

# Operating Systems

Isfahan University of Technology  
Electrical and Computer Engineering Department  
1400-1 semester

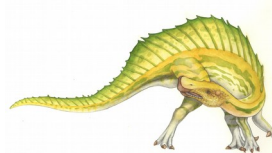
Zeinab Zali

Session 7: Inter Process Communication (IPC)



# Interprocess Communication

- Processes within a system may be *independent* or *cooperating*
- Cooperating process can affect or be affected by other processes, including sharing data
- Reasons for cooperating processes:
  - Information sharing
  - Computation speedup
  - Modularity
  - Convenience
- Cooperating processes need **interprocess communication (IPC)**
- Two models of IPC
  - **Shared memory**
  - **Message passing (for small amounts of data)**

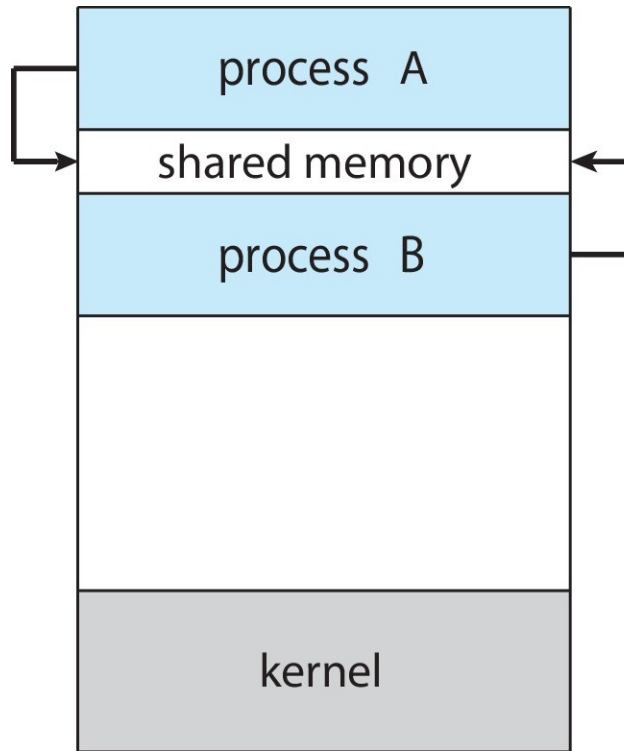




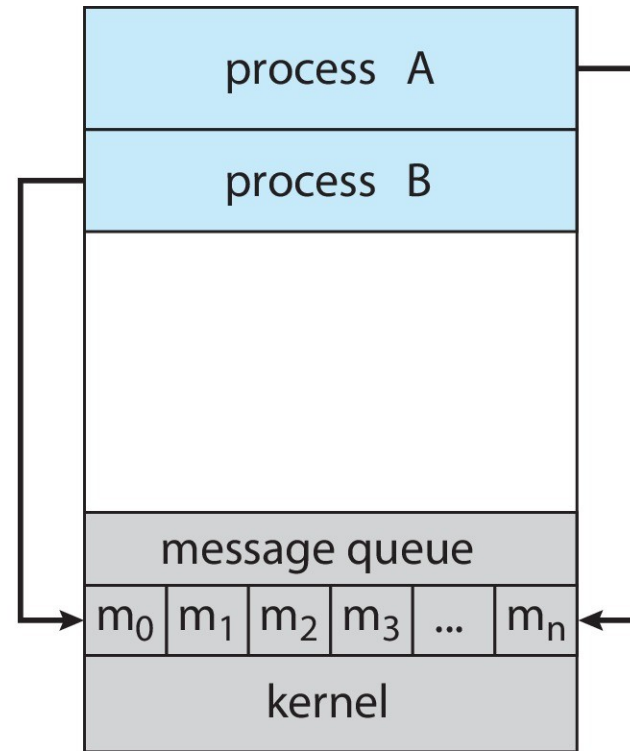
# Communications Models

(a) Shared memory.

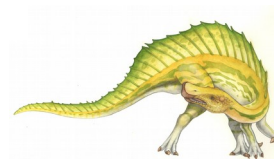
(b) Message passing.



