

# CSC 316 – Data Structures Introduction to Graphs

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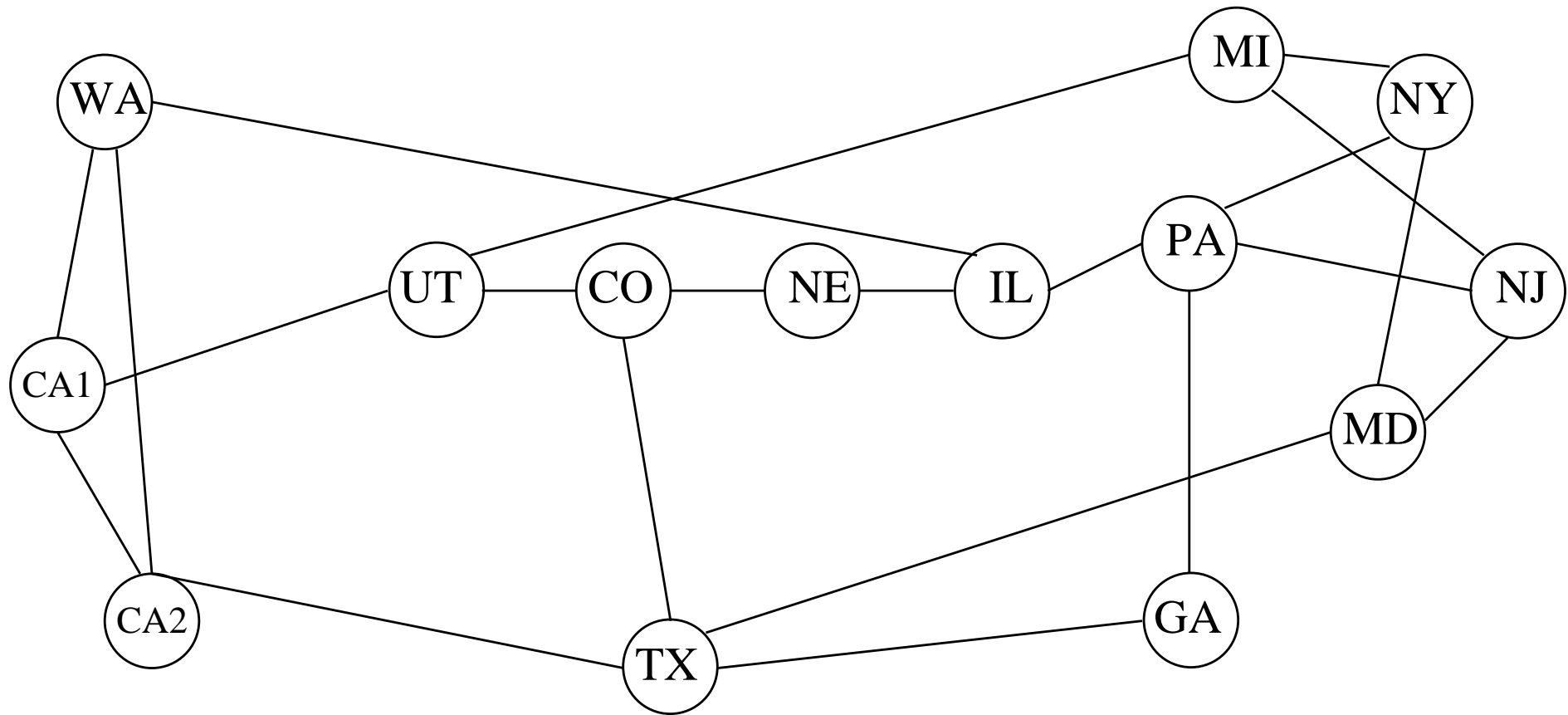
# Outline

