Freescale Semiconductor

User's Manual Addendum

MCF5282UMAD Rev. 14, 11/2006

MCF5282 User's Manual Errata

by: Microcontroller Division

This errata document describes corrections to the *MCF5282 ColdFire Microcontroller User's Manual*, order number MCF5282UM. For convenience, the addenda items are grouped by revision. Please check our website at http://www.freescale.com for the latest updates.

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Table 1. MCF5282UM Rev 2.3 Errata

Location	Description
Table 5-1/Page 5-2	The PRI1/PRI2 text description does not match the table below it. It should be: "If a bit is
	set, CPU has priority. If a bit is cleared, DMA has priority."
Chapter 8	Remove any references to the core watchdog timer being able to reset the device. It is only able to interrupt the processor. Use the peripheral watchdog timer described in Chapter 18 if needing a watchdog timer to reset the device.
Table 9-4/Page 9-7	In the table for MFD bit definition, footnote (1) equation should read:
	$f_{sys} = \frac{f_{ref} \times 2(MFD + 2)}{2^{RFD}}; f_{ref} \times 2(MFD + 2) \le f_{sys(max)}; f_{sys} \le f_{sys(max)}$
	Where f _{sys(max)} is the maximum system frequency for the particular MCF5282 device (66MHz or 80MHz)
Section 10.3.6/Page 10-11	Include the following text in the section description and as a note in Figure 10-9.
	"It is the responsibility of the software to program the ICRnx registers with unique and non-overlapping level and priority definitions. Failure to program the ICRnx registers in this manner can result in undefined behavior. If a specific interrupt request is completely unused, the ICRnx value can remain in its reset (and disabled) state."
Figure 10-6/Page 10-9	Interrupt Force Register Low (INTFRCLn) is illustrated as read-only in the figure. However, this register should be read/write.
Table 10-14/Page 10-15	Change flag clearing mechanism for sources 24-26. They should read as follows: Write ERR_INT = 1 after reading ERR_INT = 1 Write BOFF_INT = 1 after reading BOFF_INT = 1 Write WAKE_INT = 1 after reading WAKE_INT = 1
Table 12-7/Page 12-7	BAM bit field description, the first example should read "So, if CSAR0 = 0x0000 and CSMR0[BAM] = 0x0001" instead of "So, if CSAR0 = 0x0000 and CSMR0[BAM] = 0x0008".
Table 15-1/Page 15-3	NOP command entry. Replace "SRAS asserted" with "SDRAM_CS[1:0] asserted"
Chapter 17	The maximum buffer size of the FEC is 2032 bytes. Replace any mention of the max size being 2047 bytes with 2032 bytes.
Table 17-11/Page 17-19	Add RMON_R_DROP with an IPSBAR Offset of 0x1280 and a description of 'Count of frames not counted correctly'.
Figure 17-26/Page 17-41	Change EMRBR register address from "IPSBAR + 0x11B8" to "IPSBAR + 0x1188".
Section 20.5.13/Page 20-12	Deleted reference to nonexistent CF bits in the figure and bit descriptions for the GPTFLG2 register.
Figure 23-18/Page 23-18	Remove the two 16-bit divider blocks from timer input, as the divider is not available using external clock sources.
Section 23.5.1.2.2/Page 23-19	Remove 16-bit divider from equation, as the divider is not available using external clock sources.
Section 25.5.8/Page 25-25	Change end of last sentence from "and can be written by the host to '0'." to "and can be written by the host to '1'."

Table 1. MCF5282UM Rev 2.3 Errata (continued)