(a)



(b)





# Producer-Consumer Problem

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- Paradigm for cooperating processes:
  - *producer* process produces information that is consumed by a *consumer* process
- Two variations:
  - **unbounded-buffer** places no practical limit on the size of the buffer:
    - ▶ Producer never waits
    - ▶ Consumer waits if there is no buffer to consume
  - **bounded-buffer** assumes that there is a fixed buffer size
    - ▶ Producer must wait if all buffers are full
    - ▶ Consumer waits if there is no buffer to consume





# Interprocess Communication – Shared Memory

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- An area of memory shared among the processes that wish to communicate
- The communication is under the control of the users processes not the operating system.
- **Benefits:**
  - Faster than message passing
- **Disadvantages:**
  - Major issues is to provide mechanism that will allow the user processes to synchronize their actions when they access shared memory.





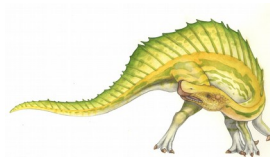
# Bounded-Buffer – Shared-Memory Solution

- Shared data

```
#define BUFFER_SIZE 10
typedef struct {
    . . .
} item;

item buffer[BUFFER_SIZE];
int in = 0;
int out = 0;
```

- Solution is correct, but can only use `BUFFER_SIZE-1` elements



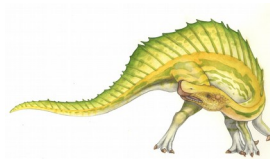


# Producer Process – Shared Memory

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```
item next_produced;

while (true) {
    /* produce an item in next produced */
    while (((in + 1) % BUFFER_SIZE) == out)
        ; /* do nothing */
    buffer[in] = next_produced;
    in = (in + 1) % BUFFER_SIZE;
}
```





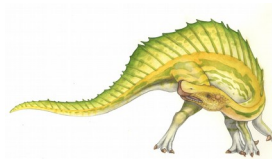
# Consumer Process – Shared Memory

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```
item next_consumed;

while (true) {
    while (in == out)
        ; /* do nothing */
    next_consumed = buffer[out];
    out = (out + 1) % BUFFER_SIZE;

    /* consume the item in next consumed */
}
```



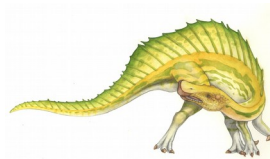




# What about Filling all the Buffers?

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- Suppose that we wanted to provide a solution to the consumer-producer problem that fills **all** the buffers.
- We can do so by having an integer **counter** that keeps track of the number of full buffers.
- Initially, **counter** is set to 0.
- The integer **counter** is incremented by the producer after it produces a new buffer.
- The integer **counter** is and is decremented by the consumer after it consumes a buffer.





# Producer

---

```
while (true) {  
    /* produce an item in next produced */  
  
    while (counter == BUFFER_SIZE)  
        ; /* do nothing */  
    buffer[in] = next_produced;  
    in = (in + 1) % BUFFER_SIZE;  
    counter++;  
}
```

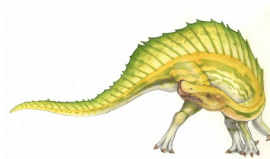




# Consumer

---

```
while (true) {  
    while (counter == 0)  
        ; /* do nothing */  
    next_consumed = buffer[out];  
    out = (out + 1) % BUFFER_SIZE;  
    counter--;  
    /* consume the item in next consumed */  
}
```





# Race Condition

- **counter++** could be implemented as

```
register1 = counter
register1 = register1 + 1
counter = register1
```

- **counter--** could be implemented as

```
register2 = counter
register2 = register2 - 1
counter = register2
```

- Consider this execution interleaving with “count = 5” initially:

S0: producer execute	<b>register1 = counter</b>	{register1 = 5}
S1: producer execute	<b>register1 = register1 + 1</b>	{register1 = 6}
S2: consumer execute	<b>register2 = counter</b>	{register2 = 5}
S3: consumer execute	<b>register2 = register2 - 1</b>	{register2 = 4}
S4: producer execute	<b>counter = register1</b>	{counter = 6}
S5: consumer execute	<b>counter = register2</b>	{counter = 4}

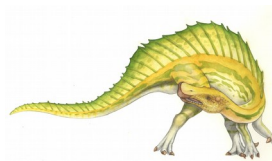




# Race Condition (Cont.)

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- Question – why was there no race condition in the first solution (where at most  $N - 1$  buffers can be filled?)
- More in Chapter 6.





