آشنایی با زبان AVR C انواع داده

Dr. Aref Karimiafshar A.karimiafshar@ec.iut.ac.ir



Why program the AVR in C?

- Compilers produce hex files
 - We download it into the Flash of μC
 - The size of hex file is one of main concerns
 - Because of the limited on-chip Flash
- The choice of programming language affects the compiled program size
 - Assembly language produce a hex file that is much smaller than C
 - Assembly language is often tedious and time consuming
 - C programming is less time consuming and much easier to write
 - But the size is much larger

Major reasons for programming in C instead of Assembly

- ✓ It is easier and less time consuming
- ✓ Easier to modify and update
- ✓ You can use code available in function libraries
- ✓ C code is portable to other µCs with little or no modification

C Data Types for AVR C

- To create smaller hex file
 - You need, A good understanding of C data types
- Most common and widely used data types

Some Data Types Widely Used by C Compilers

Data Type	Size in Bits	Data Range/Usage
unsigned char	8-bit	0 to 255
char	8-bit	-128 to +127
unsigned int	16-bit	0 to 65,535
int	16-bit	-32,768 to +32,767
unsigned long	32-bit	0 to 4,294,967,295
long	32-bit	-2,147,483,648 to +2,147,483,648
float	32-bit	±1.175e-38 to ±3.402e38
double	32-bit	±1.175e-38 to ±3.402e38

Unsigned char

- Because the AVR is an 8-bit μC
 - The character data type is the most natural choice
- Range: 0-255 (00-FF H)
- In situations, such as setting a counter value
- We must pay careful attention to the size of data
 - Try to use unsigned char instead of int, if possible
- C compliers use the signed char as the default
 - Unless we put the keyword unsigned in front of the char
- In situations where + and are needed to represent a given quantity such as temperature
 - The use of signed char is necessary

Unsigned int

- Unsigned int is a 16-bit data type
- Used to define 16-bit variables such as memory addresses
 - Also set counter values of more than 256
- Because AVR is an 8-bit μC, int data type takes 2 bytes of RAM
 - We must not use int data type unless we have to!
 - Misuse of int result in
 - Larger hex files
 - Slower execution
 - More memory usage
 - Such misuse is not problem in PCs (with 512 MB, bus speed 133 Mhz, ...)

Other Data Types

- Unsigned int is limited to 0-65,535 (0000-FFFF H)
- For values greater than 16-bit
 - AVR C compiler supports long data types
- Also to deal with fractional numbers
 - Float
 - Double

Data Types

Write an AVR C program to toggle all bits of Port B 50,000 times.

```
//standard AVR header
#include <avr/io.h>
int main (void)
  unsigned int z;
  DDRB = 0xFF;
                                     //PORTB is output
  for(z=0; z<50000; z++)
    PORTB = 0x55;
    PORTB = 0xAA;
  while (1);
                                     //stay here forever
  return 0;
```

Data Types

Write an AVR C program to toggle all bits of Port B 100,000 times.

```
//toggle PB 100,00 times
                                     //standard AVR header
#include <avr/io.h>
int main (void)
                                     //long is used because it should
  unsigned long z;
                                     //store more than 65535.
                                     //PORTB is output
  DDRB = 0xFF:
  for (z=0; z<100000; z++){
    PORTB = 0x55:
    PORTB = 0xAA;
                                     //stay here forever
  while (1):
  return 0:
```

Time Delay

- There are three ways to create a time delay in AVR C:
 - Using a simple for loop
 - Using predefined C functions
 - Using AVR timers
- In creating a time delay using for loop, there are two factors that can affect the accuracy of the delay:
 - The Crystal frequency
 - The Compiler used to compile the C program
 - Because it is the C compiler that convert C statements and functions to assembly language instructions
 - Different compilers produce different code
 - For the above reasons, we must use oscilloscope to measure the exact duration

