

2021 T1

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Most of these solutions have been derived entirely by me, so there may be imperfections and wrong answers/reasonings. Please contact me at my student email for any corrections.

These solutions were made to aid the preparation of MATH1231 students, not replace it. Good luck :)

Q2)

a) $\{v_1, v_2, v_3\}$ is a linearly independent set

S: We cannot know if this is true; what if v_3 is a scalar multiple?

b) $\{v_1, v_2, v_3\}$ spans \mathbb{R}^4

S: For a set of basis vectors that span \mathbb{R}^n , we need n vectors.

c) $\dim(S) = 2$

S: We have zero clue what v_3 is, so we are not sure if it is exactly 2.

d) $\dim(S) = 3$

S: Same as above

e) $\dim(S) \geq 2$

S: We know this is true. We already have two lin. ind. vectors, so it is either 2 or greater than 2.

f) $\dim(S) < 2$

S: Definitely false, we already have two lin. ind. vectors

g) there exists a vector v_4 such that $\{v_1, v_2, v_3, v_4\}$ is a basis for \mathbb{R}^4

S: Impossible to know without knowing what v_3 is.

h) there exists vectors v_4, v_5 such that $\{v_1, v_2, v_3, v_4, v_5\}$ spans \mathbb{R}^4

S: Definitely true, as we already have enough vectors (4) excluding v_3 to make a basis.

i) one of the vectors v_1, v_2, v_3 is a linear combination of the other two

S: We don't know what v_3 is

j) \mathbb{R}^4 has a basis including at least two of the vectors v_1, v_2, v_3 :

S: Definitely true – we have v_1, v_2 already and they are linearly independent, so we can construct a basis out of them.

Q3)

a)

For a matrix to be diagonalisable, the algebraic multiplicities must = the geometric multiplicities. Hence, we must reduce the algebraic multiplicities to below 2.

Hence, find the characteristic polynomial:

$$\begin{pmatrix} 82 & x \\ -61 & -73 \end{pmatrix}$$

Our goal is to turn the characteristic polynomial into the form $(x - c)^2$.

$$\lambda^2 - 9\lambda + 61x - 5986$$

Therefore, our equation will look like $(\lambda - \frac{9}{2})^2$, and hence, we must make $61x - 5986 = \frac{81}{4}$.

b) Look above for reasoning

Q4)

a) You can construct the matrix using matrix representation theorem for linear maps.

$$\frac{dy_1}{dt} = y_1(-k_1 - k_2) + k_2 y_2 \quad \frac{dy_2}{dt} = k_2 y_1 + y_2(-k_2 - k_3)$$

This can be then represented trivially as:

$$\begin{pmatrix} (-k_1 - k_2) & k_2 \\ k_2 & (-k_2 - k_3) \end{pmatrix}$$

b)

Input the values of k_1, k_2, k_3 given to create a matrix and use:

```
Eigenvectors(A)
and
Eigenvalues(A)
```

to solve the question

c)

To solve a differential equations from a linear first-order differential equation, we create a matrix with the differential equations and then find eigenvalues λ_1, λ_2 and eigenvectors \vec{a}, \vec{b} :

$$\text{solution} = e^{\lambda_1 t} \vec{a} + e^{\lambda_2 t} \vec{b}$$

Therefore, our solution is:

```
C1*exp(-0.02*t)*<0.707106781186548, 0.707106781186547> +
C2*exp(-0.32*t)*<-0.707106781186547, 0.707106781186548>
```

d)

With the initial conditions of 7 degrees in the storage area, and 26 degrees in the living area, create a matrix equation and use linear solve:

```
M := <<0.707106781186548, 0.707106781186547>|
<-0.707106781186547, 0.707106781186548>|<7, 26>>
LinearSolve(M)
Output: <23.3345237791561, 13.4350288425444>
```

Q5)

a) Consider if the zero element exists within $T(p)$.

