cmake\_minimum\_required(VERSION 2.8.3)

project(turtlebot\_interactive\_markers)

find\_package(catkin REQUIRED COMPONENTS roscpp

visualization\_msgs

interactive\_markers)

catkin\_package()

include\_directories(${catkin\_INCLUDE\_DIRS})

add\_executable(turtlebot\_marker\_server src/turtlebot\_marker\_server.cpp)

target\_link\_libraries(turtlebot\_marker\_server ${catkin\_LIBRARIES})

install(TARGETS turtlebot\_marker\_server DESTINATION ${CATKIN\_PACKAGE\_BIN\_DESTINATION})

install(DIRECTORY launch DESTINATION ${CATKIN\_PACKAGE\_SHARE\_DESTINATION})