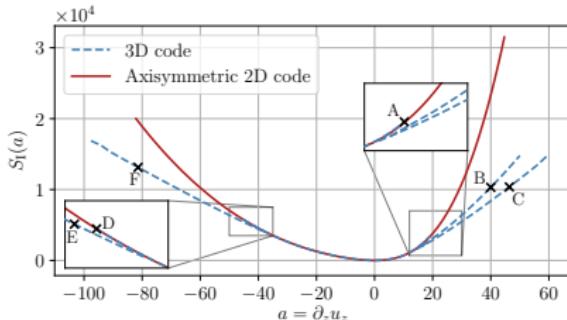
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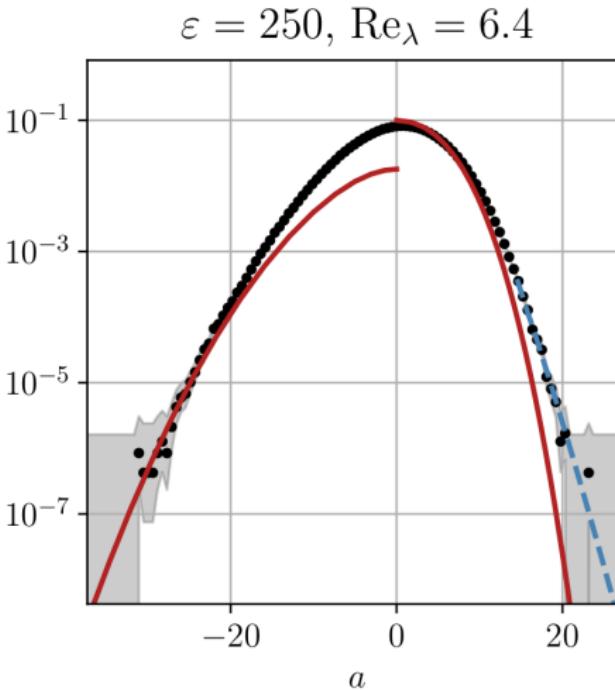
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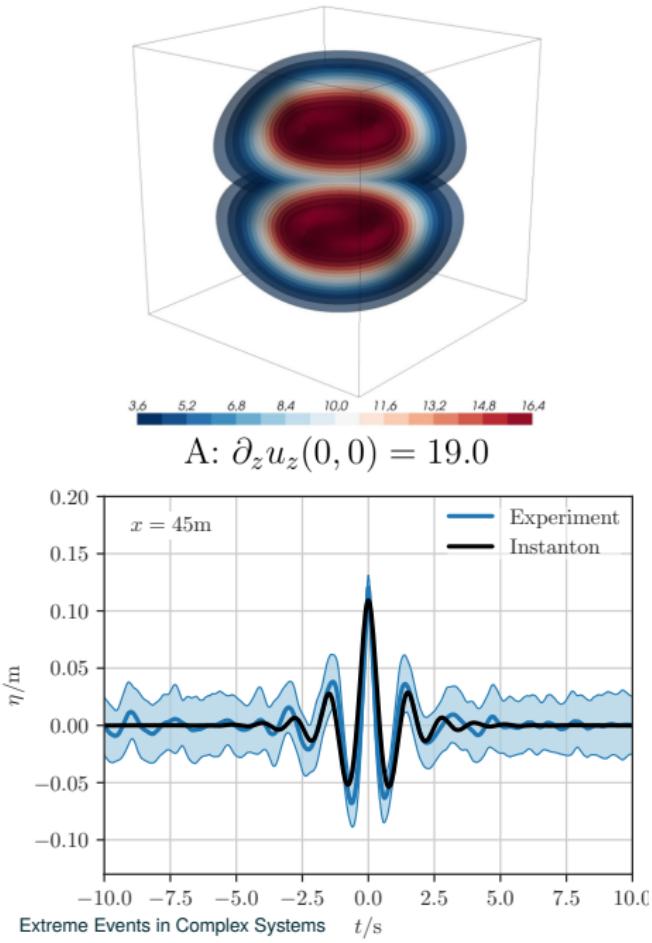


## Large Deviation Theory

- Rare events can effectively be treated by **large deviation theory**
- This applies both to **random parameters** and **random noise**, and even **random fields**
- Yields **most likely configuration** that realizes a rare event
- Yields **probability scaling** for rare events

Timo Schorlepp, Tobias Grafke, Sandra May, and Rainer Grauer. In: *arXiv:2107.06153 [physics]* (July 2021)

Tobias Grafke and Eric Vanden-Eijnden. In: *Chaos: An Interdisciplinary Journal of Nonlinear Science* 29.6 (June 2019).  
doi: [10.1063/1.5084025](https://doi.org/10.1063/1.5084025)



## Problem

Large Deviations captures only the **exponential scaling**:

$$\mathcal{P}(z) \sim \exp(-\varepsilon^{-1} S(\phi_z^*)) \quad \rightarrow \quad P(z) = C(z) \exp(-\varepsilon^{-1} S(\phi_z^*))$$

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- (1) Find **Large Deviation Minimizer**
- (2) Find **determinant** of the **second variation** of the action  
(in general, this will be a functional determinant)

## Computation of the Fluctuation Determinant

This amounts to accounting for the **effects of fluctuations**  $\xi$  around the minimizer  $\phi_z^*$ .