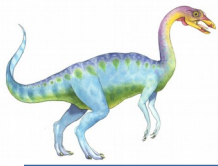
# Examples of IPC Systems - POSIX

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## ■ POSIX Shared Memory

- Process first creates shared memory segment  
`shm_fd = shm_open(name, O_CREAT | O_RDWR, 0666);`
- Also used to open an existing segment
- Set the size of the object  
`ftruncate(shm_fd, 4096);`
- Use `mmap()` to memory-map a file pointer to the shared memory object
- Reading and writing to shared memory is done by using the pointer returned by `mmap()`.





# IPC POSIX Producer

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <fcntl.h>
#include <sys/shm.h>
#include <sys/stat.h>

int main()
{
    /* the size (in bytes) of shared memory object */
    const int SIZE = 4096;
    /* name of the shared memory object */
    const char *name = "OS";
    /* strings written to shared memory */
    const char *message_0 = "Hello";
    const char *message_1 = "World!";

    /* shared memory file descriptor */
    int shm_fd;
    /* pointer to shared memory object */
    void *ptr;

    /* create the shared memory object */
    shm_fd = shm_open(name, O_CREAT | O_RDWR, 0666);

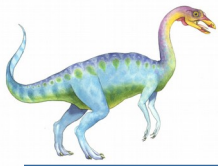
    /* configure the size of the shared memory object */
    ftruncate(shm_fd, SIZE);

    /* memory map the shared memory object */
    ptr = mmap(0, SIZE, PROT_WRITE, MAP_SHARED, shm_fd, 0);

    /* write to the shared memory object */
    sprintf(ptr,"%s",message_0);
    ptr += strlen(message_0);
    sprintf(ptr,"%s",message_1);
    ptr += strlen(message_1);

    return 0;
}
```





# IPC POSIX Consumer

```
#include <stdio.h>
#include <stdlib.h>
#include <fcntl.h>
#include <sys/shm.h>
#include <sys/stat.h>

int main()
{
    /* the size (in bytes) of shared memory object */
    const int SIZE = 4096;
    /* name of the shared memory object */
    const char *name = "OS";
    /* shared memory file descriptor */
    int shm_fd;
    /* pointer to shared memory object */
    void *ptr;

    /* open the shared memory object */
    shm_fd = shm_open(name, O_RDONLY, 0666);

    /* memory map the shared memory object */
    ptr = mmap(0, SIZE, PROT_READ, MAP_SHARED, shm_fd, 0);

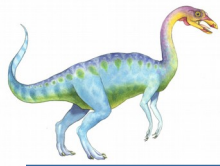
    /* read from the shared memory object */
    printf("%s", (char *)ptr);

    /* remove the shared memory object */
    shm_unlink(name);

