Pose Error vs Time Angular Error X Angular Error Y 0.2 1e-5 Angular Error Z 0.000 -0.0000 0.0 -0.005 -0.2 · -0.0001-0.010-0.49 -0.015 3 -0.020 (rad) -0.0002 wz (rad) -0.6-0.8-0.025-0.0003-1.0 -0.030 -1.2 · -0.0004-0.035-1.415 20 25 20 10 30 15 25 10 15 20 25 30 0 5 10 30 Time (s) Time (s) Time (s) Linear Error X Linear Error Y Linear Error Z 0.006 0.00000 0.175 --0.000250.004 0.150 -0.000500.125 0.002 -0.00075 € 0.100 × 0.075 vz (m) 0.000 > −0.00100 · -0.00125-0.0020.050 --0.00150 -0.0040.025 --0.00175 -0.006 0.000 20 25 10 15 30 10 15 20 25 30 10 15 20 25 30 0 0 5 5 Time (s) Time (s) Time (s)