# Exploitation of dynamic symmetries for solving SAT problems

Doctorat de Sorbonne Université

#### Hakan Metin

Le, 18 décembre 2019

Rapporteurs:

PASCAL FONTAINE Professeur, Université de Liège LAURE PETRUCCI Professeur, Université Paris 13

**Examinateurs:** 

BART BOGAERTS
JEAN-MICHEL COUVREUR
EMMANUELLE ENCRENAZ
Assistant Professor, Vrije Universiteit Brussel
Professeur, Université d'Orléans
Maître de conférences, Sorbonne Université

Directeurs:

SOUHEIB BAARIR Maître de conférences, Université Paris Nanterre FABRICE KORDON Professeur, Sorbonne Université



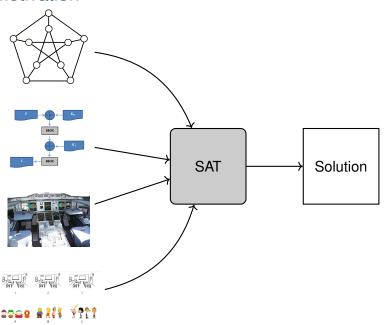


#### Motivation

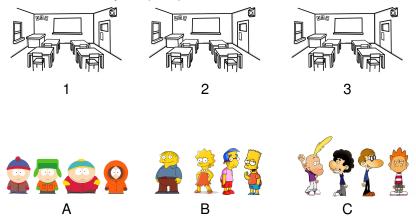
#### Boolean SATisfiability is widely used in different domains

- Artificial intelligence (planning [KS<sup>+</sup>92], ...)
- Bioinformatics (haplotype inference [LMS06], ...)
- Security (cryptanalysis [MM00], ...)
- Computationally hard problems (ramsey numbers, graph coloring, ...)
- Formal methods,(bounded model checking [BCCZ99], ...)

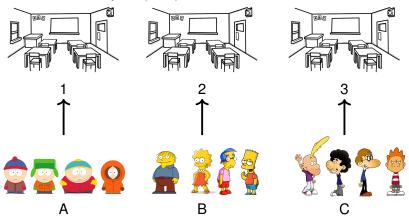
# Motivation



# SAT: an example (1/2)

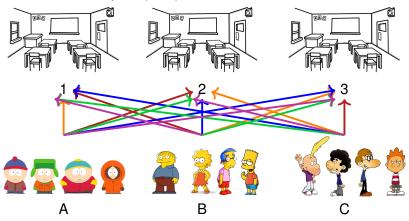


# SAT: an example (1/2)



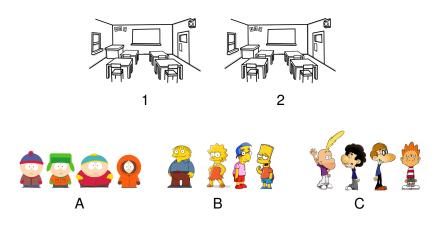
YES! SAT 
$$\alpha = (A, 1), (B, 2), (C, 3)$$

# SAT: an example (1/2)

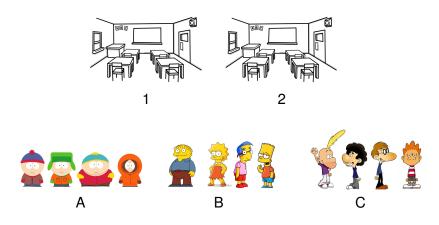


YES! SAT 
$$\alpha = (A, 1), (B, 2), (C, 3)$$
  
Many solutions  $\alpha = (A, 2), (B, 3), (C, 1); \cdots$ 

# SAT: an example (2/2)



# SAT: an example (2/2)



Is it possible to attribute each group to a unique classroom?

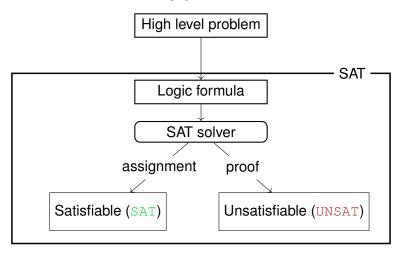
No! UNSAT

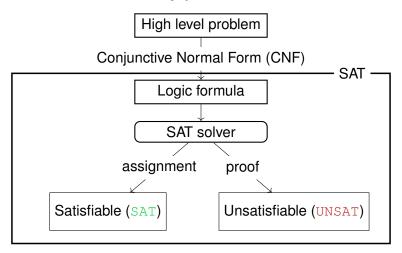
5/31

# Encoding the problem

#### Conjunctive Normal Form (CNF)

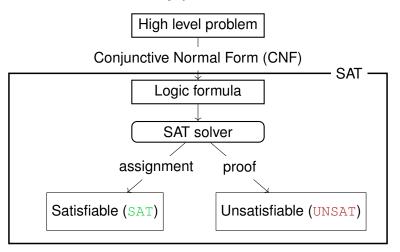
$$(A,1)(A,2)(A,3) & x_1 \lor x_2 \lor x_3 \\ (B,1)(B,2)(B,3) & x_4 \lor x_5 \lor x_6 \\ (C,1)(C,2)(C,3) & x_7 \lor x_8 \lor x_9 \\ \hline \neg (A,1)\neg (B,1) & \neg x_1 \lor \neg x_4 \\ \neg (A,1)\neg (C,1) & \neg x_4 \lor \neg x_7 \\ \hline \neg (B,1)\neg (C,1) & \neg x_4 \lor \neg x_7 \\ \hline \neg (A,2)\neg (B,2) & \neg x_2 \lor \neg x_5 \\ \neg (A,2)\neg (C,2) & \neg x_2 \lor \neg x_8 \\ \hline \neg (B,2)\neg (C,2) & \neg x_5 \lor \neg x_8 \\ \hline \neg (A,3)\neg (B,3) & \neg x_3 \lor \neg x_6 \\ \hline \neg (A,3)\neg (C,3) & \neg x_6 \lor \neg x_9 \\ \hline \neg (B,3)\neg (C,3) & \neg x_6 \lor \neg x_9 \\ \hline \end{pmatrix}$$





