

# **Introduction to Software Testing** *(2nd edition)*

## **Chapter 7.1, 7.2**

### **Overview Graph Coverage Criteria**

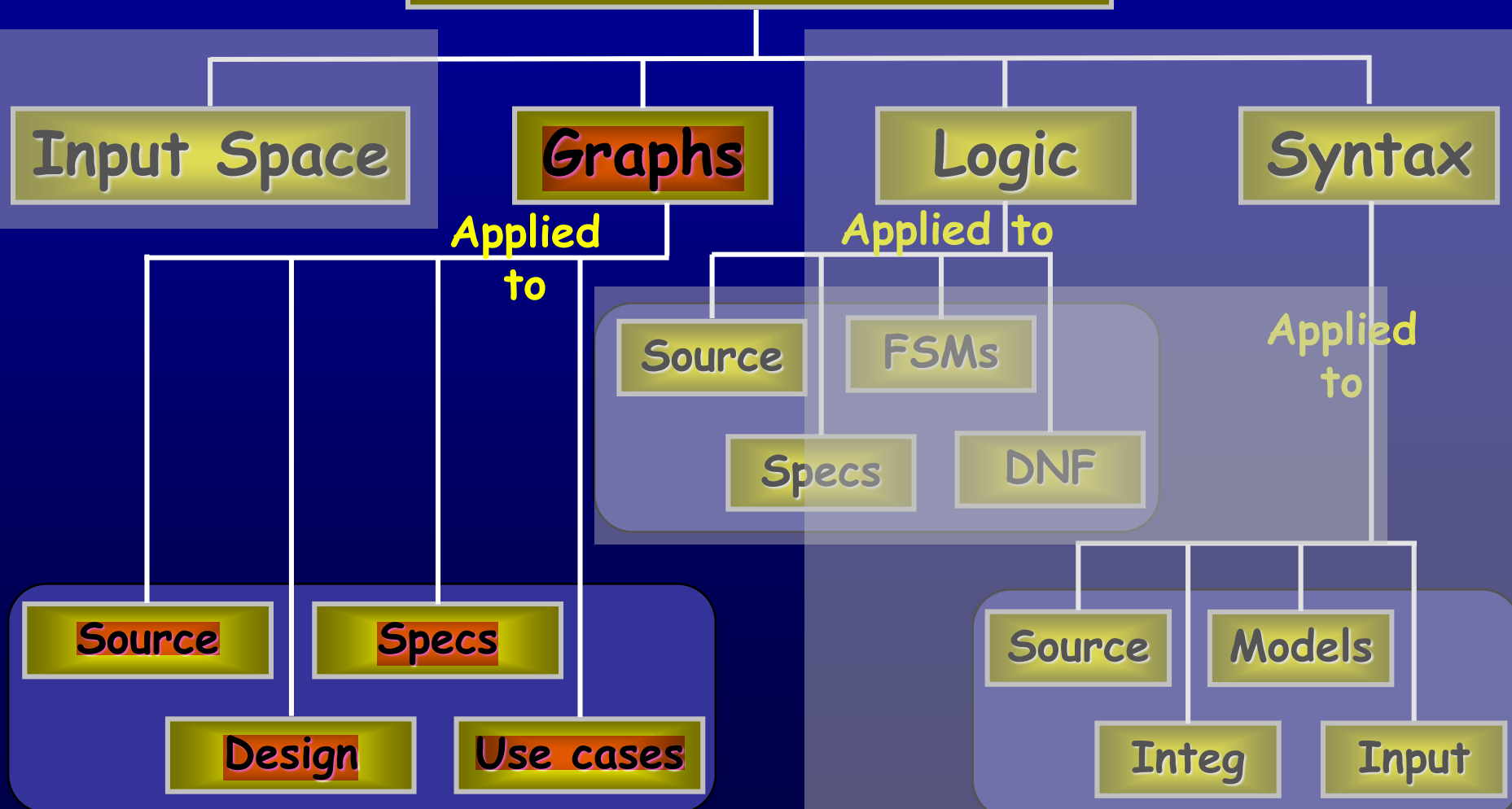
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<http://www.cs.gmu.edu/~offutt/softwaretest/>

*Update, January 2016*

# Ch. 7 : Graph Coverage

## Four Structures for Modeling Software



# Covering Graphs (7.1)

- Graphs are the most commonly used structure for testing
- **Graphs** can come from many sources
  - Control flow graphs
  - Design structure
  - FSMs and statecharts
  - Use cases
- **Tests** usually are intended to “cover” the graph in some way

# Definition of a Graph

- A set  $N$  of nodes,  $N$  is not empty
- A set  $N_0$  of initial nodes,  $N_0$  is not empty
- A set  $N_f$  of final nodes,  $N_f$  is not empty
- A set  $E$  of edges, each edge from one node to another
  - $(n_i, n_j)$ ,  $i$  is predecessor,  $j$  is successor

Is this a  
graph?