1. Definition
2. Terminology
3. Implementation
4. Trees as Graphs

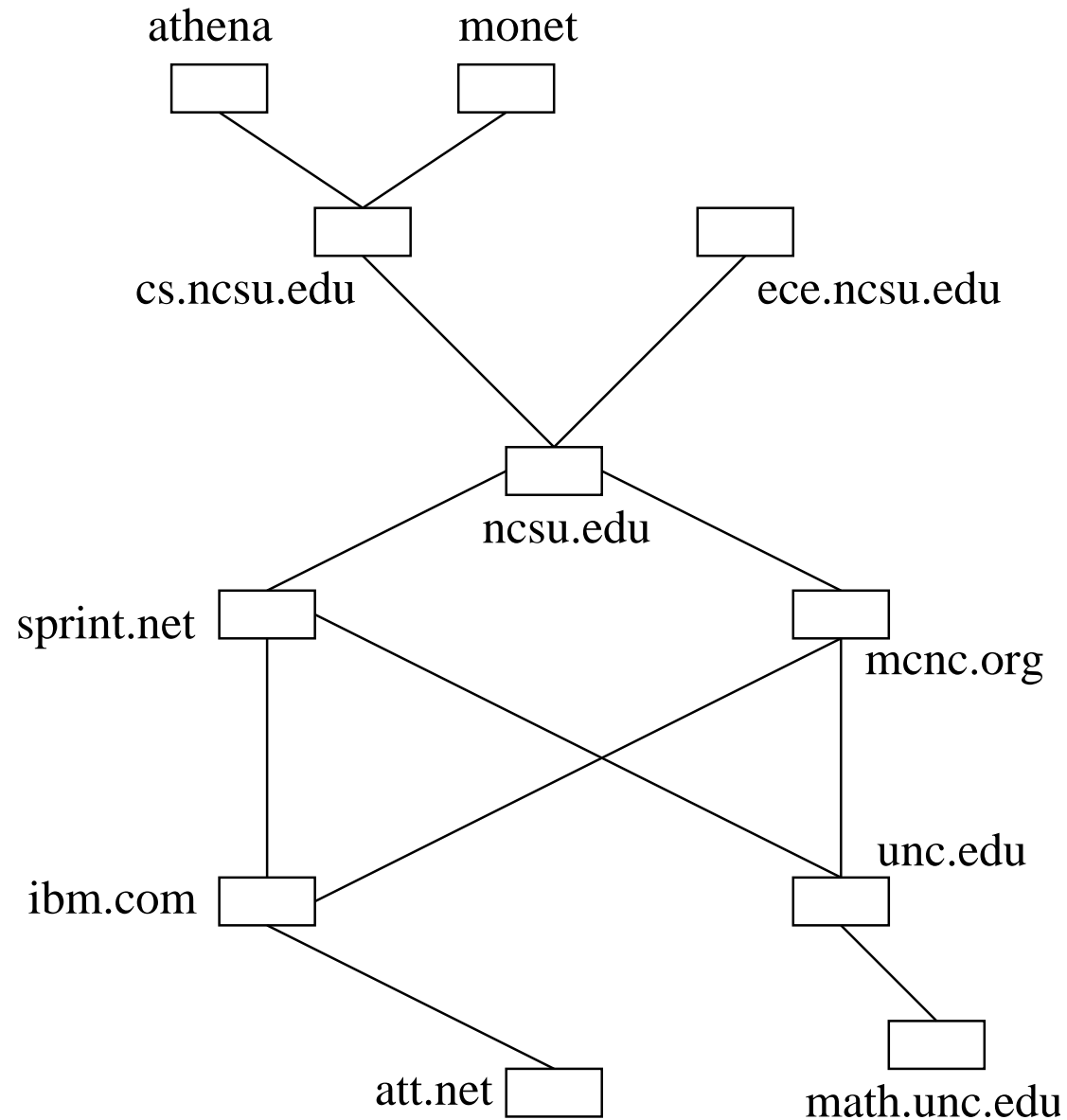
# Undirected Graphs

- An undirected graph is a pair  $(V, E)$ :
  - $V = \{v_1, v_2, \dots, v_n\}$  is a set of **nodes**  $\rightarrow$  vertex set
  - $E = \{e_1, e_2, \dots, e_m\}$  is a set of **unordered pairs of vertices**  $\rightarrow$  edge set
- Vertices:
  - represent arbitrary entities (e.g., cities)
  - store auxiliary information (e.g., city code)
- Edge  $e = \{v, u\} \in E$ 
  - implies a relationship between  $v$  and  $u$  (e.g., highway exists between two cities)
  - relationship is **symmetrical**  $\rightarrow$  order of vertices unimportant
  - $v$  and  $u$  are **adjacent** or **neighbors**  $\rightarrow$  **endpoints** of edge  $e$

# Undirected Graph Example



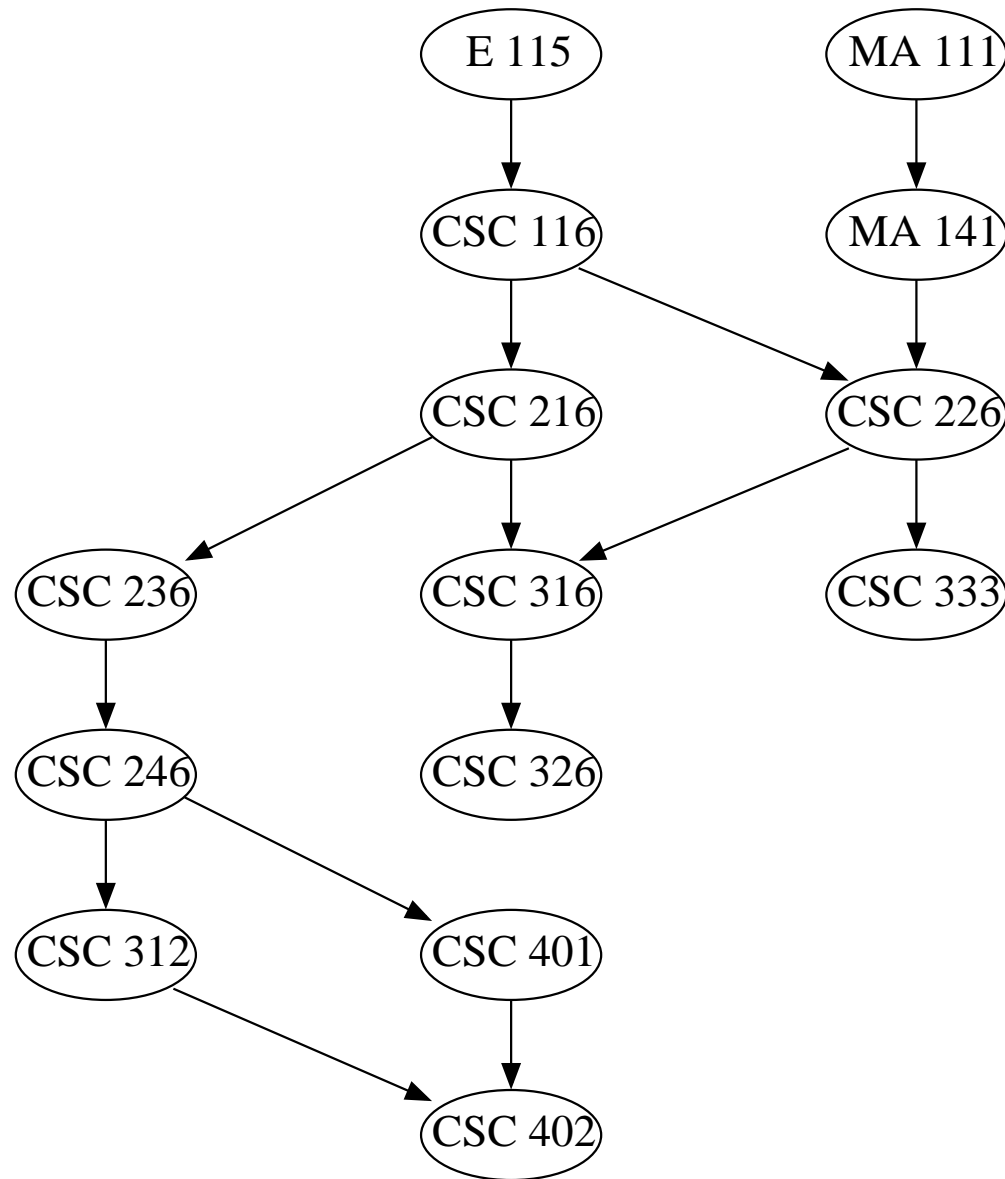
# Undirected Graph Example (2)



# Directed Graphs

- A directed graph is a pair  $(V, A)$ 
  - $V$  is the vertex set
  - $A = \{a_1, a_2, \dots, a_m\}$  is a set of **ordered** pairs of vertices  
→ arc set
- Arc  $a = \langle v, u \rangle \in A$ 
  - **departs** from  $v$  and **enters**  $u$
  - $u$  is **adjacent to (neighbor of)**  $v$
  - the reverse is not true **unless**  $\langle u, v \rangle \in A$

