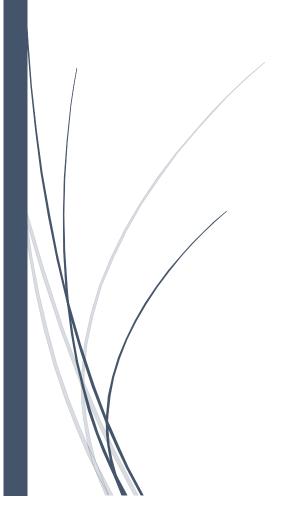
# FUNDAMENTAL OF PROGRAMMING

LAB TASK 9

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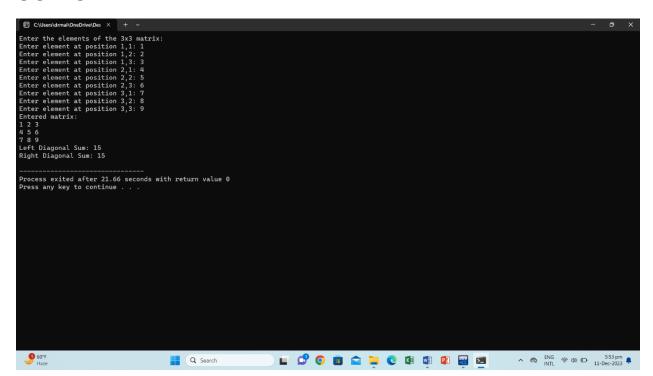
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# Make 2D Array in C++ and print left diagonal and right diagonal sum of a 3x3 matrix

```
#include <iostream>
using namespace std;
int main() {
  int size = 3;
  int matrix[size][size];
  cout<<"Enter the elements of the 3x3 matrix:"<<endl;
  for(int i = 0; i < size; i++){
    for (int j = 0; j < size; j++) {
       cout<<"Enter element at position "<<i+1<<","<<j+1<<": ";
       cin >> matrix[i][j];
    }
  }
  cout << "Entered matrix:" << endl;</pre>
  for (int i = 0; i < size; i++) {
    for (int j = 0; j < size; j++) {
       cout << matrix[i][j] << " ";
    }
    cout << endl;
  }
  int leftDiagonalSum = 0;
  for (int i = 0; i < size; i++) {
```

```
leftDiagonalSum += matrix[i][i];
}
int rightDiagonalSum = 0;
for (int i = 0; i < size; i++) {
    rightDiagonalSum += matrix[i][size - 1 - i];
}
cout << "Left Diagonal Sum: " << leftDiagonalSum << endl;
cout << "Right Diagonal Sum: " << rightDiagonalSum << endl;
return 0;</pre>
```



# Write a function to add two 2D arrays of size 3x3.

```
#include <iostream>
using namespace std;
const int size = 3;
void addMatrices(int mat1[size][size], int mat2[size][size], int result[size][size]) {
  for (int i = 0; i < size; i++) {
    for (int j = 0; j < size; j++) {
       result[i][j] = mat1[i][j] + mat2[i][j];
    }
  }
}
int main() {
  int matrix1[size][size], matrix2[size][size], resultMatrix[size][size];
  cout << "Enter elements for the first 3x3 matrix:" << endl;
  for (int i = 0; i < size; i++) {
    for (int j = 0; j < size; j++) {
       cout << "Enter element at position " << i + 1 << "," << j + 1 << ": ";
       cin >> matrix1[i][j];
    }
  }
  cout << "Enter elements for the second 3x3 matrix:" << endl;
  for (int i = 0; i < size; i++) {
    for (int j = 0; j < size; j++) {
```

```
cout << "Enter element at position " << i + 1 << "," << j + 1 << ": ";
    cin >> matrix2[i][j];
}

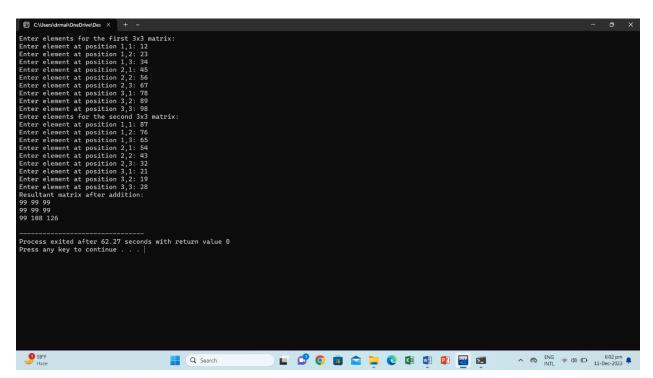
addMatrices(matrix1, matrix2, resultMatrix);

cout << "Resultant matrix after addition:" << endl;

for (int i = 0; i < size; i++) {
    for (int j = 0; j < size; j++) {
        cout << resultMatrix[i][j] << " ";
    }

    cout << endl; }

return 0;
}</pre>
```



