Exploitation of dynamic symmetries for solving SAT problems

Thèse de doctorat de Sorbonne Université

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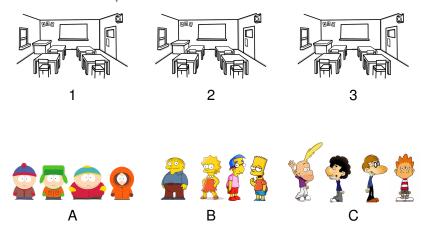


Motivation

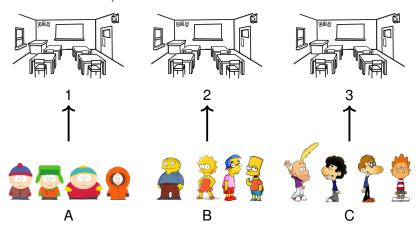
SAT is widely used in different domains

- Artificial intelligence (planning, games, ...)
- Bioinformatics (haplotype inference, ...)
- Security (cryptanalysis, inversion attack on hash, ...)
- Computationally hard problems (graph coloring, ...)
- Formal methods (hardware model checking, ...)

SAT an example



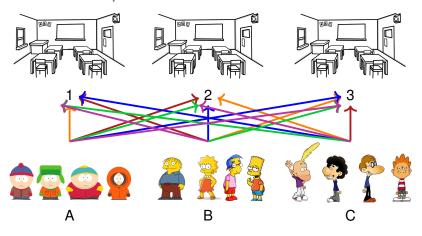
SAT an example



Is it possible to attribute each group to a classroom?

YES!

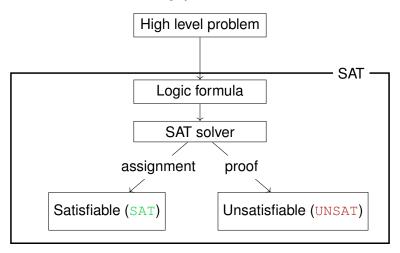
SAT an example

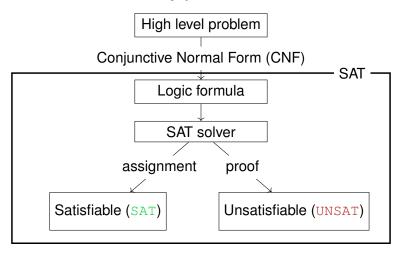


Is it possible to attribute each group to a classroom?

YES! Many solutions

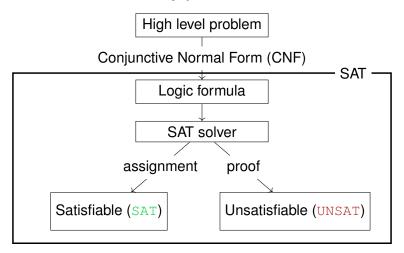
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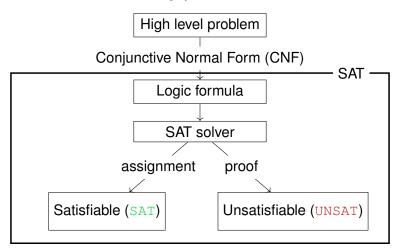
CNF representation:

$$\underbrace{\left(x_1 \lor x_2 \lor \neg x_3\right)}_{\text{Clause with literals } x_1, x_2, \neg x_3}$$



CNF representation:

Formula (CNF)
$$\underbrace{\left(x_1 \lor x_2 \lor \neg x_3\right)}_{Clause} \land \left(\neg x_1 \lor \neg x_2\right) \land \left(x_2 \lor \neg x_4\right)$$



Clause representation as a set:

$$(x_1 \vee x_2 \vee \neg x_3) \rightarrow \{x_1, x_2, \neg x_3\}$$

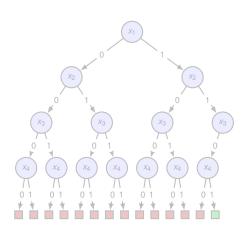
SAT Solving

Solving SAT formula is known to be **NP-complete** [Coo71]