Location		Description							
Table 25-17/Page 25-29	Cł	Remove the following information from the BITERR and ACKERR descriptions as these fields are read only: "To clear this bit, first read it as a one, then write it as a one. Writing zero has no effect." (This is a rescindment of a previous documentation errata.) Change last sentence in ERRINT description from: "To clear this bit, first read it as a one, then write as a zero. Writing a one has no effect." to "To clear this bit, first read it as a one, then write a one. Writing a zero has no effect." Add the following information to the BOFFINT and WAKEINT descriptions: "To clear this bit, first read it as a one, then write it as a one. Writing zero has no effect."							
Table 25-17/Page 25-27	De	Definition of bits ERRINT and BOFFINT are incorrect for register ESTAT: ERRINT should be bit 1, BOFFINT should be bit 2. They should be cleared by writing a one instead of a zero.							
Table 26-1/Page 26-5	Cł	Change description field for DTOUT1 from "DMA timer 1 output / Port TD[3]" to "DMA timer 1 output / Port TD[2]" Change description field for DTIN0 from "DMA timer 0 input / Port TD[3]" to "DMA timer 1 output / Port TD[1]" Change description field for DTOUT0 from "DMA timer 0 output / Port TD[3]" to "DMA timer 1 output / Port TD[0]"							
Chapter 33	Ac	dd the following note: "It is crucial during power-up that ' are diode devices between the two latch-up condition."							
Table 33-3/Page 33-3	In	the V_{OH} and V_{OL} entries, change to " I_{OH} = -5.0mA" and " I_{OL} = +2.0			I _{OL} specs	from "I _{OH}	= -2.0mA"		
Table 33-8/Page 33-7	In	the PLL Electrical Specifications to listed. Insert specs for the 66MHz $f_{\text{sys(max)}}$, as shown below:							
		Characteristic	Symbol	Min	Ma	X	Unit		
		Characteristic	Symbol	IVIIII	66MHz	80MHz	O'IIIC		
		PLL Reference Frequency Range Crystal reference External reference	f _{ref_crystal}	2 2	8.33 8.33	10.0 10.0	MHz		
		1:1 Mode	f _{ref_ext} f _{ref_1:1}	33.33	66.66	80			
			f _{ref_1:1}				MHz		
Section 33.13.1/Page 33-21	Re	1:1 Mode System Frequency ¹ External Clock Mode	f _{ref_1:1}	33.33 0 f _{ref} / 32	66.66 f _{sys(max)} 66.66	f _{sys(max)}	MHz		
Section 33.13.1/Page 33-21 Section 33.13.2/Page 33-22	Re	1:1 Mode System Frequency ¹ External Clock Mode On-Chip PLL Frequency emove second sentence: "There is no minimum frequ	f _{ref_1:1} f _{sys} Hency require the requirement is not D[3:0], ETX ing or falling tions allows	0 f _{ref} / 32 rement." rement." supported EN, ETXE g edge of Es the use of	f _{sys(max)} 66.66 66.66 60.66	f _{sys(max)} 80 80 80 vice: programmed the timi	ed to		

2 Errata for Revision 2.1 & 2.2

Table 2. MCF5282UM Rev 2.1 & 2.2 Errata

Location	Description
Figure 4-2/4-6	Changed bit 23 from DIDI to DISI
Table 4-6/4-9	Under 'Configuration' for 'Instruction Cache' the 'Operation' entry changed to "Invalidate 2 KByte data cache"
Table 4-6/4-9	Under 'Configuration' for 'Data Cache' the 'Operation' entry changed to "Invalidate 2 KByte instruction cache"
Figure 6-3/6-6	Changed bit 8 to write-only instead of read/write
Table 6-10/6-15	Removed "selected by BKSL[1:0]" as these are internal signal names not necessary for end-user.
Table 9-4/9-7	In the table for MFD bit definition, footnote (1) equation should read:
	$f_{sys} = \frac{f_{ref} \times 2(MFD + 2)}{2^{RFD}}; f_{ref} \times 2(MFD + 2) \le f_{sys(max)}; f_{sys} \le f_{sys(max)}$
	Where f _{sys(max)} is the maximum system frequency for the particular MCF5282 device (66MHz or 80MHz)
10.3.2/10-8	Add the following note: 'If an interrupt source is being masked in the interrupt controller mask register (IMR) or a module's interrupt mask register while the interrupt mask in the status register (SR[I]) is set to a value lower than the interrupt's level, a spurious interrupt may occur. This is because by the time the status register acknowledges this interrupt, the interrupt has been masked. A spurious interrupt is generated because the CPU cannot determine the interrupt source. To avoid this situation for interrupts sources with levels 1-6, first write a higher level interrupt mask to the status register, before setting the mask in the IMR or the module's interrupt mask register. After the mask is set, return the interrupt mask in the status register to its previous value. Since level seven interrupts cannot be disabled in the status register prior to masking, use of the IMR or module interrupt mask registers to disable level seven interrupts is not recommended.'
Chapter 17	The maximum buffer size of the FEC is 2032 bytes. Replace any mention of the max size being 2047 bytes with 2032 bytes.
Table 17-2/17-5	In PALR/PAUR entry, delete "(only needed for full duplex flow control)"
Figure 17-23/17-39	Change FRSR to read/write instead of read-only.
25.4.10/25-16	Change CANICR to ICRn.
Table 25-17/25-29	Add the following information to BITERR and ACKERR descriptions: "To clear this bit, first read it as a one, then write it as a one. Writing zero has no effect."
Table 25-17/25-30	Change bit ordering: ERRINT should be bit 2 and BOFFINT should be bit 1.
Table 25-19/25-32	Change BUF nl field description from "To clear an interrupt flag, first read the flag as a one, then write it as a zero" to "To clear an interrupt flag, first read the flag as a one, then write it as a one."

