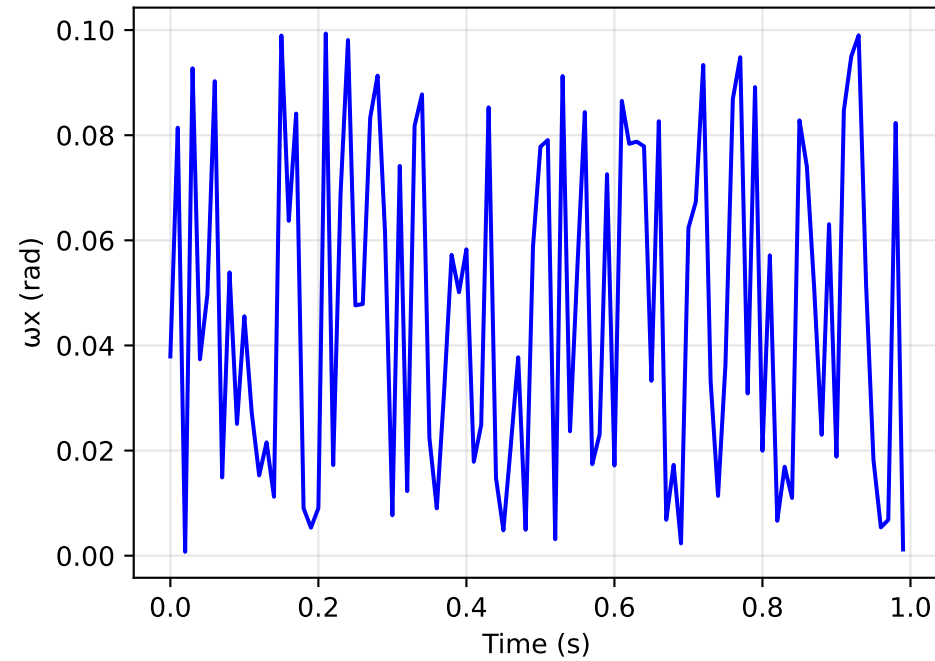
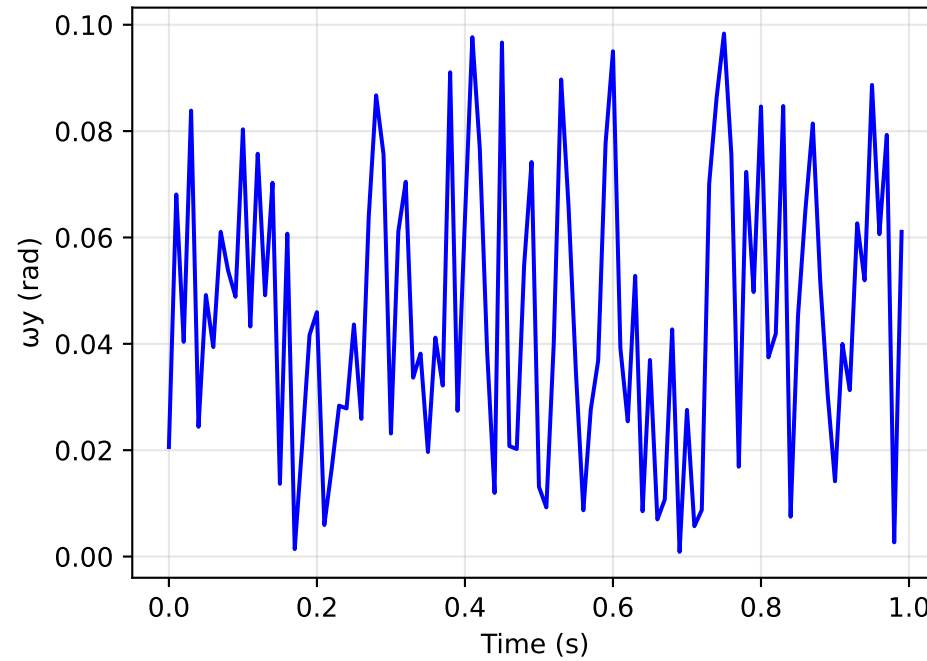


