

Documentation

Steps to install WSL:

1. Open PowerShell (or Windows Command Prompt) and enter: `wsl --install`
2. Once the process of installing your Linux distribution with WSL is complete, open the distribution (Ubuntu by default) using the Start menu. You will be asked to create a User Name and Password for your Linux distribution.

Steps to install pip on wsl:

1. `sudo apt upgrade`
2. `sudo apt install python3`
3. `sudo apt install python3-pip`

Steps to connect Visual Studio Code to Wsl Terminal:

1. Open Visual Studio Code, install the Remote - WSL extension: Open Visual Studio Code, go to the Extensions view by clicking on the square icon on the left sidebar, and search for "Remote - WSL". Install the "Remote - WSL" extension provided by Microsoft.
2. Then back to Wsl terminal, go to the directory you want to edit your code file. Input command line : `"code ."`. Then the visual studio code should pop up immediately.

Steps to install roboflow server:

1. `pip install roboflow --quiet`

Steps to install numpy:

1. `pip install numpy`

Steps to install tkinter:

1. `sudo apt-get install python3-tk`

Steps to install pylas library:

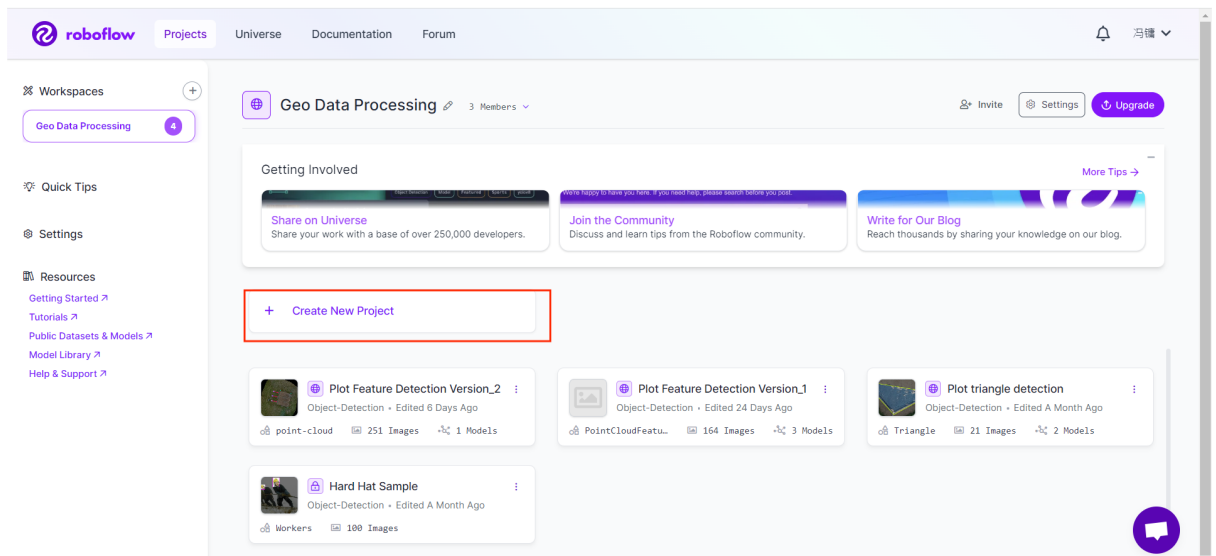
1. `pip install pylas`

If you want to build a stronger or more customized model, you can use the below steps to rebuild the program object detection model:

Training Model:

1. Google Roboflow and create your personal account. (<https://roboflow.com/>)

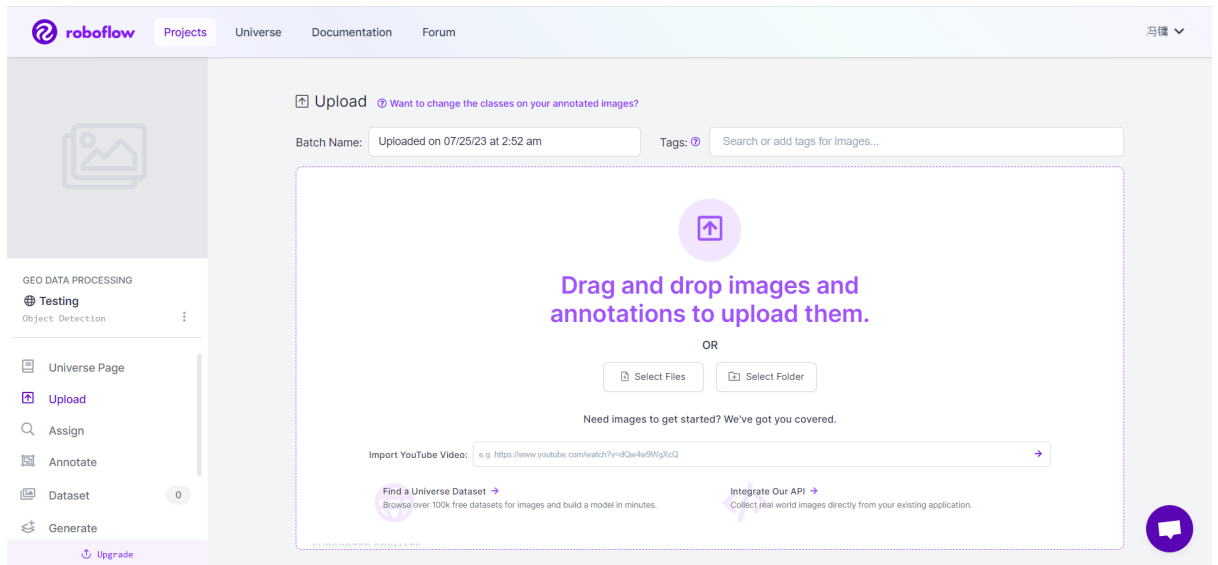
2. Click the Create New Project.



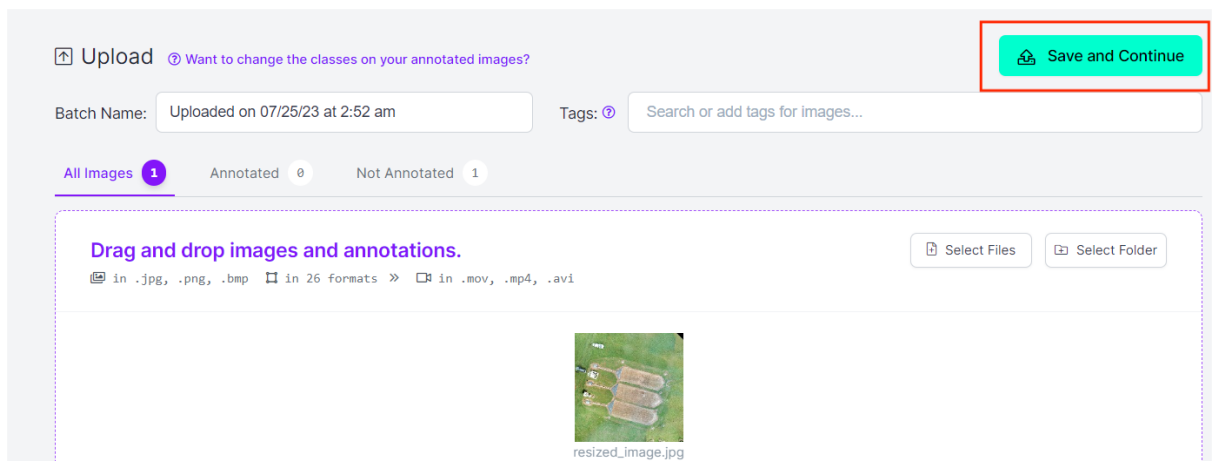
3. Input information about your project. After that, click the 'Create Public Project' button.

The image shows a 'Create Project' modal window. At the top, it says 'Geo Data Processing / New Public Project'. The 'Project Type' dropdown is set to 'Object Detection (Bounding Box)'. The 'What Are You Detecting?' dropdown is set to 'PointCloudFeature'. The 'Project Name' text field contains 'Testing'. The 'License' dropdown is set to 'CC BY 4.0'. At the bottom right, the 'Create Public Project' button is highlighted in purple, while the 'Cancel' button is in white.