Table 2. MCF5282UM Rev 2.1 & 2.2 Errata (continued)

Location		Description								
Chapter 33		t is crucial during power-up that VDD never exceeds VDDH by more that ~0.3V. There are diode devices between the two voltage domains, and violating this rule can lead to a latch-up condition.								
Table 33-8/33-7	•	, , ,		es for the 80MHz MCF5282 device were first 2 rows and also declare symbol						
	Characteristic	Characteristic Symbol Min U				Unit				
	Onaracteristic	Cymbol		8.33 10.0 8.33 10.0 66.66 80		Oilit				
	PLL Reference Frequency Range Crystal reference External reference 1:1 Mode	f _{ref_crystal} f _{ref_ext} f _{ref_1:1}	2 2 33.33			MHz				
	System Frequency ¹ External Clock Mode On-Chip PLL Frequency	f _{sys}	0 f _{ref} / 32	f _{sys(max)} 66.66 66.66	f _{sys(max)} 80 80	MHz				

Table 3. MCF5282UM Rev 2.0 Errata

Location	Description
Table 33-8/33-9	Reference to 'TA = TL to TH' was not deleted. Delete.

4 Errata for Revision 1.0

Table 4. MCF5282UM Rev 1.0 Errata

Location	Description
1.1/1-1	Change 'Real time debug support, with two user-visible hardware breakpoint registers' To 'Real time debug support, with one user-visible hardware breakpoint register'
Table 2-2/2-7	Change the I field description to read: "Interrupt level mask. Defines the current interrupt level. Interrupt requests are inhibited for all priority levels less than or equal to the current level, except the edge-sensitive level 7 request, which cannot be masked."

Table 4. MCF5282UM Rev 1.0 Errata (continued)

Location		Description								
Table 5-1/5-2	Replace the	Replace the description of PRI1 and PRI2 with the following:								
		Description								
	Priority bit. PRI1 determines if DMA or CPU has priority in upper 32K bank of memory. PRI2 determines if DMA or CPU has priority in lower 32K bank of memory. If bit is set, DMA has priority. If bit is reset, CPU has priority. Priority is determined according to the following table.									
		PRI[1:2]	Upper Bank Priority	Lower Bank Priority						
		00	DMA Accesses	DMA Accesses	1					
		01	DMA Accesses	CPU Accesses	†					
		10	CPU Accesses	DMA Accesses						
		11	CPU Accesses	CPU Accesses]					
	NOTE:	The Motorola-recom	mended setting for th	e priority bits is 00.						
Table 5-1/5-3	register m	ust also be set to all	/ bit description: "The ow dual port access t ase Address Register	o the SRAM. For mo						