# Directed Graph Example



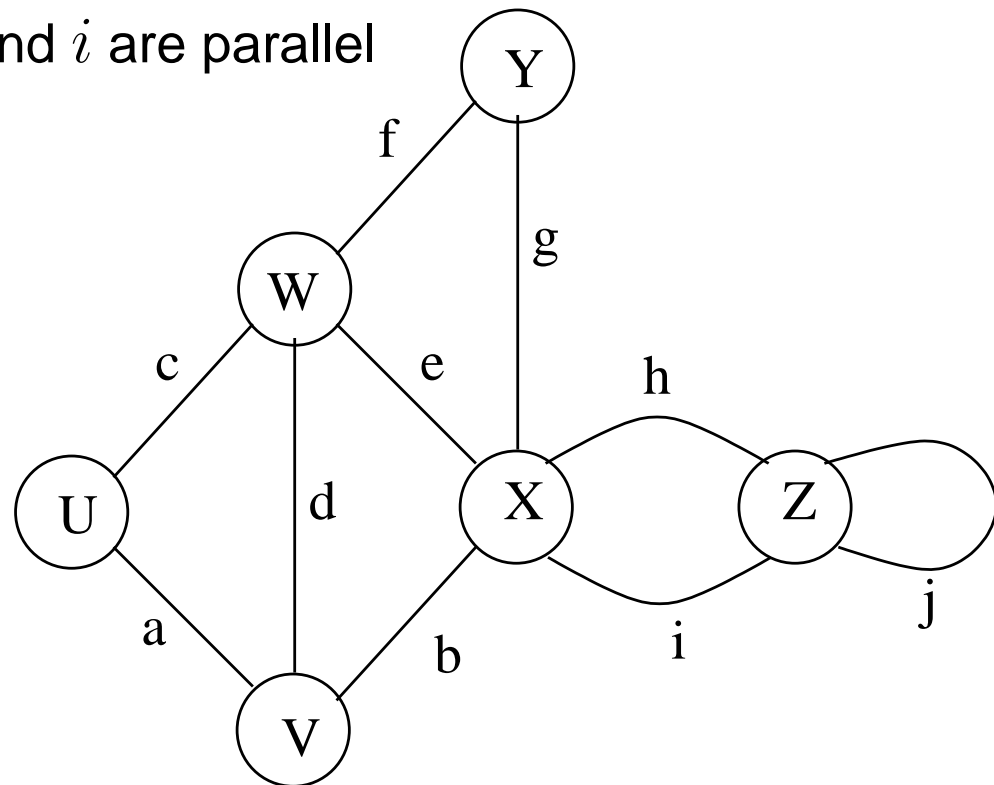
# Applications

- Transportation networks:
  - highway network
  - flight network
- Computer networks:
  - campus network
  - internet
  - web
- Databases: entity-relationship diagrams
- Electronic circuits:
  - printed circuit board
  - integrated circuit
- Scheduling
- . . .



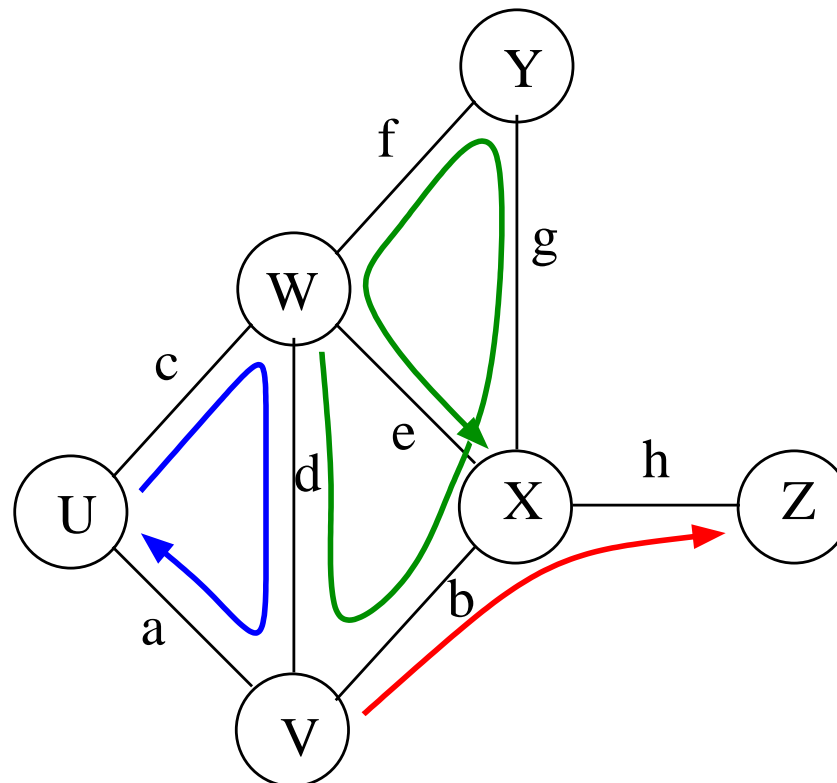
# Terminology

- Endpoints of an edge  $\rightarrow U, V$  endpoints of  $a$
- Edges incident on a vertex  $\rightarrow a, b, d$  incident on  $V$
- Adjacent vertices  $\rightarrow U$  and  $V$  are adjacent
- Degree of a vertex  $\rightarrow X$  has degree 5
- Parallel edges  $\rightarrow h$  and  $i$  are parallel
- Self-loop  $\rightarrow$  edge  $j$