# Using 2D arrays in C++, take transpose of a 3x3 matrix. Make a transpose function

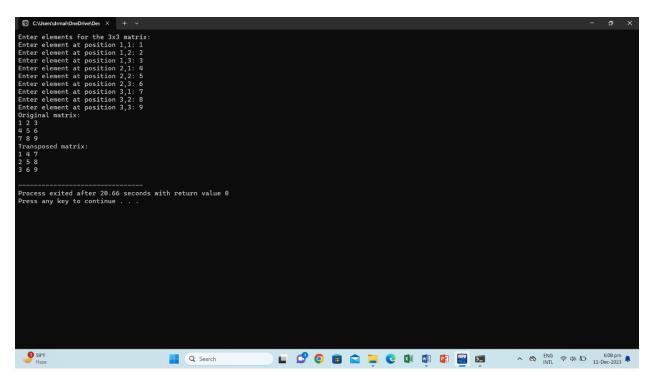
```
#include <iostream>
using namespace std;
const int size = 3;
void transposeMatrix(int original[size][size], int transposed[size][size]) {
  for (int i = 0; i < size; ++i) {
    for (int j = 0; j < size; ++j) {
       transposed[j][i] = original[i][j];
    }
  }
}
int main() {
  int matrix[size][size], transposedMatrix[size][size];
  cout << "Enter elements for the 3x3 matrix:" << endl;</pre>
  for (int i = 0; i < size; ++i) {
    for (int j = 0; j < size; ++j) {
       cout << "Enter element at position " << i + 1 << "," << j + 1 << ": ";
       cin >> matrix[i][j];
    }
  }
  transposeMatrix(matrix, transposedMatrix);
  cout << "Original matrix:" << endl;</pre>
```

```
for (int i = 0; i < size; ++i) {
    for (int j = 0; j < size; ++j) {
        cout << matrix[i][j] << " ";
    }
    cout << endl;
}

cout << "Transposed matrix:" << endl;

for (int i = 0; i < size; ++i) {
    for (int j = 0; j < size; ++j) {
        cout << transposedMatrix[i][j] << " ";}
    cout << endl;}

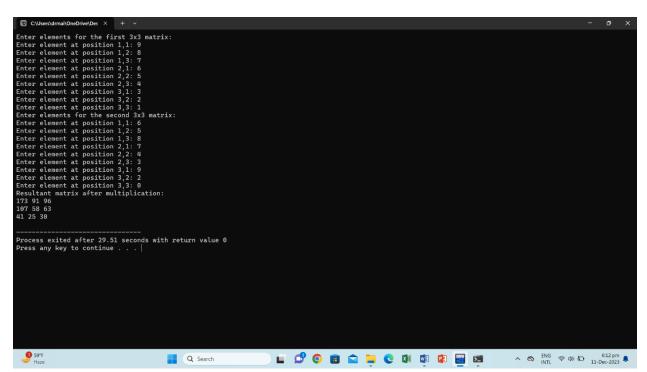
return 0;}</pre>
```