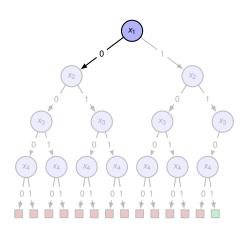
Enumerative algorithm:

- Davis, Putnam, Logemann, and Loveland (DPLL) [DLL62]
 - Boolean Constraint Propagation (BCP)

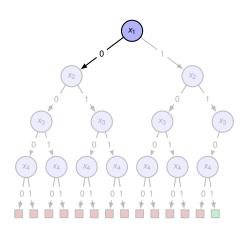
- Conflict Driven Clause Learning (CDCL) [MSS99]
 - Derived from DPLL
 - Clause learning



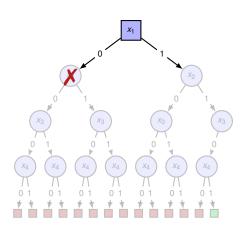
$$\omega_{1} = \{x_{1}, x_{2}, x_{3}, x_{4}\}
\omega_{2} = \{x_{1}, \neg x_{4}\}
\omega_{3} = \{x_{1}, x_{4}\}
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\omega_{6} = \{x_{3}, x_{4}\}$$



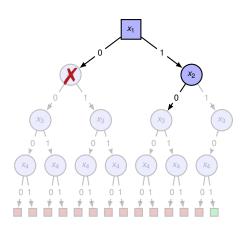
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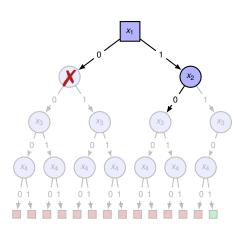
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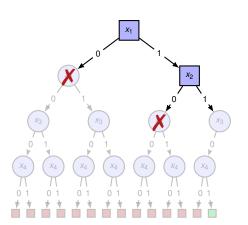
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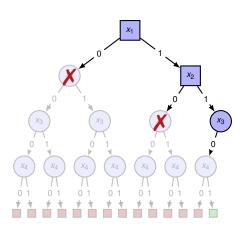
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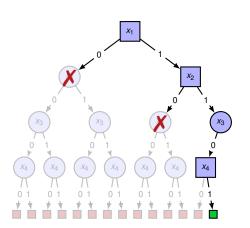
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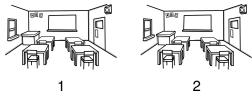
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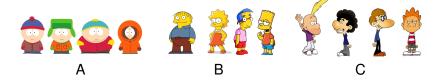


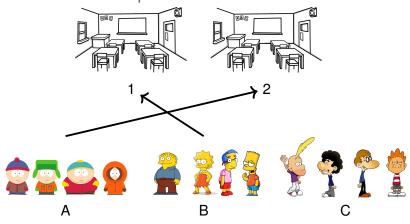
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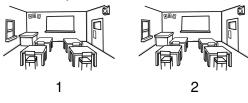


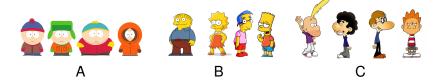
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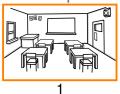


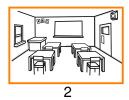


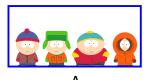


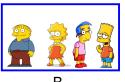
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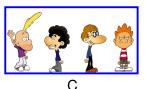
No!











Is it possible to attribute each group to a classroom?

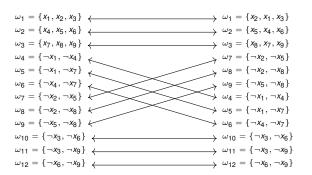
No!