Time Delay

Write an AVR C program to toggle all the bits of Port B continuously with a 100 ms delay. Assume that the system is ATmega 32 with XTAL = 8 MHz.

```
//standard AVR header
#include <avr/io.h>
void delay100ms (void)
  unsigned int i;
                                     //try different numbers on your
  for(i=0; i<42150; i++);
                                     //compiler and examine the result.
int main(void)
                                     //PORTB is output
  DDRB = 0xFF:
  while (1)
    PORTB = 0xAA:
    delay100ms();
    PORTB = 0x55;
    delay100ms();
  return 0;
```

Predefined Functions Time Delay

- Generating time delay using predefined functions:
 - delay_ms()
 - delay_us()
- Drawback of using these functions
 - Portability problem
 - Because different compilers do not use the same name for delay functions
 - You have to change every place in which the delay functions are used
 - To compile the program on another compiler
 - To overcome the problem
 - Use macro or wrapper function
 - Wrapper functions do nothing more than call the predefined delay function
 - Instead of changing all instances of predefined delay functions, you simply change the wrapper function

Predefined Functions Time Delay

Write an AVR C program to toggle all the pins of Port C continuously with a 10 ms delay. Use a predefined delay function in Win AVR.

```
#include <util/delay.h>
                                    //delay loop functions
#include <avr/io.h>
                                     //standard AVR header
int main(void)
      void delay ms(int d)
                                    //delay in d microseconds
            delay ms(d);
                                    //PORTA is output
      DDRB = 0xFF:
      while (1){
            PORTB = 0xFF;
            delay ms(10);
            PORTB = 0x55;
            delay ms(10);
      return 0:
```

- To access a PORT register as a byte
 - We use the PORTx label
 - x indicates the name of the port
- To access the data direction register
 - We use DDRx label
 - x indicates the name of the port
- To access a PIN register
 - We use PINx label
 - x indicates the name of the port

LEDs are connected to pins of Port B. Write an AVR C program that shows the count from 0 to FFH (0000 0000 to 1111 1111 in binary) on the LEDs.

Write an AVR C program to get a byte of data from Port B, and then send it to Port C.

```
//standard AVR header
#include <avr/io.h>
int main(void)
  unsigned char temp;
                                      //Port B is input
  DDRB = 0 \times 00;
                                      //Port C is output
  DDRC = 0xFF;
  while (1)
    temp = PINB;
    PORTC = temp;
  return 0;
```

Write an AVR C program to get a byte of data from Port C. If it is less than 100, send it to Port B; otherwise, send it to Port D.

```
//standard AVR header
#include <avr/io.h>
int main(void)
  DDRC = 0;
                                      //Port C is input
                                      //Port B is output
  DDRB = 0xFF:
                                      //Port D is output
  DDRD = 0 \times FF;
  unsigned char temp;
  while (1)
                                      //read from PINB
    temp = PINC;
    if ( temp < 100 )
      PORTB = temp;
    else
       PORTD = temp;
  return 0:
```

Bit size I/O

- I/O ports of ATmega32 are bit-accessible
 - But some AVR C compilers do not support this features
 - Also, there is no standard way of using it
- To set the first pin of Port B
 - In Code Vision, we can use

PORTB.0=1

- But it can not be used in other compilers such as WinAVR
- To write portable code
 - We must use AND or OR bit-wise operations

- Bit-Wise operators in C
 - Widely used in software engineering for embedded system and control

Bit-wise Logic Operators for C

		AND	OR	EX-OR	Inverter
A	В	A&B	A B_	A^B	$Y = \sim B$
0	0	0	0	0	1
0	1	0	1	1	0
1	0	0	1	1	
1	1	1	1	0	

The following shows some examples using the C bit-wise operators:

