Solutions to Assignment 1 of CS-E4830 Kernel Methods in Machine Learning 2021

Pen and paper exercise

Question 1 (2 points): Recall from the Lecture 1, the general form for the polynomial kernel

$$K(\mathbf{x}, \mathbf{y}) = (\langle \mathbf{x}, \mathbf{y} \rangle + c)^m = (\mathbf{x}^T \mathbf{y} + c)^m$$

where $c \geq 0$, m is a positive integer and $\mathbf{x}, \mathbf{y} \in \mathbb{R}^d$.

• Prove that $K(\mathbf{x}, \mathbf{y})$ is a valid kernel

Solution

- Given $K(\mathbf{x}, \mathbf{y}) = (\langle \mathbf{x}, \mathbf{y} \rangle + c)^m$ given that $\mathbf{x}, \mathbf{y} \in \mathbb{R}^d$.
- Using Binomial Theorem : $(\langle \mathbf{x}, \mathbf{y} \rangle)^m$ can be expanded as follows:

$$\binom{m}{0}(\langle \mathbf{x}, \mathbf{y} \rangle)^m c^0 + \binom{m}{1}(\langle \mathbf{x}, \mathbf{y} \rangle)^{m-1} c^1 + \ldots + \binom{m}{m}(\langle \mathbf{x}, \mathbf{y} \rangle)^0 c^m$$

- Now, $\langle \mathbf{x}, \mathbf{y} \rangle$ is an inner product in \mathbb{R}^d , hence it is a kernel.
- Since product of kernels is a kernel, therefore $(\langle \mathbf{x}, \mathbf{y} \rangle)^2$, and $(\langle \mathbf{x}, \mathbf{y} \rangle)^3$ and so on are also kernels
- Furthermore, multiplying a kernel by a positive number is also a kernel
- Therefore, all the terms (except the last term which is a constant), and hence their sum is a kernel. Call it $K_s(\mathbf{x}, \mathbf{y})$, and its corresponding feature map be $\phi(.)$ such that $K_s(\mathbf{x}, \mathbf{y}) = \langle \phi(\mathbf{x}), \phi(\mathbf{y}) \rangle$
- Call the last term α , therefore we have $K(\mathbf{x}, \mathbf{y}) = K_s(\mathbf{x}, \mathbf{y}) + \alpha = \langle \phi(\mathbf{x}), \phi(\mathbf{y}) \rangle + \alpha$
- Therefore, K(.,.) can be expressed as an inner product with the following feature map $\begin{bmatrix} \phi(\mathbf{x}) \\ \sqrt{\alpha} \end{bmatrix}$.
- Hence K(.,.) is a kernel.

Question 2 (4 points): Recall from lecture 2, in the context of binary classification, the Parzen window classifier assigns a test instance x based on the distance to the centroids in the following way:

$$h(x) = \begin{cases} +1 & \text{if } \|\phi(x) - c_-\|^2 > \|\phi(x) - c_+\|^2 \\ -1 & \text{otherwise.} \end{cases}$$

where c_{-} and c_{+} represent the centroids in the feature space of the negative and positive classes respectively. Show by deriving appropriate expressions for α_{i} and b that the above decision function can be written in the following form $h(x) = \operatorname{sgn}(\sum_{i=1}^{n} \alpha_{i} k(x, x_{i}) + b)$ such that $k(x, x_{i}) = \langle \phi(x), \phi(x_{i}) \rangle$. Here $\operatorname{sgn}(.)$ represents the sign function, and n is the total number of training samples.

Solution

- We can rewrite $h(x) = \operatorname{sgn}(\|\phi(x) c_-\|^2 \|\phi(x) c_+\|^2)$
- Using $||x||^2 = \langle x, x \rangle$ we have $h(x) = \operatorname{sgn}(\langle \phi(x) c_-, \phi(x) c_- \rangle \langle \phi(x) c_+, \phi(x) c_+ \rangle)$
- Now expanding the terms inside the sgn(.) using properties $\langle x,y+z\rangle=\langle x,y\rangle+\langle x,z\rangle$ we have

$$\langle \phi(x) - c_-, \phi(x) - c_- \rangle - \langle \phi(x) - c_+, \phi(x) - c_+ \rangle = 2 \langle \phi(x), c_+ \rangle - 2 \langle \phi(x), c_- \rangle + \langle c_-, c_- \rangle - \langle c_+, c_+ \rangle - 2 \langle \phi(x), c_- \rangle - \langle c_+, c_+ \rangle - 2 \langle \phi(x), c_- \rangle - \langle c_+, c_+ \rangle - 2 \langle \phi(x), c_- \rangle - \langle c_+, c_- \rangle - \langle c_+, c_+ \rangle - 2 \langle \phi(x), c_- \rangle - \langle c_+, c_- \rangle - \langle c_+, c_+ \rangle - 2 \langle \phi(x), c_- \rangle - \langle c_+, c_- \rangle -$$