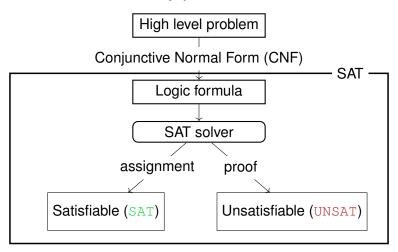
#### CNF representation:

$$\underbrace{\left(x_1 \lor x_2 \lor \neg x_3\right)}_{\text{Clause with literals } x_1, x_2, \neg x_3}$$



#### CNF representation:

Formula (CNF)
$$\underbrace{\left(x_1 \lor x_2 \lor \neg x_3\right)}_{Clause} \land \left(\neg x_1 \lor \neg x_2\right) \land \left(x_2 \lor \neg x_4\right)$$



Clause representation as a set:

$$(x_1 \lor x_2 \lor \neg x_3) \to \{x_1, x_2, \neg x_3\}$$

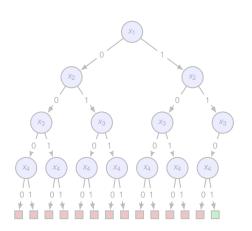
# SAT Solving

Solving SAT formula is known to be **NP-complete** [Coo71]

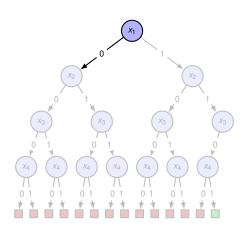
#### Enumerative algorithms:

- Davis, Putnam, Logemann, and Loveland (DPLL) [DLL62]
  - Boolean Constraint Propagation (BCP)

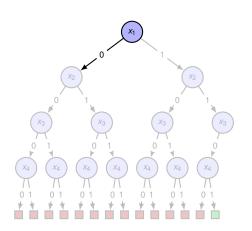
- Conflict Driven Clause Learning (CDCL) [MSS99]
  - Derived from DPLL
  - Clause learning



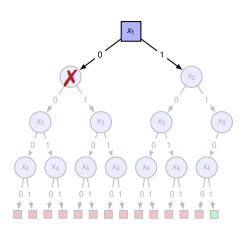
$$\omega_{1} = \{x_{1}, x_{2}, x_{3}, x_{4}\} 
\omega_{2} = \{x_{1}, \neg x_{4}\} 
\omega_{3} = \{x_{1}, x_{4}\} 
\omega_{4} = \{x_{2}, \neg x_{4}\} 
\omega_{5} = \{x_{2}, x_{4}\} 
\omega_{6} = \{x_{3}, x_{4}\}$$



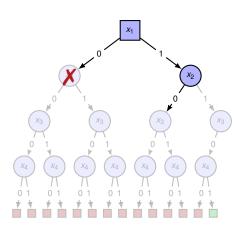
$$\omega_{1} = \{x_{1}, x_{2}, x_{3}, x_{4}\} 
\omega_{2} = \{x_{1}, \neg x_{4}\} 
\omega_{3} = \{x_{1}, x_{4}\} 
\omega_{4} = \{x_{2}, \neg x_{4}\} 
\omega_{5} = \{x_{2}, x_{4}\} 
\omega_{6} = \{x_{3}, x_{4}\}$$



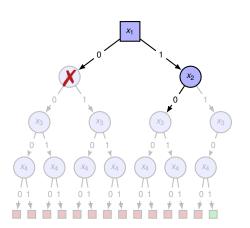
$$\omega_{1} = \{x_{1}, x_{2}, x_{3}, x_{4}\} 
\omega_{2} = \{x_{1}, \neg x_{4}\} 
\omega_{3} = \{x_{1}, x_{4}\} 
\omega_{4} = \{x_{2}, \neg x_{4}\} 
\omega_{5} = \{x_{2}, x_{4}\} 
\omega_{6} = \{x_{3}, x_{4}\}$$



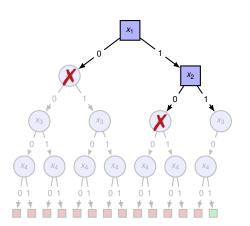
$$\omega_{1} = \{x_{1}, x_{2}, x_{3}, x_{4}\} 
\omega_{2} = \{x_{1}, \neg x_{4}\} 
\omega_{3} = \{x_{1}, x_{4}\} 
\omega_{4} = \{x_{2}, \neg x_{4}\} 
\omega_{5} = \{x_{2}, x_{4}\} 
\omega_{6} = \{x_{3}, x_{4}\} 
\omega_{7} = \{x_{1}\}$$



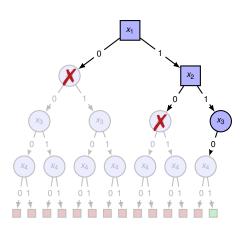
$$\omega_{1} = \{x_{1}, x_{2}, x_{3}, x_{4}\} 
\omega_{2} = \{x_{1}, \neg x_{4}\} 
\omega_{3} = \{x_{1}, x_{4}\} 
\omega_{4} = \{x_{2}, \neg x_{4}\} 
\omega_{5} = \{x_{2}, x_{4}\} 
\omega_{6} = \{x_{3}, x_{4}\} 
\omega_{7} = \{x_{1}\}$$



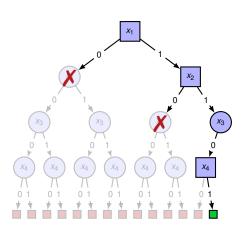
$$\omega_{1} = \{x_{1}, x_{2}, x_{3}, x_{4}\} 
\omega_{2} = \{x_{1}, \neg x_{4}\} 
\omega_{3} = \{x_{1}, x_{4}\} 
\omega_{4} = \{x_{2}, \neg x_{4}\} 
\omega_{5} = \{x_{2}, x_{4}\} 
\omega_{6} = \{x_{3}, x_{4}\} 
\omega_{7} = \{x_{1}\}$$



