

The Wronskian is a quantity associated to 2nd-order linear DEs that allow us to determine whether two <sup>given</sup> solutions can be used to generate \*all\* solutions to that DE; and in so doing, whether some linear combination thereof can be used to satisfy a given set of initial conditions.

To talk about the Wronskian it will be useful to define the notion of a Differential operator.

Let  $p(t), q(t)$  be continuous on ~~interval~~ <sup>(2nd-order)</sup>  $\alpha < t < \beta$ .

Define 3.2.1 • A differential operator is a "function of functions" that acts on any twice differentiable function  $\phi(t)$  to produce another function.

• The differential operator  $L[\phi] = \phi'' + p(t) \cdot \phi' + q(t) \cdot \phi$  takes function  $\phi(t)$  to a function whose value at  $t$  is  $\phi''(t) + p(t) \cdot \phi'(t) + q(t) \phi(t)$ .

Example 3.2.2 Let  $p(t) = t^2$ ,  $q(t) = 1+t$  &  $\phi(t) = \sin(3t)$ .

$$\begin{aligned} \text{Then } L[\phi](t) &= (\sin 3t)'' + t^2 \cdot (\sin 3t)' + (1+t) \cdot (\sin 3t) \\ &= -9 \sin(3t) + 3t^2 \cos(3t) + (1+t) \sin(3t). \end{aligned}$$

Note: A differential operator  $L$  is often written in terms of the differentiation operator  $D (= \frac{d}{dt})$ , i.e.  $L = D^2 + pD + q$ .

In the above example  $L = D^2 + t^2 D + (1+t)$

Note too that a solution ~~of~~ the DE  $y'' + p(t)y' + q(t)y = 0$  is a function  $y(t)$  s.t.  $L[y] = 0$ .

Start with this

### Theorem 3.2.3 Existence & Uniqueness for 2nd-order DEs

Consider the IVP  $y'' + p(t)y' + q(t)y = g(t)$ ,  $y(t_0) = y_0$ ,  $y'(t_0) = y_0'$

Let  $I$  be the largest  $t$ -interval containing  $t_0$  on which  $p(t)$ ,  $q(t)$  &  $g(t)$  are all continuous. Then there exists a unique solution to the IVP  $y = \phi(t)$  for all  $t \in I$ .

Corollary: The IVP  $ay'' + by' + cy = g$ ,  $a, b, c, g$  constant ( $a \neq 0$ )  
 $y(t_0) = y_0$ ,  $y'(t_0) = y_0'$   
has a unique solution that is defined for all  $t$ .

### Theorem 3.2.4: Principle of superposition

If  $y_1$  &  $y_2$  are two solutions to  $L[y] = 0$  (i.e.  $y'' + p(t)y' + q(t)y = 0$ ), then any linear combination  $c_1 y_1 + c_2 y_2$  is too.

Proof: 
$$\begin{aligned} L[c_1 y_1 + c_2 y_2] &= [c_1 y_1 + c_2 y_2]'' + p(t) \cdot [c_1 y_1 + c_2 y_2]' + q(t) \cdot [c_1 y_1 + c_2 y_2] \\ &= c_1 y_1'' + c_2 y_2'' + p(t) \cdot c_1 y_1' + p(t) \cdot c_2 y_2' + q(t) c_1 y_1 + q(t) c_2 y_2 \\ &= c_1 (y_1'' + p(t)y_1' + q(t)y_1) + c_2 (y_2'' + p(t)y_2' + q(t)y_2) \\ &= c_1 L[y_1] + c_2 L[y_2] \end{aligned}$$

$\Rightarrow = 0$  if  $L[y_1] = L[y_2] = 0$

Suppose  $y_1(t)$  &  $y_2(t)$  both solve the DE  $L[y] = 0$  and we want to find the solution to the IVP  $L[y] = 0$ ,  $y(t_0) = y_0$ ,  $y'(t_0) = y_0'$ . By the above, the solution <sup>should be</sup>  $y = c_1 y_1 + c_2 y_2$ , for specific values of  $c_1$  &  $c_2$  s.t.

$$c_1 y_1(t_0) + c_2 y_2(t_0) = y_0$$

$$c_1 y_1'(t_0) + c_2 y_2'(t_0) = y_0'$$

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The Wronskian, (continued)

Solving for  $c_1$  &  $c_2$  symbolically we get

$$c_1 = \frac{y_0 y_2'(t_0) - y_0' y_2(t_0)}{y_1(t_0) y_2'(t_0) - y_1'(t_0) y_2(t_0)}$$

$$c_2 = \frac{-y_0 y_1'(t_0) + y_0' y_1(t_0)}{y_1(t_0) y_2'(t_0) - y_1'(t_0) y_2(t_0)}.$$

This is ugly! Thankfully there is a much nicer way to write  $c_1$  &  $c_2$  in terms of determinants of  $2 \times 2$  matrices:

$$c_1 = \frac{\det \begin{pmatrix} y_0 & y_2(t_0) \\ y_0' & y_2'(t_0) \end{pmatrix}}{\det \begin{pmatrix} y_1(t_0) & y_2(t_0) \\ y_1'(t_0) & y_2'(t_0) \end{pmatrix}}$$

$$c_2 = \frac{\det \begin{pmatrix} y_1(t_0) & y_0 \\ y_1'(t_0) & y_0' \end{pmatrix}}{\det \begin{pmatrix} y_1(t_0) & y_2(t_0) \\ y_1'(t_0) & y_2'(t_0) \end{pmatrix}}$$

Note the matrix in the bottom is the same. If its determinant at the point  $t_0$  is nonzero then we can solve for  $c_1$  &  $c_2$ .