Pose Error vs Time

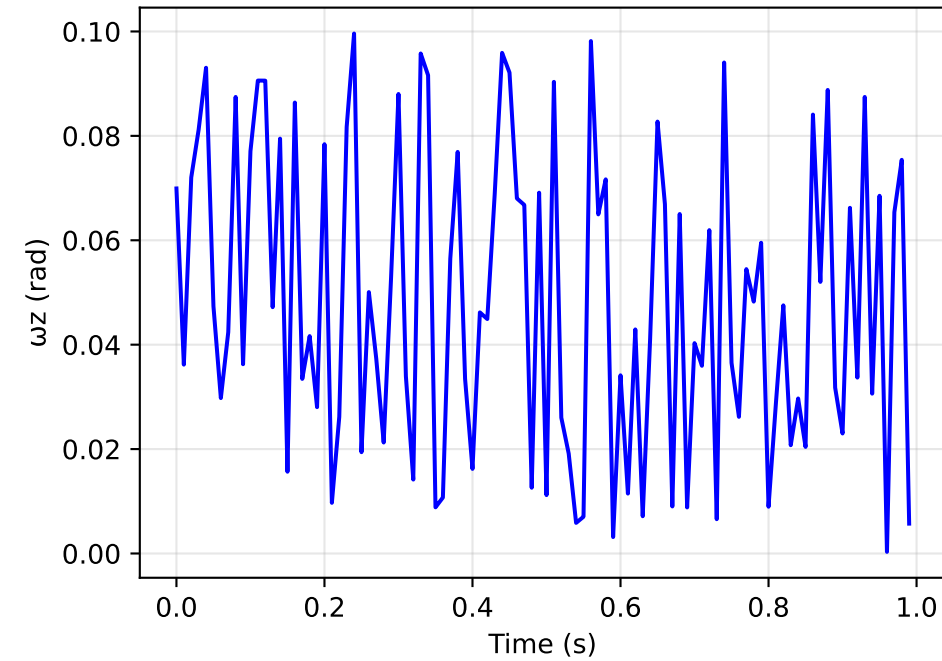
Angular Error X



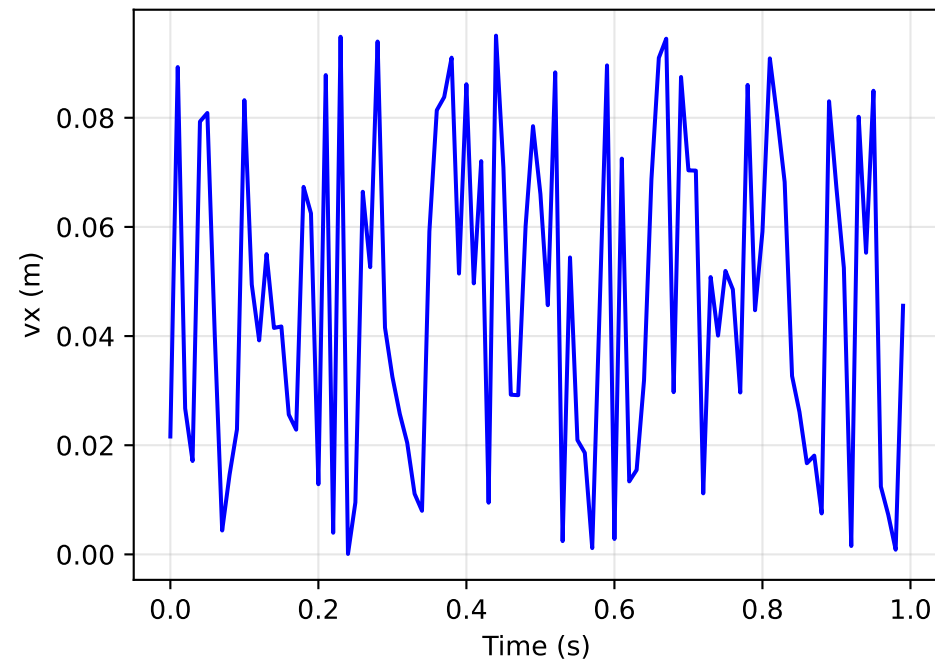
Angular Error Y



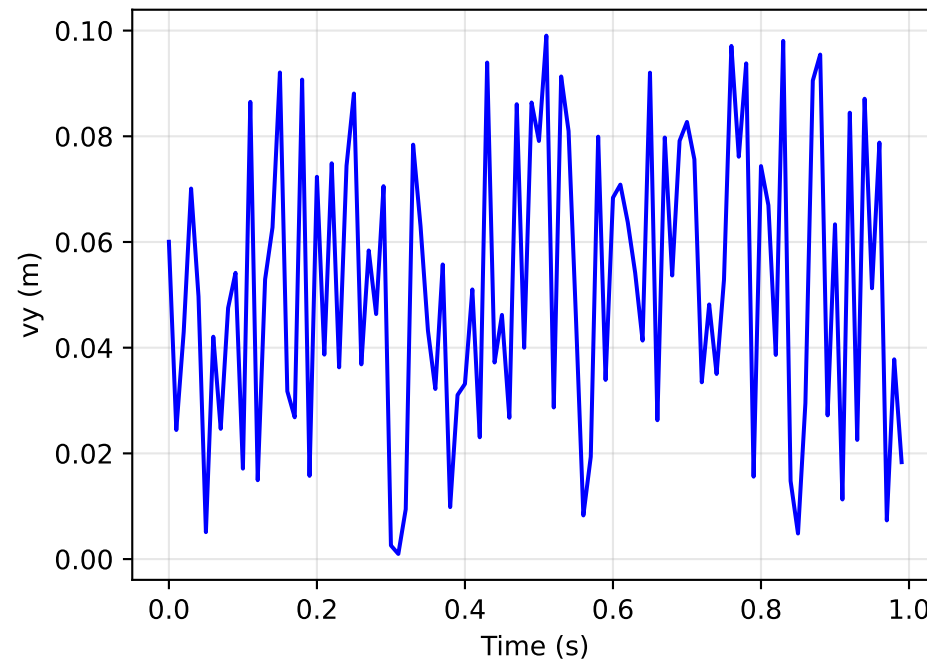
Angular Error Z



Linear Error X



Linear Error Y



Linear Error Z