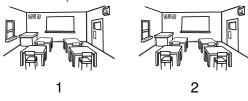
$$\omega_{1} = \{X_{1}, X_{2}, X_{3}, X_{4}\} 
\omega_{2} = \{X_{1}, \neg X_{4}\} 
\omega_{3} = \{X_{1}, X_{4}\} 
\omega_{4} = \{X_{2}, \neg X_{4}\} 
\omega_{5} = \{X_{2}, X_{4}\} 
\omega_{6} = \{X_{3}, X_{4}\} 
\omega_{7} = \{X_{1}\} 
\omega_{8} = \{X_{2}\}$$

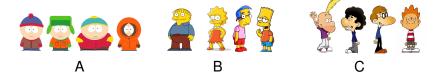


$$\omega_{1} = \{X_{1}, X_{2}, X_{3}, X_{4}\} 
\omega_{2} = \{X_{1}, \neg X_{4}\} 
\omega_{3} = \{X_{1}, X_{4}\} 
\omega_{4} = \{X_{2}, \neg X_{4}\} 
\omega_{5} = \{X_{2}, X_{4}\} 
\omega_{6} = \{X_{3}, X_{4}\} 
\omega_{7} = \{X_{1}\} 
\omega_{8} = \{X_{2}\}$$



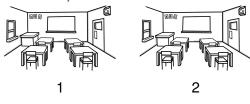
$$\omega_{1} = \{X_{1}, X_{2}, X_{3}, X_{4}\} 
\omega_{2} = \{X_{1}, \neg X_{4}\} 
\omega_{3} = \{X_{1}, X_{4}\} 
\omega_{4} = \{X_{2}, \neg X_{4}\} 
\omega_{5} = \{X_{2}, X_{4}\} 
\omega_{6} = \{X_{3}, X_{4}\} 
\omega_{7} = \{X_{1}\} 
\omega_{8} = \{X_{2}\}$$

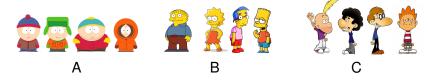




Is it possible to attribute each group to a unique classroom?

В

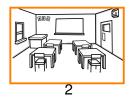


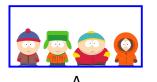


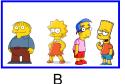
Is it possible to attribute each group to a unique classroom?

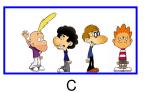
No!











Is it possible to attribute each group to a unique classroom?

No!

Presence of symmetries hinders the performance of the solver

# Symmetry

A symmetry (permuation) g is a bijective function (on variables) that leaves the formula invariant

$$g = \begin{pmatrix} x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_7 & x_8 & x_9 \\ x_2 & x_1 & x_3 & x_5 & x_4 & x_6 & x_8 & x_7 & x_9 \end{pmatrix} \rightarrow (x_1 \ x_2)(x_4 \ x_5)(x_7 \ x_8)$$

$$\begin{array}{c} \omega_1 = \{x_1, x_2, x_3\} & & \omega_1 = \{x_2, x_1, x_3\} \\ \omega_2 = \{x_4, x_5, x_6\} & & \omega_2 = \{x_5, x_4, x_6\} \\ \omega_3 = \{x_7, x_8, x_9\} & & \omega_3 = \{x_8, x_7, x_9\} \\ \omega_4 = \{-x_1, -x_4\} & & \omega_7 = \{-x_2, -x_5\} \\ \omega_5 = \{-x_1, -x_7\} & & \omega_8 = \{-x_2, -x_8\} \\ \omega_6 = \{-x_4, -x_7\} & & \omega_9 = \{-x_5, -x_8\} \\ \omega_9 = \{-x_5, -x_8\} & & \omega_9 = \{-x_1, -x_7\} \\ \omega_9 = \{-x_5, -x_8\} & & \omega_1 = \{-x_3, -x_6\} \\ \omega_{11} = \{-x_3, -x_9\} & & \omega_{12} = \{-x_6, -x_9\} \\ & \omega_{12} = \{-x_6, -x_9\} & & \omega_{12} = \{-x_6, -x_9\} \\ \end{array}$$

The set of symmetries of a formula is a group noted G

# Computing symmetries of a SAT problem

CNF formula

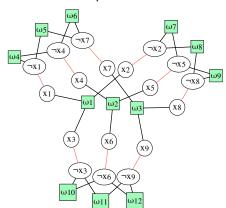
$$\begin{array}{l} (x_1 \vee x_2 \vee x_3) \wedge (x_4 \vee x_5 \vee x_6) \wedge (x_7 \vee x_8 \vee x_9) \\ \wedge (\neg x_1 \vee \neg x_4) \wedge (\neg x_1 \vee \neg x_7) \wedge (\neg x_4 \vee \neg x_7) \\ \wedge (\neg x_2 \vee \neg x_5) \wedge (\neg x_2 \vee \neg x_8) \wedge (\neg x_5 \vee \neg x_8) \\ \wedge (\neg x_3 \vee \neg x_6) \wedge (\neg x_3 \vee \neg x_9) \wedge (\neg x_6 \vee \neg x_9) \end{array}$$

# Computing symmetries of a SAT problem $(x_1 \lor x_2 \lor x_3) \land (x_4 \lor x_5 \lor x_6) \land (x_7 \lor x_8 \lor x_9)$

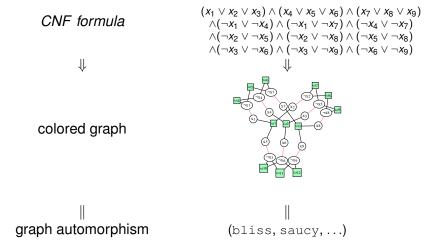
CNF formula

colored graph

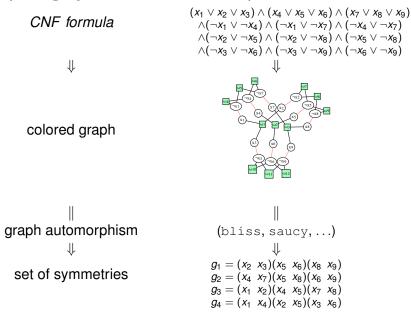




# Computing symmetries of a SAT problem



# Computing symmetries of a SAT problem



#### Orbit

Orbit of an assignment  $\alpha = G.\alpha = \{g.\alpha \mid g \in G\}$ 

#### Orbit

Orbit of an assignment  $\alpha = G \cdot \alpha = \{g \cdot \alpha \mid g \in G\}$ 

