# **Laboratory Exercise 10**

### Đỗ Hải Dương - 20194528

### **Assignment 3**

#### Code:

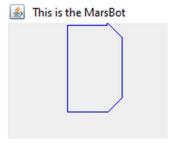
```
1 .eqv HEADING Oxffff8010 # Integer: An angle between 0 and 359
 2 # 0 : North (up)
 3 # 90: East (right)
 4 # 180: South (down)
 5 # 270: West (left)
   .eqv MOVING 0xffff8050 # Boolean: whether or not to move
    .eqv LEAVETRACK 0xfffff8020 # Boolean (0 or non-0):
   # whether or not to leave a track
   .eqv WHEREX 0xfffff8030 # Integer: Current x-location of MarsBot
10
   .eqv WHEREY 0xfffff8040 # Integer: Current y-location of MarsBot
11 .text
12 main:
           #jal TRACK # draw track line
13
14
          addi $a0, $zero, 90 # Marsbot rotates 90* and start running
15
           jal ROTATE
           jal GO
16
17
           nop
18
19 sleep1: addi $v0,$zero,32 # Keep running by sleeping in 5000 ms
     li $a0,5000
20
           syscall
21
          jal UNTRACK # keep old track
22
23
          jal TRACK # and draw new track line
24
25
26
27 goRIGHTDOWN: addi $a0, $zero, 135 # Marsbot rotates 210*
           jal ROTATE
28
30 sleep2: addi $v0, $zero, 32 # Keep running by sleeping in 5000 ms
           li $a0,1000
31
           syscall
32
           jal UNTRACK # keep old track
33
34
           nop
35
           jal TRACK # and draw new track line
36
           nop
37
38 goDOWN: addi $a0, $zero, 180 # Marsbot rotates 210*
39
           jal ROTATE
40
           nop
41 sleep3: addi $v0,$zero,32 # Keep running by sleeping in 5000 ms
          li $a0,3000
43
           syscall
44
            jal UNTRACK # keep old track
45
           nop
           jal TRACK # and draw new track line
46
47
48
```

```
49 goLEFTDOWN: addi $a0, $zero, 225 # Marsbot rotates 330*
            jal ROTATE
50
51
            nop
52
   sleep4: addi $v0,$zero,32 # Keep running by sleeping in 5000 ms
            li $a0,1000
53
54
            syscall
55
            jal UNTRACK # keep old track
56
            nop
            jal TRACK # and draw new track line
57
58
            nop
59
60 goLEFT: addi $a0, $zero, 270 # Marsbot rotates 330*
61
            jal ROTATE
62
            nop
63
   sleep5: addi $v0,$zero,32 # Keep running by sleeping in 5000 ms
            li $a0,2000
64
65
            syscall
66
            jal UNTRACK # keep old track
67
            nop
68
            jal TRACK # and draw new track line
69
            nop
70
           addi $a0, $zero, 0 # Marsbot rotates 330*
71 goUP:
72
            jal ROTATE
```

```
73
74 sleep6: addi $v0,$zero,32 # Keep running by sleeping in 5000 ms
          li $a0,4350
75
76
           syscall
           jal UNTRACK # keep old track
77
78
           nop
           jal TRACK # and draw new track line
79
80
           nop
82 goRIGHT:
83
          addi $a0, $zero, 90 # Marsbot rotates 330*
84
           jal ROTATE
85
           nop
86 sleep7: addi $v0,$zero,32 # Keep running by sleeping in 5000 ms
87
          li $a0,2000
88
           syscall
           jal UNTRACK # keep old track
89
90
          nop
91
           jal TRACK # and draw new track line
92
           nop
93
94 goUP2:
95
           addi $a0, $zero, 0 # Marsbot rotates 330*
96
           jal ROTATE
```

```
97
98 sleep8:
99
         addi $v0,$zero,32 # Keep running by sleeping in 5000 ms
100
         li $a0,2000
101
         syscall
102
        jal UNTRACK # keep old track
103
        nop
         jal TRACK # and draw new track line
104
105
         nop
106
107 sleep:
108
         addi $v0,$zero,32 # Keep running by sleeping in 1000 ms
109
        li $a0,0
110
        syscall
         j STOP
111
112
113 end main:
114 #-----
115 # GO procedure, to start running
116 # param[in] none
117 #-----
118 GO:
119
        li $at, MOVING # change MOVING port
   li Şat, Moving # January addi ŞkO, Şzero,1 # to logic 1,
120
sb $k0, 0($at) # to start running
122
         jr $ra
123
         nop
124 #-----
125 # STOP procedure, to stop running
126 # param[in] none
127 #-----
128 STOP:
129 li Şat, MOVING # change MOVING port to 0
         sb $zero, O($at) # to stop
130
131
          jr $ra
132
         nop
133 #-----
134 # TRACK procedure, to start drawing line
135 # param[in] none
136 #-----
137 TRACK:
    li Şat, LEAVETRACK # change LEAVETRACK port
138
         addi $k0, $zero,1 # to logic 1,
139
         sb $k0, 0($at) # to start tracking
140
141
         jr $ra
142 #-----
143 # UNTRACK procedure, to stop drawing line
144 # param[in] none
145 #-----
146 UNTRACK:
147 li Şat, LEAVETRACK # change LEAVETRACK port to 0
148
          sb $zero, 0($at) # to stop drawing tail
149
         jr $ra
150
         nop
152 # ROTATE procedure, to rotate the robot
153 # param[in] $a0, An angle between 0 and 359
154 # 0 : North (up)
155 # 90: East (right)
156 # 180: South (down)
157 # 270: West (left)
158 #-----
159 ROTATE:
160 li Şat, HEADING # change HEADING port
         sw $a0, 0($at) # to rotate robot
161
162
          jr $ra
       nop
163
164
```