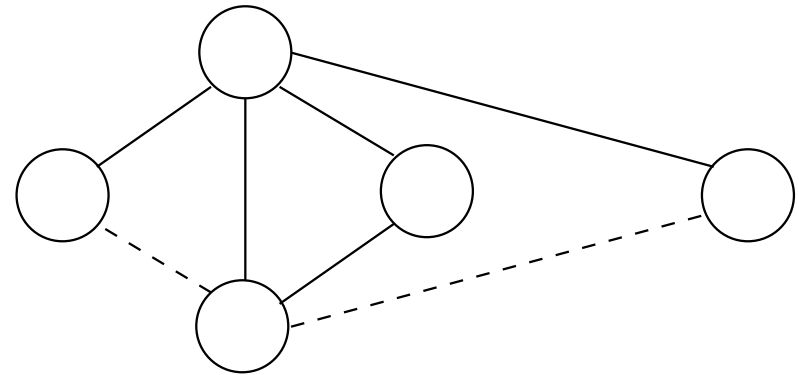
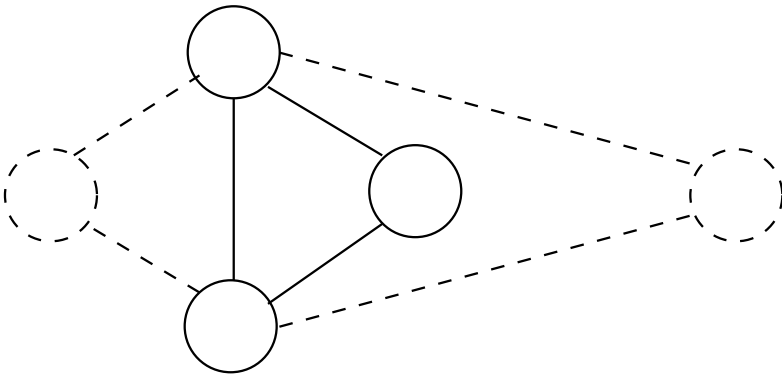
# Terminology: Paths

- **Path** from vertex  $v_0$  to  $v_n$ :
  - a sequence of vertices  $v_0, v_1, \dots, v_n$
  - $\{v_0, v_1\}, \{v_1, v_2\}, \dots, \{v_{n-1}, v_n\}$  are edges of the graph
- **Simple** path: all vertices in the path are distinct
- **Cycle**: a path with  $v_0 = v_n$ , no two successive edges are the same



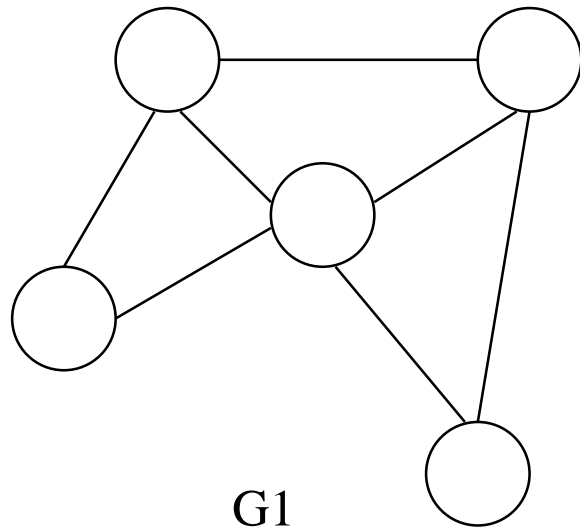
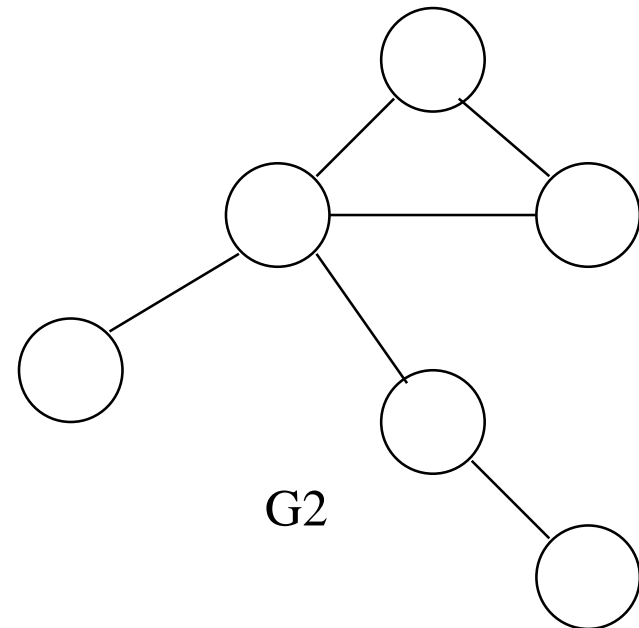
# Terminology: Subgraphs

- Graph  $G = (V, E)$
- Subgraph  $G' = (V', E')$  of  $G$ 
  - $V' \subseteq V$
  - $E' \subseteq E$
- **Spanning** subgraph:  $V' = V$



# Terminology: Connected Components

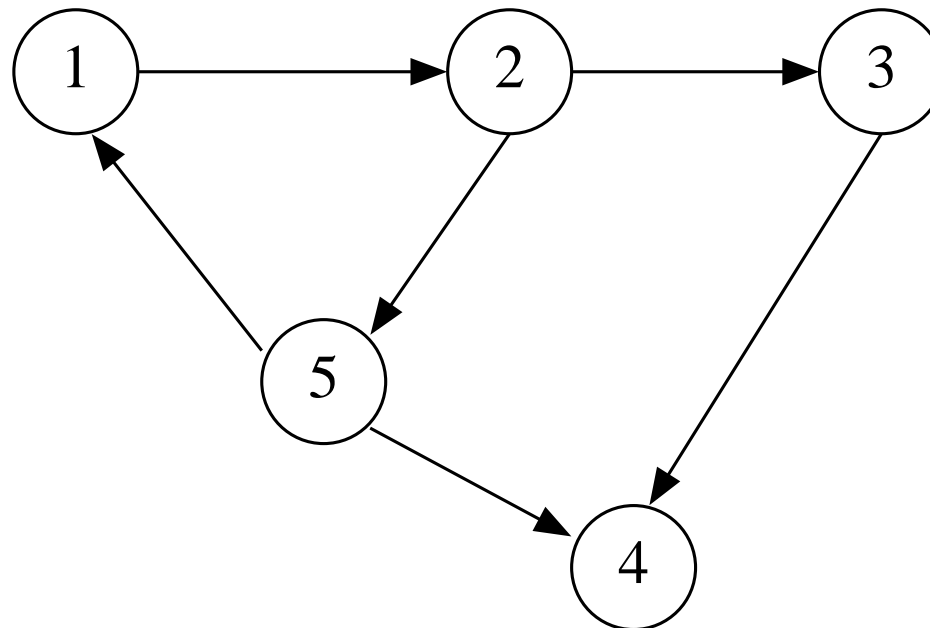
- **Connected** graph:  $\forall u, v \in V$ , there exists a path between  $u$  and  $v$   
→ each vertex is **reachable** from any other vertex
- **Connected component**: a maximal connected subgraph of a graph  $G$
- Two extreme cases:
  - connected graph → single connected component
  - graph with no edges → each vertex is a connected component