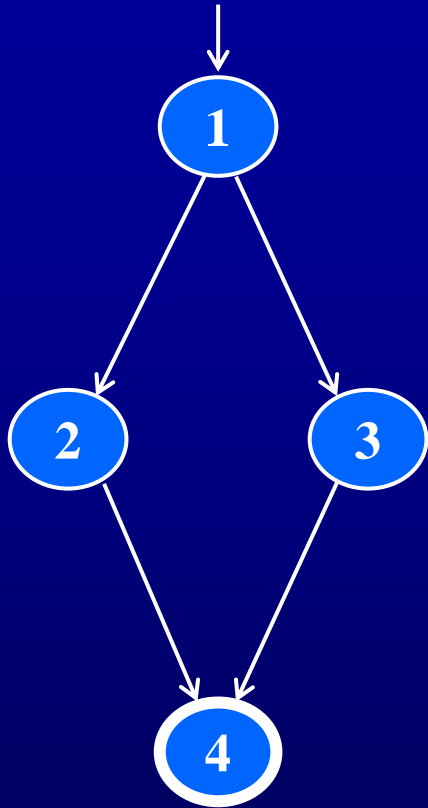
$N_0 = \{1\}$

$N_f = \{1\}$

$E = \{\}$



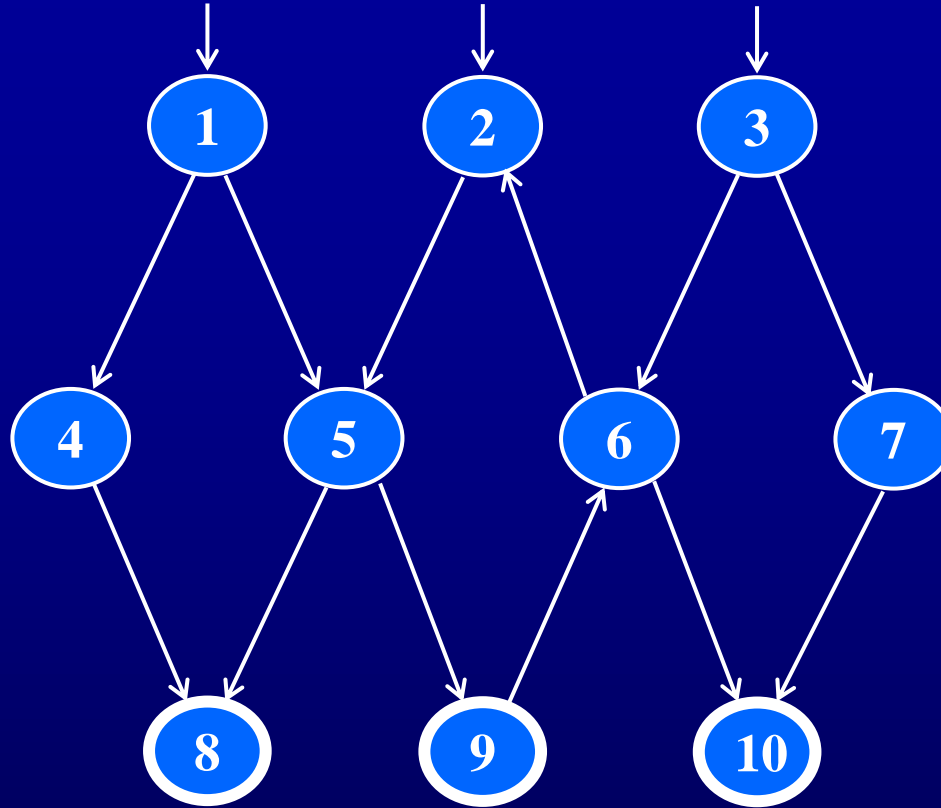
# Example Graphs



$$N_0 = \{ 1 \}$$

$$N_f = \{ 4 \}$$

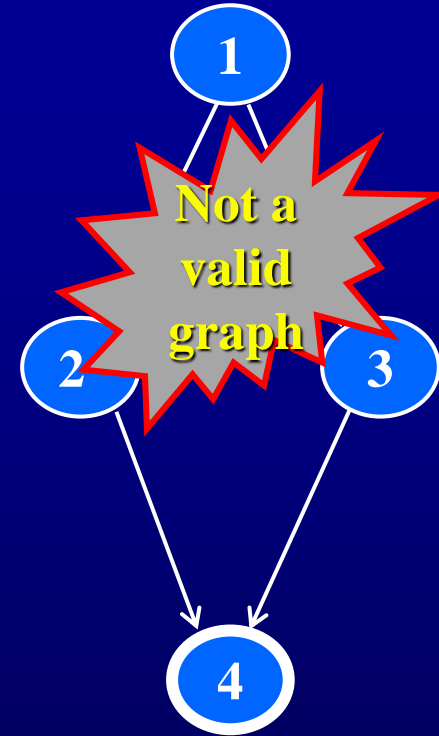
$$E = \{ (1,2), (1,3), (2,4), (3,4) \}$$



$$N_0 = \{ 1, 2, 3 \}$$

$$N_f = \{ 8, 9, 10 \}$$

$$E = \{ (1,4), (1,5), (2,5), (3,6), (3,7), (4,8), (5,8), (5,9), (6,2), (6,10), (7,10), (9,6) \}$$



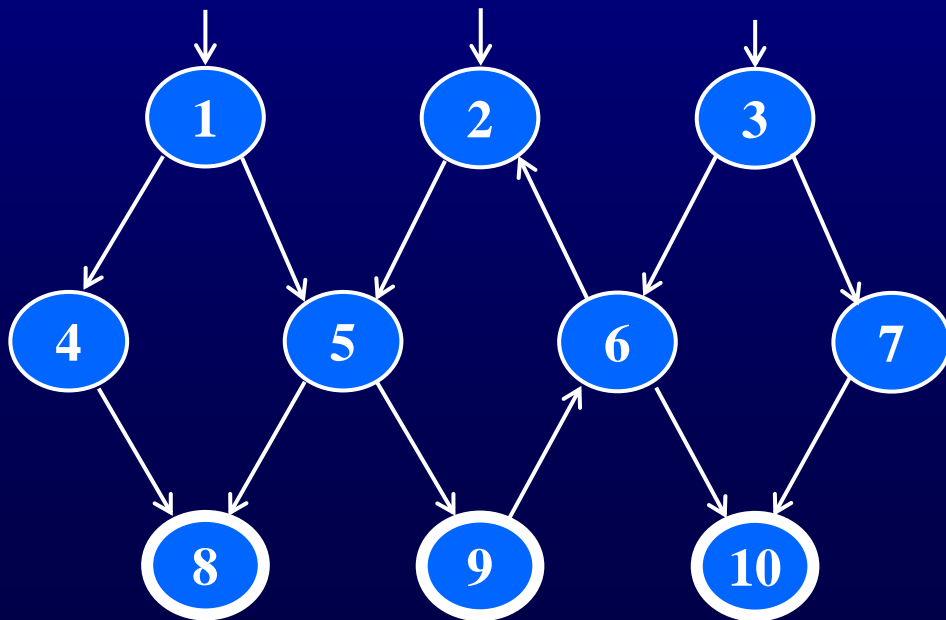
$$N_0 = \{ \}$$

$$N_f = \{ 4 \}$$

$$E = \{ (1,2), (1,3), (2,4), (3,4) \}$$

# Paths in Graphs

- **Path** : A sequence of nodes –  $[n_1, n_2, \dots, n_M]$ 
  - Each pair of nodes is an edge
- **Length** : The number of edges
  - A single node is a path of length 0
- **Subpath** : A subsequence of nodes in  $p$  is a subpath of  $p$