    return 0;
}
```

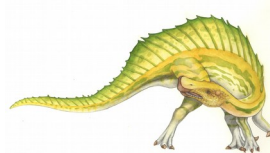
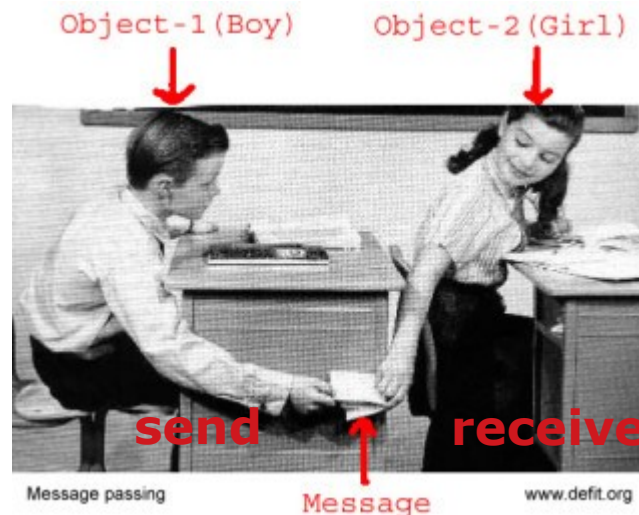






# IPC – Message Passing

- Message system – processes communicate with each other without sharing the same address space directly
- IPC facility provides two operations:
  - **send(message)**
  - **receive(message)**
- The *message* size is either fixed or variable





# Message Passing

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- If processes  $P$  and  $Q$  wish to communicate, they need to:
  - Establish a **communication link** between them
  - Exchange messages via send/receive
- Implementation issues:
  - How are links established?
  - Can a link be associated with more than two processes?
  - How many links can there be between every pair of communicating processes?
  - What is the capacity of a link?
  - Is the size of a message that the link can accommodate fixed or variable?
  - Is a link unidirectional or bi-directional?





# Message Passing model

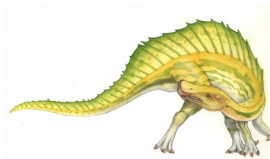
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## ■ Physical link

- Shared memory, Hardware bus, Network

## ■ Logical link

- Naming
  - Direct (name the process), indirect (name the mailbox or link)
- Synchronization
  - Block, Non-block
- Buffering
  - Zero, bounded, un-bounded





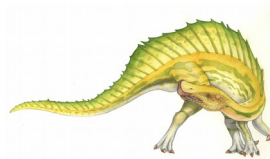
# Producer-Consumer: Message Passing

- Producer

```
message next_produced;  
while (true) {  
    /* produce an item in next_produced */  
  
    send(next_produced) ;  
}
```

- Consumer

```
message next_consumed;  
while (true) {  
    receive(next_consumed)  
  
