Operating Systems

Isfahan University of Technology Electrical and Computer Engineering Department 1400-1 semester

Zeinab Zali

Session 6: Operation on Processes (API)



Process Creation

- Parent process create children processes, which, in turn create other processes, forming a tree of processes
- Generally, process identified and managed via a process identifier (pid)
- Resource sharing options
 - Parent and children share all resources
 - Children share subset of parent's resources
 - Parent and child share no resources
- Execution options
 - Parent and children execute concurrently
 - Parent waits until children terminate

Prevent overloading the system by too many child processes

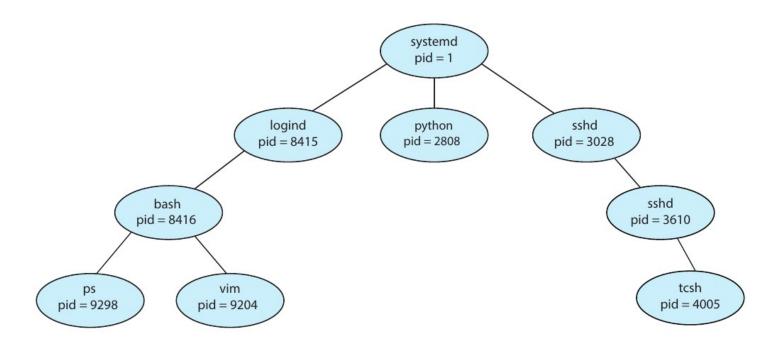


pstree

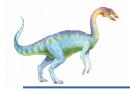


A Tree of Processes in Linux

pstree

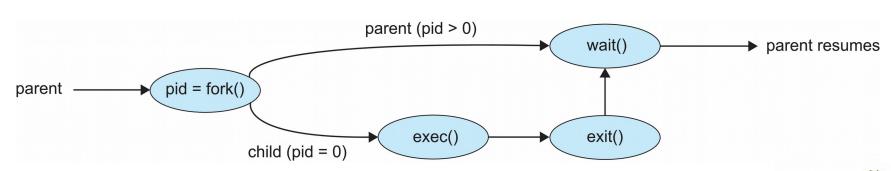


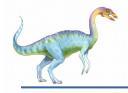




Process Creation (Cont.)

- Address space
 - Child duplicate of parent
 - Child has a program loaded into it
- UNIX examples
 - fork() system call creates new process
 - exec() system call used after a fork() to replace the process' memory space with a new program
 - Parent process calls wait () waiting for the child to terminate





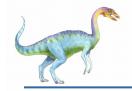
C Program Forking Separate Process

```
#include <sys/types.h>
#include <stdio.h>
#include <unistd.h>
int main()
pid_t pid;
   /* fork a child process */
   pid = fork();
   if (pid < 0) { /* error occurred */
      fprintf(stderr, "Fork Failed");
      return 1:
   else if (pid == 0) { /* child process */
      execlp("/bin/ls", "ls", NULL);
   else { /* parent process */
      /* parent will wait for the child to complete */
      wait (NULL);
      printf("Child Complete");
   return 0;
```

Practice

What is the output of following code? How many processes are created?

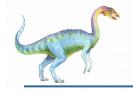
```
Main(){
  pid_t pid1, pid2, pid3;
  pid1 = fork();
  wait()
  pid2 = fork();
  if (pid1 == 0 \text{ or } pid2 == 0){
     printf('new child process');
  pid3 = fork();
  printf("End of the process");
```



Process Termination

- Process executes last statement and then asks the operating system to delete it using the exit() system call.
 - Returns status data from child to parent (via wait())
 - Process' resources are deallocated by operating system
- Parent may terminate the execution of children processes using the kill () system call. Some reasons for doing so:
 - Child has exceeded allocated resources
 - Task assigned to child is no longer required
 - The parent is exiting and the operating systems does not allow a child to continue if its parent terminates





Process Termination

- Some operating systems do not allow child to exists if its parent has terminated. If a process terminates, then all its children must also be terminated.
 - cascading termination. All children, grandchildren, etc. are terminated.
 - The termination is initiated by the operating system.
- The parent process may wait for termination of a child process by using the wait() system call. The call returns status information and the pid of the terminated process

```
pid = wait(&status);
```

- A process that has terminated, but whose parent has not yet called wait(), is known as a zombie process
- if a parent did not invoke wait() and instead terminated, thereby leaving its child processes as orphans





Process Termination

- Some operating systems do not allow child to exists if its parent has terminated. If a process terminates, then all its children must also be terminated.
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All processes transition to zombie state when they terminate, but generally they exist as zombies only briefly.