## A Few Paths

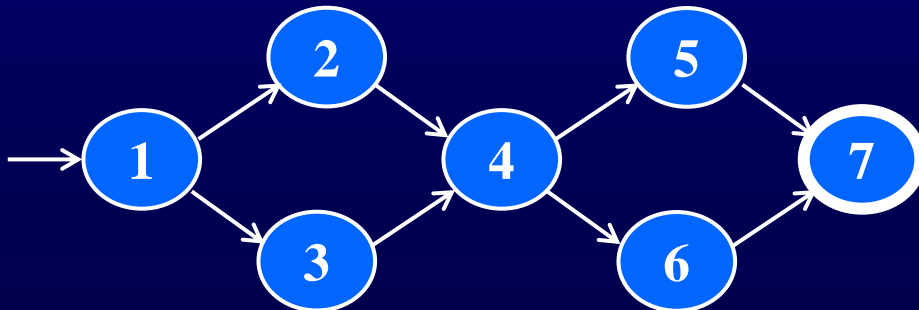
[ 1, 4, 8 ]

[ 2, 5, 9, 6, 2 ]

[ 3, 7, 10 ]

# Test Paths and SESEs

- **Test Path** : A path that starts at an initial node and ends at a final node
- Test paths represent execution of test cases
  - Some test paths can be executed by many tests
  - Some test paths cannot be executed by any tests
- **SESE graphs** : All test paths start at a single node and end at another node
  - Single-entry, single-exit
  - N0 and Nf have exactly one node



## Double-diamond graph

### Four test paths

[1, 2, 4, 5, 7]  
[1, 2, 4, 6, 7]  
[1, 3, 4, 5, 7]  
[1, 3, 4, 6, 7]

# Visiting and Touring

- **Visit** : A test path  $p$  visits node  $n$  if  $n$  is in  $p$   
A test path  $p$  visits edge  $e$  if  $e$  is in  $p$
- **Tour** : A test path  $p$  tours subpath  $q$  if  $q$  is a subpath of  $p$

**Path** [ 1, 2, 4, 5, 7 ]

**Visits nodes** 1, 2, 4, 5, 7

**Visits edges** (1, 2), (2, 4), (4, 5), (5, 7)

**Tours subpaths** [1, 2, 4], [2, 4, 5], [4, 5, 7], [1, 2, 4, 5], [2, 4, 5, 7], [1, 2, 4, 5, 7]

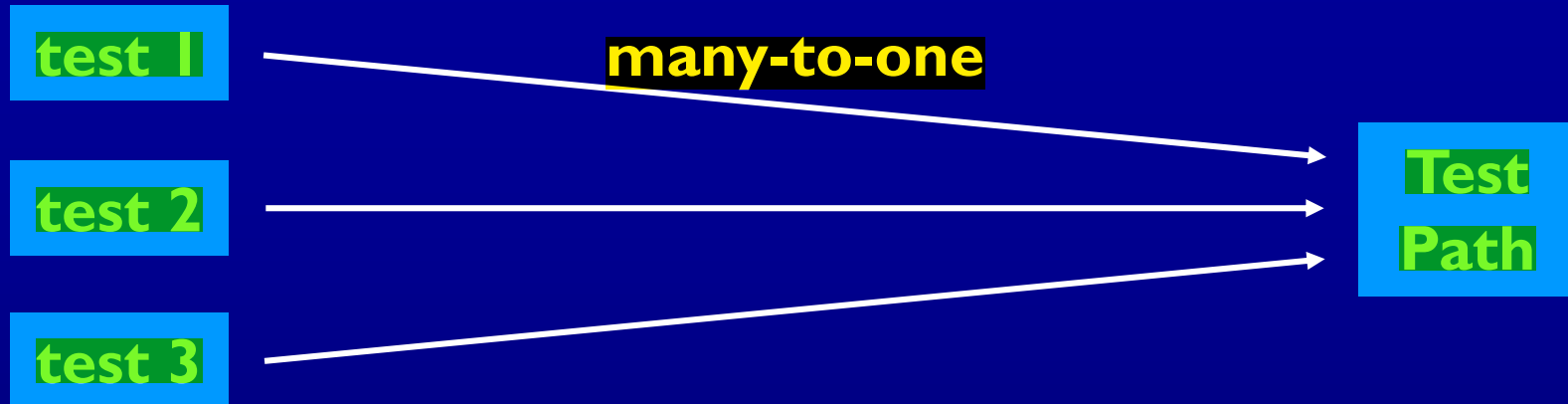
(Also, *each edge is technically a subpath*)



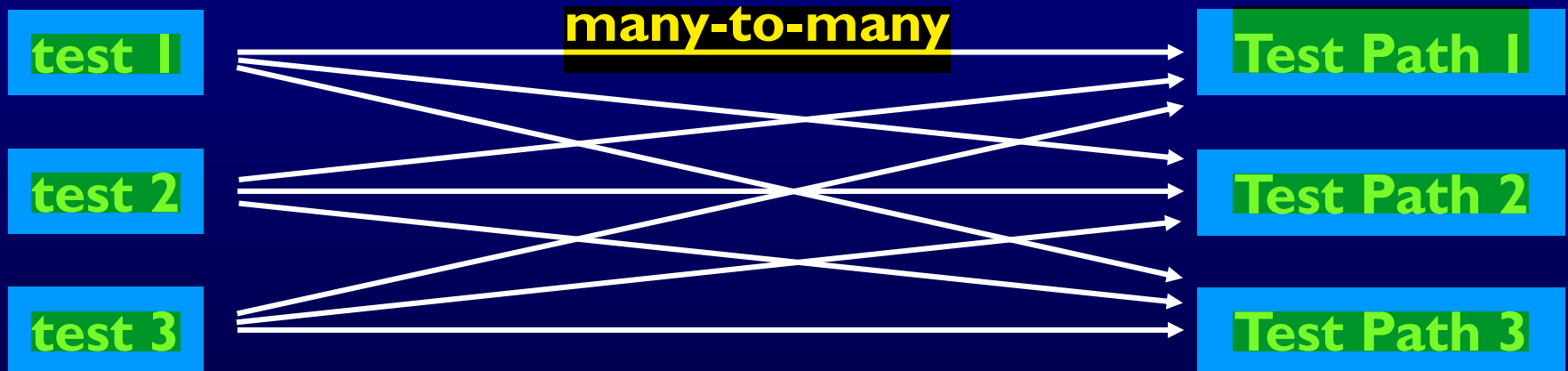
# Tests and Test Paths

- **path ( $t$ )** : The **test path executed by test  $t$**
- **path ( $T$ )** : The **set of test paths** executed by the **set of tests  $T$**
- **Each test executes one and only one test path**
  - **Complete execution** from a **start node** to an **final node**
- A **location** in a graph (node or edge) can be **reached** from **another location** if there is a **sequence of edges** from the first location to the second
  - **Syntactic reach** : A **subpath exists** in the graph
  - **Semantic reach** : A **test exists** that can **execute that subpath**
  - This distinction will become important in section 7.3