• As sgn(.) is unaffected by a positive multiple we can write

$$h(x) = \operatorname{sgn}(\langle \phi(x), c_{+} \rangle - \langle \phi(x), c_{-} \rangle + 0.5 \langle c_{-}, c_{-} \rangle - 0.5 \langle c_{+}, c_{+} \rangle)$$

• Now using the definitions of c_+ and c_- we can expand each term using properties of inner products as follows

$$\langle \phi(x), c_{+} \rangle = \left\langle \phi(x), \frac{1}{m_{+}} \sum_{i \in \mathcal{I}^{+}} \phi(x_{i}) \right\rangle$$

$$= \frac{1}{m_{+}} \left\langle \phi(x), \sum_{i \in \mathcal{I}^{+}} \phi(x_{i}) \right\rangle \qquad \qquad \therefore \langle ax, y \rangle = a \langle x, y \rangle$$

$$= \frac{1}{m_{+}} \sum_{i \in \mathcal{I}^{+}} \langle \phi(x), \phi(x_{i}) \rangle \qquad \qquad \therefore \langle x, y + z \rangle = \langle x, y \rangle + \langle y, z \rangle$$

$$= \frac{1}{m_{+}} \sum_{i \in \mathcal{I}^{+}} k(x, x_{i})$$

Similarly $\langle \phi(x), c_{-} \rangle = \frac{1}{m_{-}} \sum_{i \in \mathcal{I}^{-}} k(x, x_{i})$

• A similar process for $\langle c_-, c_- \rangle$

$$\langle c_{-}, c_{-} \rangle = \left\langle \frac{1}{m_{-}} \sum_{i \in \mathcal{I}^{-}} \phi(x_{i}), \frac{1}{m^{-}} \sum_{j \in \mathcal{I}^{-}} \phi(x_{j}) \right\rangle$$

$$= \frac{1}{m_{-}^{2}} \left\langle \sum_{i \in \mathcal{I}^{-}} \phi(x_{i}), \sum_{j \in \mathcal{I}^{-}} \phi(x_{j}) \right\rangle$$

$$= \frac{1}{m_{-}^{2}} \sum_{i \in \mathcal{I}^{-}} \sum_{j \in \mathcal{I}^{-}} \langle \phi(x_{i}), \phi(x_{j}) \rangle$$

$$= \frac{1}{m_{-}^{2}} \sum_{i,j \in \mathcal{I}^{-}} k(x_{i}, x_{j})$$

Similarly $\langle c_+, c_+ \rangle = \frac{1}{m_+^2} \sum_{i,j \in \mathcal{I}^+} k(x_i, x_j)$

• We can now take $b = 0.5(\langle c_-, c_- \rangle - \langle c_+, c_+ \rangle)$, therefore

$$b = \frac{1}{2m_{-}^{2}} \sum_{i,j \in \mathcal{I}^{-}} k(x_{i}, x_{j}) - \frac{1}{2m_{+}^{2}} \sum_{i,j \in \mathcal{I}^{+}} k(x_{i}, x_{j})$$

• Now combining all previous results we have

$$h(x) = \operatorname{sgn}\left(\frac{1}{m_{+}} \sum_{i \in \mathcal{I}^{+}} k(x, x_{i}) - \frac{1}{m_{-}} \sum_{i \in \mathcal{I}^{-}} k(x, x_{i}) + b\right)$$

• As $\mathcal{I} = \mathcal{I}^+ \cup \mathcal{I}^-$ and $n = m_+ + m_-$ we can combine the integrals by introducing a coefficient term α_i like

$$h(x) = \operatorname{sgn}\left(\sum_{i=1}^{n} \alpha_i k(x, x_i) + b\right)$$

Where

$$\begin{cases} \frac{1}{m_+}, & y_i = +1\\ \frac{-1}{m_-}, & y_i = -1 \end{cases}$$

Hence derived

Question 3 (3 points): For $x, y \in \mathbb{R}$ check if $K_2(x, y) = \cos(x + y)$ is a valid kernel function.