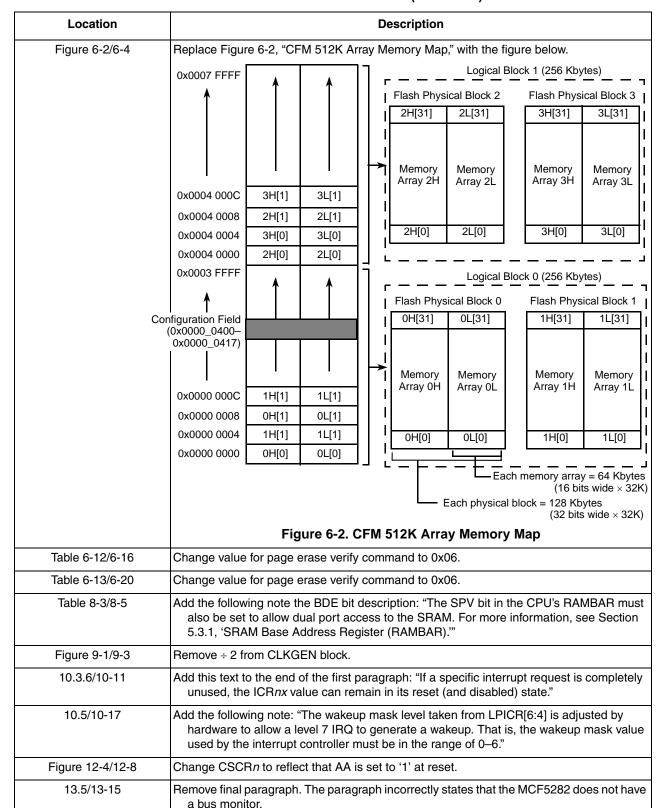


Table 4. MCF5282UM Rev 1.0 Errata (continued)

Table 4. MCF5282UM Rev 1.0 Errata (continued)

Location	Description
Table 17-13/17-26	Change encodings for bits 31–9 to: 0The corresponding interrupt source is masked. 1The corresponding interrupt source is not masked.
Chapter 19	Change PIT1–PIT4 to PIT0–PIT3 throughout chapter. When a timer is referenced individually, PIT1 should be PIT0, PIT2 should be PIT1, PIT3 should be PIT2, and PIT4 should be PIT3. Other chapters in the user's manual use the correct nomenclature: PIT0–PIT3.
19.6.3/19-7	Change timeout period equation to the equation below. Timeout period = $\frac{PRE[3:0] \times (PM[15:0] + 1) \times 2}{system clock}$
Figure 23-11	Change UISR bits 5–3 to reserved bits
24.6.1/24-11	Change 'I2CR = 0xA' to 'I2CR = 0xA0.'
27.2.1/27-2	Change 'When interfacing to 16-bit ports, the port C and D pins and PJ[7:6] (BS[3:2]) can be configured as general-purpose input/output (I/O)' To 'When interfacing to 16-bit ports, the port C and D pins and PJ[5:4] (BS[1:0]) can be configured as general-purpose input/output (I/O)'
32.2/32-7	Added additional device number order information to Table 32-2.

Table 32-2. Orderable Part Numbers

Motorola Part Number	Description	Speed	Temperature		
MCF5280CVF66	MCF5280 RISC Microprocessor, 256 MAPBGA	66.67 MHz	-40° to +85° C		
MCF5280CVF80	MCF5280 RISC Microprocessor, 256 MAPBGA	80 MHz	-40° to +85° C		
MCF5281CVF66	MCF5281 RISC Microprocessor, 256 MAPBGA	66.67 MHz	-40° to +85° C		
MCF5281CVF80	MCF5281 RISC Microprocessor, 256 MAPBGA	80 MHz	-40° to +85° C		
MCF5282CVF66	MCF5282 RISC Microprocessor, 256 MAPBGA	66.67 MHz	-40° to +85° C		
MCF5282CVF80	MCF5282 RISC Microprocessor, 256 MAPBGA	80 MHz	-40° to +85° C		
Chapter 33	Delete references to 'TA = TL to TH'.				
able 33-1/33-1	The Digital Input Voltage ($V_{\mbox{\scriptsize IN}}$) absolute maximum rating should be -0.3 to 6.0 V				
able 33-6/33-8	The normal operation analog supply current (I _{DDA}) 5.0 mA.	maximum val	ue has been ch		

Table 4. MCF5282UM Rev 1.0 Errata (continued)

