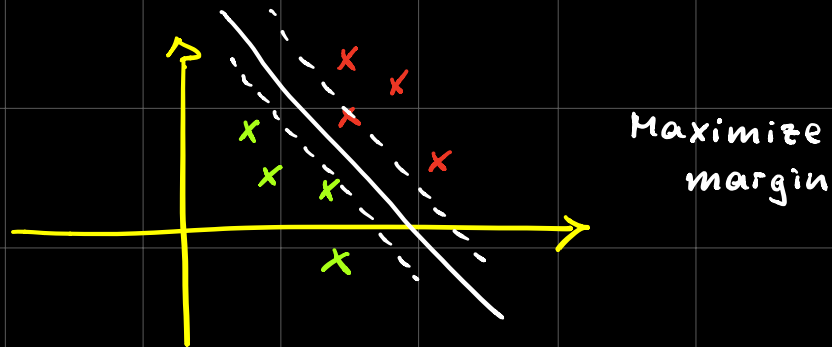


Support Vector Machines



Steps:

1) Set constraints

$$y_i (\vec{x}_i^T \vec{\omega} + b) - 1 \geq 0$$

2) Distance to separating hyperplane:

Minimize $d = \frac{y_i (\vec{x}_i^T \vec{\omega} + b)}{\|\omega\|} \geq \frac{1}{\|\omega\|}$

3) Set Lagrangian:

$$\text{Min } L_P = \frac{1}{2} \|\omega\|^2 - \sum_{i=1}^k \alpha_i y_i (\vec{x}_i^T \vec{\omega} + b) + \sum_{i=1}^k \alpha_i$$

4) Transform into dual:

$$\frac{\partial L_P}{\partial \vec{\omega}} = 0$$

$$\frac{\partial L_P}{\partial b} = 0$$

$$\frac{\partial L_P}{\partial \alpha_i} = \vec{\omega} - \sum \alpha_i y_i \vec{x}_i = 0$$

$\frac{\partial \bar{w}}{\partial b}$

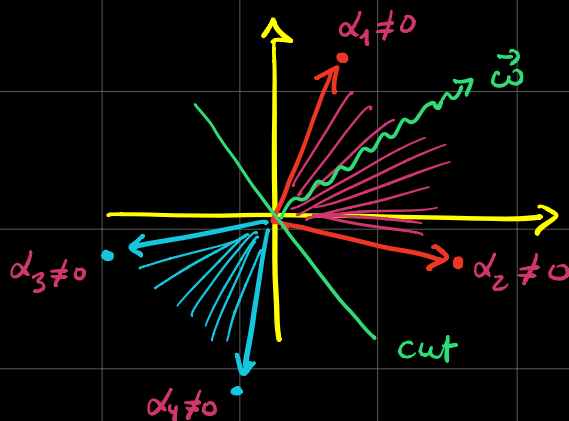
$$\Rightarrow \boxed{\vec{w} = \sum \alpha_i \vec{x}_i y_i}$$

$$\frac{\partial L_D}{\partial b} = \underbrace{\sum \alpha_i y_i}_{\text{sum of positive weights equal in magnitude to sum of negative weights}} = 0$$

sum of positive weights
equal in magnitude to sum
of negative weights

Visualization

in the case $b=0$



\vec{w} is a linear combination of the
vectors closer to the cut.

5) Substituting into L_D

$$\text{Max } L_D = \sum \alpha_i - \frac{1}{2} \sum_i \sum_j \alpha_i \alpha_j y_i y_j \vec{x}_i^T \vec{x}_j$$

$$\text{Max } L_D = \sum \alpha_i - \frac{1}{2} \sum_i \alpha_i y_i (C(x_i) - b)$$

$$\text{If } y_i C(x_i) > 0 \Rightarrow \text{good } \alpha_i = 0$$

$$y_i C(x_i) < 0 \Rightarrow \text{bad } \alpha_i > 0$$

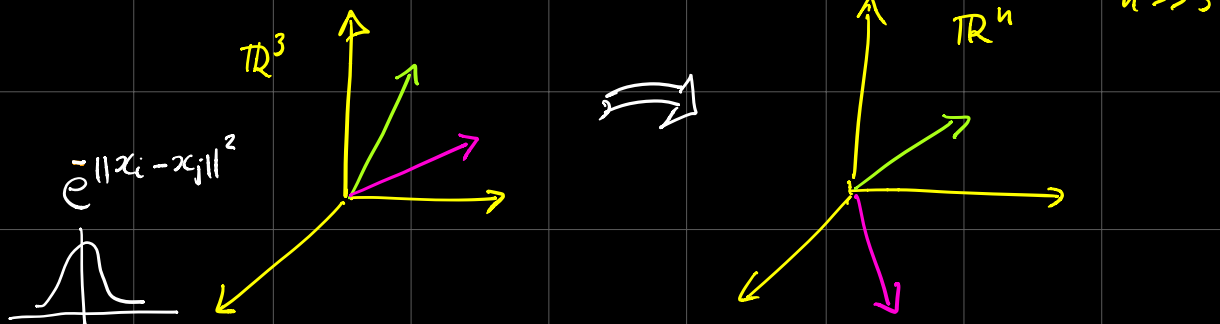
$$C(\vec{x}_i) = \sum \alpha_j y_j \vec{x}_i^T \cdot \vec{x}_j + b$$

6) The dual problem is only a function of the α 's. Solve for α .