Solution: Recall from lecture 2 that a kernel function needs to be positive definite. A symmetric function $k: \mathcal{X} \times \mathcal{X} \mapsto \mathbb{R}$ is positive definite if $\forall n \geq 1, \forall (a_1, ..., a_n) \in \mathbb{R}^n, \forall (x_1, ..., x_n) \in \mathcal{X}^n$,

$$\sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_i \alpha_j k(x_i, x_j) \ge 0$$

The above should hold even for a single point, i.e., $a^2k(x,x) \geq 0$ for all $x \in \mathcal{X}$ and $a \in \mathbb{R}$

Now, take $x = \frac{\pi}{2}$ and a = 1. In this case, it is $1^2 \times \cos(\pi/2 + \pi/2) = -1 < 0$. Hence it is not a kernel. Of course, there could be many other counter-examples.

Question 4 (3 points): For $x, y \in \mathcal{X} = (-1, 1)$, prove that $K_3(x, y) = \frac{1}{1-xy}$ is a valid kernel

Solution: Since $x, y \in \mathcal{X} = (-1, 1)$, therefore, $K_3(x, y) = \frac{1}{1-xy} = 1+xy+(xy)^2+(xy)^3+...$ Each of individual terms (apart from 1) is a kernel, either by definition or product of kernels is a kernel property. Hence the sum of kernels is also kernel. The sum of kernel and a constane (the first term 1) is also a kernel as well. Hence $K_3(x, y)$ is a kernel.

Exercise 01

Kernel Methods in Machine Learning (CS-E4830)

Submission deadline: 30.3.2021 at 4pm

Tutorial session: 18.3.2021 at 4:15pm - 6pm

Tasks: 1. [Implement kernel matrix calculation](#task_1) 1. [Linear kernel](#task_1_a) (**2 Point**) 2. [Gaussian kernel](#task_1_b) (**2 Point**) 2. [Implement the Parzen Window Classifier](#task_2) (**3 Point**) 3. [Application of the Parzen Window Classifier](#task_3) 1. [Implement the hyper parameter optimization](#task_3_a) (**3 Point**) 2. [Plot validation score for different hyper parameters](#task_3_b)(**0 Point**)

Optional Tasks: 4. [Model visualization: Non-linear vs. Linear](#task_4) (**no points**)

Version: 1.2

Version history:

- 1.0: Initial version
- 1.1: Fix typo: Parzen Window Clf. dual-variables (alpha) had wrong sign in formula. <u>Issue on MyCourses (https://mycourses.aalto.fi/mod/forum</u>/discuss.php?d=128291)
- 1.2: Fix typo: Gaussian kernel doc-string, put brackets around the denominator within exponential function.

Please add your student number and email address to the notebook into the corresponding cell.

EMAIL: firstname.lastname@aalto.fi

STUDENT NUMBER: please fill in

Import required python packages

All tasks in this exercise can be solved by using only function and packages imported below. Please **do not** use any other imports.

```
In [1]: | import numpy as np
        import matplotlib.pyplot as plt
        import matplotlib.colors as colors
        plt.set cmap("RdBu r")
        from sklearn.base import BaseEstimator, ClassifierMixin
        from sklearn.datasets import make blobs, make moons
        from sklearn.model selection import KFold, ParameterGrid, BaseCrossValidator, train test split
        from sklearn.base import clone
```

<Figure size 432x288 with 0 Axes>

1. Kernel matrix calculation

Your task is to implement two functions to calculate Linear- and Gaussian-kernel matrices for two sets of feature vectors $\mathbf{X}_A \in \mathbb{R}^{n_A \times d}$, $\mathbf{X}_B \in \mathbb{R}^{n_B \times d}$, where d is the dimension of the feature vectors, and n_a and n_B are the number of examples in set A respectively B.

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A. Linear kernel (2 Point)

Task: Implement missing code parts of the function calculation the linear kernel matrix given two feature vector matrices \mathbf{X}_A and \mathbf{X}_B . The resulting kernel matrix \mathbf{K}_{lin} must have dimension $n_A \times n_B$. For a single entry in the kernel matrix it must hold:

$$[\mathbf{K}_{lin}]_{ij} = \kappa_{lin}(\mathbf{x}_i, \mathbf{x}_j) = \langle \mathbf{x}_i, \mathbf{x}_j \rangle,$$