Presence of symmetries hinders the performance of the solver

Symmetry

A symmetry (permuation) g is a bijective function (on variables) that leaves the formula invariant.

$$g = \begin{pmatrix} x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_7 & x_8 & x_9 \\ x_2 & x_1 & x_3 & x_5 & x_4 & x_6 & x_8 & x_7 & x_9 \end{pmatrix} \rightarrow (x_1 \ x_2)(x_4 \ x_5)(x_7 \ x_8)$$



Computing symmetries of a SAT problem $(x_1 \lor x_2 \lor x_3) \land (x_4 \lor x_5 \lor x_6) \land (x_7 \lor x_8 \lor x_9)$

CNF formula

 $\begin{array}{c} (x_1 \lor x_2 \lor x_3) \land (x_4 \lor x_5 \lor x_6) \land (x_7 \lor x_8 \lor x_6) \\ \land (\neg x_1 \lor \neg x_4) \land (\neg x_1 \lor \neg x_7) \land (\neg x_4 \lor \neg x_7) \\ \land (\neg x_2 \lor \neg x_5) \land (\neg x_2 \lor \neg x_8) \land (\neg x_5 \lor \neg x_8) \\ \land (\neg x_3 \lor \neg x_6) \land (\neg x_3 \lor \neg x_9) \land (\neg x_6 \lor \neg x_9) \end{array}$

¹http://www.tcs.hut.fi/Software/bliss/

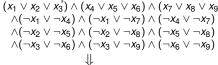
²http://vlsicad.eecs.umich.edu/BK/SAUCY/

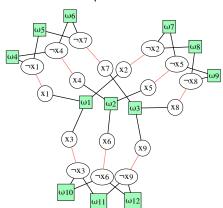
Computing symmetries of a SAT problem $(x_1 \lor x_2 \lor x_3) \land (x_4 \lor x_5 \lor x_6) \land (x_7 \lor x_8 \lor x_9)$

CNF formula



colored graph





Computing symmetries of a SAT problem $(x_1 \lor x_2 \lor x_3) \land (x_4 \lor x_5 \lor x_6) \land (x_7 \lor x_8 \lor x_9)$

CNF formula $\wedge(\neg x_1 \vee \neg x_4) \wedge (\neg x_1 \vee \neg x_7) \wedge (\neg x_4 \vee \neg x_7)$ $\wedge (\neg x_2 \vee \neg x_5) \wedge (\neg x_2 \vee \neg x_8) \wedge (\neg x_5 \vee \neg x_8)$ $\wedge(\neg x_3 \vee \neg x_6) \wedge (\neg x_3 \vee \neg x_9) \wedge (\neg x_6 \vee \neg x_9)$ colored graph (bliss¹, saucy 2) graph automorphism

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Computing symmetries of a SAT problem

CNF formula

 \Downarrow

colored graph

graph automorphism ↓

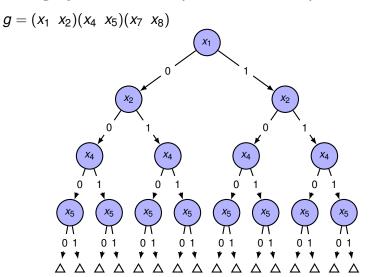
set of symmetries

 $⁽x_1 \lor x_2 \lor x_3) \land (x_4 \lor x_5 \lor x_6) \land (x_7 \lor x_8 \lor x_9)$ $\wedge(\neg x_1 \vee \neg x_4) \wedge (\neg x_1 \vee \neg x_7) \wedge (\neg x_4 \vee \neg x_7)$ $\wedge(\neg x_2 \vee \neg x_5) \wedge (\neg x_2 \vee \neg x_8) \wedge (\neg x_5 \vee \neg x_8)$ $\wedge(\neg x_3 \vee \neg x_6) \wedge (\neg x_3 \vee \neg x_9) \wedge (\neg x_6 \vee \neg x_9)$ (bliss¹, saucy $^2, \cdots$) $g_1 = (x_2 \ x_3)(x_5 \ x_6)(x_8 \ x_9)$ $g_2 = (x_4 \ x_7)(x_5 \ x_8)(x_6 \ x_9)$ $g_3 = (x_1 \ x_2)(x_4 \ x_5)(x_7 \ x_8)$ $q_4 = (x_1 \ x_4)(x_2 \ x_5)(x_3 \ x_6)$