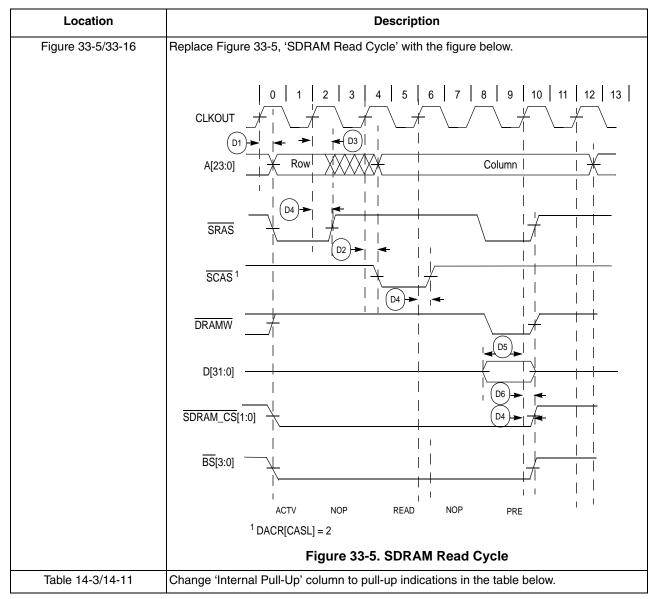


Table 14-3. MCF5282 Signals and Pin Numbers Sorted by Function

MAPBGA Pin	Pii	n Functions		Description	Primary	Internal Pull-up		
WAFBGA FIII	Primary ²	Secondary Tertiary	I/O	1				
Reset								
R11	RSTI	_	_	Reset in	1	Yes		
P11	RSTO	_	_	Reset out	0	_		
Clock								
T8	EXTAL	_	_	External clock/crystal in	1	_		

Table 14-3. MCF5282 Signals and Pin Numbers Sorted by Function (continued)

MADDCADia	Pi	n Functions		D	Primary	Internal
MAPBGA Pin	Primary ²	Secondary	Tertiary	- Description	1/0	Pull-up
R8	XTAL	_	_	Crystal drive	0	_
N7	CLKOUT	_	_	Clock out	0	_
	(Chip Configura	tion/Mode	Selection	-	
R14	CLKMOD0	_	_	Clock mode select	I	Yes
T14	CLKMOD1	_	_	Clock mode select	I	Yes
T11	RCON	_		Reset configuration enable	I	Yes
H1	D26	PA2	_	Chip mode	I/O	_
K2	D17	PB1		Chip mode	I/O	_
K3	D16	PB0		Chip mode	I/O	_
J4	D19	PB3		Boot device/data port size	I/O	_
K1	D18	PB2		Boot device/data port size	I/O	_
J2	D21	PB5		Output pad drive strength	I/O	_
	E	xternal Memor	y Interface	and Ports		
C6:B6:A5	A[23:21]	PF[7:5]	CS[6:4]	Address bus	0	Yes
C4:B4:A4:B3:A3	A[20:16]	PF[4:0]	_	Address bus	0	Yes
A2:B1:B2:C1: C2:C3:D1:D2	A[15:8]	PG[7:0]	_	Address bus	0	Yes
D3:D4:E1:E2: E3:E4:F1:F2	A[7:0]	PH[7:0]	_	Address bus	0	Yes
F3:G1:G2:G3: G4:H1:H2:H3	D[31:24]	PA[7:0]	_	Data bus	I/O	_
H4:J1:J2:J3: J4:K1:K2:K3	D[23:16]	PB[7:0]	_	Data bus	I/O	_
L1:L2:L3:L4: M1:M2:M3:M4	D[15:8]	PC[7:0]	_	Data bus	I/O	_
N1:N2:N3:P1: N5:T6:R6:P6	D[7:0]	PD[7:0]	_	Data bus	I/O	_
P14:T15:R15:R16	BS[3:0]	PJ[7:4]		Byte strobe	I/O	Yes
N16	ŌĒ	PE7	_	Output enable	I/O	_
P16	TA	PE6	_	Transfer acknowledge	I/O	Yes
P15	TEA	PE5	_	Transfer error acknowledge	I/O	Yes
N15	R/W	PE4	_	Read/write	I/O	Yes
N14	SIZ1	PE3	SYNCA	Transfer size	I/O	Yes ³

Table 14-3. MCF5282 Signals and Pin Numbers Sorted by Function (continued)

