Pose Error vs Time Angular Error X Angular Error Y Angular Error Z 0.5 -0.0 1.75 -0.4 -1.50 -<del>-</del>0.2 -1.25 -0.3 (rad) 0.2 -(pe 1.00 - 3 0.75 ωz (rad) 0.50 --0.60.1 -0.25 -0.0 -0.00 -0.820 25 25 20 15 30 15 20 25 10 15 30 10 10 30 5 Time (s) Time (s) Time (s) Linear Error X Linear Error Y Linear Error Z 0.0 0.00 0.00 -0.05-0.1 --0.05-0.10<del>-</del>0.2 -(E) N -0.3 € -0.15 × vy (m) -0.10-0.20-0.15 -0.4-0.25-0.20 -0.30-0.520 25 30 20 25 15 30 5 10 15 5 10 15 30 10 20 25 5 Time (s) Time (s) Time (s)