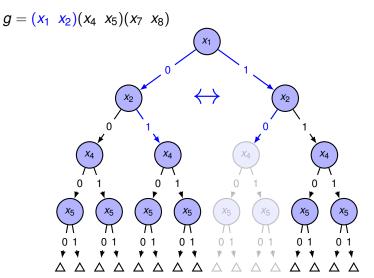
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Using symmetries to prune search space



Using symmetries to prune search space



Adds additional constraints to prune search space.

Generates symmetry breaking predicates (SBP)

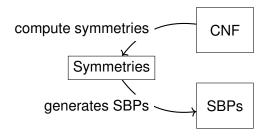
- Define lexicographic order
 - Define total order on variables
 - Define minimal value
- Forbid non minimal assignment with addition of SBP

Example:

$$x_1 \le x_2 \le x_3 \le x_4 \le x_5 \le x_6 \le x_7 \le x_8;$$
false $<$ true $g = (x_1 \ x_2)(x_4 \ x_5)(x_7 \ x_8)$

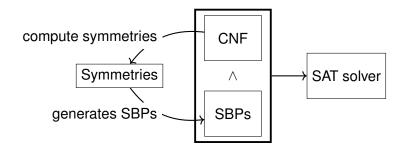
$x_1 \leq x_2$	$x_1 \vee \neg x_2$
$x_1=x_2\to x_4\le x_5$	$x_1 \vee x_2 \vee x_4 \vee \neg x_5$
	$\neg x_1 \lor \neg x_2 \lor x_4 \lor \neg x_5$
$x_1 = x_2 \wedge x_4 = x_5 \rightarrow x_8 \leq x_3$	$X_1 \vee X_2 \vee X_4 \vee X_5 \vee X_7 \vee \neg X_8$
	$\neg x_1 \vee \neg x_2 \vee x_4 \vee x_5 \vee x_7 \vee \neg x_8$
	• • •

Static symmetry breaking



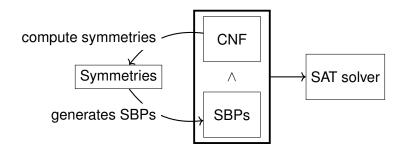
- Works well on many symmetric instances
- The solver can "explode" instead of being helped

Static symmetry breaking



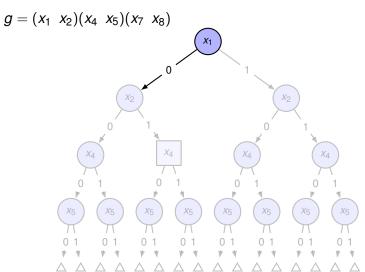
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Static symmetry breaking

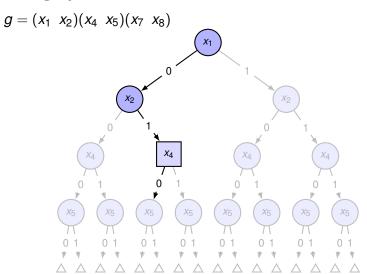


- Works well on many symmetric instances
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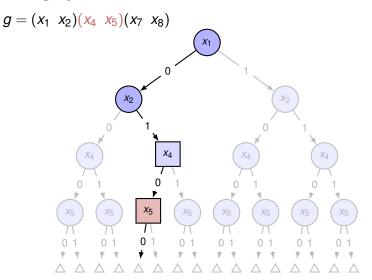
Using symmetries to accelerate tree traversal



Using symmetries to accelerate tree traversal

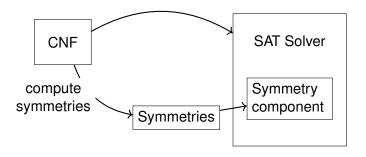


Using symmetries to accelerate tree traversal



Use symmetries to deduce symmetrical facts.