1.
$$0x35 & 0x0F = 0x05$$

2.
$$0x04 \mid 0x68 = 0x6C$$

3.
$$0x54 ^0x78 = 0x2C$$

4.
$$\sim 0x55 = 0xAA$$

```
//standard AVR header
#include <avr/io.h>
int main(void)
                               //make Port B output
  DDRB = 0xFF:
  DDRC = 0xFF:
                               //make Port C output
  DDRD = 0xFF;
                               //make Port D output
  PORTB = 0x35 \& 0x0F;
                              //ANDing
                               //ORing
  PORTC = 0x04 + 0x68;
  PORTD = 0x54 ^ 0x78;
                               //XORing
  PORTB = \sim 0 \times 55:
                               //inverting
  while (1):
  return 0:
```

Write an AVR C program to toggle only bit 4 of Port B continuously without disturbing the rest of the pins of Port B.

Write an AVR C program to monitor bit 5 of port C. If it is HIGH, send 55H to Port B; otherwise, send AAH to Port B.

```
//standard AVR header
#include <avr/io.h>
int main(void)
                            //PORTB is output
  DDRB = 0xFF;
                             //PORTC is input
  DDRC = 0x00;
                             //PORTB is output
  DDRD = 0xFF;
  while (1)
    if (PINC & Ob00100000) //check bit 5 (6th bit) of PINC
      PORTB = 0x55;
    else
      PORTB = 0xAA;
  return 0:
```

A door sensor is connected to bit 1 of Port B, and an LED is connected to bit 7 of Por C. Write an AVR C program to monitor the door sensor and, when it opens, turn on the LED.

```
#include <avr/io.h>
                                  //standard AVR header
int main(void)
  DDRB = DDRB & 0b11111101;
                                //pin 1 of Port B is input
 DDRC = DDRC \mid 0b10000000;
                                  //pin 7 of Port C is output
 while (1)
    if (PINB & 0b00000010) //check pin 1 (2nd pin) of PINB
      PORTC = PORTC | Ob10000000; //set pin 7 (8th pin) of PORTC
    else
      PORTC = PORTC & Ob011111111; //clear pin 7 (8th pin) of PORTC
  return 0;
```

Compound Assignment Operators in C

- To reduce coding (typing)
 - We can use compound statements

Compound Assignment Operator in C

Operation	Abbreviated Expression	Equal C Expression
And assignment	a &= b	a = a & b
OR assignment	a = b	a = a b

Bit-wise Shift Operation in C

Bit-wise Shift Operators for C

Operation	Symbol	Format of Shift Operation
Shift right	>>	data >> number of bits to be shifted right
Shift left	<<	data << number of bits to be shifted left

The following shows some examples of shift operators in C:

```
1. 0b00010000 >> 3 = 0b00000010 /* shifting right 3 times */
2. 0b00010000 << 3 = 0b10000000 /* shifting left 3 times */
3. 1 << 3 = 0b00001000 /* shifting left 3 times */
```

Bit-wise Shift Operation in C

Write code to generate the following numbers:

- (a) A number that has only a one in position D7
- (b) A number that has only a one in position D2
- (c) A number that has only a one in position D4
- (d) A number that has only a zero in position D5
- (e) A number that has only a zero in position D3
- (f) A number that has only a zero in position D1

- (a) (1 << 7)
- (b) (1<<2)
- (c) (1 << 4)
- (d) $\sim (1 << 5)$
- (e) $\sim (1 << 3)$
- (f) $\sim (1 << 1)$

Bit-wise Shift Operation in C

Write an AVR C program to monitor bit 7 of Port B. If it is 1, make bit 4 of Port B input; else, change pin 4 of Port B to output.

```
#include <avr/io.h>
                                            //standard AVR header
int main(void)
  DDRB = DDRB & \sim (1 << 7);
                                            //bit 7 of Port B is input
  while (1)
    if(PINB & (1<<7))
      DDRB = DDRB & \sim (1 << 4);
                                            //bit 4 of Port B is input
    else
      DDRB = DDRB ( 1 << 4);
                                            //bit 4 of Port B is output
  return 0;
```

پایان

موفق و پیروز باشید