$T(0) = (x^4 + 2x + 6) \left(\frac{d(0)}{dx} \right) = 0$ therefore, the zero element exists.

\vec{a} and \vec{b} are two arbitrary vectors in the space \mathbb{P} .

Now consider:

$$\begin{aligned} T(\vec{a}) + T(\vec{b}) &= (x^4 + 2x + 6) \left(\frac{da}{dx} \right) + (x^4 + 2x + 6) \left(\frac{db}{dx} \right) \\ T(\vec{a}) + T(\vec{b}) &= \frac{d(a+b)}{dx} (x^4 + 2x + 6) \\ &= T(a+b) \\ T(\vec{\lambda a}) &= \lambda (x^4 + 2x + 6) \left(\frac{da}{dx} \right) \\ &= \lambda T(\vec{a}) \end{aligned}$$

Hence, $T(x)$ is a linear map.

b) For $T(x) = 0$, p must equal a constant as $q(x)$ is a non-zero polynomial for all p . So choose all the constant values.

c) The only choice that is not valid within the choices is $(x^4 + 2x + 6) + 99$.

This can be proven by:

$$\begin{aligned} T(p) &= q(x) + 99 \\ q(x) \left(\frac{dp}{dx} \right) &= q(x) + 99 \\ q(x) \left(\frac{dp}{dx} - 1 \right) &= 99 \end{aligned}$$

Therefore, this is impossible. The degree of the LHS is at minimum 4. The RHS has a degree of zero.

d) This can be trivially proven

Let \vec{a} and \vec{b} be two arbitrary vectors in polynomial space \mathbb{P} .

The zero element trivially exists.

Consider closure under addition:

$$\begin{aligned}T(\vec{a}) + T(\vec{b}) &= a^2 \left(\frac{da}{dx} \right) + b^2 \left(\frac{db}{dx} \right) \\&= \frac{d(a+b)}{dx} (a^2 + b^2) \\&\neq \frac{d(a+b)}{dx} (a+b)^2\end{aligned}$$

Therefore, not closed under addition, and hence, not linear.

Q6)

Consider that $E(X) = nP(X)$.

For a probability density function, we must consider the net total probability.

Therefore, $\frac{a \cos x + b \sin x}{x^2}$ becomes $\frac{a \cos x + b \sin x}{x}$.

Sticking this in maple, we learn that:

$$0.0855769059a + 0.6593299066b = 1.3$$

Also, consider that the total probability of the *CDF* must = 1;

therefore:

$$0.0890458176a + 0.4723991777b = 1$$

Solving this as a system of linear equations, using `LinearSolve()`, we achieve the answer.

Note: The formula for the expected value given a probability density function $f_x(X)$ is:

$$E(X) = \int_{-\infty}^{\infty} x f_x(X) dx$$

b) See above

c) Variance can be found using $E(X^2) - E(X)^2$

d) Use z score and the formula $z = \frac{x-\mu}{\sigma}$

Q7)

a) The total differential approximation for a point differs from the *change of a function*.

The formula here used is:

$$f(x, y) \sim f(x_0, y_0) + F_x(x_0, y_0)(x - x_0) + F_y(x_0, y_0)(y - y_0)$$

b) This is fairly trivial; realise that this formula above is the same as the formula we use to find the tangent plane at point x_0, y_0 .

Q8)

a)

$$\cosh^2(7x) - \sinh^2(7x) = 1$$

$$\sinh^2(7x) = \cosh^2(7x) - 1$$

Therefore, the denominator can be simplified to:

$$3 \cosh^3(7x) - 3 \cosh(7x)$$

b) Sub in 0 and 7 into $\cosh(7x) = t$ for the values of a and b.

Integrate by substitution by using the sub $dx = \frac{1}{7 \sinh(x)} dt$

$$P(t) = 21(t^3 - t)$$

c) $P(t)$ can be factorised into $t(t^2 - 1)$ which can then be expanded into $t(t - 1)(t + 1)$. Therefore, we expect 3 terms.

