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Analgo 6

1. Matriks Adjacency

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Matriks Adjacency

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#include <iostream>

using namespace std;

int vertArr[20][20];

int count = 0;

void displayMatrix(int v){

int i, j;

for (i = 1; i <= v; i++){

for (j = 1; j <= v; j++)

{

cout << vertArr[i][j] << " ";

}

cout << endl;

}

}

void add\_edge(int u, int v){

vertArr[u][v] = 1;

vertArr[v][u] = 1;

}

int main(int argc, char \*argv[]){

int v;

cout << "Masukkan jumlah matrix : "; cin >> v;

int pilihan,a,b;

while(true){

cout << "1. Tambah edge " << endl;

cout << "2. Print " << endl;

cout << "3. Exit " << endl;

cout << "Masukan pilihan : "; cin >> pilihan;

if (pilihan==1){

cout << "Masukkan node A : "; cin >> a;

cout << "Masukkan node B : "; cin >> b;

add\_edge(a,b);

cout << "Edge telah ditambahkan\n";

system("Pause");

system("CLS");

} else if(pilihan==2){

displayMatrix(v);

system("Pause");

system("CLS");

} else{

return 0;

}

}

}

1. List Adjacency

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List Adjacency

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#include <iostream>

#include <cstdlib>

using namespace std;

struct AdjListNode{

int dest;

struct AdjListNode\* next;

};

struct AdjList{

struct AdjListNode \*head;

};

class Graph{

private:

int V;

struct AdjList\* array;

public:

Graph(int V){

this->V = V;

array = new AdjList [V];

for (int i = 1; i <= V; ++i)

array[i].head = NULL;

}

AdjListNode\* newAdjListNode(int dest){

AdjListNode\* newNode = new AdjListNode;

newNode->dest = dest;

newNode->next = NULL;

return newNode;

}

void addEdge(int src, int dest){

AdjListNode\* newNode = newAdjListNode(dest);

newNode->next = array[src].head;

array[src].head = newNode;

newNode = newAdjListNode(src);

newNode->next = array[dest].head;

array[dest].head = newNode;

}

void printGraph(){

int v;

for (v = 1; v <= V; ++v){

AdjListNode\* pCrawl = array[v].head;

cout << "\n Adjacency list of vertex " << v << "\n head ";

while (pCrawl){

cout<<"-> "<<pCrawl->dest;

pCrawl = pCrawl->next;

}

cout<<endl;

}

}

};

int main(){

int pilihan,a,b,n;

cout << "Banyak node : "; cin >> n;

Graph gh(n);

for(; ;){

cout << "\nMenu\n";

cout << "1. Tambah edge\n";

cout << "2. Print Edge\n";

cout << "3. Exit\n\n";

cout << "Pilihan : "; cin >> pilihan;

switch (pilihan){

case 1:

cout << "\nedge(a,b)\n";

cout << "Input a : "; cin >> a;

cout << "Input b : "; cin >> b;

gh.addEdge(a,b);

continue;

case 2:

gh.printGraph();

continue;

case 3:

return 0;

break;

default:

continue;

}

}

return 0;

}

1. BFS

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BFS

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#include<iostream>

#include <list>

using namespace std;

class Graph{

int V; // No. of vertices

list<int> \*adj;

public:

Graph(int V); // Constructor

// function to add an edge to graph

void addEdge(int v, int w);

// prints BFS traversal from a given source s

void BFS(int s);

};

Graph::Graph(int V){

this->V = V;

adj = new list<int>[V];

}

void Graph::addEdge(int v, int w){

adj[v].push\_back(w); // Add w to v’s list.