    /* consume the item in next_consumed */  
}
```





# Pipes

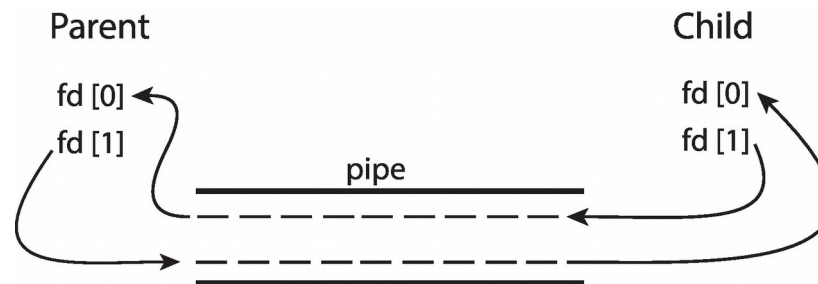
- Acts as a conduit allowing two processes to communicate
- Issues:
  - Is communication unidirectional or bidirectional?
  - In the case of two-way communication, is it half or full-duplex?
  - Must there exist a relationship (i.e., **parent-child**) between the communicating processes?
  - Can the pipes be used over a network?
- **Ordinary pipes** – cannot be accessed from outside the process that created it. Typically, a parent process creates a pipe and uses it to communicate with a child process that it created.
- **Named pipes** – can be accessed without a parent-child relationship.



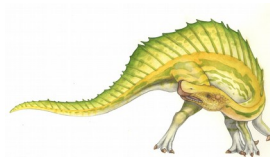


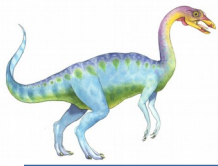
# Ordinary Pipes

- Ordinary Pipes allow communication in standard producer-consumer style
- Producer writes to one end (the **write-end** of the pipe)
- Consumer reads from the other end (the **read-end** of the pipe)
- Ordinary pipes are therefore **unidirectional**
- Require parent-child relationship between communicating processes



- Windows calls these **anonymous pipes**





# Named Pipes

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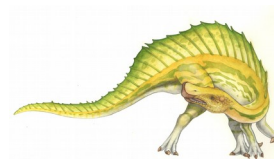
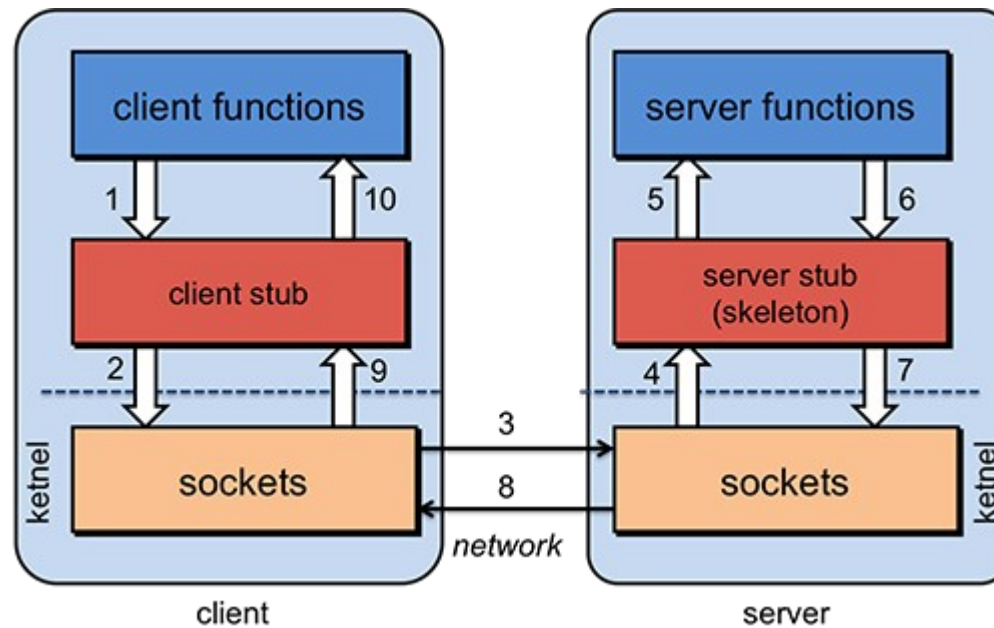
