Pose Error vs Time Angular Error X Angular Error Y Angular Error Z 2.0 0.0 0.7 0.6 -1.5 -0.20.5 0.4 (x) 0.3 (rad) (w) (n) wz (rad) -0.4 0.5 -0.60.2 0.1 0.0 -0.80.0 25 20 20 30 25 25 30 10 15 5 10 15 30 10 15 20 0 5 5 Time (s) Time (s) Time (s) Linear Error X Linear Error Y Linear Error Z 0.4 0.0 0.6 0.2 -0.10.4 -0.20.0 (E) ⇒ −0.3 vz (m) vx (m) -0.2-0.40.0 -0.4-0.5-0.215 25 30 30 25 30 5 10 20 5 10 15 20 25 5 10 15 20 0 0 Time (s) Time (s) Time (s)