Q9)

Consider the options:

The series diverges for every $x > 2$

S: This is not true – it actually converges for every $x > 2$.

The series diverges for multiple values of x

S: This is definitely true.

The series converges for at most one value of x .

S: This is not true; refer to the solution of the first option.

The series converges for at least one value of x

S: This is definitely true, as we know x converges such that $x > 2$

The series converges for every x

S: This is not true

Q10)

a)

$f(0) = 1/7$ (by inspection)

$f'(0) = 1/14$ (since $d/dx = 1$)

$f''(0) = 1/14$ (since $d/dx = 2$, $1/28 / 2$)

$f'''(0) = 6/56$ (since $d/dx = 6$, $1/56 / 6$)

b)

$$\begin{aligned} a_n &= \frac{1}{7 \cdot 2^n} \\ &= \lim_{n \rightarrow \infty} \frac{1}{7 \cdot 2^n} x^n \\ &= \lim_{n \rightarrow \infty} \frac{x^{n+1}}{7 \cdot 2^{n+1}} \frac{7 \cdot 2^n}{x^n} \\ &= \frac{|x|}{2} \end{aligned}$$

Therefore, the radius of converge is 2.

c)

Consider that the series is contained by:

$$\sum_{n=0}^{\infty} \frac{1}{7 \cdot 2^n} x^n$$

Using this, and the GP formula:

$$\begin{aligned}
&= \frac{1}{7 \cdot 2^n} \cdot \frac{1}{4^n} \\
&= \frac{1}{7} \sum \frac{1}{8^n} \\
&= \frac{1}{7} \left(\frac{1}{1 - \frac{1}{8}} \right) \\
&= \frac{8}{49}
\end{aligned}$$

d) Repeat above steps

Q11)

a) Note that for a question to be a first-order linear ODE, it must be in the form:

$$\frac{dy}{dx} + g(x)y = f(x)$$

Therefore, to find the integrating factor, we must divide $\sqrt{x^2 - 25}$ out of the derivative (or whatever your questions multiplying factor is).

b) Standard theory - check out the notes if your confused.

c) Just do this in maple:

```
int(x^3/(sqrt(x^2-25)), x)
g := x -> ((x - 5)*(x + 5)*(x^2 + 50))/(3*sqrt(x^2 - 25))
h := x -> exp(g(x))
h(sqrt(26))
Output: exp(76*(sqrt(26) - 5)*(sqrt(26) + 5)/3)
```

Q12)

a)

Let's consider the options

1. The differential equation is exact
This is false - it's not in the right form
2. The different equation is of second order

True; we have y''

3. This is a partial differential equation

False: There are no partial derivatives within this equation

4. The differential equation is of first order

False; see 2

5. The equation is homogenous linear

False; it does not $= 0$, therefore not homogenous

6. This is a linear ODE

True; linear. (There are no powers on the derivatives)

b) Since the $ODE = \frac{x^3}{3}$, the solution should be representative of the polynomial of order 3, which is $ax^3 + bx^2 + cx + d$.

Q13)

a) Find the homogenous equation:

$$\lambda^2 + a\lambda + 6$$

Consider that the homogenous equation oscillates when it passes the x-axis; therefore, we wish the discriminant > 0 . (As when the homogenous equation is floating, $\sin(x)$ and $\cos(x)$ will occur).

Therefore:

$$a^2 - 24 > 0$$

$$a > \sqrt{24}$$

b) Just means finds a particular solution.

The maple command for this is:

```
dsolve(diff(y(x), x, x) + 12*diff(y(x), x) + 6*y(x) = 15*cos(x))
```

Output:

$$y(x) = \exp((-6 + \sqrt{30})*x)*_C2 + \exp(-(6 + \sqrt{30})*x)*_C1 + (180*\sin(x))/169 + (75*\cos(x))/169$$

And we take $(180*\sin(x))/169 + (75*\cos(x))/169$ as the particular solution.