# Tests and Test Paths



**Deterministic software—test always executes the same test path**



**Non-deterministic software—the same test can execute different test paths**

# Testing and Covering Graphs (7.2)

- We use graphs in testing as follows :
  - Develop a model of the software as a graph
  - Require tests to visit or tour specific sets of nodes, edges or subpaths
- Test Requirements (TR) : Describe properties of test paths
- Test Criterion : Rules that define test requirements
- Satisfaction : Given a set  $TR$  of test requirements for a criterion  $C$ , a set of tests  $T$  satisfies  $C$  on a graph if and only if for every test requirement in  $TR$ , there is a test path in  $path(T)$  that meets the test requirement  $tr$
- Structural Coverage Criteria : Defined on a graph just in terms of nodes and edges
- Data Flow Coverage Criteria : Requires a graph to be annotated with references to variables

# Node and Edge Coverage

- The first (and simplest) two criteria require that each node and edge in a graph be executed

**Node Coverage (NC) :** Test set  $T$  satisfies node coverage on graph  $G$  iff for every syntactically reachable node  $n$  in  $N$ , there is some path  $p$  in  $path(T)$  such that  $p$  visits  $n$ .

- This statement is a bit cumbersome, so we abbreviate it in terms of the set of test requirements

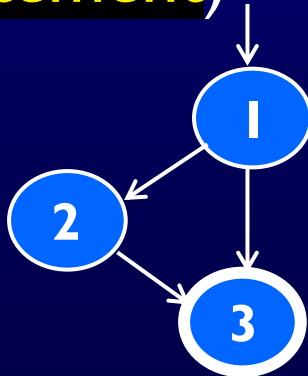
**Node Coverage (NC) :** TR contains each reachable node in  $G$ .

# Node and Edge Coverage

- **Edge coverage** is slightly **stronger** than node coverage

**Edge Coverage (EC)** : TR contains **each reachable path** of **length up to  $l$** , inclusive, in **G**.

- The phrase “**length up to  $l$** ” allows for graphs with **one node and no edges**
- **NC** and **EC** are only different when there **is an edge** and **another subpath** between a **pair of nodes** (as in an “if-else” statement)



**Node Coverage** : **TR** = { 1, 2, 3 }

**Test Path** = [ 1, 2, 3 ]

**Edge Coverage** : **TR** = { (1, 2), (1, 3), (2, 3) }

**Test Paths** = [ 1, 2, 3 ]  
[ 1, 3 ]

# Paths of Length 1 and 0

- A graph with **only one node** will **not have any edges**



- It may seem trivial, but formally, **Edge Coverage needs to require Node Coverage on this graph**
- Otherwise, Edge Coverage will not subsume Node Coverage
  - So we define “**length up to 1**” instead of simply “length 1”
- We have the same issue with **graphs** that **only have one edge** – for **Edge-Pair Coverage ...**

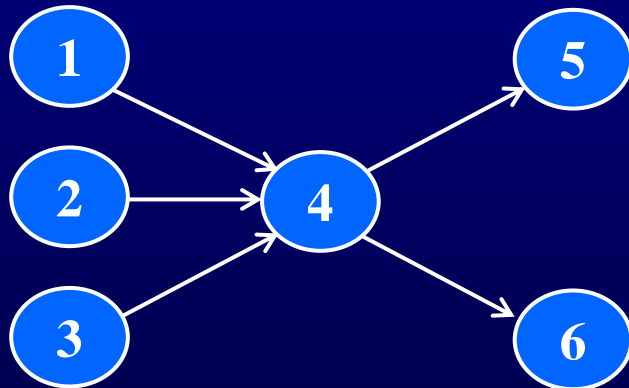


# Covering Multiple Edges

- Edge-pair coverage requires pairs of edges, or subpaths of length 2

**Edge-Pair Coverage (EPC) :** TR contains each reachable path of length up to 2, inclusive, in G.

- The phrase “length up to 2” is used to include graphs that have less than 2 edges



## **Edge-Pair Coverage :**

TR = { [1,4,5], [1,4,6], [2,4,5], [2,4,6], [3,4,5], [3,4,6] }

- The logical extension is to require all paths ...

# Covering Multiple Edges

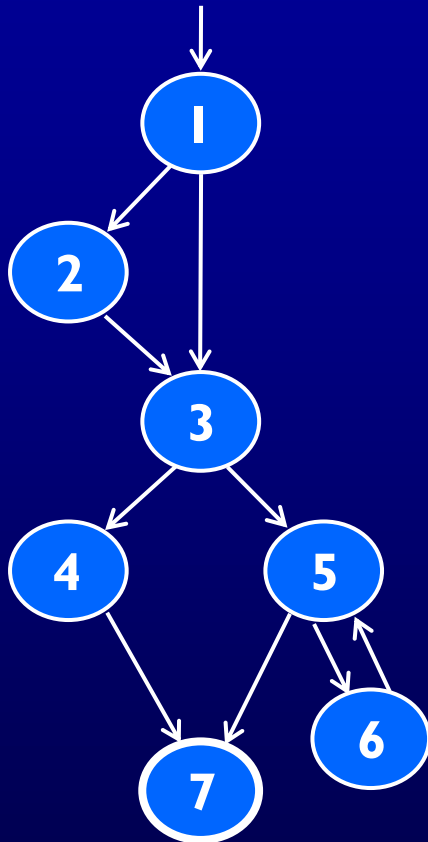
**Complete Path Coverage (CPC) : TR contains all paths in G.**

Unfortunately, **this is impossible** if the **graph has a loop**, so a weak compromise makes the tester decide which paths:

**Specified Path Coverage (SPC) : TR contains a set S of test paths, where S is supplied as a parameter.**



# Structural Coverage Example



## Node Coverage

**TR** = { 1, 2, 3, 4, 5, 6, 7 }

**Test Paths:** [ 1, 2, 3, 4, 7 ] [ 1, 2, 3, 5, 6, 5, 7 ]

## Edge Coverage

**TR** = { (1,2), (1,3), (2,3), (3,4), (3,5), (4,7), (5,6), (5,7), (6,5) }

**Test Paths:** [ 1, 2, 3, 4, 7 ] [ 1, 3, 5, 6, 5, 7 ]

## Edge-Pair Coverage

**TR** = { [1,2,3], [1,3,4], [1,3,5], [2,3,4], [2,3,5], [3,4,7], [3,5,6], [3,5,7], [5,6,5], [6,5,6], [6,5,7] }

**Test Paths:** [ 1, 2, 3, 4, 7 ] [ 1, 2, 3, 5, 7 ] [ 1, 3, 4, 7 ]  
[ 1, 3, 5, 6, 5, 6, 5, 7 ]

## Complete Path Coverage

**Test Paths:** [ 1, 2, 3, 4, 7 ] [ 1, 2, 3, 5, 7 ] [ 1, 2, 3, 5, 6, 5, 6 ]  
[ 1, 2, 3, 5, 6, 5, 6, 5, 7 ] [ 1, 2, 3, 5, 6, 5, 6, 5, 6, 5, 7 ] ...