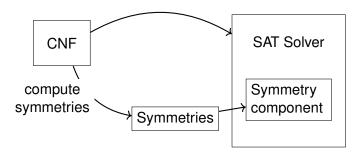
Dynamic Symmetry Breaking



Different approaches:

- Symmchaff [Sab05]
- Symmetry Propagation (SP) [DBdC⁺12]
- Symmetry Learning Scheme (SLS) [BNOS10]
- Symmetry Explanation Leaning (SEL) [DBB17]

Dynamic Symmetry Breaking



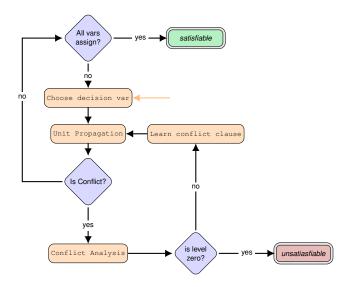
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Works under some conditions

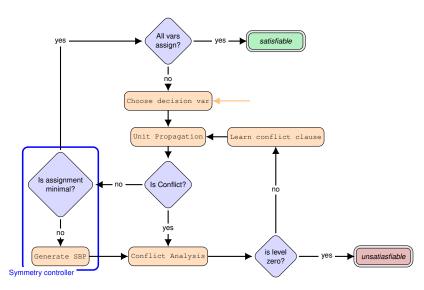
Our contribution CDCL[Sym]

Compute and inject SBP opportunistically, during the solving



Our contribution CDCL[Sym]

Compute and inject SBP opportunistically, during the solving



Symmetry status

- reducer: $g.\alpha \prec \alpha$
- inactive: $\alpha \prec g.\alpha$
- active: not enough information

Efficient implementation of symmetry status

Keep track the smallest unassigned variable x:

- **①** $\alpha(g.x) \leq \alpha(x)$, then *g* is reducer ⇒ Effective SBP (ESBP)
- 2 $\alpha(x) \leq \alpha(g.x)$, then g is inactive $\Rightarrow g$ cannot reduce α
- 3 $\alpha(g.x)$ or $\alpha(x)$ is unassigned then g is active

Update whenever variables are assigned / unassigned

- 1 reducer: $\alpha(g.x) \leq \alpha(x)$
- 2 inactive: $\alpha(x) \leq \alpha(g.x)$
- 3 active: $\alpha(g.x)$ or $\alpha(x)$ is unassigned

$$x_1 \le x_2 \le x_3 \le x_4 \le x_5 \le x_6 \le x_7 \le x_8$$
; false < true
 $g_1 = (x_2 \quad x_3) \quad (x_5 \quad x_6) \quad (x_8 \quad x_9) \quad x = x_2 \quad g.x = x_3$ active
 $g_2 = (x_1 \quad x_2) \quad (x_4 \quad x_5) \quad (x_7 \quad x_8) \quad x = x_1 \quad g.x = x_2$ active
...

 $\alpha = \{$

- 1 reducer: $\alpha(g.x) \leq \alpha(x)$
- 2 inactive: $\alpha(x) \leq \alpha(g.x)$
- 3 active: $\alpha(g.x)$ or $\alpha(x)$ is unassigned

$$x_1 \le x_2 \le x_3 \le x_4 \le x_5 \le x_6 \le x_7 \le x_8$$
; false < true $g_1 = \begin{pmatrix} x_2 & x_3 \end{pmatrix} \begin{pmatrix} x_5 & x_6 \end{pmatrix} \begin{pmatrix} x_8 & x_9 \end{pmatrix} \begin{vmatrix} x = x_2 & g.x = x_3 \\ & & \text{active} \end{pmatrix}$ $g_2 = \begin{pmatrix} x_1 & x_2 \end{pmatrix} \begin{pmatrix} x_4 & x_5 \end{pmatrix} \begin{pmatrix} x_7 & x_8 \end{pmatrix} \begin{vmatrix} x = x_1 & g.x = x_2 \\ & & \text{active} \end{pmatrix}$...