#### Example:

full assignment

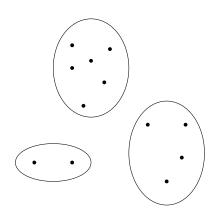
13/31

#### Orbit

Orbit of an assignment  $\alpha = G.\alpha = \{g.\alpha \mid g \in G\}$ 

#### Example:

- · full assignment
- orbit

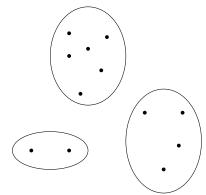


#### Orbit

Orbit of an assignment  $\alpha = G.\alpha = \{g.\alpha \mid g \in G\}$ 

#### Example:

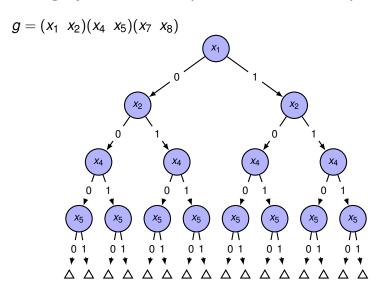
- full assignment
- orbit



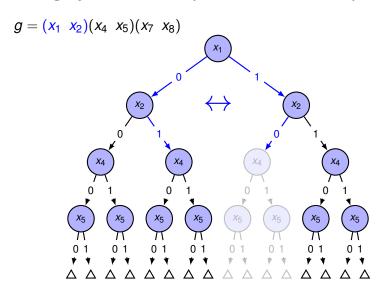
#### Equivalence relation with respect to SAT:

- Either  $G.\alpha$  contains no solution
- Or all elements of  $G.\alpha$  are solutions

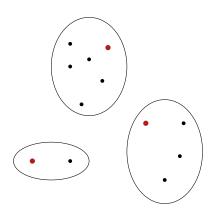
## Using symmetries to prune the search space



## Using symmetries to prune the search space



# Representative assignment



- full assignment
- orbit
- representative assignment

- Define lexicographic order
  - Define total order on variables
  - Define minimal value
- Forbid non minimal assignment for each orbit

$$x_1 \le x_2 \le x_3 \le x_4 \le x_5 \le x_6 \le x_7 \le x_8; \mathbb{F} < \mathbb{T}$$
  
 $g = (x_1 \ x_2)(x_4 \ x_5)(x_7 \ x_8)$ 

$x_1 \mid x_2 \mid x_3 \mid x_4 \mid x_5 \mid \cdots \mid \text{lex-leader} \mid$	SBP

- Define lexicographic order
  - Define total order on variables
  - Define minimal value
- · Forbid non minimal assignment for each orbit

$$x_1 \le x_2 \le x_3 \le x_4 \le x_5 \le x_6 \le x_7 \le x_8; \mathbb{F} < \mathbb{T}$$
  
 $g = (x_1 \ x_2)(x_4 \ x_5)(x_7 \ x_8)$ 

	x <sub>1</sub>	<i>x</i> <sub>2</sub>	<i>X</i> <sub>3</sub>	<i>x</i> <sub>4</sub>	<i>x</i> <sub>5</sub>		lex-leader	SBP
<i>O</i> <sub>1</sub>	F	Т	-	-	-		<b> </b>	

- Define lexicographic order
  - Define total order on variables
  - Define minimal value
- · Forbid non minimal assignment for each orbit

$$x_1 \le x_2 \le x_3 \le x_4 \le x_5 \le x_6 \le x_7 \le x_8; \mathbb{F} < \mathbb{T}$$
  
 $g = (x_1 \ x_2)(x_4 \ x_5)(x_7 \ x_8)$ 

	<i>x</i> <sub>1</sub>	<i>x</i> <sub>2</sub>	<i>X</i> <sub>3</sub>	<i>x</i> <sub>4</sub>	<i>X</i> <sub>5</sub>		lex-leader	SBP
0.	F	Т	-	_	_		✓ ×	
<i>U</i> <sub>1</sub>	Т	F	–	_	-		×	$\rightarrow \neg x_1 \lor x_2$
	I							

- Define lexicographic order
  - Define total order on variables
  - Define minimal value
- Forbid non minimal assignment for each orbit

$$x_1 \le x_2 \le x_3 \le x_4 \le x_5 \le x_6 \le x_7 \le x_8; \mathbb{F} < \mathbb{T}$$
  
 $g = (x_1 \ x_2)(x_4 \ x_5)(x_7 \ x_8)$ 

	<i>x</i> <sub>1</sub>	<i>x</i> <sub>2</sub>	<i>X</i> <sub>3</sub>	<i>x</i> <sub>4</sub>	<i>x</i> <sub>5</sub>		lex-leader	SBP
O <sub>1</sub>	F T	T F	_	_	_		✓ X	$\rightarrow \neg x_1 \lor x_2$
							/	

- Define lexicographic order
  - Define total order on variables
  - Define minimal value
- Forbid non minimal assignment for each orbit

$$x_1 \le x_2 \le x_3 \le x_4 \le x_5 \le x_6 \le x_7 \le x_8; \mathbb{F} < \mathbb{T}$$
  
 $g = (x_1 \ x_2)(x_4 \ x_5)(x_7 \ x_8)$ 

$\begin{array}{c c c c c c c c c c c c c c c c c c c $							lex-leader	SBP
$\Omega_{t}$	F	Т	-	_	-		✓ X	
	Т	F	-	_	-		×	$\rightarrow \neg x_1 \lor x_2$
	F	F	-	F	Т		/	$\bigg  \to x_1 \vee x_2 \vee \neg x_4 \vee x_5$
$O_2$	F	F	–	Т	F		×	$\rightarrow x_1 \vee x_2 \vee \neg x_4 \vee x_5$

- Define lexicographic order
  - Define total order on variables
  - Define minimal value
- Forbid non minimal assignment for each orbit

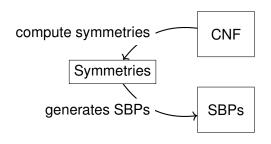
#### Example:

$$x_1 \le x_2 \le x_3 \le x_4 \le x_5 \le x_6 \le x_7 \le x_8; \mathbb{F} < \mathbb{T}$$
  
 $g = (x_1 \ x_2)(x_4 \ x_5)(x_7 \ x_8)$ 

$  x_1   x_2   x_3   x_4   x_5   \cdots   lex$						lex-leader	SBP	
$O_1$	F	Т	-	_	-		✓ X	
	Т	F	–	_	-		X	$\rightarrow \neg x_1 \lor x_2$
0-	F	F	-	F	T		✓	$\bigg  \to x_1 \vee x_2 \vee \neg x_4 \vee x_5$
<b>U</b> <sub>2</sub>	F	F	-	Т	F		×	$\rightarrow x_1 \vee x_2 \vee \neg x_4 \vee x_5$

. .

