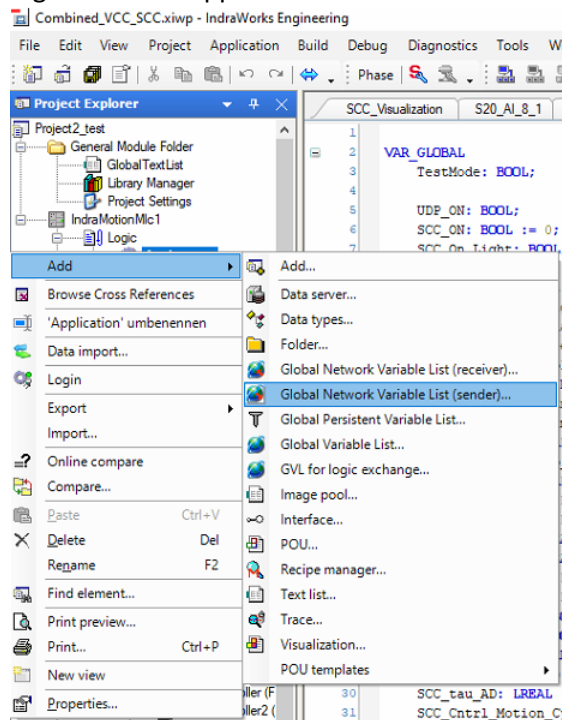


Simulink RT XM22 UDP Interface Guidance

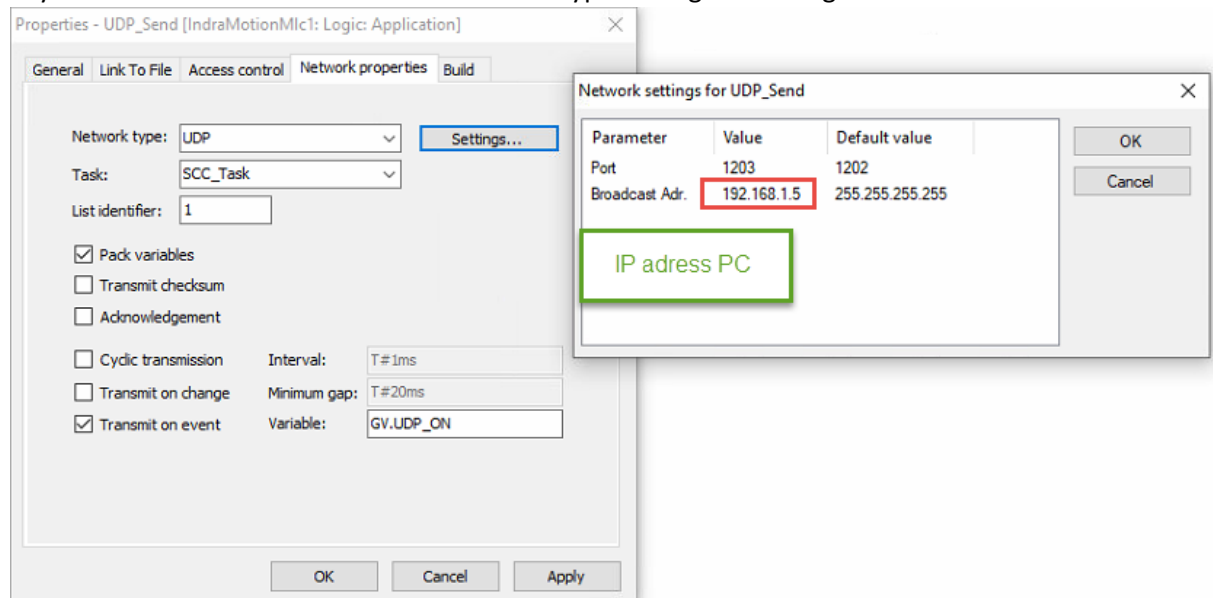
Daniel Hagen

Rexroth XM22 (PLC):