with $\mathbf{x}_i, \mathbf{x}_i \in \mathbb{R}^d$ being two examples from set A respecively B.

```
In [3]: X A = np.array([[1], [2], [3], [4]])
        X B = np.array([[0], [2], [1]])
        # Test size
        np.testing.assert equal(linear kernel(X A, X B).shape, (4, 3))
        np.testing.assert equal(linear kernel(X A).shape, (4, 4))
        # Test values
        np.testing.assert equal(linear kernel(X A)[0, 0], 1)
        np.testing.assert equal(linear kernel(X A)[1, 1], 4)
        np.testing.assert equal(linear kernel(X A)[0, 2], 3)
        np.testing.assert equal(linear kernel(X A)[2, 0], 3)
        np.testing.assert equal(linear kernel(X A, X B)[0, 0], 0)
        np.testing.assert equal(linear kernel(X A, X B)[0, 1], 2)
        # Test performance
        import time
        time tolerance = 1 # in seconds
        size = 3000
        t0 = time.time()
        a = linear kernel(np.random.rand(size), np.random.rand(size))
        t1 = time.time()
        total = t1 - t0
        print('Time to run with size {} = {:.4f} seconds'.format(size, total))
        assert total < time tolerance, 'Time limit exceeded'</pre>
```

Time to run with size 3000 = 0.0004 seconds

B. Gaussian kernel (2 Point)

Task: Implement missing code parts of the function calculation the Gaussian kernel matrix given two feature vector matrices X_A and X_B . The resulting kernel matrix K_{gau} must have dimension $n_A \times n_B$. For a single entry in the kernel matrix it must hold:

$$[\mathbf{K}_{gau}]_{ij} = \kappa_{gau}(\mathbf{x}_i, \mathbf{x}_j) = \exp\left(-\frac{\|\mathbf{x}_i - \mathbf{x}_j\|^2}{2\sigma^2}\right)$$

with $\mathbf{x}_i, \mathbf{x}_i \in \mathbb{R}^d$ being two examples from set A respectively B, and $\gamma > 0$ being the bandwidth parameter.

```
In [4]: def gaussian kernel(X A, X B=None, sigma=None):
            Calculate the Gaussian kernel matrix, so that
                k \ ij = \exp(-||x \ i - x \ j||^2 / (2 * sigma^2))
             :param X A: array-like, shape=(n samples A, n features), feature-matrix of set A
             :param X B: array-like, shape=(n samples B, n features), feature-matrix of set B or None, than X B =
        X A
             :param sigma: scalar, bandwidth parameter
            :return: array-like, shape=(n samples A, n samples B), kernel matrix
            if X B is None:
                X B = X A
            n A = X A.shape[0]
            n B = X B.shape[0]
            if sigma is None:
                 sigma = np.sqrt(X A.shape[1] / 2.0)
            # YOUR CODE HERE
            K A lin diag = np.sum(X A * X A, axis=1)[:, np.newaxis] # diag(K X), shape=(n A, 1)
            K B lin diag = np.sum(X B * X B, axis=1)[np.newaxis, :] # diag(K Y), shape=(1, n B)
            K AB lin = X A @ X B.T
            K\_AB = (K\_A\_lin\_diag @ np.ones((1, n\_B)) + np.ones((n\_A, 1)) @ K\_B\_lin\_diag - 2 * K\_AB\_lin) # ||x_i|
        - x i | |^2
            K AB /= (-2. * sigma**2)
            K AB = np.exp(K AB)
            return K AB
```

```
In [5]: X A = np.array([[1], [2], [3], [4]])
        X B = np.array([[0], [2], [1]])
        # Test size
        np.testing.assert equal(gaussian kernel(X A, X B).shape, (4, 3))
        np.testing.assert equal(gaussian kernel(X A).shape, (4, 4))
        # Test values
        np.testing.assert equal(gaussian kernel(X A, sigma=1)[0, 0], 1)
        np.testing.assert equal(gaussian kernel(X A, sigma=1)[1, 1], 1)
        np.testing.assert equal(gaussian kernel(X A, sigma=1)[0, 2], np.exp(-2))
        np.testing.assert equal(gaussian kernel(X A, sigma=1)[2, 0], np.exp(-2))
        np.testing.assert equal(gaussian kernel(X A, X B, sigma=1)[0, 0], np.exp(-0.5))
        np.testing.assert equal(gaussian kernel(X A, X B, sigma=1)[0, 1], np.exp(-0.5))
        # Test performance
        import time
        time tolerance = 1 # in seconds
        size = 3000
        features = 10
        t0 = time.time()
        a = gaussian kernel(np.random.rand(size, features), np.random.rand(size, features))
        t1 = time.time()
        total = t1 - t0
        print('Time to run with size {} = {:.4f} seconds'.format(size, total))
        assert total < time tolerance, 'Time limit exceeded'</pre>
```