Definition 3.2.5 The determinant, as a function of  $t$ ,

$$W = \det \begin{pmatrix} y_1(t) & y_2(t) \\ y_1'(t) & y_2'(t) \end{pmatrix} = y_1 y_2' - y_2 y_1'$$

is called the Wronskian of the solutions  $y_1$  &  $y_2$ .

In other words, it is possible to solve the previous IVP with some linear combination of  $y_1$  &  $y_2$ , so long as the Wronskian of  $y_1$  &  $y_2$  is not zero at  $t_0$ .

Theorem 3.2.6

Let  $y_1(t)$  &  $y_2(t)$  be two solutions to  $L[y] = y'' + p(t)y' + q(t)y = 0$

The family  $y = c_1 y_1(t) + c_2 y_2(t)$  comprises \*all\* solutions to the DE if and only if the Wronskian of  $y_1$  &  $y_2$  is nonzero somewhere.

Example 3.2.7

$y'' + 5y' + 6y = 0$  had solutions  $y_1(t) = e^{-2t}$ ,  $y_2(t) = e^{-3t}$

$$\begin{aligned} \text{Then } W &= \det \begin{pmatrix} e^{-2t} & e^{-3t} \\ -2e^{-2t} & -3e^{-3t} \end{pmatrix} = (e^{-2t})(-3e^{-3t}) - (e^{-3t})(-2e^{-2t}) \\ &= -3e^{-5t} + 2e^{-5t} \\ &= -e^{-5t} \\ &\neq 0 \text{ for all } t \end{aligned}$$

$\Rightarrow$  Any set of ICs can be satisfied to yield a solution to the IVP.

### Definition 3.2.8

- Any pair of solutions  $y_1(t), y_2(t)$  that to the DE  $y'' + p(t)y' + q(t)y = 0$  with nonzero Wronskian is called a fundamental set of solutions to the DE.
- $y = c_1 y_1(t) + c_2 y_2(t)$  is called the general solution to the DE.

Example 3.2.9: Show that  $y_1(t) = t^{\frac{1}{2}}$  &  $y_2(t) = t^{-1}$  form a fundamental set of solutions to  $2t^2 y'' + 3ty' - y = 0, t > 0$

Solution: • Verify  $y_1(t)$  &  $y_2(t)$  obey the DE:

$$\begin{aligned} y_1'(t) &= \frac{1}{2}t^{-\frac{1}{2}}, \quad y_1''(t) = -\frac{1}{4}t^{-\frac{3}{2}} \\ \text{Then } 2t^2 y_1'' + 3t y_1' - y_1 &= 2t^2 \left(-\frac{1}{4}t^{-\frac{3}{2}}\right) + 3t \left(\frac{1}{2}t^{-\frac{1}{2}}\right) - (t^{\frac{1}{2}}) \\ &= -\frac{1}{2}t^{\frac{1}{2}} + \frac{3}{2}t^{\frac{1}{2}} - t^{\frac{1}{2}} \\ &= 0 \quad \checkmark \end{aligned}$$

$$y_2'(t) = -t^{-2}, \quad y_2''(t) = +2t^{-3}$$

$$\begin{aligned} \Rightarrow 2t^2 y_2'' + 3t y_2' - y_2 &= 2t^2 (2t^{-3}) + 3t (-t^{-2}) - (t^{-1}) \\ &= 4t^{-1} - 3t^{-1} - t^{-1} \\ &= 0 \quad \checkmark \end{aligned}$$

• Compute Wronskian:

$$W = \det \begin{pmatrix} t^{\frac{1}{2}} & t^{-1} \\ \frac{1}{2}t^{-\frac{1}{2}} & -t^{-2} \end{pmatrix} = (t^{\frac{1}{2}})(-t^{-2}) - (t^{-1})\left(\frac{1}{2}t^{-\frac{1}{2}}\right) = -\frac{3}{2}t^{-\frac{3}{2}}$$

Since  $W \neq 0$  for  $t > 0$ , conclude  $y_1(t)$  &  $y_2(t)$  form a fundamental set of solutions to the DE.

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Note 3.2.10: Given a DE  $Ly = y'' + p(t)y' + q(t)y = 0$ , we can always find a fundamental set of solutions by  $y_1(t)$  &  $y_2(t)$  by solving

$$\begin{aligned} & \text{and} \\ & \begin{aligned} y_1(t_0) &= 1, & y_1'(t_0) &= 0 \\ y_2(t_0) &= 0, & y_2'(t_0) &= 1 \end{aligned} \end{aligned}$$

In this case, the solution to the IVP  $Ly = 0, y(t_0) = y_0, y'(t_0) = y_0'$  is then just

$$y = y_0 \cdot y_1(t) + y_0' \cdot y_2(t).$$

Example 3.2.11: Find the fundamental set of solutions to  $y'' - y = 0, t_0 = 0$ .

Recall we previously found solutions  $y = e^t$  &  $y = e^{-t}$   
The solution to  $y(0) = 1, y'(0) = 0$  is

$$y_1 = \frac{1}{2}(e^t + e^{-t}) = \cosh(t)$$

While the solution to  $y_2(0) = 0, y_2'(0) = 1$  is

$$y_2 = \frac{1}{2}(e^t - e^{-t}) = \sinh(t)$$

$\Rightarrow y_1(t) = \cosh(t), y_2(t) = \sinh(t)$  form a fundamental set of solutions to  $y'' - y = 0$ .

Note 3.2.12: From the above we see that there can be more than one fundamental set of solutions to a given DE. So just pick the one that's easiest to work with in general.