- Named Pipes are more powerful than ordinary pipes
- Communication is **bidirectional**
- No parent-child relationship is necessary between the communicating processes
- Several processes can use the named pipe for communication
- Provided on both UNIX and Windows systems





# Communications in Client-Server Systems

- Sockets
- Remote Procedure Calls (RPC)







# Sockets

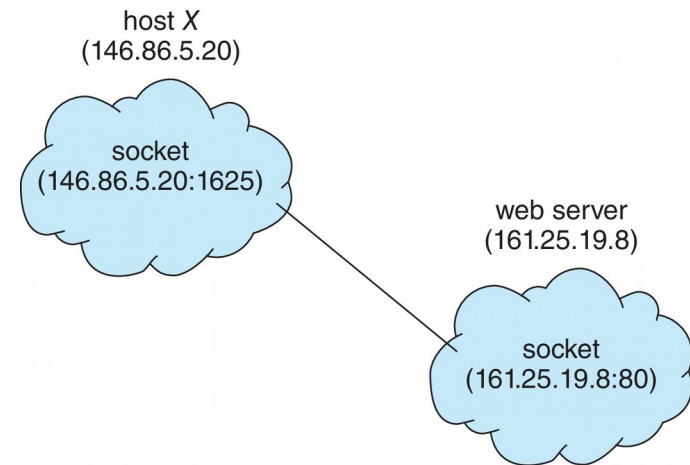
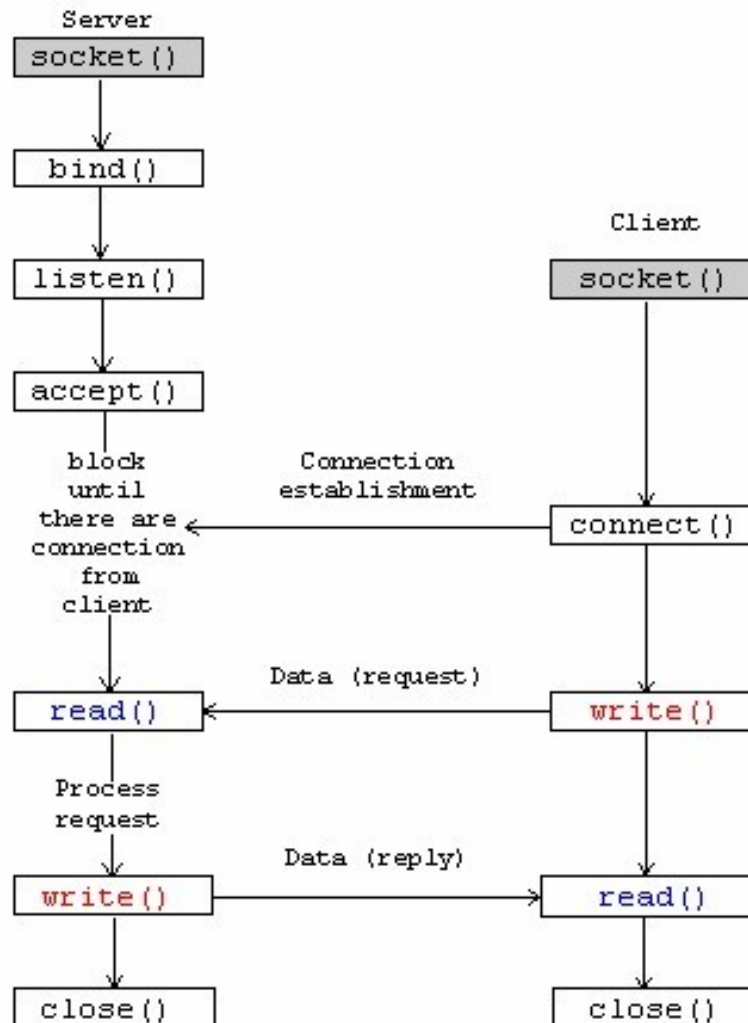
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- A **socket** is defined as an endpoint for communication
- Concatenation of IP address and **port** – a number included at start of message packet to differentiate network services on a host
- The socket **161.25.19.8:1625** refers to port **1625** on host **161.25.19.8**
- Communication consists between a pair of sockets
- All ports below 1024 are **well known**, used for standard services
- Special IP address 127.0.0.1 (**loopback**) to refer to system on which process is running
  
- Three types of sockets
  - **Connection-oriented (TCP)**
  - **Connectionless (UDP)**
  - **MulticastSocket** class– data can be sent to multiple recipients
- Consider this “Date” server in Java:





# Socket Communication

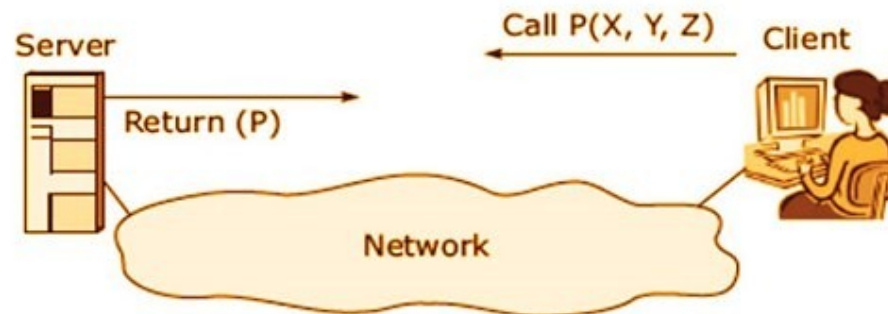




# Remote Procedure Calls

- Remote procedure call (RPC) abstracts procedure calls between processes on networked systems