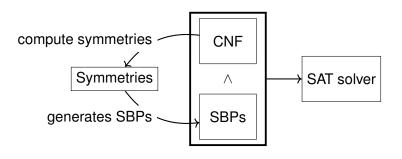
## Static symmetry breaking



#### Different approaches:

- Shatter [ASM06]
- BreakID [DBBD16]
- ...

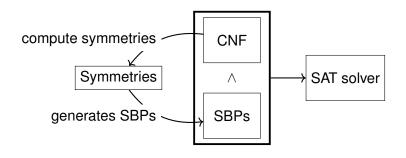
## Static symmetry breaking



#### Different approaches:

- Shatter [ASM06]
- BreakID [DBBD16]
- ...

## Static symmetry breaking



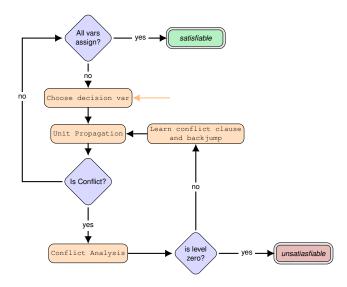
#### Different approaches:

- Shatter [ASM06]
- BreakID [DBBD16]
- ...

The solver can "explode" instead of being helped

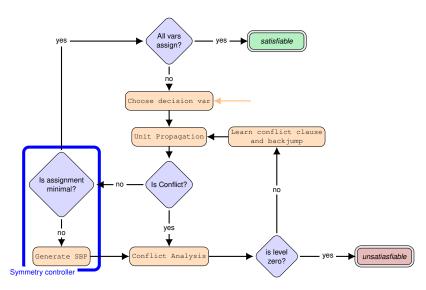
## Our contribution CDCL[Sym] [MBCK18]

Compute and inject SBP opportunistically, during the solving



## Our contribution CDCL[Sym] [MBCK18]

Compute and inject SBP opportunistically, during the solving



## Symmetry status

- reducer:  $g.\alpha \prec \alpha$
- inactive:  $\alpha \prec g.\alpha$
- active: not enough information

## Efficient implementation of symmetry status

Keep track the smallest unassigned variable x:

- **①**  $\alpha(g.x) \leq \alpha(x)$ , then *g* is reducer ⇒ Effective SBP (ESBP)
- 2  $\alpha(x) \leq \alpha(g.x)$ , then g is inactive  $\Rightarrow g$  cannot reduce  $\alpha$
- 3  $\alpha(g.x)$  or  $\alpha(x)$  is unassigned then g is active

Update whenever variables are assigned / unassigned

$$g_1 = (x_2 \ x_3)(x_5 \ x_6)(x_8 \ x_9)$$
  $g_2 = (x_1 \ x_2)(x_4 \ x_5)(x_7 \ x_8)$ 

$$F < T \quad x_1 \le x_2 \le x_3 \le x_4 \le x_5 \le x_6 \le x_7 \le x_8 \le x_9$$

$$\overline{g_1}$$

$$\alpha = \quad \underline{U} \quad \overline{U} \quad U \quad U \quad U \quad U \quad U \quad U$$

$$\underline{g_2} \quad \Box$$

$$g_1 = (x_2 \ x_3)(x_5 \ x_6)(x_8 \ x_9)$$
  $g_2 = (x_1 \ x_2)(x_4 \ x_5)(x_7 \ x_8)$ 

$$F < T \quad x_1 \le x_2 \le x_3 \le x_4 \le x_5 \le x_6 \le x_7 \le x_8 \le x_9$$

$$\overline{g_1}$$

$$\alpha = \underbrace{U}_{F} \quad U \quad U \quad U \quad U \quad U \quad U \quad U$$

$$\underline{g_2} \quad \Box$$

$$g_1 = (x_2 \ x_3)(x_5 \ x_6)(x_8 \ x_9)$$

$$g_2 = (x_1 \ x_2)(x_4 \ x_5)(x_7 \ x_8)$$

$$F < T \quad x_1 \le x_2 \le x_3 \le x_4 \le x_5 \le x_6 \le x_7 \le x_8 \le x_9$$

$$\overline{g_1}$$

$$\alpha = \underline{T} \quad F \quad F \quad U \quad \overline{U} \quad U \quad U \quad U$$

$$\underline{g_2} \quad \Box$$

$$g_2$$
 generates ESBP  $\omega = \{\neg x_1, x_2\}$ 

## CDCL[Sym] Implementation

- Packaged as a library cosy<sup>1</sup>
- Lightweight
- Fast update and low memory
- Follows symmetry status

- Works with any enumerative SAT solver
- Can be integrated easily

ightarrow e.g. +3% LOC on MiniSAT.

