$$H_{z} = \begin{pmatrix} -\frac{\hbar^{2}(\vec{k} - \tau \vec{k}_{b})^{2}}{2m_{b}} + \Delta_{b}(\vec{r}) & \Delta_{T}, \tau(\vec{r}) \\ -\frac{\hbar^{2}(\vec{k} - \tau \vec{k}_{b})^{2}}{2m_{b}} + \Delta_{t}(\vec{r}) \end{pmatrix}$$

$$\Delta_{b,t}(\vec{r}) = 2V_{b,t} \sum_{j=1,3,5} \cos(\vec{g}_{j} \cdot \vec{r} + \psi_{b,t}) + V_{b,t}^{(0)}$$

$$\Delta_{T_{t}}(\vec{r}) = w(1 + e^{i\frac{2\pi}{3}\tau} e^{i\tau\vec{g}_{2}\cdot\vec{r}} + e^{i\frac{4\pi}{3}} e^{i\tau\vec{g}_{3}\cdot\vec{r}})$$

$$\left(\begin{array}{ccc} e^{i\tau\vec{k}_{b}\cdot\vec{r}} & o \\ o & e^{i\tau\vec{k}_{b}\cdot\vec{r}} \end{array}\right) H_{\tau} \left(\begin{array}{ccc} e^{i\tau\vec{k}_{b}\cdot\vec{r}} & o \\ o & e^{i\tau\vec{k}_{b}\cdot\vec{r}} \end{array}\right)$$

$$= \left( -\frac{\hbar^{2}\vec{k}^{2}}{2m_{b}} + \Delta_{b}(\vec{r}) - \frac{\Delta_{T}\tau(\vec{r})}{2m_{t}} + \Delta_{t}(\vec{r}) - \frac{\hbar^{2}[\vec{k}-\tau(\vec{k}_{t}-\vec{k}_{b})]^{2}}{2m_{t}} + \Delta_{t}(\vec{r}) \right)$$

$$= \widetilde{H}_{\tau}$$

$$H_{\tau} = e^{i\tau \vec{k}_{b} \cdot \vec{l}} + \widetilde{H}_{\tau} e^{-i\tau \vec{k}_{b} \cdot \vec{l}}$$

