cmake\_minimum\_required(VERSION 2.8.3)

project(turtlebot\_description)

find\_package(catkin REQUIRED COMPONENTS urdf xacro)

catkin\_package(

CATKIN\_DEPENDS urdf xacro

)

install(DIRECTORY robots

DESTINATION ${CATKIN\_PACKAGE\_SHARE\_DESTINATION}

)

install(DIRECTORY meshes

DESTINATION ${CATKIN\_PACKAGE\_SHARE\_DESTINATION}

)

install(DIRECTORY test

DESTINATION ${CATKIN\_PACKAGE\_SHARE\_DESTINATION}

)

install(DIRECTORY urdf

DESTINATION ${CATKIN\_PACKAGE\_SHARE\_DESTINATION}

)

if(CATKIN\_ENABLE\_TESTING)

catkin\_add\_gtest(${PROJECT\_NAME}\_test\_urdf test/test\_urdf.cpp)

endif()