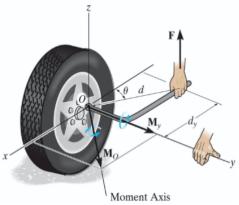
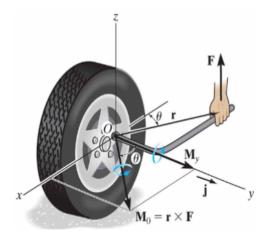
Lecture 7 Note - Moments II (Moments acting about an axis, couple moments)

Textbook Chapter 4.5-4.7

Moment of a force about an axis:

- Sometimes we have a moment acting upon multiple axes, but only care about how much of it acts in 1 direction, like the y-axis of the problem on the right.
- The moment about the y-axis in this case can be evaluated by: $M_v = Fd_v = F(d \cos \theta)$.
- It can also be found with a vector approach using $M_y = \mathbf{j} \cdot \mathbf{M}_o = \mathbf{j} \cdot (\mathbf{r} \times \mathbf{F})$. See image below. Note that y and \mathbf{j} can be swapped for x and \mathbf{i} or z and \mathbf{k} .





-In the vector approach, determine moment vector \mathbf{M}_o by first crossing \mathbf{F} with its position vector \mathbf{r} relative to O. Then dot this moment vector \mathbf{M}_o with unit vector \mathbf{u}_A to find how much of it acts in direction a.

-The formula for this problem is $M_A = u_A \cdot M_o = u_A \cdot (r \times F)$ and is called the scalar triple product. It is solved as a cross product with 3 rows; Unit vector, pos. vector, & force vector. Order matters, and M_o can be negative.

• <u>Tip: When solving, pick the position vector with the most 0s to save time.</u> As long as it starts *somewhere* on the axis of a moment and ends on a force's line of action, it's OK.

Couple moments:

- A couple is a pair of two parallel forces with the same magnitude *F*, but acting in opposite directions separated by distance *d*. The resultant translational force is 0, but they exert a rotational force that we call the <u>couple moment</u>. Think RCS thrusters.
- Can be calculated via M = Fd (scalar approach) OR $M = r \times F$ (vector approach).
- The M_R of multiple couple moments can be calculated via vector addition. Just add the components of all couple moments, or the $(r \times F)$'s.