# Handling Loops in Graphs

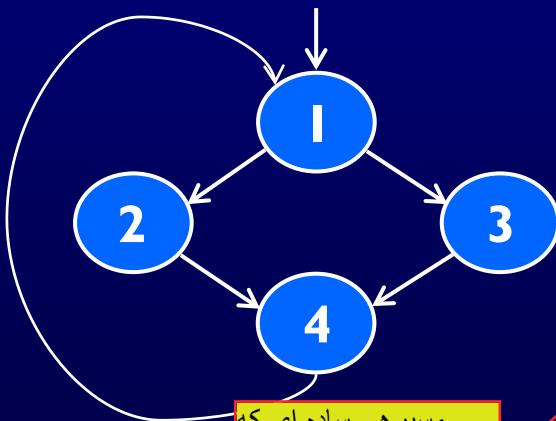
- If a graph contains a loop, it has an infinite number of paths
- Thus, CPC is not feasible
- SPC is not satisfactory because the results are subjective and vary with the tester
- Attempts to “deal with” loops:
  - 1970s : Execute cycles once ([4, 5, 4] in previous example, informal)
  - 1980s : Execute each loop, exactly once (formalized)
  - 1990s : Execute loops 0 times, once, more than once (informal description)
  - 2000s : Prime paths (touring, sidetrips, and detours)

# Simple Paths and Prime Paths

- **Simple Path** : A path from node  $n_i$  to  $n_j$  is simple if no node appears more than once, except possibly the first and last nodes are the same
  - No internal loops
  - A loop is a simple path
- **Prime Path** : A simple path that does not appear as a proper subpath of any other simple path

در تعریف مسیرهای ساده:

مسیرهای به طول صفر که نودها همون هستن و مسیر به طول یک که یال هامونه و ... را داریم



مسیرهای ساده ای که بیشترین طول را دارند

**Simple Paths** : [1,2,4,1], [1,3,4,1], [2,4,1,2], [2,4,1,3], [3,4,1,2], [3,4,1,3], [4,1,2,4], [4,1,3,4], [1,2,4], [1,3,4], [2,4,1], [3,4,1], [4,1,2], [4,1,3], [1,2], [1,3], [2,4], [3,4], [4,1], [1], [2], [3], [4]

**Prime Paths** : [2,4,1,2], [2,4,1,3], [1,3,4,1], [1,2,4,1], [3,4,1,2], [4,1,3,4], [4,1,2,4], [3,4,1,3]

ماکس تعداد نودی که در این مسیرها میبینیم به تعدادنودهای گرافمون است

# Prime Path Coverage

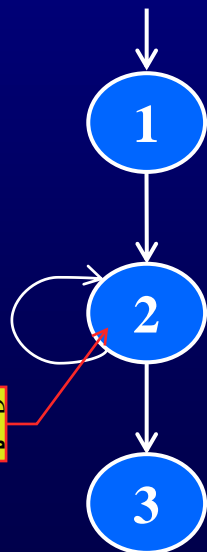
- A simple, elegant and **finite criterion** that **requires loops** to **be executed** as well as **skipped**

**Prime Path Coverage (PPC)** : **TR** contains **each prime path** in **G**.

- Will tour **all paths of length 0, 1, ...**
- That is, **it subsumes node and edge coverage**
- **PPC** almost, but **not quite**, subsumes **EPC** ...

# PPC Does Not Subsume EPC

- If a node  $n$  has an edge to itself (self edge), EPC requires  $[n, n, m]$  and  $[m, n, n]$
- $[n, n, m]$  is not prime
- Neither  $[n, n, m]$  nor  $[m, n, n]$  are simple paths (not prime)



در گراف نودی داریم که  
طوقه داره

**EPC Requirements :**

**TR** = {  $[1,2,3]$ ,  $[1,2,2]$ ,  $[2,2,3]$ ,  $[2,2,2]$  }

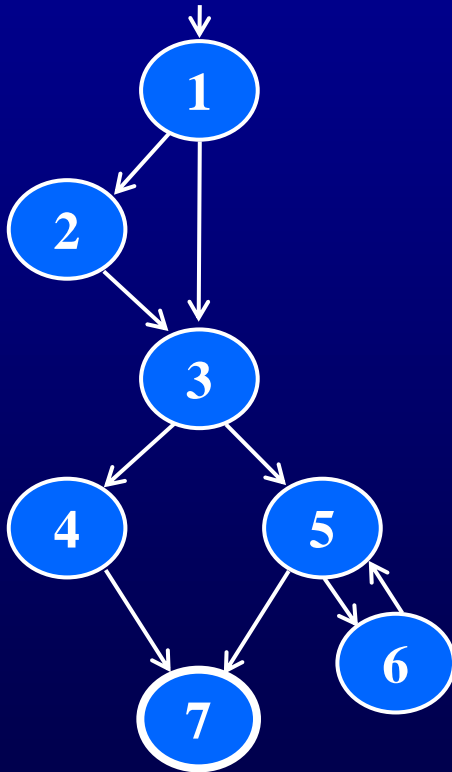
یال های مجاور هم رو  
باید داشته باشیم

**PPC Requirements :**

**TR** = {  $[1,2,3]$ ,  $[2,2]$  }

# Prime Path Example

- The previous example has **38 simple paths**
- Only **nine prime paths**



## Prime Paths

[1, 2, 3, 4, 7]

[1, 2, 3, 5, 7]

[1, 2, 3, 5, 6]

[1, 3, 4, 7]

[1, 3, 5, 7]

**[1, 3, 5, 6]**

[6, 5, 7]