 $G_1$  $G_2$ 

$$G = G_1 \cup G_2$$

# Terminology: Connected Components (2)

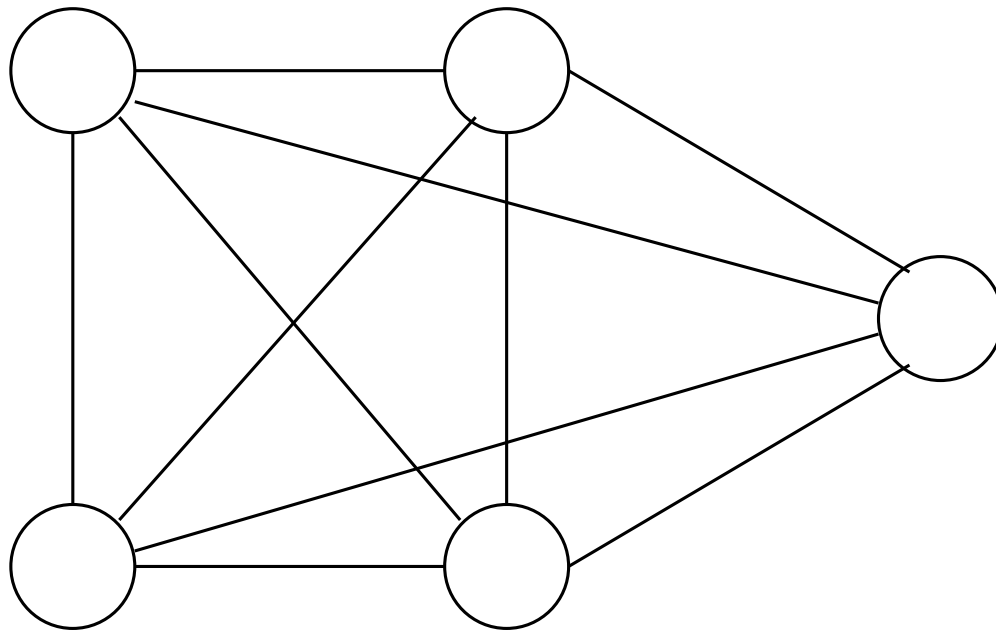
- Directed graph (digraph)  $G = (V, A)$
- Strongly connected graph: connected in both directions
- Strongly connected component: a maximal strongly connected subgraph of  $G$



# Complete Graphs

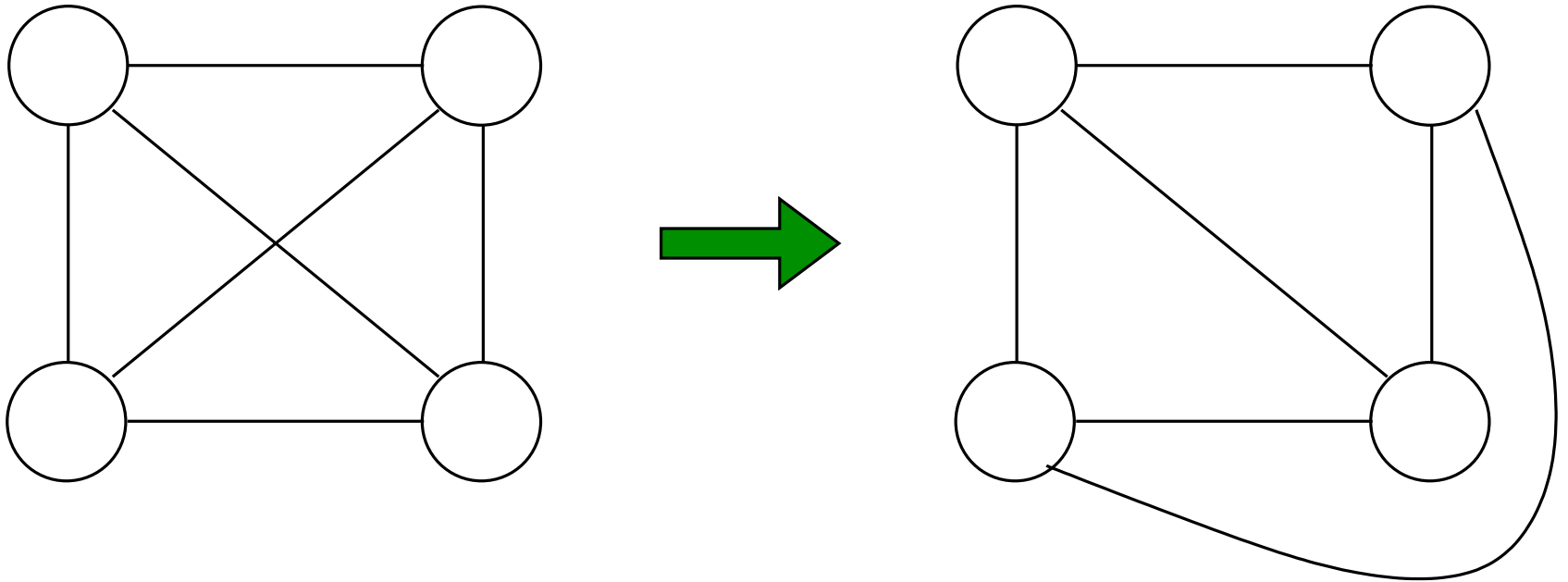
- Undirected graph with an edge between **every** distinct pair of vertices
- Property:

$$|E| = \frac{|V|(|V| - 1)}{2}$$



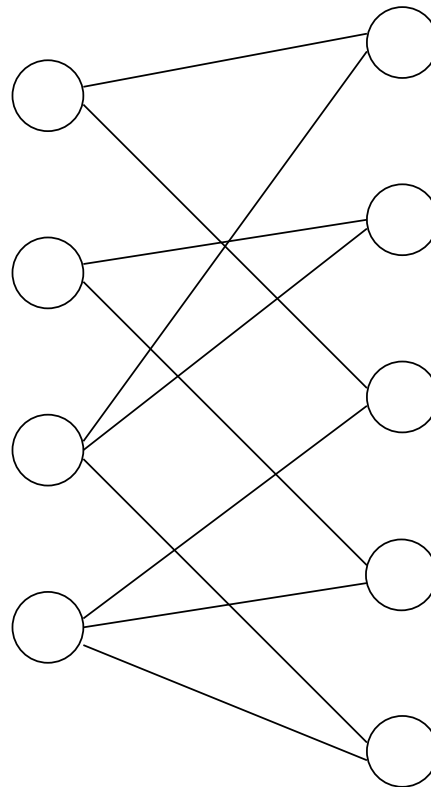
# Planar Graphs

- Can be drawn so that their edges intersect only at the vertices



# Bipartite Graphs

- The vertex set  $V$  can be partitioned into two sets,  $V_1$  and  $V_2$   
 $\rightarrow V_1 \cap V_2 = \phi, V_1 \cup V_2 = V$
- For all edges  $\{u, v\} \in E \rightarrow u \in V_1$  and  $v \in V_2$ , or vice versa