<sup>1</sup>https://github.com/lip6/cosy

## **Experiments**

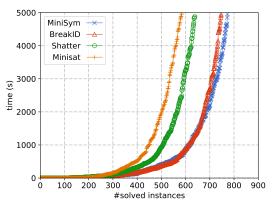
#### Benchmark:

- from SAT contests 2012 2017
- filter: bliss finds significant symmetries in 1000s
- 36 % of instances, 1 350/3 700

#### Setup:

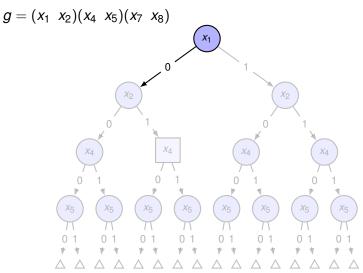
- four tools
  - MiniSat (no symmetry, baseline)
  - MiniSat + BreakID (SOTA SAT solver using symmetries)
  - MiniSat + Shatter (SOTA SAT solver using symmetries)
  - MiniSym = MiniSat + CDCL[Sym] (our approach)
- 5000s timeout, 8GB memory
- includes time to compute symmetries (except for MiniSat)

# Experimental results

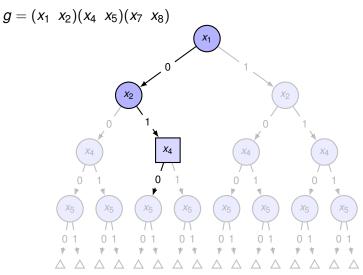


Solver	PAR-2	ALL	SAT	UNSAT
MiniSAT	2243h	586	325	261
Shatter	2088h	640	316	324
BreakID	1790h	749	334	415
MiniSym	1735h	775	336	439

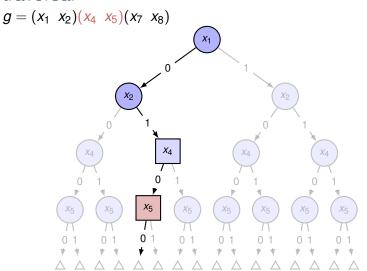
# Using symmetries to accelerate the tree traversal



# Using symmetries to accelerate the tree traversal

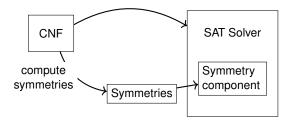


# Using symmetries to accelerate the tree traversal



Use symmetries to deduce symmetrical facts.

# Dynamic Symmetry Breaking

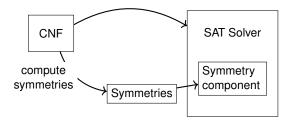


#### Different approaches:

- Symmchaff [Sab05]
- Symmetry Propagation (SP) [DBdC+12]
- Symmetry Learning Scheme (SLS) [BNOS10]
- Symmetry Explanation Leaning (SEL) [DBB17]

• ...

# Dynamic Symmetry Breaking



#### Different approaches:

- Symmchaff [Sab05]
- Symmetry Propagation (SP) [DBdC+12]
- Symmetry Learning Scheme (SLS) [BNOS10]
- Symmetry Explanation Leaning (SEL) [DBB17]
- ...

Cannot handle some instances solved by static approach

## ESBP + SP [MBK19]

Compose the symmetry propagation and the ESBP prune the decision tree while accelerating its traversal

#### Problems:

- ESBP breaks symmetries (incrementally)
- SP considers the manipulated symmetries valid all time

In a hybrid approach, SP must be able to identify valid symmetries

 $\omega_1 \leftarrow \text{(Local symmetries)}$   $\omega_2 \leftarrow \text{(Local symmetries)}$  Formula  $\leftarrow \text{(Symmetries)}$   $\omega_3 \leftarrow \text{(Local symmetries)}$   $\omega_4 \leftarrow \text{(Local symmetries)}$ 

Macro level  $\rightarrow$  Micro level

 $\omega_1 \leftarrow \text{(Local symmetries)}$   $\omega_2 \leftarrow \text{(Local symmetries)}$   $\omega_3 \leftarrow \text{(Local symmetries)}$   $\omega_4 \leftarrow \text{(Local symmetries)}$   $\omega_5$   $\omega_5$  Macro level  $\rightarrow$  Micro level

```
\omega_1 \leftarrow \text{(Local symmetries)} \omega_2 \leftarrow \text{(Local symmetries)} \omega_3 \leftarrow \text{(Local symmetries)} \omega_4 \leftarrow \text{(Local symmetries)} \omega_5 \leftarrow \text{(Local symmetries)} \omega_6 \leftarrow \text{(Local symmetries)} \omega_6 \leftarrow \text{(Local symmetries)}
```

Compute valid local symmetries on-the-fly at a minimal cost.

```
\omega_1 \leftarrow \text{(Local symmetries)} \omega_2 \leftarrow \text{(Local symmetries)} \omega_3 \leftarrow \text{(Local symmetries)} \omega_4 \leftarrow \text{(Local symmetries)} \omega_5 \leftarrow \text{(Local symmetries)} \omega_6 \leftarrow \text{(Local symmetries)} \omega_6 \leftarrow \text{(Local symmetries)}
```

Compute valid local symmetries on-the-fly at a minimal cost.

- Inductive construction of the valid symmetries
- During the solving
- At a minimal cost

## Experimental results

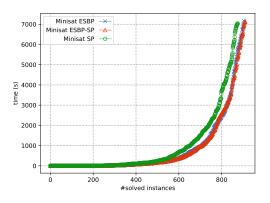
#### **Benchmark:**

- from SAT contests 2012 2018
- retain only instances for which bliss finds significant symmetries in 1000s
- 1400 symmetric instances (out of 4000)

#### Setup:

- three tools
  - MiniSat SP (Minisat with Symmetry Propagation)
  - MiniSat ESBP (Minisat with CDCL[Sym])
  - Minisat ESBP-SP (our approach)
- 7200s timeout

# Experimental results



Solver	PAR-2	ALL	SAT	UNSAT
SP	1674h00	876	406	470
ESBP	1578h30	904	416	488
ESBP-SP	1570h15	911	420	491

#### Conclusion

- A new dynamic symmetry breaking approach
  - Generation of SBP on the fly
  - Package as a library cosy usable with any CDCL solver
  - Overcomes drawbacks of the existing approaches

- A new hybrid approach (ESBP-SP)
  - Take advantage of static and dynamic approach
  - Introduce local symmetries

# Perspectives

 Combination of CDCL[Sym] with other dynamic symmetry breaking approach

Combination with parallel SAT solver

Exploitation of partial symmetries

# Perspectives

 Combination of CDCL[Sym] with other dynamic symmetry breaking approach

Combination with parallel SAT solver

Exploitation of partial symmetries

Thanks!