Time to run with size 3000 = 0.4363 seconds

2. Parzen Window Classifier implementation (3 Points)

The Parzen Window Classifier prediction model can be written as:

$$h(\mathbf{x}) = \operatorname{sign}(g(\mathbf{x})) = \operatorname{sign}\left(\sum_{i=1}^{n} \alpha_i \kappa(\mathbf{x}_i, \mathbf{x}) + b\right),$$

with:

- $g: \mathbb{R}^d \to \mathbb{R}$ being the **decision function**
- $b \in \mathbb{R}$ being the **bias term** defined as:

$$b = \frac{1}{2n_-^2} \sum_{i,j \in I^-} \kappa(\mathbf{x}_i, \mathbf{x}_j) - \frac{1}{2n_+^2} \sum_{i,j \in I^+} \kappa(\mathbf{x}_i, \mathbf{x}_j),$$

• α_i 's $\in \mathbb{R}$ being the **dual variables** for all training examples \mathbf{x}_i defined as:

$$\alpha_i = \begin{cases} \frac{1}{n_+} & \text{if } y_i = +1 \\ -\frac{1}{n_-} & \text{if } y_i = -1 \end{cases}.$$

We denote the number of positive / negative training examples as n_+ / n_- , and $n=n_++n_-$, and I^+ / I^- are the indices of the positive / negative training examples.

Below you find the class-template for the Parzen Window Classifier. It's functionality is split into three parts:

1. Intialization of Classifier Object using init()

A Parzen Window Classifier instance can be created using its constructor and the kernel to be used can be specified, e.g.:

est = ParzenWindowClassifier(kernel="gaussian").

2. Model Training using fit()

This function takes as input the features of the training examples \mathbf{X}_{train} and their corresponding labels $\mathbf{y}_{train} \in \{-1,1\}^{n_{train}}$ and estimates the α_i 's and b.

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The necessary kernel values between the training examples, i.e. $\kappa(\mathbf{x}_i, \mathbf{x}_i)$ are calculated during the fitting process.

```
est.fit(X train, y train)
```

3. Prediction for new Examples using predict() and decision function()

When the model parameters, i.e. b and α_i s, are fitted, than we can make predictions for a new example x using the function h(x).

```
y_test_pred = est.predict(X_test)
```

Task: Implement the missing code parts of fit(), decision_function() and predict(). Make use of the provided formulas (see above).

Hint: The NumPy function **np.sum** can be used to sum over the elements of a matrix.

```
In [6]: class ParzenWindowClassifier(BaseEstimator, ClassifierMixin):
            def init (self, kernel="gaussian", sigma=None):
                Parzen Window Classifier
                :param kernel: string, specifying which kernel to use. Can be 'gaussian' or 'linear'.
                :param sigma: scalar, gaussian kernel parameter, can be None if the linear kernel is used.
                # Parzen Window Classifier model parameter
                self.b = None # bias term
                self.alphas = None # dual variables
                # Training data needed for the prediction phase
                self.X train = None
                # Set up kernel function
                self.kernel = kernel
                self.sigma = sigma
            def fit(self, X train, y train):
                Fit a Parzen Window Classifier using training data
                :param X train: array-like, shape=(n samples, n features), feature-matrix
                :param y_train: array-like, shape=(n samples,) or (n samples, 1), label vector
                # Calculate the specified kernel
                self.X train = X train
                KX_train = self._get_kernel(self.X_train)
                # Get indices of positive and negative examples: I n, I p
                # YOUR CODE HERE
                I n = (y train == -1)
                Ip = (y train == 1)
                # Count the number of postitive and negative examples: n n, n p
                # YOUR CODE HERE
                n n = np.sum(I n)
                n p = np.sum(I p)
```