# Using 2D arrays in C++, implement 3x3 matrix multiplication. Make a function.

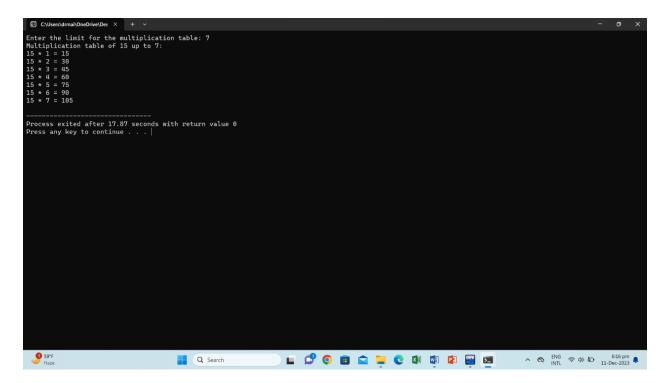
```
#include <iostream>
using namespace std;
const int size = 3;
void multiplyMatrices(int mat1[size][size], int mat2[size][size], int
result[size][size]) {
  for (int i = 0; i < size; ++i) {
    for (int j = 0; j < size; ++j) {
       result[i][j] = 0;
       for (int k = 0; k < size; ++k) {
         result[i][j] += mat1[i][k] * mat2[k][j];
       }
    }
  }
}
int main() {
  int matrix1[size][size], matrix2[size][size], resultMatrix[size][size];
  cout << "Enter elements for the first 3x3 matrix:" << endl;
  for (int i = 0; i < size; ++i) {
    for (int j = 0; j < size; ++j) {
       cout << "Enter element at position " << i + 1 << "," << j + 1 << ": ";
       cin >> matrix1[i][j]; } }
```

```
cout << "Enter elements for the second 3x3 matrix:" << endl;
for (int i = 0; i < size; ++i) {
    for (int j = 0; j < size; ++j) {
        cout << "Enter element at position " << i + 1 << "," << j + 1 << ": ";
        cin >> matrix2[i][j];}    }
multiplyMatrices(matrix1, matrix2, resultMatrix);
cout << "Resultant matrix after multiplication:" << endl;
for (int i = 0; i < size; ++i) {
        cout << resultMatrix[i][j] << " ";}
        cout << endl;}
return 0;}</pre>
```



# Print the multiplication table of 15 using recursion

```
#include <iostream>
using namespace std;
void printMultiplicationTable(int number, int limit, int current) {
  if (current > limit) {
    return;
  }
  cout << number << " * " << current << " = " << number * current << endl;</pre>
  printMultiplicationTable(number, limit, current + 1);
}
int main() {
  const int tableOf = 15;
  int limit;
  cout << "Enter the limit for the multiplication table: ";</pre>
  cin >> limit;
  cout << "Multiplication table of " << tableOf << " up to " << limit << ":" << endl;
  printMultiplicationTable(tableOf, limit, 1);
  return 0;
}
```



Write a C++ program to take inverse of a 3x3 matrix using its determinant and adjoint.

```
#include <iostream>
using namespace std;
const int size = 3;
int determinant(int mat[size][size]) {
    return mat[0][0] * (mat[1][1] * mat[2][2] - mat[2][1] * mat[1][2]) -
        mat[0][1] * (mat[1][0] * mat[2][2] - mat[2][0] * mat[1][2]) +
        mat[0][2] * (mat[1][0] * mat[2][1] - mat[2][0] * mat[1][1]);}
void transposeMatrix(int original[size][size], int transposed[size][size]) {
    for (int i = 0; i < size; ++i) {
        for (int j = 0; j < size; ++j) {</pre>
```

```
transposed[j][i] = original[i][j];} } }
void cofactorMatrix(int mat[size][size], int cofactor[size][size]) {
  for (int i = 0; i < size; ++i) {
    for (int j = 0; j < size; ++j) {
       int sign = ((i + j) \% 2 == 0) ? 1 : -1;
       cofactor[i][j] = sign * determinant(mat[i][j]);} } }
void inverseMatrix(int mat[size][size], int inverse[size][size]) {
  int det = determinant(mat);
  if (det == 0) {
    cout << "The matrix is singular, and its inverse does not exist." << endl;
    return 0;}
  int cofactorMatrix[size][size];
  cofactorMatrix(mat, cofactorMatrix);
  int adjoint[size][size];
  transposeMatrix(cofactorMatrix, adjoint);
  for (int i = 0; i < size; ++i) {
    for (int j = 0; j < size; ++j) {
       inverse[i][j] = adjoint[i][j] / det;} } }
void printMatrix(int mat[size][size]) {
  for (int i = 0; i < size; ++i) {
    for (int j = 0; j < size; ++j) {
       cout << mat[i][j] << " ";}
    cout << endl;}
int main() {
```

```
int matrix[size][size], inverseMatrixResult[size][size];
cout << "Enter elements for the 3x3 matrix:" << endl;
    for (int i = 0; i < size; ++i) {
    for (int j = 0; j < size; ++j) {
        cout << "Enter element at position " << i + 1 << "," << j + 1 << ": ";
        cin >> matrix[i][j];}    }
    inverseMatrix(matrix, inverseMatrixResult);
cout << "Original matrix:" << endl;
printMatrix(matrix);
cout << "\nInverse matrix:" << endl;
printMatrix(inverseMatrixResult);
return 0;}</pre>
```