	Pin Functions				Primary	Internal
MAPBGA Pin	Primary ²	Secondary	Tertiary	- Description	1/0	Pull-up 1
M16	SIZ0	PE2	SYNCB	Transfer size	I/O	Yes ⁴
M15	TS	PE1	SYNCA	Transfer start	I/O	Yes
M14	TIP	PE0	SYNCB	Transfer in progress	I/O	Yes
		Chi	p Selects		1	J
L16:L15:L14:L13	CS[3:0]	PJ[3:0]	_	Chip selects 3-0	I/O	Yes
C6:B6:A5	A[23:21]	PF[7:5]	CS[6:4]	Chip selects 6-4	0	Yes
		SDRAI	M Controlle	r	I	
H15	SRAS	PSD5	_	SDRAM row address strobe	I/O	<u> </u>
H16	SCAS	PSD4	_	SDRAM column address strobe	I/O	_
G15	DRAMW	PSD3	_	SDRAM write enable	I/O	_
H13:G16	SDRAM_CS[1:0]	PSD[2:1]	_	SDRAM chip selects	I/O	_
H14	SCKE	PSD0	_	SDRAM clock enable	I/O	_
	•	External	Interrupts F	Port	1	•
B15:B16:C14:C15: C16: D14:D15	ĪRQ[7:1]	PNQ[7:1]	_	External interrupt request	I/O	_
		E	thernet		1	J
C10	EMDIO	PAS5	URXD2	Management channel serial data	I/O	_
B10	EMDC	PAS4	UTXD2	Management channel clock	I/O	_
A8	ETXCLK	PEH7	_	MAC Transmit clock	I/O	_
D6	ETXEN	PEH6	_	MAC Transmit enable	I/O	_
D7	ETXD0	PEH5	_	MAC Transmit data	I/O	_
B11	ECOL	PEH4	_	MAC Collision	I/O	_
A10	ERXCLK	PEH3	_	MAC Receive clock	I/O	_
C8	ERXDV	PEH2	_	MAC Receive enable	I/O	_
D9	ERXD0	PEH1	_	MAC Receive data	I/O	_
A11	ECRS	PEH0		MAC Carrier sense	I/O	
A7:B7:C7	ETXD[3:1]	PEL[7:5]	_	MAC Transmit data	I/O	_
D10	ETXER	PEL4	_	MAC Transmit error	I/O	_
A9:B9:C9	ERXD[3:1]	PEL[3:1]	_	MAC Receive data	I/O	
B8	ERXER	PEL0	_	MAC Receive error	I/O	-

Table 14-3. MCF5282 Signals and Pin Numbers Sorted by Function (continued)

MADDOADin	Pin Functions			Description	Primary	Internal			
MAPBGA Pin	Primary ²	Secondary	Tertiary	Description	1/0	Pull-up 1			
	FlexCAN								
D16	CANRX	PAS3	URXD2	FlexCAN Receive data	I/O	_			
E13	CANTX	PAS2	UTXD2	FlexCAN Transmit data	I/O	_			
			I ² C	•	<u> </u>				
E14	SDA	PAS1	URXD2	I ² C Serial data	I/O	Yes ⁵			
E15	SCL	PAS0	UTXD2	I ² C Serial clock	I/O	Yes ⁶			
	1		QSPI	1					
F13	QSPI_DOUT	PQS0	_	QSPI data out	I/O	_			
E16	QSPI_DIN	PQS1	_	QSPI data in	I/O	_			
F14	QSPI_CLK	PQS2	_	QSPI clock	I/O	_			
G14:G13:F16:F15	QSPI_CS[3:0]	PQS[6:3]	_	QSPI chip select	I/O	_			
	-	ι	JARTs		•				
R7	URXD1	PUA3	_	U1 receive data	I/O	_			
P7	UTXD1	PUA2	_	U1 transmit data	I/O	_			
N6	URXD0	PUA1	_	U0 receive data	I/O	_			
T7	UTXD0	PUA0	_	U0 transmit data	I/O	_			
C10	EMDIO	PAS5	URXD2	U2 receive data	I/O	_			
B10	EMDC	PAS4	UTXD2	U2 transmit data	I/O	_			
D16	CANRX	PAS3	URXD2	U2 receive data	I/O	_			
E13	CANTX	PAS2	UTXD2	U2 transmit data	I/O	_			
E14	SDA	PAS1	URXD2	U2 receive data	I/O	Yes ⁵			
E15	SCL	PAS0	UTXD2	U2 transmit data	I/O	Yes ⁶			
K16	DTIN3	PTC3	URTS1/ URTS0	U1/U0 Request to Send	I/O	_			
K15	DTOUT3	PTC2	URTS1/ URTS0	U1/U0 Request to Send	I/O	_			
K14	DTIN2	PTC1	UCTS1/ UCTS0	U1/U0 Clear to Send	I/O	_			
K13	DTOUT2	PTC0	UCTS1/ UCTS0	U1/U0 Clear to Send	I/O	_			
J16	DTIN1	PTD3	URTS1/ URTS0	U1/U0 Request to Send	I/O	_			

