cmake\_minimum\_required(VERSION 2.8.3)

project(openni2\_launch)

find\_package(catkin)

catkin\_python\_setup()

catkin\_package()

install(DIRECTORY launch

DESTINATION ${CATKIN\_PACKAGE\_SHARE\_DESTINATION}/

)

if (CATKIN\_ENABLE\_TESTING)

find\_package(roslaunch REQUIRED)

roslaunch\_add\_file\_check(launch)

# roslaunch\_add\_file\_check(launch/includes) # 20181003 this fails.

endif()