Fadi A. Aloul, Karem A. Sakallah, and Igor L. Markov. Efficient symmetry breaking for boolean satisfiability.

IEEE Trans. Computers, 55(5):549-558, 2006.



Armin Biere, Alessandro Cimatti, Edmund Clarke, and Yunshan Zhu.

#### Symbolic model checking without bdds.

Tools and Algorithms for the Construction and Analysis of Systems, pages 193–207, 1999.



Belaid Benhamou, Tarek Nabhani, Richard Ostrowski, and Mohamed Reda Saidi.

#### Enhancing clause learning by symmetry in sat solvers.

In 2010 22nd IEEE International Conference on Tools with Artificial Intelligence, volume 1, pages 329–335. IEEE, 2010.



Stephen A Cook.

#### The complexity of theorem-proving procedures.

In Proceedings of the third annual ACM symposium on Theory of computing, pages 151–158. ACM, 1971.



Jo Devriendt, Bart Bogaerts, and Maurice Bruynooghe.

Symmetric explanation learning: Effective dynamic symmetry handling for sat. In *International Conference on Theory and Applications of Satisfiability Testing*, pages 83–100. Springer, 2017.



Jo Devriendt, Bart Bogaerts, Maurice Bruynooghe, and Marc Denecker. Improved static symmetry breaking for sat.

In International Conference on Theory and Applications of Satisfiability Testing, pages 104–122. Springer, 2016.



Jo Devriendt, Bart Bogaerts, Broes de Cat, Marc Denecker, and Christopher Mears.

Symmetry propagation: Improved dynamic symmetry breaking in SAT. In *IEEE 24th International Conference on Tools with Artificial Intelligence, ICTAI 2012, Athens, Greece, November 7-9, 2012*, pages 49–56, 2012.



Martin Davis, George Logemann, and Donald Loveland.

A machine program for theorem-proving. *Commun. ACM*, 5(7):394–397, July 1962.



Henry A Kautz, Bart Selman, et al.

Planning as satisfiability. In *ECAI*, volume 92, pages 359–363, 1992.



Inês Lynce and Joao Marques-Silva.

Sat in bioinformatics: Making the case with haplotype inference.

In International Conference on Theory and Applications of Satisfiability Testing, pages 136–141. Springer, 2006.



Hakan Metin, Souheib Baarir, Maximilien Colange, and Fabrice Kordon. Cdclsym: Introducing effective symmetry breaking in sat solving.

In International Conference on Tools and Algorithms for the Construction and Analysis of Systems, pages 99–114. Springer, 2018.



Hakan Metin, Souheib Baarir, and Fabrice Kordon.

Composing symmetry propagation and effective symmetry breaking for sat solving.

In NASA Formal Methods Symposium, pages 316–332. Springer, 2019.



Fabio Massacci and Laura Marraro.

Logical cryptanalysis as a sat problem.

Journal of Automated Reasoning, 24(1):165–203, 2000.



Joao P Marques-Silva and Karem A Sakallah.

Grasp: A search algorithm for propositional satisfiability. *IEEE Transactions on Computers*, 48(5):506–521, 1999.



Ashish Sabharwal.

Symchaff: A structure-aware satisfiability solver.

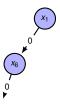
In AAAI, volume 5, pages 467-474, 2005.



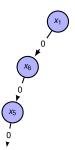
$$\omega_{1} = \{x_{1}, x_{2}, x_{3}\} 
\omega_{2} = \{x_{4}, x_{5}, x_{6}\} 
\omega_{3} = \{\neg x_{1}, \neg x_{5}\} 
\omega_{4} = \{\neg x_{2}, \neg x_{4}\} 
\omega_{5} = \{\neg x_{3}, \neg x_{4}\} 
\omega_{6} = \{\neg x_{3}, \neg x_{6}\}$$



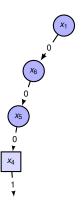
$$\omega_{1} = \{x_{1}, x_{2}, x_{3}\} 
\omega_{2} = \{x_{4}, x_{5}, x_{6}\} 
\omega_{3} = \{\neg x_{1}, \neg x_{5}\} 
\omega_{4} = \{\neg x_{2}, \neg x_{4}\} 
\omega_{5} = \{\neg x_{3}, \neg x_{4}\} 
\omega_{6} = \{\neg x_{3}, \neg x_{6}\}$$



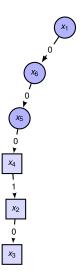
$$\omega_{1} = \{x_{1}, x_{2}, x_{3}\} 
\omega_{2} = \{x_{4}, x_{5}, x_{6}\} 
\omega_{3} = \{\neg x_{1}, \neg x_{5}\} 
\omega_{4} = \{\neg x_{2}, \neg x_{4}\} 
\omega_{5} = \{\neg x_{3}, \neg x_{4}\} 
\omega_{6} = \{\neg x_{3}, \neg x_{6}\}$$



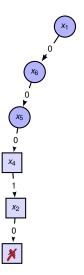
$$\omega_{1} = \{x_{1}, x_{2}, x_{3}\} 
\omega_{2} = \{x_{4}, x_{5}, x_{6}\} 
\omega_{3} = \{\neg x_{1}, \neg x_{5}\} 
\omega_{4} = \{\neg x_{2}, \neg x_{4}\} 
\omega_{5} = \{\neg x_{3}, \neg x_{4}\} 
\omega_{6} = \{\neg x_{3}, \neg x_{6}\}$$



$$\omega_{1} = \{x_{1}, x_{2}, x_{3}\} 
\omega_{2} = \{x_{4}, x_{5}, x_{6}\} 
\omega_{3} = \{\neg x_{1}, \neg x_{5}\} 
\omega_{4} = \{\neg x_{2}, \neg x_{4}\} 
\omega_{5} = \{\neg x_{3}, \neg x_{4}\} 
\omega_{6} = \{\neg x_{3}, \neg x_{6}\}$$



$$\omega_{1} = \{x_{1}, x_{2}, x_{3}\} 
\omega_{2} = \{x_{4}, x_{5}, x_{6}\} 
\omega_{3} = \{\neg x_{1}, \neg x_{5}\} 
\omega_{4} = \{\neg x_{2}, \neg x_{4}\} 
\omega_{5} = \{\neg x_{3}, \neg x_{4}\} 
\omega_{6} = \{\neg x_{3}, \neg x_{6}\}$$