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```
# Calcualte the bias term: self.b
        # YOUR CODE HERE
        b n = np.sum(KX train[I n][:, I n]) / (2. * n n ** 2)
        b p = np.sum(KX train[I p][:, I p]) / (2. * n p ** 2)
        self.b = b n - b p
       # Calculate alpha i's: self.alpha
        self.alphas = np.zeros((n n + n p, 1))
       # YOUR CODE HERE
        self.alphas[I n] = -1. / n n
        self.alphas[I p] = 1. / n p
   def decision function(self, X):
        Calculate decision function:
            g(x) = sum \ i \ a \ i \ k(x \ i, \ x) + b
        :param X: array-like, shape=(n samples test, n features), feature-matrix of new data.
        :return: array-like, shape=(n \text{ samples test},), decision function value g(x) for all new data poin
ts
        if self.alphas is None or self.b is None or self.X train is None:
            raise RuntimeError("Call fit-function first.")
       # Calculate the specified kernel between the training and test examples
       KX test train = self. get kernel(X, self.X train)
       # Calculate the value of the decision function for each test example
       # YOUR CODE HERE
       g X = KX test train @ self.alphas + self.b
        return g X.flatten() # output a one-dimensional vector
   def predict(self, X):
       Predict labels using Parzen Window Classifier:
            h(x) = sign(q(x)), with q(x) being the decision function
```

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```
:param X: array-like, shape=(n samples test, n features), feature-matrix of new data.
        :return: array-like, shape=(n samples test,), predicted labels {-1, 1} for all new data points
        if self.alphas is None or self.b is None or self.X train is None:
            raise RuntimeError("Call fit-function first.")
        # Calculate prediction h(x) = sign(g(x))
        # YOUR CODE HERE
        h_X = np.sign(self.decision_function(X))
        return h X
   def _get_kernel(self, X, Y=None):
        Calcualte kernel matrix using specified kernel-function and parameters.
        :param X: array-like, shape=(n samples A, n features), feature-matrix of set A
        :param Y: array-like, shape=(n \ samples \ B, \ n \ features), feature-matrix of set \ B or None, than \ Y =
X
        :return: array-like, shape=(n samples A, n samples B), kernel matrix
        if self.kernel == "gaussian":
            return gaussian kernel(X, Y, self.sigma)
        elif self.kernel == "linear":
            return linear_kernel(X, Y)
        else:
            raise ValueError("Invalid kernel chosen.")
```

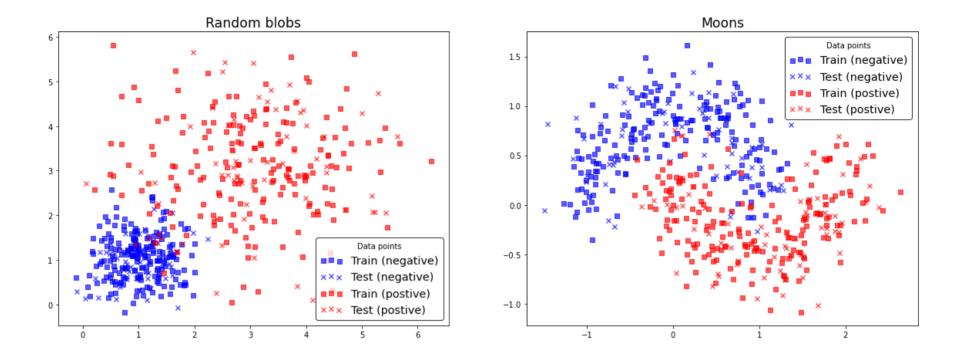
```
In [7]: X, y = make blobs(n samples=50, centers=[[1, 1], [1.5, 1.5]], cluster_std=[0.1, 0.1],
                           random state=80)
        v[v==0] = -1
        test est = ParzenWindowClassifier(kernel="linear")
        test est.fit(X, y)
        # Test correct shape of self.b and self.alphas
        assert(np.isscalar(test est.b))
        np.testing.assert equal(test est.alphas.shape, (50, 1))
        # Test correct shape of the predictions
        X_{\text{test}} = \text{np.array}([[1, 1], [1.5, 1.5], [1, 0], [2, 3]])
        # Validate predictions
        np.testing.assert equal(test est.decision function(X test).shape, (4,))
        np.testing.assert equal(test est.predict(X test).shape, (4,))
        np.testing.assert equal(test est.predict(X test), np.array([-1, 1, -1, 1]))
        # Validate score
        np.testing.assert equal(test est.score(X, y), 1.0)
```

3. Application of the Parzen Window Classifier

It is time to apply your Parzen Window Classifier to some datasets. For that you are given two synthetic datasets X. Each is splitted into a training and test subset: X_{train} (75%) and X_{test} (25%).