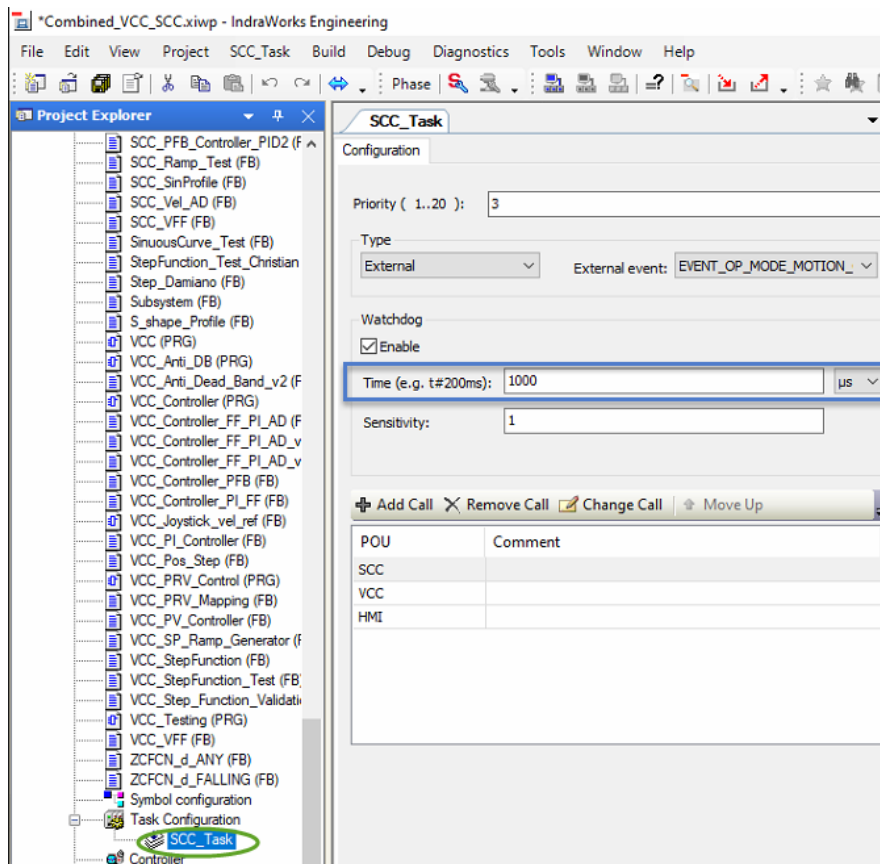
1. Right click on "Application" and add:



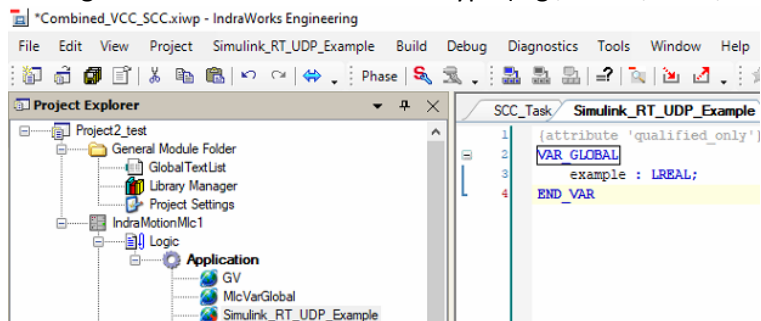
2. Select network type UDP, assign task, select transmit on event and assign a trigger variable (I recommend to do this so the PLC is not sending data all the time, but only when needed, e.g., when generated PLC time is started → enable "UDP_ON" signal), alternatively select "Cyclic transmission Interval". Check Network type settings according to:



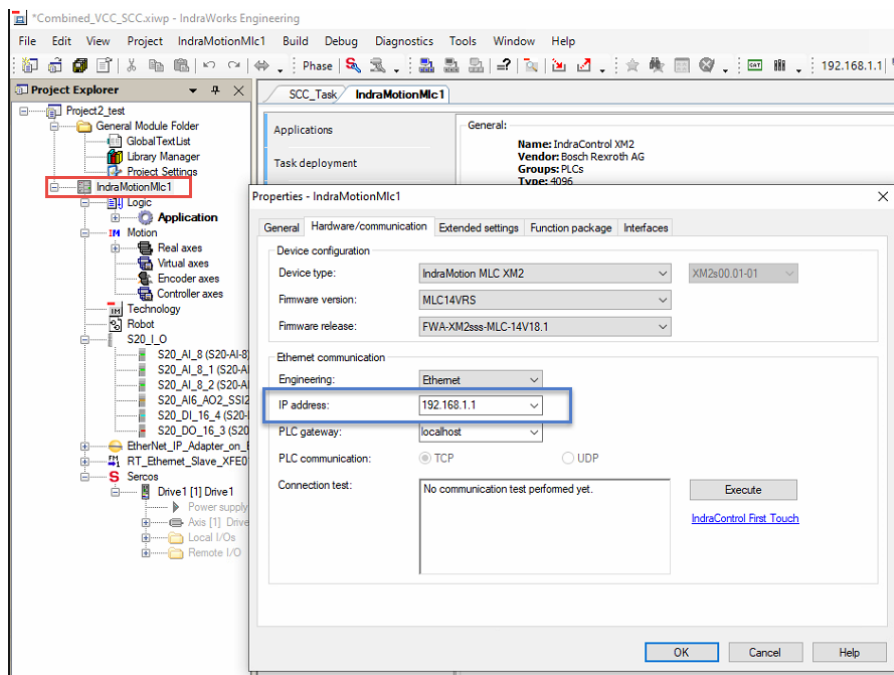
The chosen sample time should be greater or equal to the cyclic time of the task:



3. Add signal to be sent and chose datatype (e.g., LREAL, REAL, BOOL etc.).

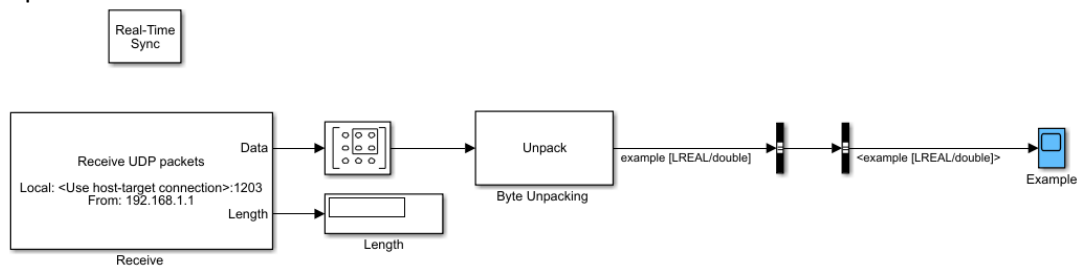


4. Identify the IP address of the PLC → right click on the “IndraMotion”:

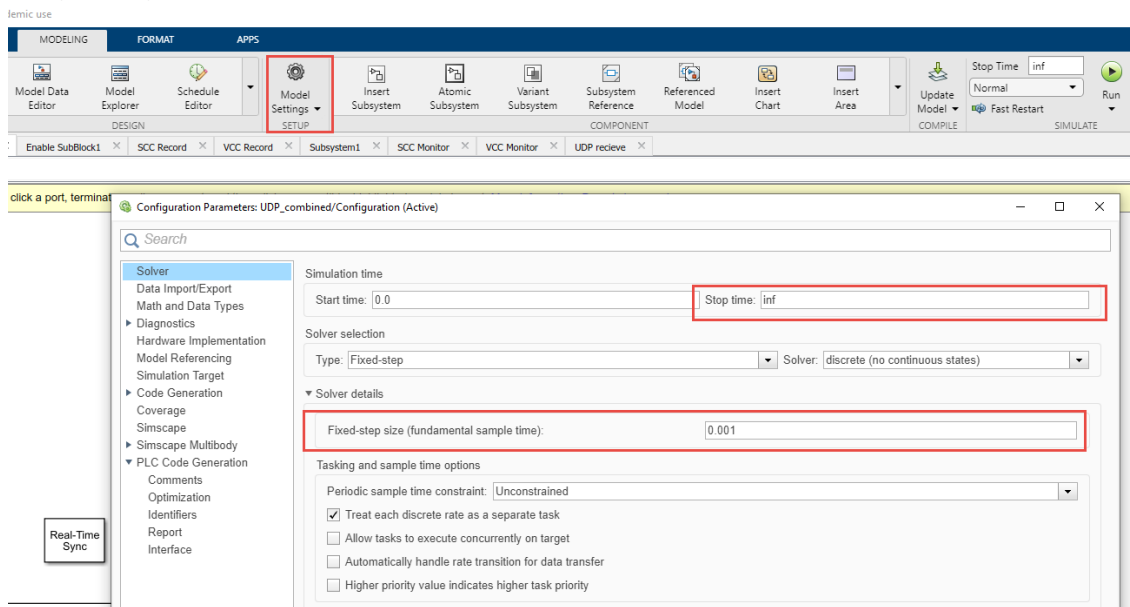


MATLAB/Simulink:

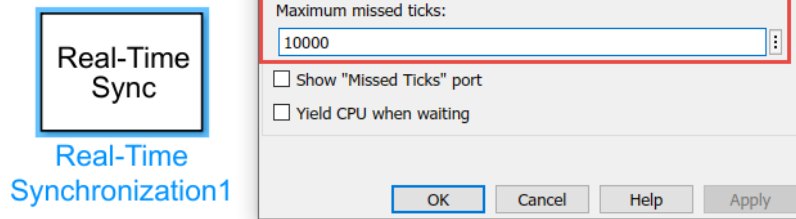
1. Install Simulink RT kernel for current Matlab version:
<https://se.mathworks.com/help/sldrt/ug/real-time-windows-target-kernel.html>
2. Open Simulink file



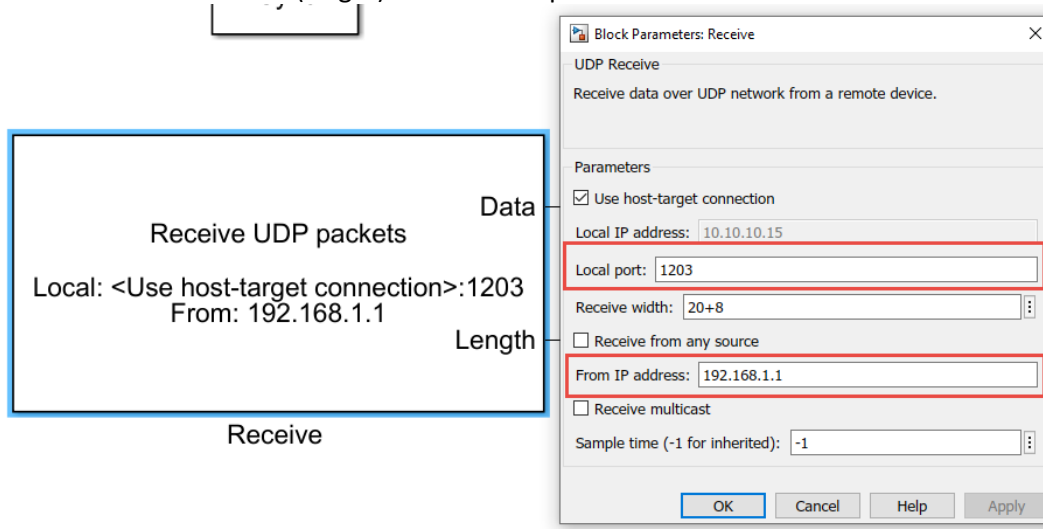
3. Model settings → select fixed step time and sample time same as for the Network Variable List (sender) chosen above:



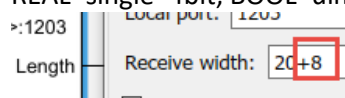
4. Increase the maximum missed ticks to avoid errors:



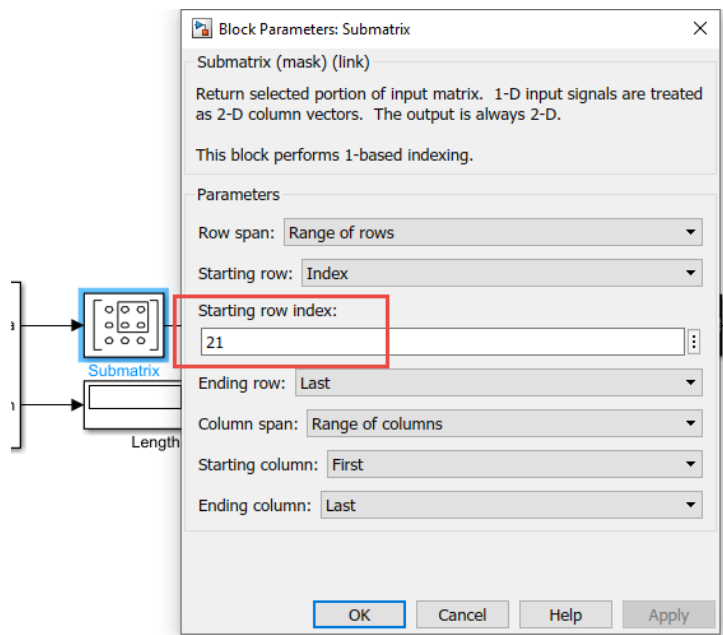
5. Add IP address from PLC (target) and set local port to "1203".



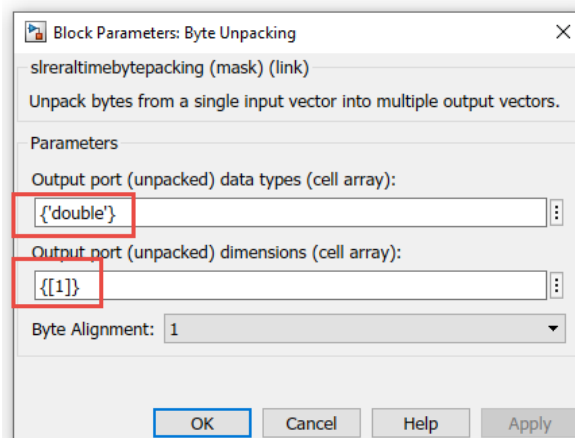
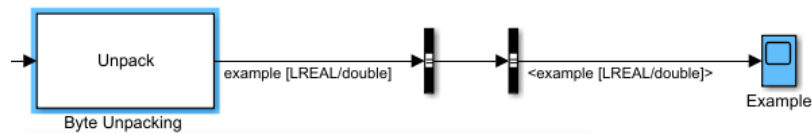
6. Add width of received signals, the first 20 is automatically occupied by the Network Variable List (sender), the +8 represent the 8bit LREAL from the example signal (LREAL=double=8bit, REAL=single=4bit, BOOL=uint8=1bit).:



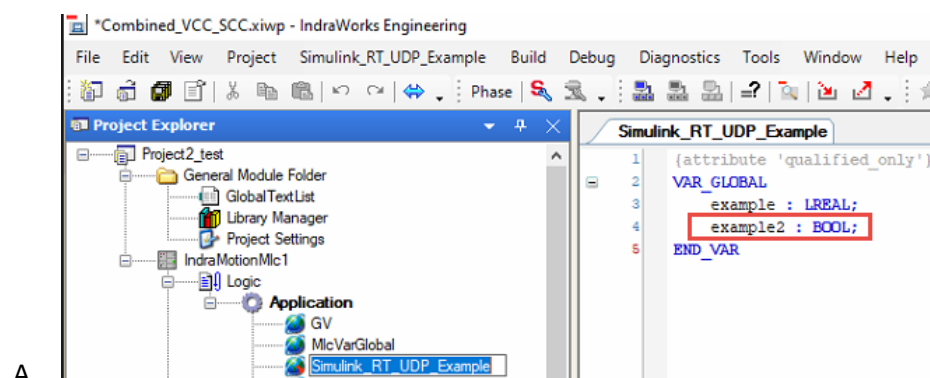
7. Select the "Starting row index":