  - Again uses ports for service differentiation
- **Stubs** – client-side proxy for the actual procedure on the server
- The client-side stub locates the server and **marshalls** the parameters
- The server-side stub receives this message, unpacks the marshalled parameters, and performs the procedure on the server
- On Windows, stub code compile from specification written in **Microsoft Interface Definition Language (MIDL)**

## Remote Procedure Call (RPC)



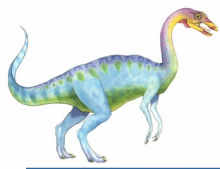


# Remote Procedure Calls (Cont.)

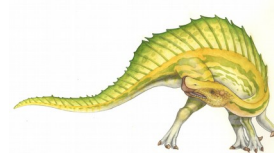
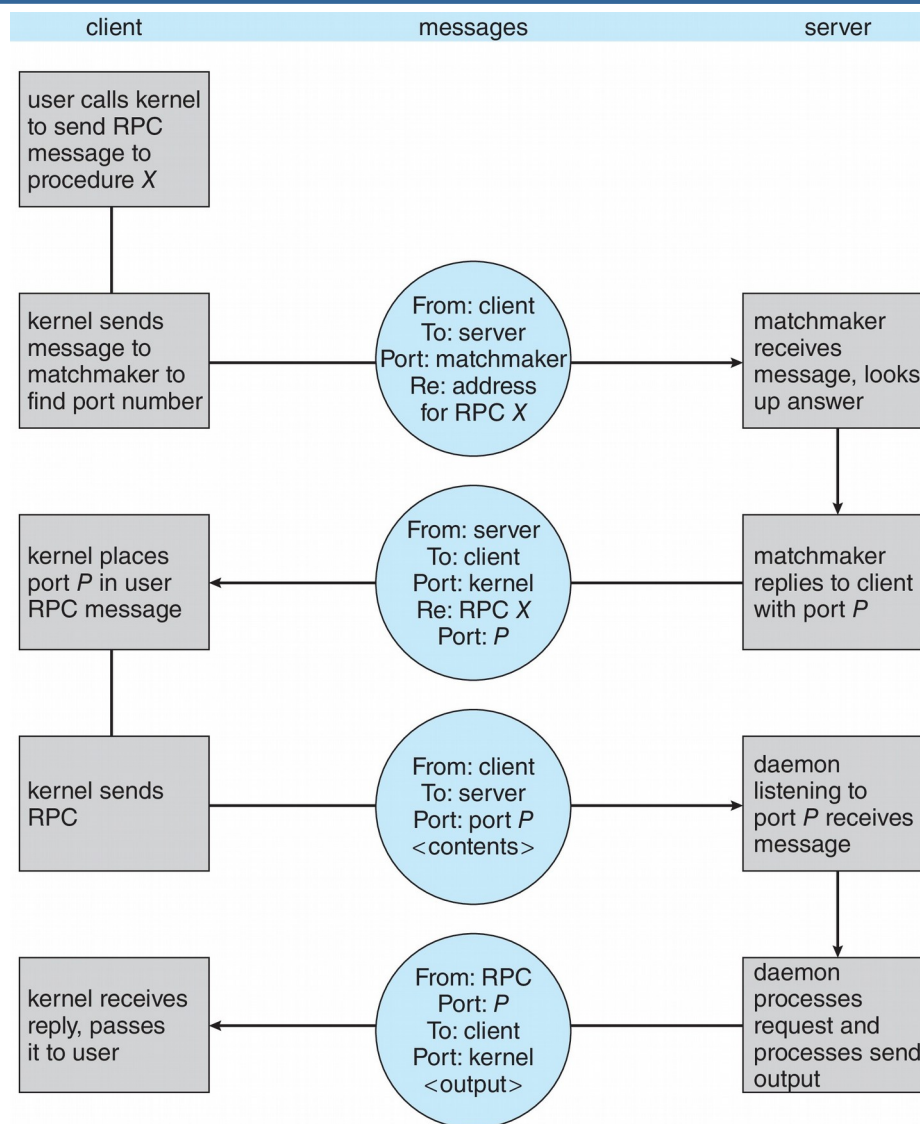
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- Data representation handled via **External Data Representation (XDL)** format to account for different architectures
  - **Big-endian** and **little-endian**
- Remote communication has more failure scenarios than local
  - Messages can be delivered ***exactly once*** rather than ***at most once***
- OS typically provides a rendezvous (or **matchmaker**) service to connect client and server





# Execution of RPC



# Examples of IPC Applications

- X Server and client
  - Unix-domain sockets, named pipes, ...
- Piping commands in shell
  - pipe
- Database server
  - Socket, RPC
- Web services
  - Kind of RPC
- ...



# End of Chapter 3