# Properties

• Simple undirected graph with:

•  $n$  nodes

•  $m$  edges

• degree  $\deg(v)$  of vertex  $v$

• Property 1:

$$\sum_{v \in V} \deg(v) = 2m$$

• Property 2: if there are no parallel edges/self-loops, then:

$$m \leq \frac{n(n-1)}{2}$$

# Properties (2)

- Simple directed graph with:
  - $n$  nodes
  - $m$  arcs
  - in-degree  $\text{indeg}(v)$  and out-degree  $\text{outdeg}(v)$  of vertex  $v$

- Property 1:

$$\sum_{v \in V} \text{indeg}(v) = \sum_{v \in V} \text{outdeg}(v) = m$$

- Property 2:

$$m \leq n(n - 1)$$

# Data Structures for Graphs

1. Edge List structure → list of edge and vertex records
2. Adjacency Matrix
3. Adjacency List

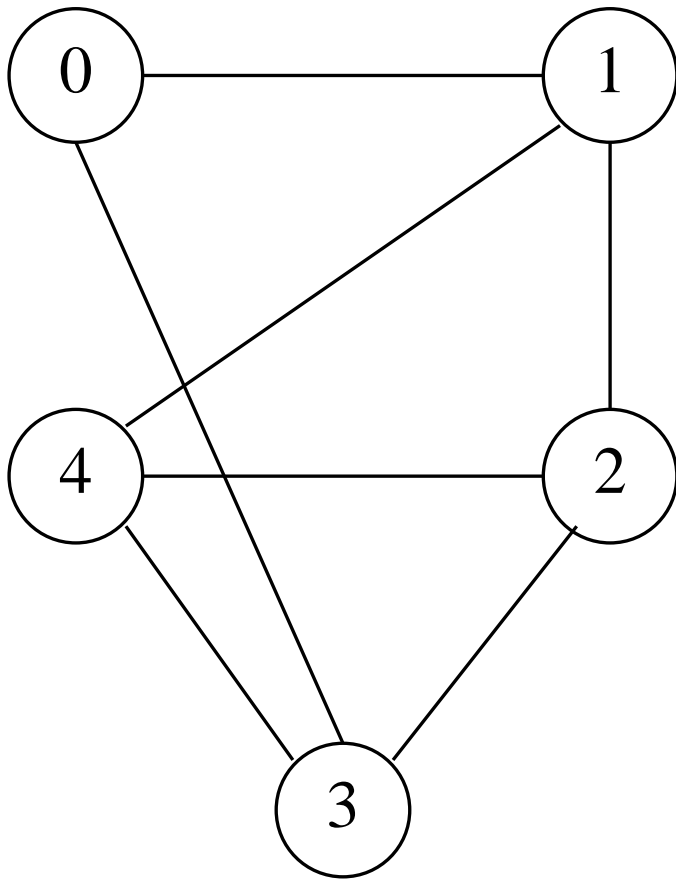
# Adjacency Matrix

- Integer **index** associated w/ vertex  $\rightarrow$  vertices labeled  $v_0, \dots, v_{n-1}$
- A  $n \times n$  matrix  **$M$**  defined as:

$$M[i, j] = \begin{cases} 1, & \text{if there is an edge (arc) from } v_i \text{ to } v_j \\ 0, & \text{otherwise} \end{cases}$$