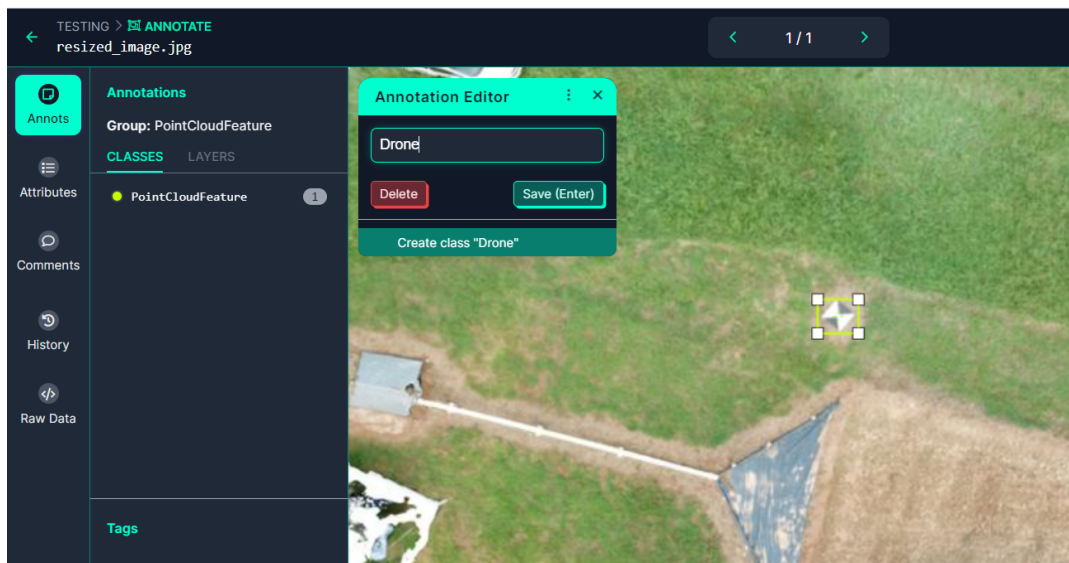
4. Input your dataset.



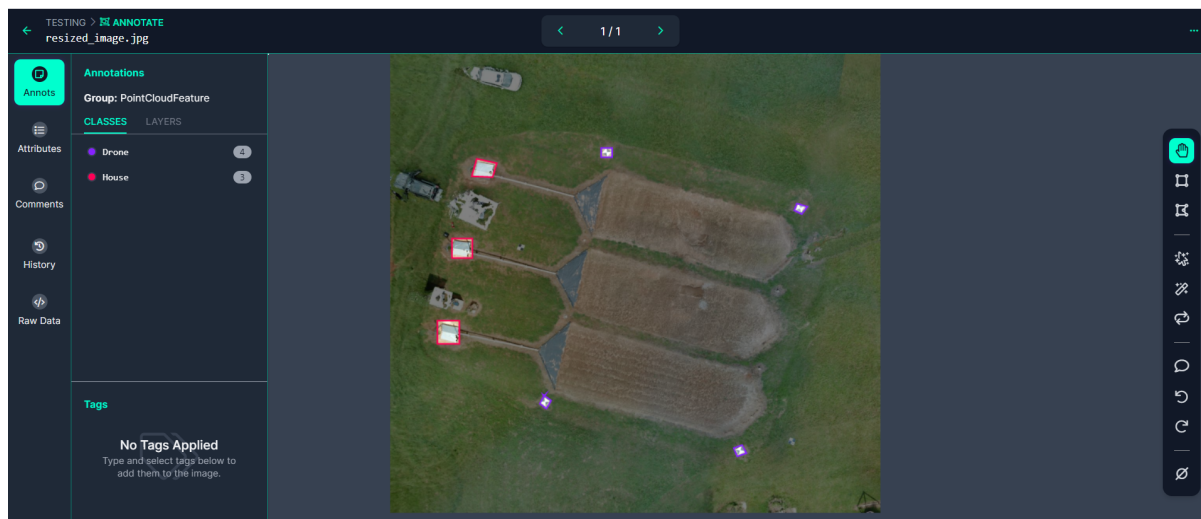
5. Click the 'Save and Continue' after the you have uploaded your image



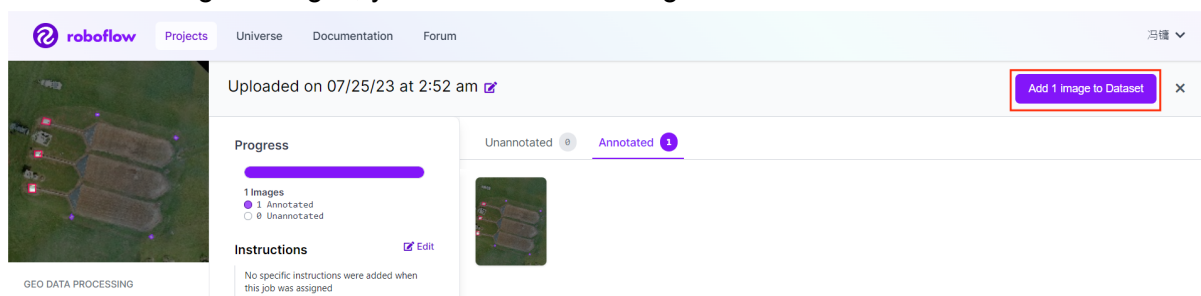
6. Draw bounding box to the object if you want the Model to detect later automatically.