We can plot the datasets to get an impression what we are dealing with:

```
In [9]: # Plot datasets
        fig, axrr = plt.subplots(1, 2, figsize=(20, 7))
        # Blobs
        for l str, l num, col in [("negative", -1, "blue"), ("postive", 1, "red")]:
            axrr[0].scatter(
                X blobs train[y blobs train==l num, 0], X blobs train[y blobs train==l num, 1],
                c=col, alpha=0.65, label="Train (%s)" % l str, marker="s")
            axrr[0].scatter(
                X blobs test[y blobs test==l num, 0], X blobs test[y blobs test==l num, 1],
                c=col, alpha=0.65, label="Test (%s)" % l str, marker="x")
        # Blobs
        for l str, l num, col in [("negative", -1, "blue"), ("postive", 1, "red")]:
            axrr[1].scatter(
                X moons train[y moons train==l num, 0], X moons train[y moons train==l num, 1],
                c=col, alpha=0.65, label="Train (%s)" % l str, marker="s")
            axrr[1].scatter(
                X moons test[y moons test==l num, 0], X moons test[y moons test==l num, 1],
                c=col, alpha=0.65, label="Test (%s)" % l str, marker="x")
        axrr[0].set title("Random blobs", fontsize="xx-large")
        axrr[0].legend(title="Data points", fontsize="x-large", scatterpoints=3, edgecolor="k")
        axrr[1].set title("Moons", fontsize="xx-large")
        axrr[1].legend(title="Data points", fontsize="x-large", scatterpoints=3, edgecolor="k")
        plt.show()
```



A. Implement the hyper parameter optimization (3 point)

Train (fit) your Parzen Window Classifier with Gaussian kernel on the training examples, i.e. X_blobs_train and X_moons_train . To find the optimal Gaussian bandwidth parameter σ we search a grid of different parameter values and score each one using CV.

Task: Implement the missing code parts of the hyper_parameter_search_using_cv function.

The function gets in a set of training examples and a grid of different parameters, e.g. σ 's, calculates an average validation set score for all of them using cross-validation. Subsequently, a model using all the training data ist used, to train a model with the best set of parameters.

Hints: - Make use of the Python tutorial (fetch on JupyterHub), if you want to see the pseudo-code of the parameter search. - Read the documentation of the sklearn [**KFold** function](https://scikit-learn.org/stable/modules/generated/sklearn.model_selection.KFold.html#sklearn.model_selection.KFold). - You can calculate the performance score using **est.score(...)** . Read also: https://scikit-learn.org/stable/modules/generated/sklearn.base.ClassifierMixin.html#sklearn.base.ClassifierMixin.score

```
In [10]: def hyper parameter search_using_cv(estimator, X, y, param_grid, n_cv_folds=5,
                                              random state=None):
             Function calculating the estimator score for a grid of hyper parameters.
             :param estimator: object, subclass of RegressorMixin or ClassifierMixin and BaseEstimator
             :param X: array-like, shape=(n samples, n features), feature-matrix used for training
             :param y: array-like, shape=(n samples,) or (n samples, 1), label vector used for training
             :param param grid: dictionary,
                 keys: different parameter names
                 values: grid-values for each parameter
             :param n cv folds: scalar, a KFold cross-validation is performed where the number of splits is equal
         the scalar.
             :param random state: scalar, RandomState instance or None, optional, default=None
                 If int, random state is the seed used by the random number generator;
                 If RandomState instance, random state is the random number generator;
                 If None, the random number generator is the RandomState instance used
                 by `np.random`.
             :return: tuple = (
                     best estimator,
                     param grid as list and corresponding evaluation scores,
                     score of best parameter
                     best parameter
              0.00
             # Get an iterator over all parameters
             param grid iter = ParameterGrid(param grid)
             # Create cross-validation object
             cv = KFold(n splits=n cv folds, random state=random state)
             # Store the valdidation set performance scores for all folds and parameters
             perf scores = np.zeros((cv.get n splits(), len(param grid iter)))
             for fold, (train set, val set) in enumerate(cv.split(X, y)):
                 # Separate training and validation set from X and v,
                 # i.e. X train, X val, y train and y val
                 # YOUR CODE HERE
```

```
X train = X[train set]
    X val = X[val set]
    y train = y[train set]
    y val = y[val set]
    for idx, param in enumerate(param_grid_iter):
        # Clone the estimator object to get an un-initialized object
        est = clone(estimator)
        # Set model parameters
        est.set params(**param)
        # Fit the model using training set
        # YOUR CODE HERE
        est.fit(X train, y train)
        # Calculate the perf. score on validation set for current fold and parameter index
        # YOUR CODE HERE
        perf scores[fold, idx] = est.score(X val, y val)
# Find best performing hyper-parameter
# Average the perf. scores for each parameter across each fold
# YOUR CODE HERE
avg perf scores = np.mean(perf scores, axis=0)
idx best = np.argmax(avg perf scores)
best perf score = avg perf scores[idx best]
best param = param grid iter[idx best]
# Fit model using all data with the best parameters
est = clone(estimator)
est.set params(**best param)
est.fit(X, y)
return (est, {"params": list(param grid iter), "scores": avg perf scores},
        best perf score, best param)
```

B. Plot validation score for different hyper parameters

With the hyper parameter optimization function at hand, we find the best σ parameter for the two synthetic datasets and also inspect the average validation error for different values of σ .