- Space requirements:  $O(n^2)$

# Adjacency Matrix Example



	0	1	2	3	4
0	0	1	0	1	0
1	1	0	1	0	1
2	0	1	0	1	1
3	1	0	1	0	1
4	0	1	1	1	0

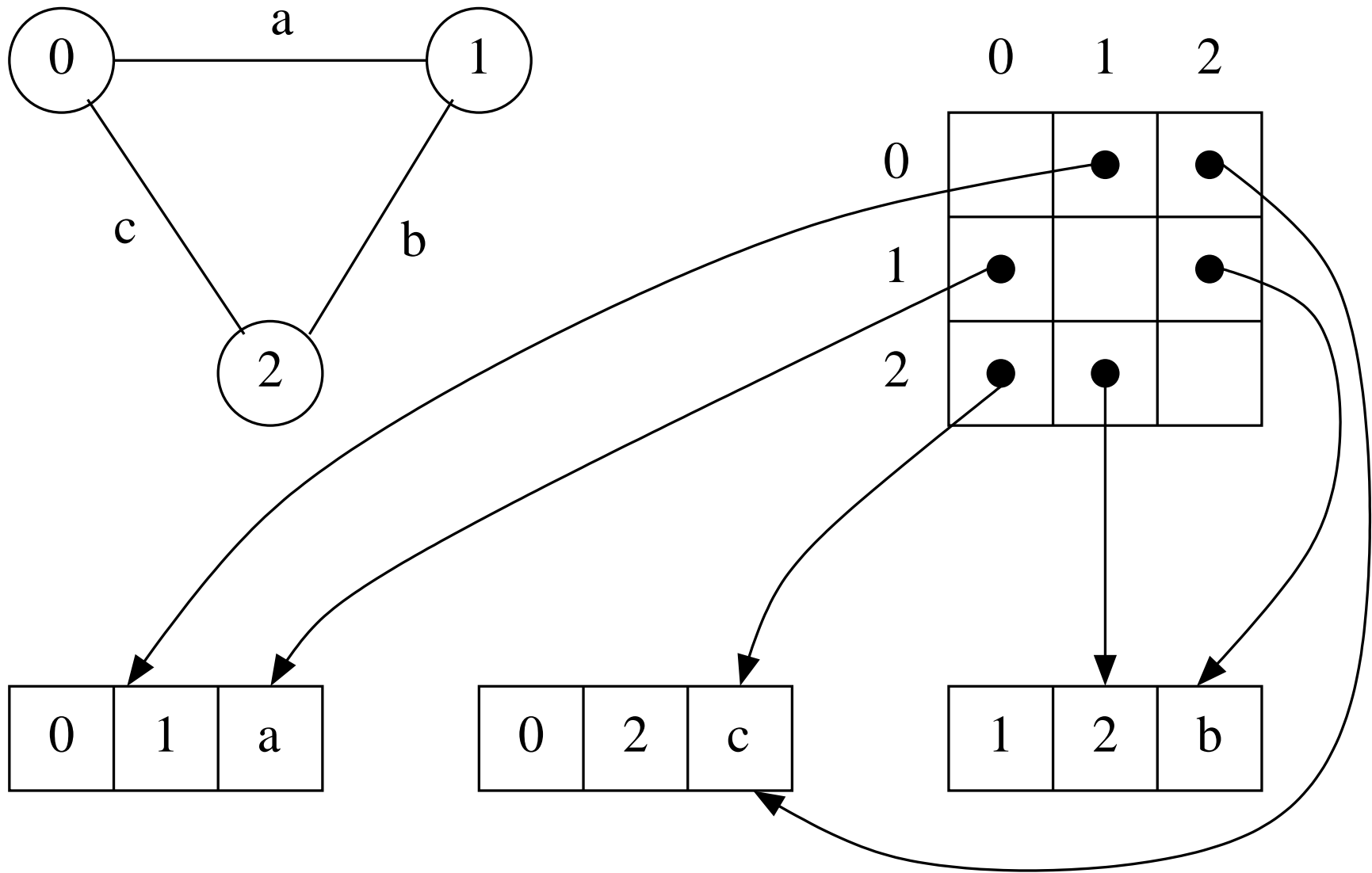
# Adjacency Matrix, v.2

- Redefine matrix  $M$  as:

$$M[i, j] = \begin{cases} \text{pointer to edge object for } (v_i, v_j), & \text{if edge exists} \\ \text{null}, & \text{otherwise} \end{cases}$$

- **Edge** object holds references to:
  - the two vertices incident on this edge
  - the information (element) associated with the edge

## Adjacency Matrix, v.2 Example

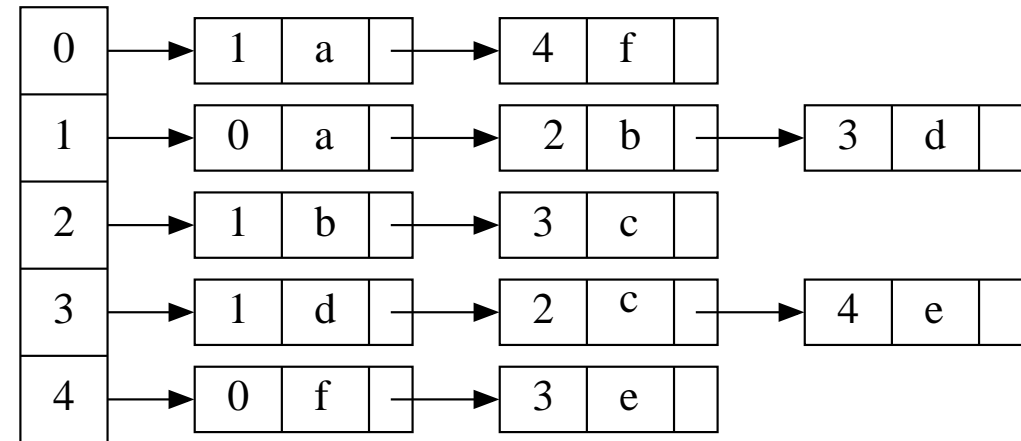
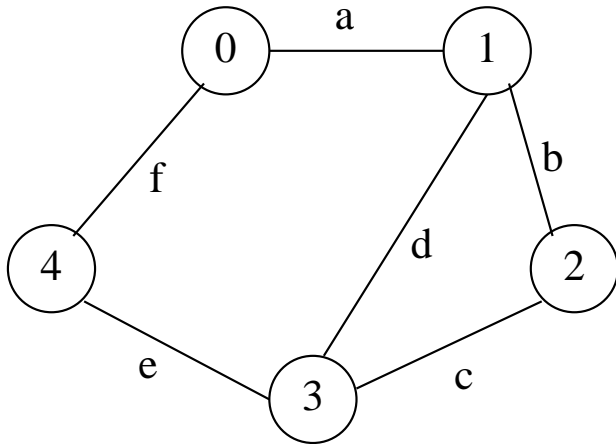


# Adjacency List

- Adjacency list for vertex  $v \rightarrow$  list of vertex records  $\forall$  neighbors of  $v$
- Vertex record contains:
  - neighbor vertex  $u$  of  $v$
  - the information (element) associated with edge  $(v, u)$
  - pointer to next vertex record in the adjacency list
- Space requirements:  $O(n + m)$
- More efficient for **sparse** graphs  $\rightarrow m \approx O(n)$



# Adjacency List Example



# Comparison: Assumptions

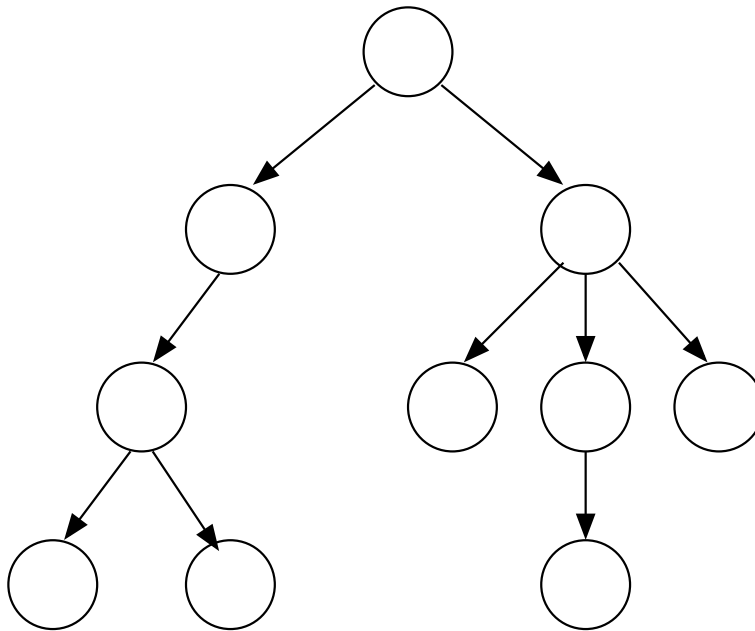
- $n$  vertices
- $m$  edges
- No parallel edges
- No self-loops