**[6, 5, 6]**

**[5, 6, 5]**

**Execute  
loop 0 times**

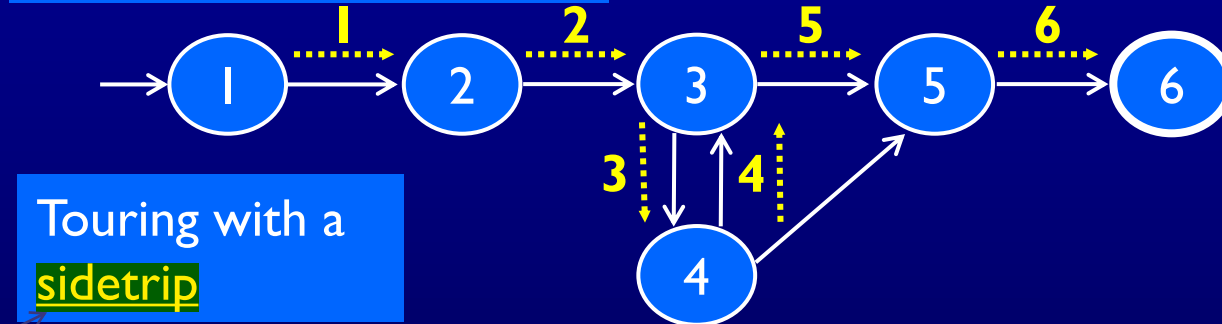
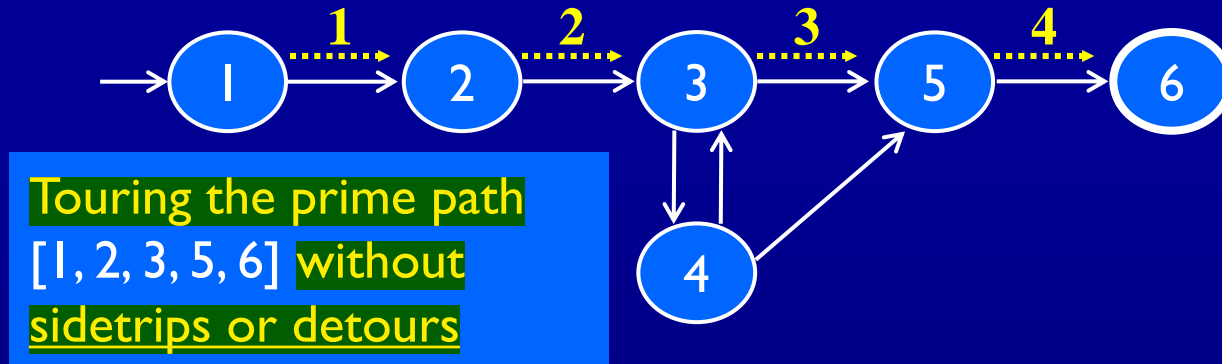
**Execute  
loop once**

**Execute loop  
more than once**

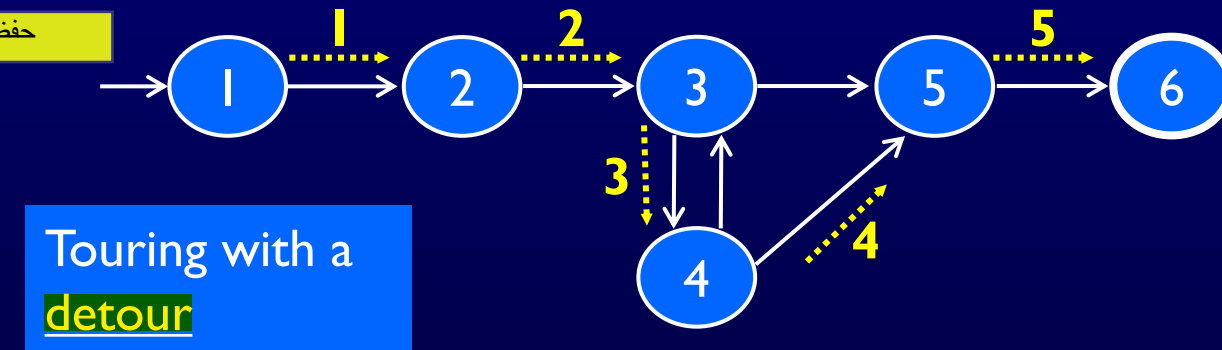
# Touring, Sidetrips, and Detours

- **Prime paths** do **not** have internal loops ... **test paths** **might** (page 170)
- **Tour** : A **test path  $p$**  **tours subpath  $q$**  if  **$q$  is a subpath of  $p$**
- **Tour With Sidetrips** : A **test path  $p$**  **tours subpath  $q$  with sidetrips** iff **every edge in  $q$  is also in  $p$  in the same order**
  - The tour can include a sidetrip, as long as it comes back to the same node
- **Tour With Detours** : A **test path  $p$**  **tours subpath  $q$  with detours** iff **every node in  $q$  is also in  $p$  in the same order**
  - The tour can include a detour from node  $n_i$ , as long as it comes back to the prime path at a successor of  $n_i$

# Sidetrrips and Detours Example



حفظ ترتیب یال ها





# Infeasible Test Requirements

- An **infeasible test requirement** cannot be satisfied
  - Unreachable statement (**dead code**)
  - Subpath that can only be executed **with a contradiction** ( $X > 0$  and  $X < 0$ )
- Most **test criteria** have some **infeasible test requirements**
- It is usually **undecidable** **whether all test requirements** are feasible
- When **sidetrips** are **not allowed**, many structural criteria have **more infeasible test requirements**
- However, always allowing **sidetrips** **weakens the test criteria**

## Practical recommendation—**Best Effort Touring**

- Satisfy **as many test requirements as possible** **without sidetrips**
- Allow sidetrips to try to satisfy remaining test requirements

# Round Trips

- **Round-Trip Path** : A *prime path* that starts and ends at the same node

**Simple Round Trip Coverage (SRTC)** : TR contains at least one round-trip path for each reachable node in G that begins and ends a round-trip path.

**Complete Round Trip Coverage (CRTC)** : TR contains all round-trip paths for each reachable node in G.

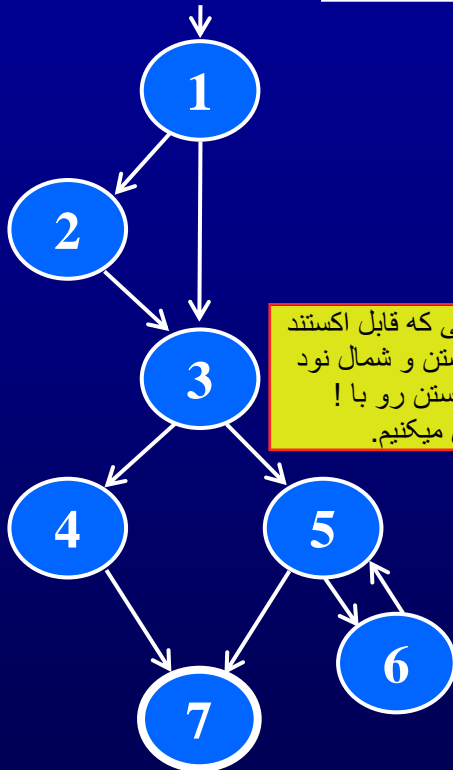
- These criteria omit nodes and edges that are not in round trips
- Thus, they do not subsume edge-pair, edge, or node coverage

# Simple & Prime Path Example

همه ی نودها در گراف

همه ی پال ها

Simple paths



سیرهایی که قابل اکستند شدن نیستن و شمال نود فاینال هستن رو با ! مشخص میکنیم.