For kernels

$$C(x_i) = \sum \alpha_j y_j \underbrace{k(x_i, x_j)}_{\text{instead of inner product}} + b$$

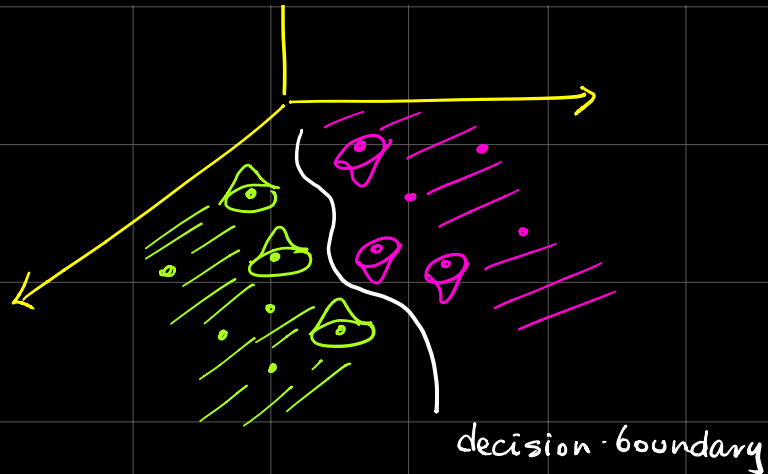
Kernel-trick



there exists a transformation to a high dimensional space where the inner product is identical to the kernel function

Intuition





$$\sum \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i y_i \alpha_j y_j K(\vec{x}_i, \vec{x}_j)$$

$$\text{Max } \boxed{\sum \alpha_i - \frac{1}{2} \sum_i \alpha_i y_i C(x_i)}$$

↑ we want to make the α_i 's big

↑ but increasing α_i can increase this negative term

put the most weight
on points closer to
the cut (wrong $C(x_i)$ or very small)

Numerics

| | \vec{x}_1 | \vec{x}_2 | $\vec{x}_3 \dots$ | \vec{x}_L |
|-------------|-------------|-------------|-------------------|-------------|
| \vec{x}_1 | K_{11} | K_{12} | \dots | K_{1L} |
| \vec{x}_2 | K_{21} | | | |

$$\vec{x}_k \begin{vmatrix} K_{k1} & K_{k2} & \dots & K_{kl} \end{vmatrix}$$

The kernel functions are computed once
It is the generalization of the covariance matrix.

$$\Sigma = X^T X = X X^T = \begin{pmatrix} \vec{x}_1 \\ \vec{x}_2 \\ \vdots \\ \vec{x}_l \end{pmatrix} (\vec{x}_1 \ \vec{x}_2 \ \dots \ \vec{x}_l)$$

The dual problem is

$$\text{Max} \quad \sum \alpha_i - \frac{1}{2} \vec{\alpha}^T \Sigma \vec{\alpha} \quad \alpha_i \geq 0$$

$$\text{where} \quad \vec{\alpha} = \begin{pmatrix} \alpha_1 y_1 \\ \alpha_2 y_2 \\ \vdots \end{pmatrix}$$

Quadratic with constraints

Algorithm

If constraints cannot be kept, we cap the α 's

$$0 \leq \alpha_i \leq C$$

We then solve

$$\text{Max} \quad L_D = \sum \alpha_i - \frac{1}{2} \sum \alpha_i y_i C(\vec{x}_i)$$

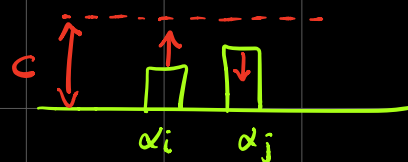
with $0 \leq d_i \leq C$

Procedure

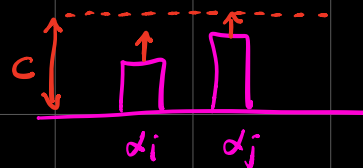
Look for a wrongly classified x_i
with $d_i < C$. Select another x_j

Adjust d_i and d_j

If same class

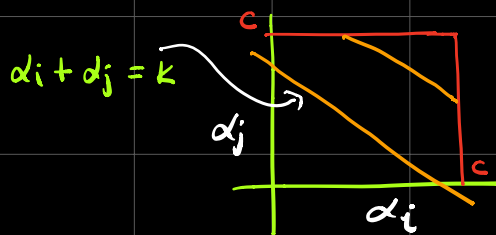


If different class



$$In \quad \left. \sum d_i - \frac{1}{2} \sum_{ij} d_i y_i d_j y_j \vec{x}_i^T \vec{x}_j \right\} \text{Eq.}$$

all d 's are fixed, except the two selected ones. Optimize the quadratic.



SMD algorithm