Table 14-3. MCF5282 Signals and Pin Numbers Sorted by Function (continued)

MAPBGA Pin	Pin Functions			Description	Primary	Internal
	Primary ²	Secondary	Tertiary	- Description	I/O	Pull-up 1
J15	DTOUT1	PTD2	URTS1/ URTS0	U1/U0 Request to Send	I/O	_
J14	DTIN0	PTD1	UCTS1/ UCTS0	U1/U0 Clear to Send	I/O	_
J13	DTOUT0	PTD0	UCTS1/ UCTS0	U1/U0 Clear to Send	I/O	_
		General P	urpose Tin	ners		
T13:R13:P13:N13	GPTA[3:0]	PTA[3:0]	_	Timer A IC/OC/PAI	I/O	Yes
T12:R12:P12:N12	GPTB[3:0]	PTB[3:0]	_	Timer B IC/OC/PAI	I/O	Yes
N14	SIZ1	PE3	SYNCA	Timer A synchronization input	I/O	Yes ³
M16	SIZ0	PE2	SYNCB	Timer B synchronization input	I/O	Yes ⁴
M15	TS	PE1	SYNCA	Timer A synchronization input	I/O	Yes
M14	TIP	PE0	SYNCB	Timer B synchronization input	I/O	Yes
		DM	A Timers			
K16	DTIN3	PTC3	URTS1/ URTS0	Timer 3 in	I/O	_
K15	DTOUT3	PTC2	URTS1/ URTS0	Timer 3 out	I/O	_
K14	DTIN2	PTC1	UCTS1/ UCTS0	Timer 2 in	I/O	_
K13	DTOUT2	PTC0	UCTS1/ UCTS0	Timer 2 out	I/O	_
J16	DTIN1	PTD3	URTS1/ URTS0	Timer 1 in	I/O	_
J15	DTOUT1	PTD2	URTS1/ URTS0	Timer 1 out	I/O	_
J14	DTIN0	PTD1	UCTS1/ UCTS0	Timer 0 in	I/O	_
J13	DTOUT0	PTD0	UCTS1/ UCTS0	Timer 0 out	I/O	_
	Queu	ed Analog-to-	Digital Con	verter (QADC)		1
T3	AN0	PQB0	ANW	Analog channel 0	I/O	_
R2	AN1	PQB1	ANX	Analog channel 1	I/O	_
T2	AN2	PQB2	ANY	Analog channel 2	I/O	_
R1	AN3	PQB3	ANZ	Analog channel 3	I/O	_

Table 14-3. MCF5282 Signals and Pin Numbers Sorted by Function (continued)

MAPBGA Pin	Pin Functions			Description	Primary	Internal
MAPBGA PIN	Primary ²	Secondary	Tertiary	- Description	1/0	Pull-up 1
R4	AN52	PQA0	MA0	Analog channel 52	I/O	_
T4	AN53	PQA1	MA1	Analog channel 53	I/O	_
P3	AN55	PQA3	ETRIG1	Analog channel 55	I/O	_
R3	AN56	PQA4	ETRIG2	Analog channel 56	I/O	_
P4	VRH	_	_	High analog reference	ı	_
T5	VRL	_	_	Low analog reference	ı	_
	Γ	Debug and JTA	AG Test Por	t Control		•
R9	JTAG_EN	_	_	JTAG Enable	I	_
P9	DSCLK	TRST	_	Debug clock / TAP reset	I	Yes ⁷
Т9	TCLK	_	_	TAP clock	Į	Yes ⁷
P10	ВКРТ	TMS	_	Breakpoint/TAP test mode select	I	Yes ⁷
R10	DSI	TDI	_	Debug data in / TAP data in	I	Yes ⁷
T10	DSO	TDO	_	Debug data out / TAP data out	0	_
C12:D12:A13:B13	DDATA[3:0]	PDD[7:4]	_	Debug data	I/O	_
C13:A14:B14:A15	PST[3:0]	PDD[3:0]	_	Processor status data	I/O	_
			Test			
N10	TEST	_		Test mode pin	I	_
	1	Powe	er Supplies			
R5	VDDA	_	_	Analog positive supply	I	_
P5:T1	VSSA	_	_	Analog ground	I	_
P2	VDDH	_	_	ESD positive supply	I	_
N8	VDDPLL	_	_	PLL positive supply	I	_
P8	VSSPLL	_	_	PLL ground	I	_
A6:C11	VPP	_	_	Flash (stress) programming voltage	I	_
A12:C5:D5:D11	VDDF	_	_	Flash positive supply	ı	_
B5:B12:	VSSF	_	_	Flash module ground	ı	_
N11	VSTBY	_	_	Standby power	ı	_