### Kết quả:



Chữ D (tên Dương)

# **Assignment 4**

#### Code:

```
1 .eqv KEY_CODE 0xFFFF0004 # ASCII code from keyboard, 1 byte
2 .eqv KEY_READY 0xFFFF0000 # =1 if has a new keycode ?
3 # Auto clear after lw
4 .eqv DISPLAY_CODE 0xffff000C # ASCII code to show, 1 byte
5 .eqv DISPLAY_READY 0xFFFFF0008 # =1 if the display has already to do
6 # Auto clear after sw
7 .eqv e 0x65
8 .eqv x 0x78
9 .eqv i 0x69
10 .eqv t 0x74
11 .text
           li $k0, KEY_CODE
12
           li $k1, KEY_READY
13
14 li $
15 li $
16 loop: nop
          li $s0, DISPLAY_CODE
           li $s1, DISPLAY_READY
17 WaitForKey:
18 lw $t1, 0($k1)
                                          \# $t1 = [$k1] = KEY READY
                                          # if $t1 == 0 then Polling
19
           beq $t1, $zero, WaitForKey
20 ReadKey:
21
22
           lw $t0, 0($k0)
                                           # $t0 = [$k0] = KEY CODE
           j check_e
23 WaitForDis:
24
           lw $t2, 0($s1)
                                          # $t2 = [$s1] = DISPLAY_READY
           beq $t2, $zero, WaitForDis
                                         # if $t2 == 0 then Polling
           sw $t0, 0($s0)
                                         # show key
27
28
           nop
29
           j loop
 30 check_e:
          beq $t3, e, check_x
                                         # if character e exist then check x
31
           bne $t0, e, WaitForDis
                                         # if character != e then continue
32
           add $t3, $t0, $0
                                         # else $t3 = 'e'
33
34
          j WaitForDis
 35
36 check_x:
                                         # if character x exist then check i
37
           beq $t4, x, check_i
38
           bne $t0, x, reset
                                         # if character != i then continue
           add $t4, $t0, $0
                                         # else $t4 = 'x'
           j WaitForDis
40
41 check i:
42
 43
           beq $t5, i, check_t
                                         # if character i exist then check t
           bne $t0, i, reset
                                         # if character != t then continue
44
           add $t5, $t0, $0
                                         # else $t5 = 't'
45
           j WaitForDis
46
48 check_t:
```

```
49
50
           beq $t0, t, exit
                                            # if character t exist then exit
           j reset
51
                                   # if character != t then continue
52 reset: li $t3, 0
                                           # reset 'e' to 0
           li $t4, 0
                                           # reset 'x' to 0
# reset 'i' to 0
53
54
           li $t5, 0
55
            j WaitForDis
56
57 exit: li $v0, 10
58
            syscall
59
```

# Kết quả:

