## imglib2 network transfer

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# The Goal of DAIS wp 1.3

- Direct transmission of the imglib2 data between two peers
- Peers are assumed to be two independent processes
- Processes may:
  - ▶ live on the same machine
  - ▶ live on machines connected over TCP/IP network
  - ▶ any app, e.g., FIJI, KNIME, wrapped C/C++/Python library
- Inspired by the BlueTooth principles
- Uses proprietary/own protocol:
  - text header and binary voxel data
  - similar to ICS (Image Cytometry Standard)
  - default TCP port 54545
  - no collision in /etc/services
- Networking is done via ZeroMQ package.

### The API of DAIS wp 1.3

#### How to use it from Java:

```
import de.mpicbg.ulman.imgtransfer.lmgPacker;
[ import de.mpicbg.ulman.imgtransfer.ProgressCallback; ]
ImgPlus<?> imgP = ...;
A_sendsTo_B:
A: ImgPacker.sendImage((ImgPlus) imgP, "tcp://"+remoteURL, timeoutTime[, logger]);
B: imgP = ImgPacker.receiveImage(portNo, timeoutTime[, logger]);
- or -
```

• TimeoutTime is given in seconds as int, max waiting time 68 yrs

B: ImgPacker.serveImage((ImgPlus) imgP, portNo, timeoutTime[, logger]);
A: imgP = ImgPacker.requestImage("tcp://"+remoteURL, timeoutTime[, logger]);

Logger is optional

A downloadsFrom B.

 Logger must implement ProgressCallback.info(String) and ProgressCallback.setProgress(0≤float≤1)

# The Principle of DAIS wp 1.3

#### Why two communication models:

- Network stand point:
- A and B on the same local network:
   A\_sendsTo\_B, B\_sendsTo\_A, A\_downloadsFrom\_B, B\_downloadsFrom\_A
- A on local network (behind firewall/NAT),
- B on remote network with public IP:
  - → A\_sendsTo\_B, A\_downloadsFrom\_B
- A on local network (behind firewall/NAT),
- B on remote network (behind firewall/NAT):
  - $\rightarrow$  only with tunneling through public IP SSH server, or alike
- PLANNED, local network discovery mode:
  - A broadcasts "who is around"
  - ▶ B replies "B is at this IP"
  - A collects replies, presents them to user
  - A sends to...

# The Principle of DAIS wp 1.3

#### Why two communication models:

- Flow control stand point:
- A is the main program that asks someone to process data
- A\_sendsTo\_B, B does some work, A\_downloadsFrom\_B
- A knows B because it asks B to do some work for A
- B does not need to know identification of A
  - B: imgP = ImgPacker.receiveImage(portNo, timeoutTime);
  - B: process(imgP);
  - B: ImgPacker.serveImage((ImgPlus) imgP, portNo, timeoutTime);

# The Principle of DAIS wp 1.3

How to batch execute foreign code/binary (not tested yet):

- B: construct the foreign binary as:
  - receive image, process image, serve image
  - only portNo is required
- A: construct the Java caller as:
  - pre-process image,
  - send the image in thread Q & exec() the foreign binary in thread W,
  - receive image in thread Q & wait for thread W,
  - post-process image
  - connecting address of B is required
- Foreign code can be any executable
   e.g. Fiji-headless-plugin or wrapped C++ library

### The API of DAIS wp 1.3

How to use it from Java (reminder):

import de.mpicbg.ulman.imgtransfer.ImgPacker;
[ import de.mpicbg.ulman.imgtransfer.ProgressCallback; ]

ImgPlus<?> imgP = ...;

A\_sendsTo\_B:
A: ImgPacker.sendImage((ImgPlus) imgP, "tcp://"+remoteURL, timeoutTime[, logger]);

B: imgP = ImgPacker.receiveImage(portNo, timeoutTime[, logger]);

```
A_downloadsFrom_B:
```

— or —

```
\begin{split} &B\colon ImgPacker.serveImage((ImgPlus)\ imgP,\ portNo,\ timeoutTime[,\ logger]);\\ &A\colon imgP = ImgPacker.requestImage("tcp://"+remoteURL,\ timeoutTime[,\ logger]); \end{split}
```

- TimeoutTime is given in seconds as int, max waiting time 68 yrs
- Logger is optional
- Logger must implement ProgressCallback.info(String) and ProgressCallback.setProgress( $0 \le float \le 1$ )

- All 4 functions should finish either with:
  - success after image was for sure sent or received
  - exception due to timeout (no functional connection was established)
  - exception due to other error (e.g. socket issues, protocol error)
- Currently supported:
  - only the image imgP.getName() metadata
  - ImpPacker.SUPPORTED\_VOXEL\_CLASSES list supported voxel imglib2 types (ByteType, UnsignedByteType, ShortType, UnsignedShortType, FloatType, DoubleType)
  - Arraylmg, Planarlmg supported; CellImg, CachedCellImg not yet

#### Technical details, A sends image to B:

- A calls ImgPacker.sendImage()
- B calls ImgPacker.receiveImage()
- B← periodically (non-blocking) reads its port until timeout: ImgPacker.receiveImage()
- B← reads header, tries to create empty image: ImgPacker.receiveAndUnpack()
- B→ sends "ready": ImgPacker.receiveAndUnpack()
- A
   — periodically (non-blocking) reads its port until timeout: ImgPacker.packAndSendHeader()
- $\bullet \ \ \, \mathsf{A} \leftarrow \mathsf{needs} \mathsf{\ to} \mathsf{\ read} \mathsf{\ ''ready''}, \mathsf{\ else} \mathsf{\ complain:} \mathsf{\ ImgPacker.packAndSendHeader()}$
- B — reads metadata, parses them with the separator QQ (ImgPacker.mdMsgSep): ImgPacker.receiveAndUnpackPlusData()
- A→ keeps sending PlanarImg voxel data: ImgPacker.packAndSendPlanarImg()
- B← keeps reading PlanarImg voxel data: ImgPacker.receiveAndUnpackPlanarImg()
- B→ sends "done" after it finishes reading: ImgPacker.receiveAndUnpack()
- B finishes

#### Technical details, A sends image to B:

- $\bullet \ \ \, \mathsf{A} \! \to \mathsf{keeps} \mathsf{\ sending\ PlanarImg\ voxel\ data}$
- B← keeps reading PlanarImg voxel data
- ArrayImg is sent in one "chunk"
- Planarlmg is sent plane-wise in multiple "chunks", one per plane
- (CellImg will be sent cell-wise)
- Planarlmg:

```
for (int slice = 0; slice < img.numSlices(); ++slice)
{
    final Object data = img.getPlane(slice).getCurrentStorageArray();
    ArraySender.sendArray(data, socket)
    // ArrayReceiver.receiveArray(data, socket);
}</pre>
```

- ArraySender.sendArray() & ArrayReceiver.receiveArray()
  - send/receive one "chunk" of data
  - figure voxel type from Object data
  - call sending/receiving routines specific for that voxel type
- Example specific for float:
- void sendFloats(final float[] data, final ZMQ.Socket socket)
  - data is length-limited array of 4B elements
  - ▶ but ZeroMQ consumes ByteBuffer: length-limited array of 1B elements
  - solution: send as 4 messages
  - one "chunk" is sent as 4 ZeroMQ messages for FloatType
- Summary:
  - ArrayImg is sent as a single plane
  - PlanarImg is sent plane-wise
  - each plane is sent as multiple ZeroMQ messages, depends on voxel type