- 1 reducer: $\alpha(g.x) \leq \alpha(x)$
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$$\alpha = \{\neg x_2, \neg x_3, x_1\}$$

- 1 reducer: $\alpha(g.x) \leq \alpha(x)$
- 2 inactive: $\alpha(x) \leq \alpha(g.x)$
- 3 active: $\alpha(g.x)$ or $\alpha(x)$ is unassigned

$$x_1 \leq x_2 \leq x_3 \leq x_4 \leq x_5 \leq x_6 \leq x_7 \leq x_8$$
; false < true $g_1 = \begin{pmatrix} x_2 & x_3 \end{pmatrix} \begin{pmatrix} x_5 & x_6 \end{pmatrix} \begin{pmatrix} x_8 & x_9 \end{pmatrix} \begin{vmatrix} x = x_5 & g.x = x_6 \\ & \text{active} \end{pmatrix}$ $g_2 = \begin{pmatrix} x_1 & x_2 \end{pmatrix} \begin{pmatrix} x_4 & x_5 \end{pmatrix} \begin{pmatrix} x_7 & x_8 \end{pmatrix} \begin{vmatrix} x = x_1 & g.x = x_2 \\ & \text{reducer} \end{pmatrix}$... $\alpha = \{\neg x_2, \neg x_3, x_1\}$ g_2 generates $\omega = \{\neg x_1, x_2\}$

CDCL[Sym] Implementation

 Packaged as a library cosy³, to be combined with your solver

$$ightarrow$$
 e.g. +3% LOC on MiniSAT.

- Follows symmetry status
- Should work with any enumerative SAT solver

³https://github.com/lip6/cosy

Experiments

Benchmark:

- from SAT contests 2012 2017
- retain only instances for which bliss finds significant symmetries in 1000s
- 1350 symmetric instances (out of 3700)

Setup:

- four tools
 - MiniSat (no symmetry, baseline)
 - MiniSat + BreakID (SOTA SAT solver using symmetries)
 - MiniSat + Shatter (SOTA SAT solver using symmetries)
 - MiniSym = MiniSat + CDCL[Sym] (our approach)
- 5000s timeout, 8GB memory
- includes time to compute symmetries (except for MiniSat)

Experimental results

bliss gives more generators than saucy3

Figure: Cactus plot total number of instances

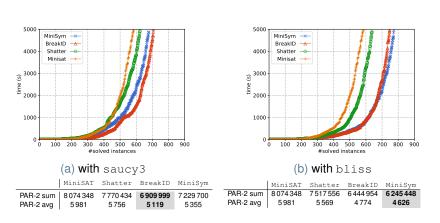


Figure: Time comparison

Experimental results (UNSAT versus SAT)

	MiniSAT	Shatter	BreakID	MiniSym		MiniSAT	Shatter	BreakID	MiniSym
TOTAL (no dup)	261	302	371	345	TOTAL (no dup	261	324	415	439
(a) With saucy3					(b) With bliss				

Figure: Comparison on UNSAT instances



Figure: Comparison on SAT instances

ESBP + SP

Compose the symmetry propagation and the ESBP prune the decision tree while accelerating its traversal

Problems

- ESBP breaks symmetries (incrementally)
- SP considers the manipulated symmetries valid all the time