$$\omega_{1} = \{x_{1}, x_{2}, x_{3}\} 
\omega_{2} = \{x_{4}, x_{5}, x_{6}\} 
\omega_{3} = \{\neg x_{1}, \neg x_{5}\} 
\omega_{4} = \{\neg x_{2}, \neg x_{4}\} 
\omega_{5} = \{\neg x_{3}, \neg x_{4}\} 
\omega_{6} = \{\neg x_{3}, \neg x_{6}\}$$



$$\omega_{1} = \{x_{1}, x_{2}, x_{3}\} 
\omega_{2} = \{x_{4}, x_{5}, x_{6}\} 
\omega_{3} = \{\neg x_{1}, \neg x_{5}\} 
\omega_{4} = \{\neg x_{2}, \neg x_{4}\} 
\omega_{5} = \{\neg x_{3}, \neg x_{4}\} 
\omega_{6} = \{\neg x_{3}, \neg x_{6}\}$$

$$\omega_7 = \{x_1, \neg x_4\}$$

# Weakly active symmetries

## Logical consequence

When  $\omega$  is satisfied in all satisfying assignments of  $\varphi$ , we say that  $\omega$  is a logical consequence of  $\varphi$ , and we denote this by  $\varphi \vdash \omega$ .

# Weakly active symmetries

## Logical consequence

When  $\omega$  is satisfied in all satisfying assignments of  $\varphi$ , we say that  $\omega$  is a logical consequence of  $\varphi$ , and we denote this by  $\varphi \vdash \omega$ .

## Weakly active symmetries

Let a subset  $\delta \subseteq \alpha$ , a symmetry  $\sigma$  of  $\varphi$  such that  $\varphi \cup \delta \vdash \varphi \cup \alpha \land \sigma.\delta \subseteq \alpha$  then  $\sigma$  is weakly active symmetry.

# Weakly active symmetries

### Logical consequence

When  $\omega$  is satisfied in all satisfying assignments of  $\varphi$ , we say that  $\omega$  is a logical consequence of  $\varphi$ , and we denote this by  $\varphi \vdash \omega$ .

### Weakly active symmetries

Let a subset  $\delta \subseteq \alpha$ , a symmetry  $\sigma$  of  $\varphi$  such that  $\varphi \cup \delta \vdash \varphi \cup \alpha \land \sigma.\delta \subseteq \alpha$  then  $\sigma$  is weakly active symmetry.

### Symmetry propagation

Let  $\sigma$  a weakly active symmetry, then

$$\varphi \cup \alpha \vdash \{I\} \Leftrightarrow \varphi \cup \alpha \vdash \sigma.\{I\}$$

# Local symmetries

### Logical consequence

When  $\omega$  is satisfied in all satisfying assignments of  $\varphi$ , we say that  $\omega$  is a logical consequence of  $\varphi$ , and we denote this by  $\varphi \vdash \omega$ .

### **Local Symmetries**

Let  $\varphi$  be a formula. We define  $L_{\omega,\varphi}$ , the set of *local symmetries* for a clause  $\omega$ , and with respect to a formula  $\varphi$ , as follows:

$$L_{\omega,\varphi} = \{ \sigma \in \mathfrak{S} \mid \varphi \vdash \sigma.\omega \}$$

# Local symmetries

### Logical consequence

When  $\omega$  is satisfied in all satisfying assignments of  $\varphi$ , we say that  $\omega$  is a logical consequence of  $\varphi$ , and we denote this by  $\varphi \vdash \omega$ .

### **Local Symmetries**

Let  $\varphi$  be a formula. We define  $L_{\omega,\varphi}$ , the set of *local symmetries* for a clause  $\omega$ , and with respect to a formula  $\varphi$ , as follows:

$$L_{\omega,\varphi} = \{ \sigma \in \mathfrak{S} \mid \varphi \vdash \sigma.\omega \}$$

We can state that:

$$\bigcap_{\omega\in\varphi} L_{\omega,\varphi}\subseteq G.$$

# Computing local symmetries

### Formula can be decomposed as : $\varphi = \varphi_o \cup \varphi_e \cup \varphi_d$ where

- $\varphi_o$  is the set of the original clauses
- $\varphi_e$  is the set of ESBPs
- $\varphi_d$  is the set of deduced clauses.

#### Local symmetries

- $\omega \in \varphi_o, L_{\omega,\varphi} \supseteq G$
- $\omega \in \varphi_e, L_{\omega,\varphi} \supseteq Stab(\omega) = \{ \sigma \in G \mid \omega = \sigma.\omega \}$
- $\omega \in \varphi_d, L_{\omega,\varphi} \supseteq (\bigcap_{\omega' \in \varphi_1} L_{\omega',\varphi}) \cup Stab(\omega)$

where  $\varphi_1$  is the set of clauses that derives  $\omega$ .

# Encoding the problem

(A, 1)(A, 2)(A, 3) (B, 1)(B, 2)(B, 3) (C, 1)(C, 2)(C, 3)	$X_1 \lor X_2 \lor X_3$ $X_4 \lor X_5 \lor X_6$ $X_7 \lor X_8 \lor X_6$
$\neg (A, 1) \neg (B, 1)$ $\neg (A, 1) \neg (C, 1)$ $\neg (B, 1) \neg (C, 1)$	$   \begin{array}{c}     \neg x_1 \lor \neg x_4 \\     \neg x_1 \lor \neg x_7 \\     \neg x_4 \lor \neg x_7   \end{array} $
$\neg (A,2) \neg (B,2)$ $\neg (A,2) \neg (C,2)$ $\neg (B,2) \neg (C,2)$	
$\neg (A,3) \neg (B,3)$ $\neg (A,3) \neg (C,3)$ $\neg (B,3) \neg (C,3)$	$ \begin{array}{c} \neg x_3 \lor \neg x_6 \\ \neg x_3 \lor \neg x_9 \\ \neg x_6 \lor \neg x_9 \end{array} $