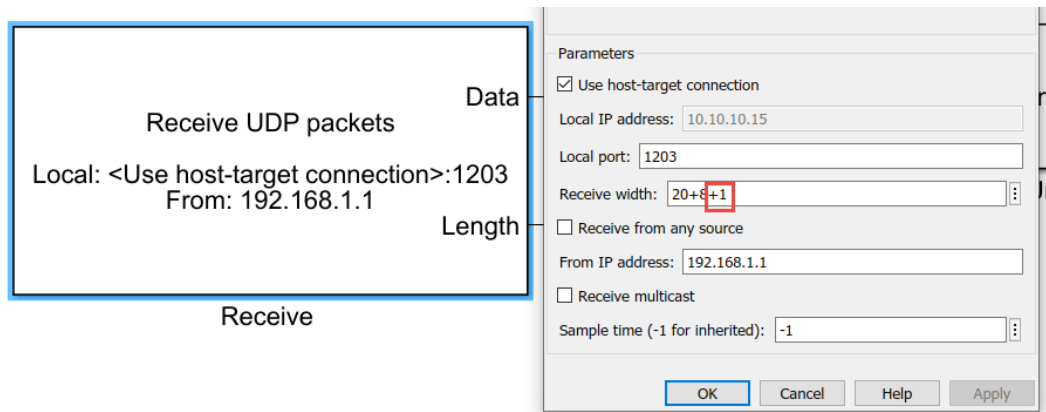


8. Unpack the signal(s):

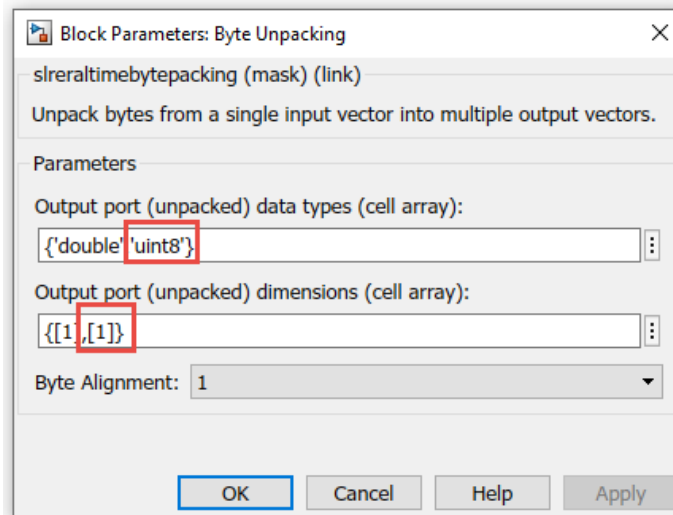
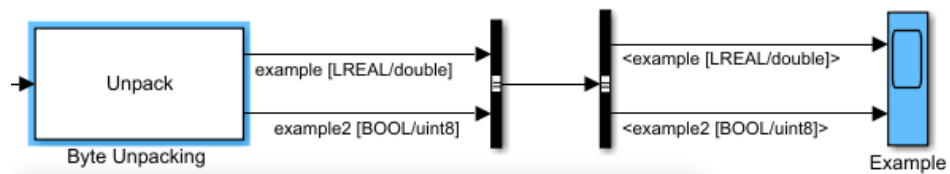


9. Example of adding more signals:





B.



C.