In hybrid approach, SP must be able to identify valid symmetries

Macro level

 $\omega_1 \leftarrow \text{(Local symmetries)}$ $\omega_2 \leftarrow \text{(Local symmetries)}$ $\omega_3 \leftarrow \text{(Local symmetries)}$ $\omega_4 \leftarrow \text{(Local symmetries)}$

Micro level

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 $\omega_1 \leftarrow \text{(Local symmetries)}$ $\omega_2 \leftarrow \text{(Local symmetries)}$ $\omega_3 \leftarrow \text{(Local symmetries)}$ $\omega_4 \leftarrow \text{(Local symmetries)}$ ω_5 ω_5

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Compute valid local symmetries on-the-fly at a minimal cost.

Experimental results

Benchmark:

- from SAT contests 2012 2018
- retain only instances for which bliss finds significant symmetries in 1000s
- 1400 symmetric instances (out of 4000)

Setup:

- Three tools
 - MiniSat SP (Minisat with Symmetry Propagation)
 - MiniSat ESBP (Minisat with CDCL[Sym])
 - Minisat ESBP-SP (our approach)
- 7200s timeout

Results:

Solver	PAR-2	ALL	SAT	UNSAT
SP	1674h00	876	406	470
ESBP	1578h30	904	416	488
ESBP-SP	1570h15	911	420	491

Conclusion

- A new dynamic symmetry breaking approach
 - Generation of SBP on the fly
 - Package as a library cosyusable with any CDCL solver
 - Overcomes drawbacks of the existing approaches

- A new hybrid approach (ESBP-SP)
 - Take advantage of static and dynamic approach

Perspectives

Combination of ESBP with other dynamic symmetry breaking approach

Exploitation of partial symmetries

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Thanks!



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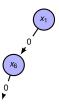
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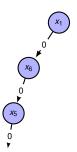
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\omega_{3} = \{\neg x_{1}, \neg x_{5}\}
\omega_{4} = \{\neg x_{2}, \neg x_{4}\}
\omega_{5} = \{\neg x_{3}, \neg x_{4}\}
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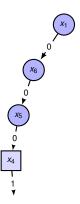
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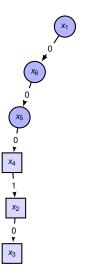
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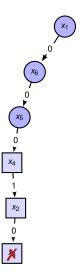
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$$\omega_7 = \{x_1, \neg x_4\}$$

Weakly active symmetries

Logical consequence

When ω is satisfied in all satisfying assignments of φ , we say that ω is a logical consequence of φ , and we denote this by $\varphi \vdash \omega$.

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Symmetry propagation

Let σ a weakly active symmetry, then

$$\varphi \cup \alpha \vdash \{I\} \Leftrightarrow \varphi \cup \alpha \vdash \sigma.\{I\}$$

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Local Symmetries

Let φ be a formula. We define $L_{\omega,\varphi}$, the set of *local symmetries* for a clause ω , and with respect to a formula φ , as follows:

$$L_{\omega,\varphi} = \{ \sigma \in \mathfrak{S} \mid \varphi \vdash \sigma.\omega \}$$

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We can state that:

$$\bigcap_{\omega\in\varphi} L_{\omega,\varphi}\subseteq G.$$

Computing local symmetries

Formula can be decomposed as : $\varphi = \varphi_o \cup \varphi_e \cup \varphi_d$ where

- φ_o is the set of the original clauses
- φ_e is the set of ESBPs
- φ_d is the set of deduced clauses.

Local symmetries

- $\omega \in \varphi_o, L_{\omega,\varphi} \supseteq G$
- $\omega \in \varphi_e, L_{\omega,\varphi} \supseteq Stab(\omega) = \{ \sigma \in G \mid \omega = \sigma.\omega \}$
- $\omega \in \varphi_d, L_{\omega,\varphi} \supseteq (\bigcap_{\omega' \in \varphi_1} L_{\omega',\varphi}) \cup Stab(\omega)$

where φ_1 is the set of clauses that derives ω .