Once the parent calls wait(), the process identifier of the zombie process and its entry in the process table are released.

```
pid = wait(&status);
```

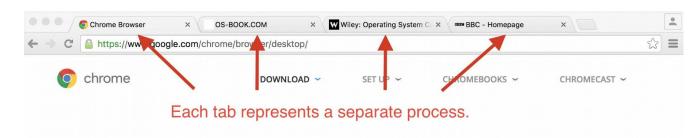
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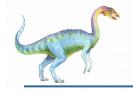


Multiprocess Architecture – Chrome Browser

- Many web browsers ran as single process (some still do)
 - If one web site causes trouble, entire browser can hang or crash
- Google Chrome Browser is multiprocess with 3 different types of processes:
 - Browser process manages user interface, disk and network I/O
 - Renderer process renders web pages, deals with HTML,
 Javascript. A new renderer created for each website opened
 - Runs in sandbox restricting disk and network I/O, minimizing effect of security exploits
 - Plug-in process for each type of plug-in



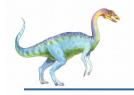




Interprocess Communication

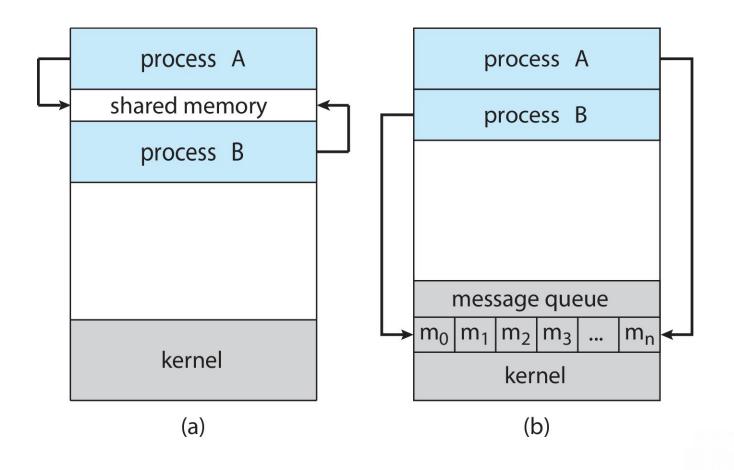
- Processes within a system may be independent or cooperating
- Cooperating process can affect or be affected by other processes, including sharing data
- Reasons for cooperating processes:
 - Information sharing
 - Computation speedup
 - Modularity
 - Convenience
- Cooperating processes need interprocess communication (IPC)
- Two models of IPC
 - Shared memory
 - Message passing (for small amounts of data)

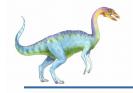




Communications Models

- (a) Shared memory. (b) Message passing.





Producer-Consumer Problem

- Paradigm for cooperating processes:
 - producer process produces information that is consumed by a consumer process
- Two variations:
 - unbounded-buffer places no practical limit on the size of the buffer:
 - Producer never waits
 - Consumer waits if there is no buffer to consume
 - bounded-buffer assumes that there is a fixed buffer size
 - Producer must wait if all buffers are full
 - Consumer waits if there is no buffer to consume





Interprocess Communication – Shared Memory

- An area of memory shared among the processes that wish to communicate
- The communication is under the control of the users processes not the operating system.
- Benefits:
 - Faster than message passing
- Disadvantages:
 - Major issues is to provide mechanism that will allow the user processes to synchronize their actions when they access shared memory.





Bounded-Buffer – Shared-Memory Solution

Shared data

```
#define BUFFER_SIZE 10

typedef struct {
    . . .
} item;

item buffer[BUFFER_SIZE];

int in = 0;

int out = 0;
```

Solution is correct, but can only use **BUFFER_SIZE-1** elements

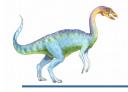




Producer Process – Shared Memory

```
item next_produced;
while (true) {
    /* produce an item in next produced */
    while (((in + 1) % BUFFER_SIZE) == out)
        ; /* do nothing */
    buffer[in] = next_produced;
    in = (in + 1) % BUFFER_SIZE;
}
```





Consumer Process – Shared Memory

```
item next_consumed;
while (true) {
    while (in == out)
        ; /* do nothing */
    next_consumed = buffer[out];
    out = (out + 1) % BUFFER_SIZE;

    /* consume the item in next consumed */
}
```

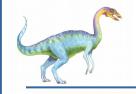




What about Filling all the Buffers?

- Suppose that we wanted to provide a solution to the consumerproducer problem that fills all the buffers.
- We can do so by having an integer counter that keeps track of the number of full buffers.
- Initially, counter is set to 0.
- The integer counter is incremented by the producer after it produces a new buffer.
- The integer counter is and is decremented by the consumer after it consumes a buffer.

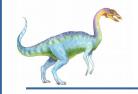




Producer

```
while (true) {
    /* produce an item in next produced */
    while (counter == BUFFER_SIZE)
       ; /* do nothing */
    buffer[in] = next_produced;
    in = (in + 1) % BUFFER_SIZE;
    counter++;
}
```

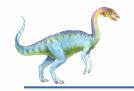




Consumer

```
while (true) {
    while (counter == 0)
        ; /* do nothing */
    next_consumed = buffer[out];
    out = (out + 1) % BUFFER_SIZE;
        counter--;
    /* consume the item in next consumed */
}
```





Race Condition

counter++ could be implemented as

```
register1 = counter
register1 = register1 + 1
counter = register1
```

counter-- could be implemented as

```
register2 = counter
register2 = register2 - 1
counter = register2
```

Consider this execution interleaving with "count = 5" initially:

```
S0: producer execute register1 = counter {register1 = 5}
S1: producer execute register1 = register1 + 1 {register1 = 6}
S2: consumer execute register2 = counter {register2 = 5}
S3: consumer execute register2 = register2 - 1 {register2 = 4}
S4: producer execute counter = register1 {counter = 6}
S5: consumer execute counter = register2
```





Race Condition (Cont.)

- Question why was there no race condition in the first solution (where at most N - 1) buffers can be filled?
- More in Chapter 6.