Perform the change of measure from  $X_t^\varepsilon$  to

$$\xi_t = \varepsilon^{-1/2} (X_t^\varepsilon - \phi_z^*) .$$

Expanding change-of-measure in  $\varepsilon$  yields

$\mathcal{O}(e^{\varepsilon^{-1}})$  is the LDT contribution

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The **prefactor** contribution is then available as expectation over the **fluctuation process**

$$d\xi_t = \nabla b(\phi_z^*) \xi_t dt + \sigma dW_t$$

via

$$C(z) = \mathbb{E}_\xi \exp \left( \frac{1}{2} \int_0^T \nabla \nabla \langle b(\phi_z^*), \theta \rangle : \xi_t \xi_t dt \right)$$

As we will see next, the effect of these fluctuations can be accounted for exactly!

# Computation of the Fluctuation Determinant

For  $dX_t^\varepsilon = b(X_t^\varepsilon) dt + \sqrt{\varepsilon} \sigma dW_t$ , with  $\chi = \sigma \sigma^\top$ , the prefactor  $C(z)$  can be calculated via a **Riccati equation** for  $Q : [0, T] \mapsto \mathbb{R}^{d \times d}$

$$\dot{Q} = Q \nabla \nabla \langle b(\phi), \theta \rangle Q + Q (\nabla b(\phi))^\top + (\nabla b(\phi)) Q + \chi$$

which is related to the covariance of the **fluctuations** around the minimizer.

$$C(z) = \sqrt{\frac{\varepsilon \kappa}{2\pi}} \langle \theta(T), Q(T) \theta(T) \rangle^{-1/2} \exp \left( -\frac{1}{2} \int_0^T \text{tr}[\nabla \nabla \langle b(\phi), \theta \rangle Q] dt \right)$$

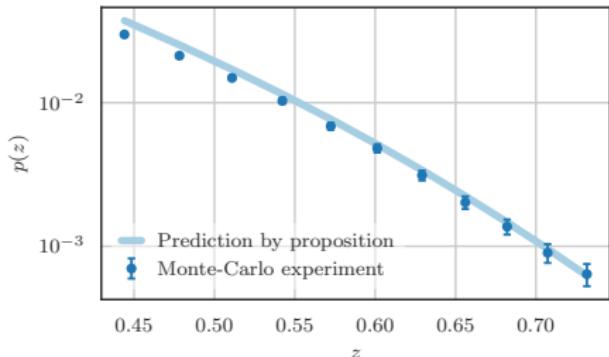
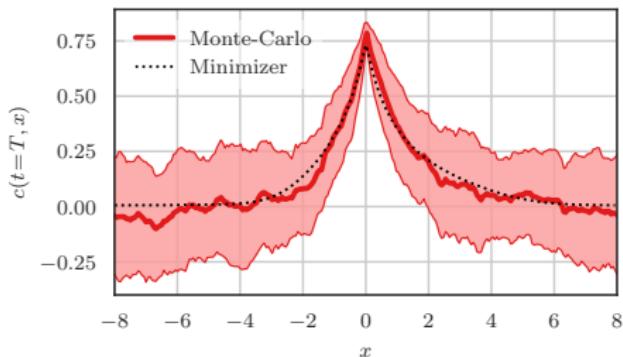
(where  $(\phi, \theta)$  is the minimizer and its conjugate momentum, and  $\kappa$  is a curvature term).

In QFT this is called the **fluctuation determinant** on the **instanton background**.

Timo Schorlepp, Tobias Grafke, and Rainer Grauer. In: *Journal of Physics A: Mathematical and Theoretical* (Apr. 2021).  
DOI: 10.1088/1751-8121/abfb26

Tobias Grafke, Tobias Schäfer, and Eric Vanden-Eijnden. In: *arXiv:2103.04837* (Apr. 2021)  
Freddy Bouchet and Julien Reygner. In: *arXiv:2108.06916 [cond-mat]* (Aug. 2021)

## Example: Stochastic Advection-Diffusion-Reaction equation



For advection-diffusion-reaction equation

$$\partial_t c = \kappa \partial_x^2 c - v(x) \partial_x c - \alpha c - \gamma c^3 + \sqrt{2\varepsilon} \eta,$$

We are interested in the probability that a sample exceeds the threshold  $z$  at the location  $x = 0$  at time  $t = T$ , i.e.

$$p(z) = \mathcal{P}(c(x=0, t=T) \geq z).$$

- We can reason about path-space measures via **sample path large deviations**
- This allows us to compute limiting **probabilities, expectations, hitting times**, etc in some limit (such as small noise)
- Sharp estimates are obtained via computation of **fluctuation determinant**
- This is applicable to many systems of relevance



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