Table 14-3. MCF5282 Signals and Pin Numbers Sorted by Function (continued)

MAPBGA Pin	Pin Functions			Description	Primary	Internal Pull-up
	Primary ²	Secondary	Tertiary	Description	I/O	1
E6-E11:F5:F7-F10: F12:G5:G6:G11: G12:H5:H6:H11: H12:J5:J6:J11:J12: K5:K6:K11:K12:L5: L7-L10:L12: M6-M11	VDD	_	ı	Positive supply	I	_
A1:A16:E5:E12:F6: F11:G7-G10:H7-H10: J7-J10:K7-K10:L6: L11:M5:M12:T16	VSS	_		Ground	I	_

NOTES:

- ¹ Pull-ups are not active when GPIO functions are selected for the pins.
- The primary functionality of a pin is not necessarily its default functionality. Pins that have GPIO functionality will default to GPIO inputs.
- Pull-up is active only with the SYNCA function.
- $^{4}\,\,$ Pull-up is active only with the SYNCB function.
- 5 Pull-up is active only with the SDA function.
- ⁶ Pull-up is active only with SCL function.
- Pull-up is active when JTAG_EN is driven high.

5 Revision History

Table 5 provides a revision history for this document.

Table 5. Revision History Table

Rev. Number	Substantive Changes	Date of Release
0	Initial release.	07/2003
1	Added page erase verify errata for Chapter 6, "ColdFire Flash Module (CFM)."	09/2003
2	 Added errata for UART interrupt status register. Added errata for PIT timer timeout equation. Added I2CR write errata. Added errata for 'Internal Pull-Up' column in 'MCF5282 Signals and Pin Numbers Sorted by Function' table. Added errata for "SDRAM Read Cycle' figure. 	11/2003
3	Added errata for Chapter 19. PIT1-PIT4 should be PIT0-PIT3.	01/2004
4	 Added errata for spurious interrupt. Added errata for Table 33-8. Single instance of T_A = T_L to T_H was overlooked in revision 2.0 of the manual. This instance has now been removed. 	03/2004
5	 Added errata for Section 25.4.10: change CANICR to ICRn. Added errata for BITERR and ACKERR field descriptions. Added errata for BOFFINT and ERRINT bit sequence. Added errata for BUFnI field description. 	03/2004

Revision History

Table 5. Revision History Table (continued)

Rev. Number	Substantive Changes	Date of Release
6	Added errata for Table 17-2 Added errata for FRSR register diagram	11/2004
7	Added errata for Figure 4-2, Table 4-6, Figure 6-3, and Table 6-10	11/2004
	Added the below errata for MCF5282UM Rev 2.3	
8	 Added FEC max buffer size errata. Added VDD/VDDH power-up requirement. Added MFD bit definition footnote errata. Added PLL spec table entries for 66MHz device. 	01/2005
9	Added INTFRCLn figure errata. Added BAM bit field example errata.	03/2005
10	Added SDRAM NOP command errata. Added UART clock source errata.	07/2005
11	 Added PRI1/PRI2 text description errata. Added CSMR1/CSCR1 register address errata. Removed Table 23-5 errata that was added in revision 10 of this document, as it was incorrect. Only the internal UART clock source is prescaled by the 16-bit divider. Added 2 UART external clock source errata, removing the 16-bit divider from a figure and equation. 	08/2005
12	 Added core watchdog unable to reset the device errata. Added EMRBR register address errata. Added I_{OH} and I_{OL} errata. 	12/2005
13	 Added FlexCAN flag clearing mechanism errata in interrupt controller. Added FlexCAN ESTAT register description errata for various bits. Added ICRnx note regarding unique and non-overlapping level and priority definitions. Added DTOUT1, DTIN0, DTOUT0 description field errata in GPIO chapter. Added FEC MII transmit and receive specification section errata. 	08/2006
14	 Deleted reference to nonexistent CF bits in the figure and bit descriptions for the GPTFLG2 register. Added RMON_R_DROP counter errata. 	11/2006

Revision History

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