‘!’ means path terminates

**Len 0**

[1]  
[2]  
[3]  
[4]  
[5]  
[6]  
[7] !

**Len 1**

[1, 2]  
[1, 3]  
[2, 3]  
[3, 4]  
[3, 5]  
[4, 7] !  
[5, 7] !  
[5, 6]  
[6, 5]

**Len 2**

[1, 2, 3]  
[1, 3, 4]  
[1, 3, 5]  
[2, 3, 4]  
[2, 3, 5]  
[3, 4, 7] !  
[3, 5, 7] !  
[3, 5, 6] !  
[5, 6, 5] \*  
[6, 5, 7] !  
[6, 5, 6] \*

**Len 3**

[1, 2, 3, 4]  
[1, 2, 3, 5]  
[1, 3, 4, 7] !  
[1, 3, 5, 7] !  
[1, 3, 5, 6] !  
[2, 3, 4, 7] !  
[2, 3, 5, 6] !  
[2, 3, 5, 7] !

is path  
es

این چندتا چون زیر مسیر به مسیر دیگه هستن نمیتونن prime path باشن.

‘\*’ means path cycles

حلقه ها هم قابل توسعه نیستند چون اگه به نود دیگه اضافه کنیم مسیر دیگه ساده نیست

**Prime Paths**

این مسیر هم قابل توسعه نیست چون بعد از نود ۶ فقط میشه به نود ۵ بریم که دیگه مسیرمون ساده نمیشه و شرط ساده بودن نقض میشه

**Len 4**

[1, 2, 3, 4, 7] !  
[1, 2, 3, 5, 7] !  
[1, 2, 3, 5, 6] !

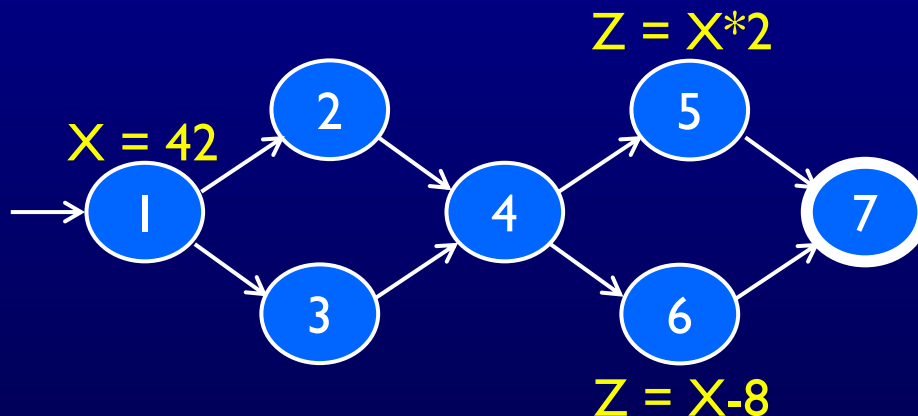
برای پیدا کردن prime path ها، از طولانی ترین مسیرها شروع میکنیم و این مسیرها نباید جزو مسیر دیگه ای باشند یعنی نباید sub-path مسیر دیگه ای باشند پس اون مسیرهایی که قابل توسعه بودن یعنی sub-path به مسیر ساده بودن پس نمیتونن prime path باشند.

الگوریتم تعداد بی نهایت ایتريشن یا تکرار نداره چرا؟ چون ماکس طول مسیر ما مثلا اینجا ۴ است و یکی از تعداد نودهای گرافمون کمتره

# Data Flow Criteria

**Goal:** Try to **ensure** that **values** are **computed** and **used correctly**

- **Definition (def)** : A **location** where a **value for a variable** is stored into **memory**
- **Use** : A location where a **variable's value** is accessed



**Defs:**  $\text{def}(1) = \{X\}$

$\text{def}(5) = \{Z\}$

$\text{def}(6) = \{Z\}$

**Uses:**  $\text{use}(5) = \{X\}$

$\text{use}(6) = \{X\}$

The **values** given in **defs** should **reach at least one, some, or all possible uses**

# DU Pairs and DU Paths

- **def (n) or def (e)** : The set of variables that are defined by node n or edge e
- **use (n) or use (e)** : The set of variables that are used by node n or edge e
- **DU pair** : A pair of locations  $(l_i, l_j)$  such that a variable  $v$  is defined at  $l_i$  and used at  $l_j$
- **Def-clear** : A path from  $l_i$  to  $l_j$  is def-clear with respect to variable  $v$  if  $v$  is not given another value on any of the nodes or edges in the path
- **Reach** : If there is a def-clear path from  $l_i$  to  $l_j$  with respect to  $v$ , the def of  $v$  at  $l_i$  reaches the use at  $l_j$
- **du-path** : A simple subpath that is def-clear with respect to  $v$  from a def of  $v$  to a use of  $v$
- **du  $(n_i, n_j, v)$**  – the set of du-paths from  $n_i$  to  $n_j$
- **du  $(n_i, v)$**  – the set of du-paths that start at  $n_i$

# Touring DU-Paths

- A test path  $p$  *du-tours* subpath  $d$  with respect to  $v$  if  $p$  tours  $d$  and the subpath taken is def-clear with respect to  $v$
- Sidetrips can be used, just as with previous touring
- Three criteria
  - Use every def
  - Get to every use
  - Follow all du-paths