7. After drawing the bounding box, the image will be like this:



8. After finishing all images, you can click 'Add Image to Dataset'



9. Generate your dataset.

The screenshot shows the Roboflow web interface for a 'Testing Dataset'. On the left sidebar, the 'Generate' button is highlighted with a red box. The main content area is titled 'Generating New Version' and includes a sub-header 'Generating New Version' with a description: 'Prepare your images and data for training by compiling them into a version. Experiment with different configurations to achieve better training results.' Below this, there are three steps: 1. Source Images (Images: 1, Classes: 2, Unannotated: 0), 2. Train/Test Split (Training Set: 1 images, Validation Set: images, Testing Set: images), and 3. Preprocessing (What can preprocessing do?).

10. Get the link of the dataset, in order to train it using google colab.

The screenshot shows the Roboflow web interface for a specific dataset version, '2023-07-25 3:07am'. The 'Get Snippet' button is highlighted with a red box. The interface displays training options, including 'Train with AutoML' and 'Custom Train'. Under 'Custom Train', the 'YOLOv8 (New!)' model is selected, and the 'Get Snippet' button is visible. Below this, there is a section for 'IMAGES' showing a list of images and a 'View All Images' link.

The screenshot shows an 'Export' dialog box. The 'Format' dropdown is set to 'YOLOv8'. Below the dropdown, there is a message: 'TXT annotations and YAML config used with YOLOv8.' There are two radio buttons: 'download zip to computer' and 'show download code', with 'show download code' being selected. At the bottom, there are 'Cancel' and 'Continue' buttons, with the 'Continue' button highlighted by a red box.

Copy the code inside the red rectangle

Your Download Code

Jupyter

Terminal

Raw URL

Paste this snippet into [a notebook from our model library >>](#) to download and unzip [your dataset >>](#):

```
!pip install roboflow
```

```
from roboflow import Roboflow
rf = Roboflow(api_key="████████████████████")
project = rf.workspace("geo-data-processing").project("testing-mct3b")
dataset = project.version(1).download("yolov8")
```

Warning: Do not share this snippet beyond your team, it contains a private key that is tied to your Roboflow account. Acceptable use policy applies.

Done

11. Open the Google Colab and copy the code to your own Google Colab script (<https://colab.research.google.com/drive/1ghV3ore6JVpzQQ6a1C1BVWG48RXZLi63?usp=sharing>)

12. Replace this part with your own dataset.

```
[ ] !pip install roboflow --quiet
```

```
from roboflow import Roboflow
rf = Roboflow(api_key="OCgMo7f3BUDqQEW2mxwo")
project = rf.workspace("geo-data-processing").project("plot-feature-detection-version_2")
dataset = project.version(3).download("yolov8")
```

13. Run the whole Google Colab script.

14. After training, you shall see you API Key on the Roboflow website.

The screenshot shows the Roboflow web interface. On the left, a sidebar displays project details for 'Plot Feature Detection Version_2', including a 'Deploy' button highlighted with a red box. The main content area shows the project's version history and a code editor for Python. The code editor displays a snippet for inferring on local and hosted images, with a red box highlighting the initialization of the Roboflow client and the selection of the project and model. The right sidebar contains links to documentation, an example web app, a video inference script, and deployment options for NVIDIA Jetson.

2023-07-06 2:22am Version 2 Generated Jul 6, 2023
Roboflow 3.0 Object Detection (Fast)

plot-feature-detection-version_2/2
96.8% mAP 87.2% Precision 98.2% Recall

Python cURL Javascript Swift .NET

Infer on Local and Hosted Images

To install dependencies, `pip install roboflow`

```
from roboflow import Roboflow
rf = Roboflow(api_key="0CgMo7f3BUDqqEW2mxwo")
project = rf.workspace().project("plot-feature-detection-version_2")
model = project.version(2).model

# infer on a local image
print(model.predict("your_image.jpg", confidence=40, overlap=30).json())

# visualize your prediction
# model.predict("your_image.jpg", confidence=40, overlap=30).save("prediction.jpg")

# infer on an image hosted elsewhere
# print(model.predict("URL_OF_YOUR_IMAGE", hosted=True, confidence=40, overlap=30).json())
```

Roboflow Documentation
Look through our full documentation for more information and resources on how to utilize this model.

Example Web App
Use this model with a full fledged web application that has all sample code included.

Video Inference Script
Our example script performs inference on a video file with Roboflow Infer.

Deploy to NVIDIA Jetson
Perform inference at the edge with a Jetson via our Docker container.

15. Copy the API back to the program and replace it with the original code in the Detection Model.

```
image_original_size = crop_center(img, percent)

#Yolo Object Detection Model
rf = Roboflow(api_key="0CgMo7f3BUDqqEW2mxwo")
project = rf.workspace().project("plot-feature-detection-version_2")
model = project.version(2).model
```