}

void Graph::BFS(int s){

// Mark all the vertices as not visited

bool \*visited = new bool[V];

for(int i = 0; i < V; i++)

visited[i] = false;

// Create a queue for BFS

list<int> queue;

// Mark the current node as visited and enqueue it

visited[s] = true;

queue.push\_back(s);

// 'i' will be used to get all adjacent

// vertices of a vertex

list<int>::iterator i;

while(!queue.empty()){

// Dequeue a vertex from queue and print it

s = queue.front();

cout << s << " ";

queue.pop\_front();

// Get all adjacent vertices of the dequeued

// vertex s. If a adjacent has not been visited,

// then mark it visited and enqueue it

for (i = adj[s].begin(); i != adj[s].end(); ++i){

if (!visited[\*i]){

visited[\*i] = true;

queue.push\_back(\*i);

}

}

}

}

// Driver program to test methods of graph class

int main(){

// Create a graph given in the above diagram

Graph g(8);

g.addEdge(1, 2);

g.addEdge(1, 3);

g.addEdge(2, 4);

g.addEdge(2, 5);

g.addEdge(2, 3);

g.addEdge(3, 7);

g.addEdge(3, 8);

g.addEdge(4, 5);

g.addEdge(5, 3);

g.addEdge(5, 6);

g.addEdge(7, 8);

cout << "Breadth First Traversal ";

cout << "(starting from vertex 1) \n";

g.BFS(1);

return 0;

}

• BFS merupakan metode pencarian secara melebar sehingga mengunjungi node dari kiri ke kanan di level yang sama. Apabila semua node pada suatu level sudah dikunjungi semua, maka akan berpindah ke level selanjutnya. Dalam worst case BFS harus mempertimbangkan semua jalur (path) untuk semua node yang mungkin, maka nilai kompleksitas waktu dari BFS adalah O( |V| + |E| ).

• Karena Big-O dari BFS adalah O(V+E) dimana V itu jumlah vertex dan E itu adalah jumlah edges maka Big-O = O(n) dimana n = v+e

• Maka dari itu Big-Ө nya adalah Ө(n).

1. DFS

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DFS

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#include<iostream>

#include<list>

using namespace std;

class Graph{

int V; // No. of vertices

list<int> \*adj;

// A recursive function used by DFS

void DFSUtil(int v, bool visited[]);

public:

Graph(int V); // Constructor

// function to add an edge to graph

void addEdge(int v, int w);

// DFS traversal of the vertices

// reachable from v

void DFS(int v);

};

Graph::Graph(int V){

this->V = V;

adj = new list<int>[V];

}

void Graph::addEdge(int v, int w){

adj[v].push\_back(w); // Add w to v’s list.

}

void Graph::DFSUtil(int v, bool visited[]){

// Mark the current node as visited and

// print it

visited[v] = true;

cout << v << " ";

// Recur for all the vertices adjacent

// to this vertex

list<int>::iterator i;

for (i = adj[v].begin(); i != adj[v].end(); ++i)

if (!visited[\*i])

DFSUtil(\*i, visited);

}

// DFS traversal of the vertices reachable from v.

// It uses recursive DFSUtil()

void Graph::DFS(int v){

// Mark all the vertices as not visited

bool \*visited = new bool[V];

for (int i = 0; i < V; i++)

visited[i] = false;

// Call the recursive helper function

// to print DFS traversal

DFSUtil(v, visited);

}

int main(){

// Create a graph given in the above diagram

Graph g(8);

g.addEdge(1, 2);

g.addEdge(1, 3);

g.addEdge(2, 4);

g.addEdge(2, 5);

g.addEdge(2, 3);

g.addEdge(3, 7);

g.addEdge(3, 8);

g.addEdge(4, 5);

g.addEdge(5, 3);

g.addEdge(5, 6);

g.addEdge(7, 8);

cout << "Depth First Traversal";

cout << " (starting from vertex 1) \n";

g.DFS(1);

return 0;

}

* DFS merupakan metode pencarian mendalam, yang mengunjungi semua node dari yang terkiri lalu geser ke kanan hingga semua node dikunjungi. Kompleksitas ruang algoritma DFS adalah O(bm), karena kita hanya hanya perlu menyimpan satu buah lintasan tunggal dari akar sampai daun, ditambah dengan simpul-simpul saudara kandungnya yang belum dikembangkan.
* Big O Kompleksitas total DFS () adalah (V+E). O(n) dengan V = Jumlah Verteks dan E = Jumlah Edges