# Data Flow Test Criteria

- First, we make sure every def reaches a use

**All-defs coverage (ADC)** : For each set of du-paths  $S = du(n, v)$ , TR contains at least one path  $d$  in  $S$ .

- Then we make sure that every def reaches all possible uses

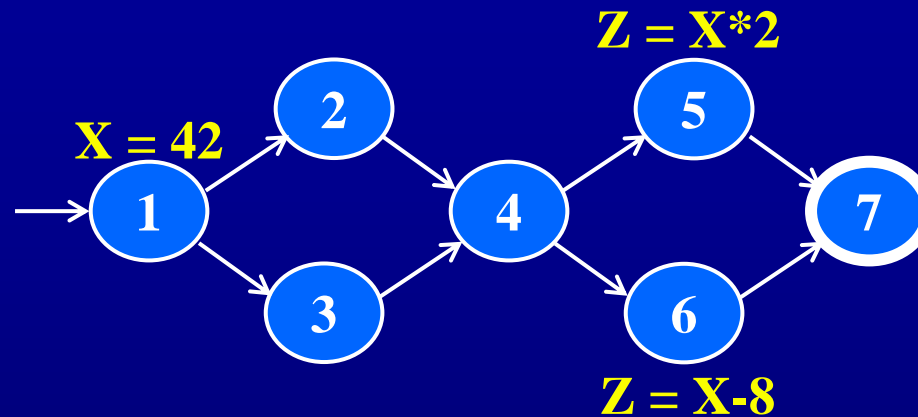
**All-uses coverage (AUC)** : For each set of du-paths to uses  $S = du(n_i, n_j, v)$ , TR contains at least one path  $d$  in  $S$ .

- Finally, we cover all the paths between defs and uses

**All-du-paths coverage (ADUPC)** : For each set  $S = du(n_i, n_j, v)$ , TR contains every path  $d$  in  $S$ .

هر def ای به هر use ای که برای یک متغیر است  
دسترسی و مسیر داشته باشد

# Data Flow Testing Example



## All-defs for $X$

[ 1, 2, 4, 5 ]

برای هر def حداقل یک use بررسی شه

## All-uses for $X$

[ 1, 2, 4, 5 ]

[ 1, 2, 4, 6 ]

برای هر def همه ی use ها بررسی بشن

## All-du-paths for $X$

[ 1, 2, 4, 5 ]

[ 1, 3, 4, 5 ]

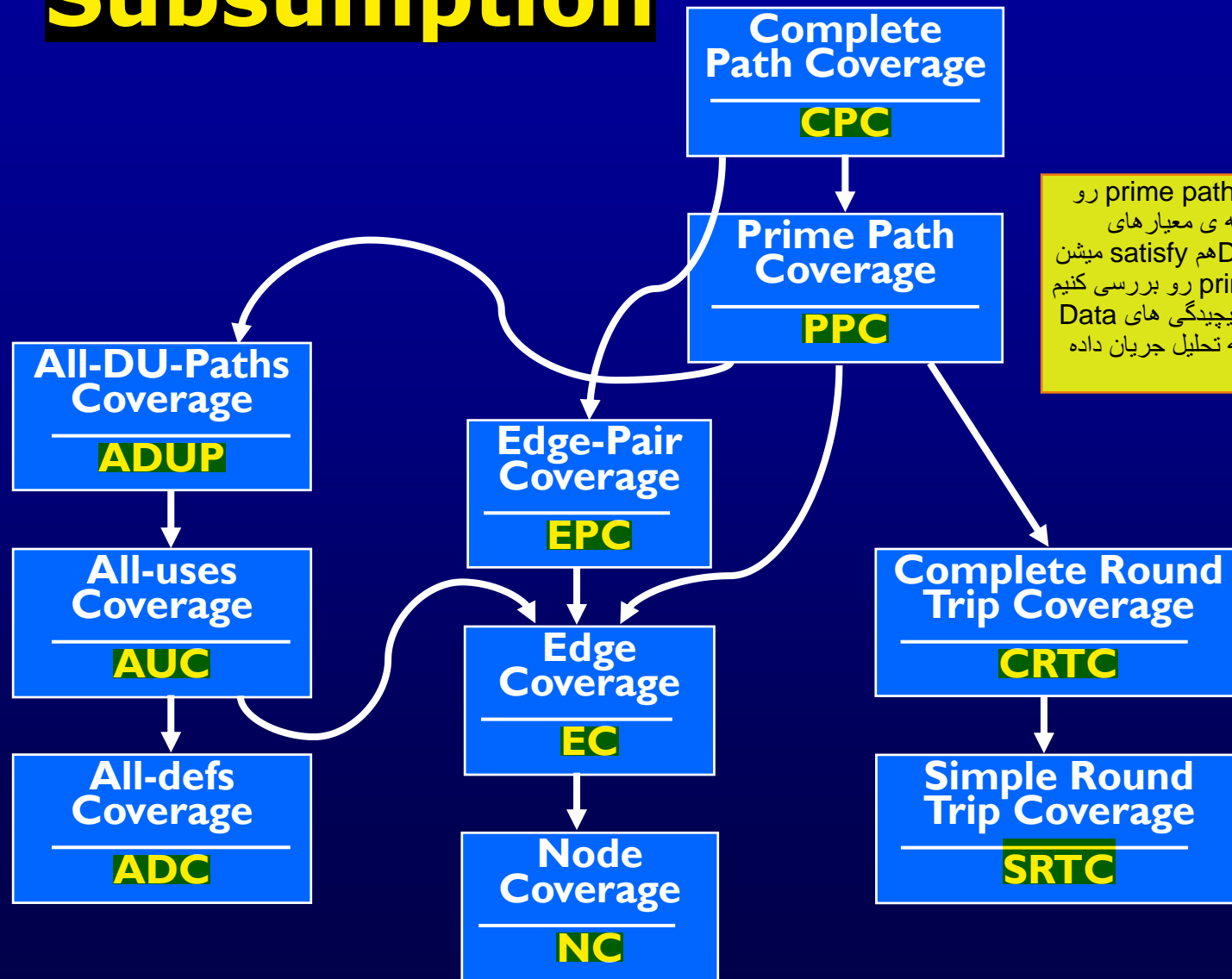
[ 1, 2, 4, 6 ]

[ 1, 3, 4, 6 ]



# Graph Coverage Criteria

## Subsumption



اگر ما prime path coverage را برقرار کنیم همه ی معیارهای مربوط به Data flow هم satisfy میشن پس وقتی prime path رو بررسی کنیم میتونیم دیگه درگیر پیچیدگی های Data flow نشیم مگه اینکه تحلیل جریان داده مهم باشه

# Summary 7.1-7.2

- Graphs are a very **powerful abstraction** for designing tests
- The various criteria allow **lots of cost / benefit tradeoffs**
- These two sections are entirely at the “**design abstraction level**” from chapter 2
- Graphs appear in **many situations** in software
  - As discussed in the rest of chapter 7