# Asymptotic Performance

	Adjacency List	Adjacency Matrix
Space	$O(n + m)$	$O(n^2)$
incidentEdges(v)	$O(deg(v))$	$O(n)$
areAdjacent(v,w)	$O(\min\{deg(v), deg(w)\})$	$O(1)$
insertVertex(v)	$O(1)$	$O(n^2)$
insertEdge((v,w))	$O(1)$	$O(1)$
removeVertex(v)	$O(deg(v))$	$O(n^2)$
removeEdge((v,w))	$O(\min\{deg(v), deg(w)\})$	$O(1)$

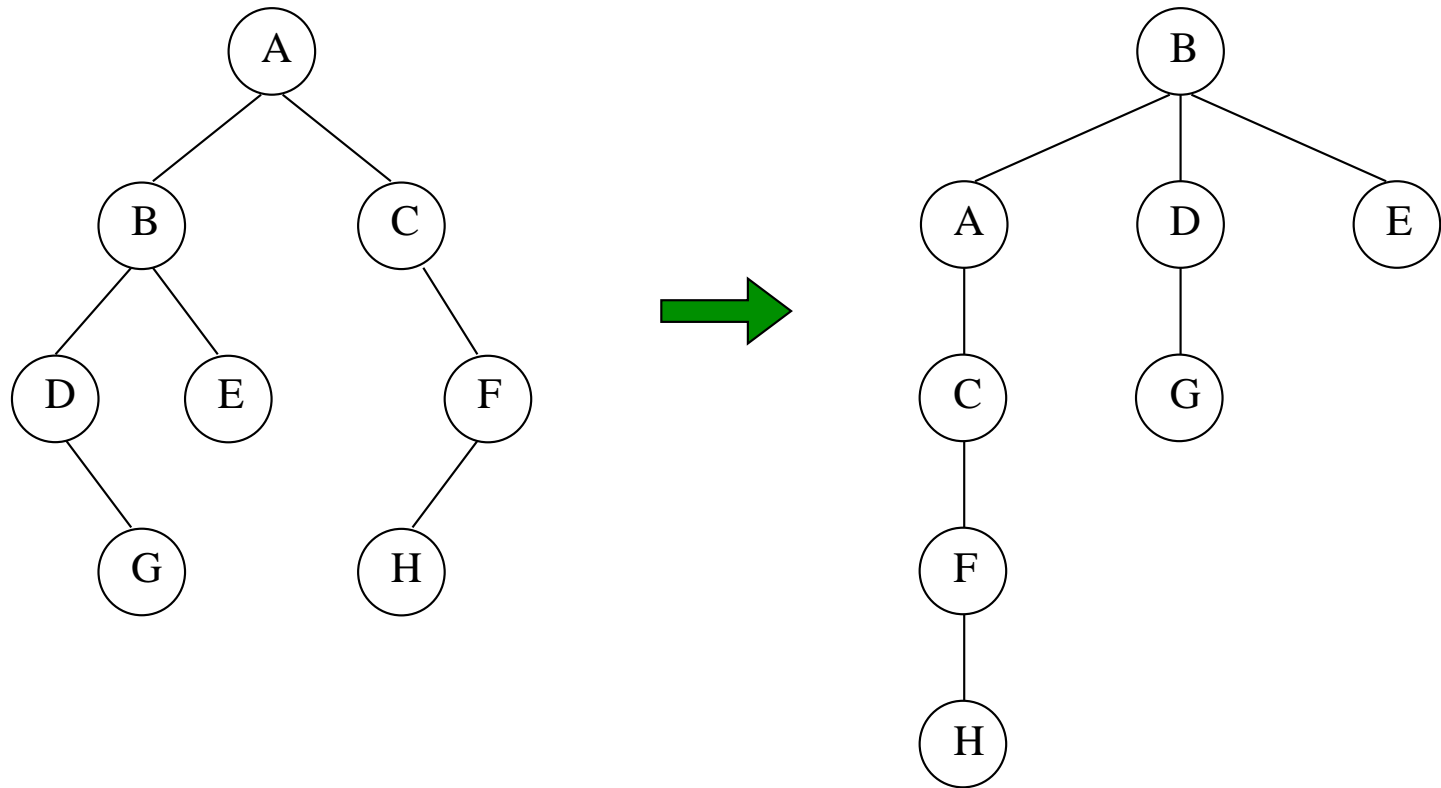
# Trees as Graphs

- **Definition:** a **directed tree** is a directed acyclic graph (DAG) such that:
  - there is exactly one vertex, the **root**, which no arcs enter
  - every vertex except the root has **exactly one** entering arc
  - there is a **unique** path from the root to each vertex



# Trees as Graphs (2)

- **Definition:** an **undirected graph**  $G$  is a tree if and only if:
  - $\forall u, v \in G$ , there exists a **unique simple path** from  $u$  to  $v$
- Undirected trees  $\rightarrow$  “root” not important  $\rightarrow$  any vertex can be root



# Graph Properties

● Undirected graph  $G = (V, E)$  with

●  $n = |V|$  vertices

●  $m = |E|$  edges

● Properties:

1.  $G$  is connected  $\Rightarrow m \geq n - 1$

2.  $G$  is acyclic  $\Rightarrow m \leq n - 1$

● Proof:

1. Graph w/  $n$  vertices, no edges  $\rightarrow$  add edges to make it connected

2. By induction on number  $k$  of vertices of the graph

# Checking for Tree Property

- A graph  $G$  with  $n$  vertices is a tree if any of these conditions are true:
  1.  $G$  is connected and acyclic
  2.  $G$  is connected and has exactly  $n - 1$  edges
  3.  $G$  is acyclic and has exactly  $n - 1$  edges
  4.  $G$  is connected, but deleting any edge disconnects the graph
  5.  $G$  is not complete, and adding any edge creates exactly one cycle that contains the new edge