First let us the parameter grid for the Gaussian kernel bandwidth parameter σ :

```
In [12]: param_grid = {"sigma": [0.01, 0.05, 0.1, 0.5, 1, 5, 10, 50]}
```

Now we run the hyper_parameter_search_using_cv function for X_blobs_train and X_blobs_test:

```
In [13]: est blobs, scores blobs, best score blobs, best param blobs = hyper parameter search using cv(
            ParzenWindowClassifier(kernel="gaussian"), X blobs train, y blobs train, param grid,
            random state=737)
         print("[Blobs] Best average validation score", best score blobs)
         print("[Blobs] Best parameter", best param blobs)
         est moons, scores moons, best score moons, best param moons = hyper parameter search using cv(
            ParzenWindowClassifier(kernel="gaussian"), X moons train, y moons train, param grid,
             random state=747)
         print("[Moons] Best average validation score", best score moons)
         print("[Moons] Best parameter", best param moons)
         /opt/conda/lib/python3.8/site-packages/sklearn/model selection/ split.py:293: FutureWarning: Setting a r
         andom state has no effect since shuffle is False. This will raise an error in 0.24. You should leave ran
         dom state to its default (None), or set shuffle=True.
          warnings.warn(
         [Blobs] Best average validation score 0.9706666666666667
         [Blobs] Best parameter {'sigma': 1}
         [Moons] Best parameter {'sigma': 0.1}
```

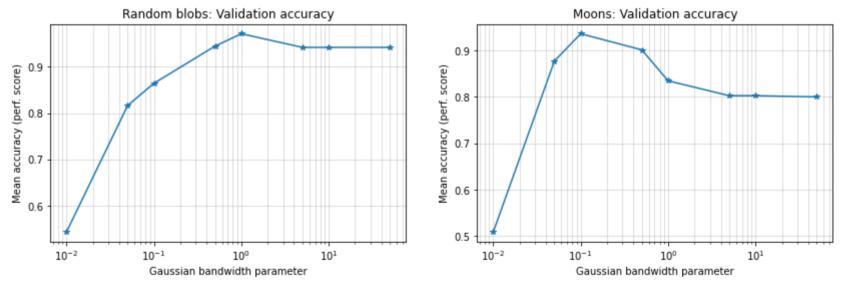
Plot validation score for the different parameter values.

Hint: Both curves should have a single maxima, if you did not change any random seeds, i.e. $random_state$ values, or data generation parameters. Otherwise, it could be that multiple σ 's are equally good. However, overall it should be a function with single maxima (maybe a region).

```
In [14]: fig, axrr = plt.subplots(1, 2, figsize=(14, 4), sharex="row")
    axrr[0].plot(param_grid["sigma"], scores_blobs["scores"], '*-')
    axrr[0].set_xscale("log")
    axrr[0].grid(True, which="both", ls="-", alpha=0.5)
    axrr[0].set_title("Random blobs: Validation accuracy")
    axrr[0].set_xlabel("Gaussian bandwidth parameter")
    axrr[0].set_ylabel("Mean accuracy (perf. score)")

axrr[1].plot(param_grid["sigma"], scores_moons["scores"], '*-')
    axrr[1].set_xscale("log")
    axrr[1].grid(True, which="both", ls="-", alpha=0.5)
    axrr[1].set_title("Moons: Validation accuracy")
    axrr[1].set_xlabel("Gaussian bandwidth parameter")
    axrr[1].set_ylabel("Mean accuracy (perf. score)")

plt.show()
```



The hyper-parameter optimization was done only using the training data. We now can apply the best model (with the optimal σ parameter) to the training data. We should see a similar performance as for the validation set:

```
In [15]: print("[Blobs] Score on test set", est_blobs.score(X_blobs_test, y_blobs_test))
    print("[Moons] Score on test set", est_moons.score(X_moons_test, y_moons_test))

[Blobs] Score on test set 0.936
[Moons] Score on test set 0.912
```

4. Model visualization: Non-linear vs. Linear (no points)

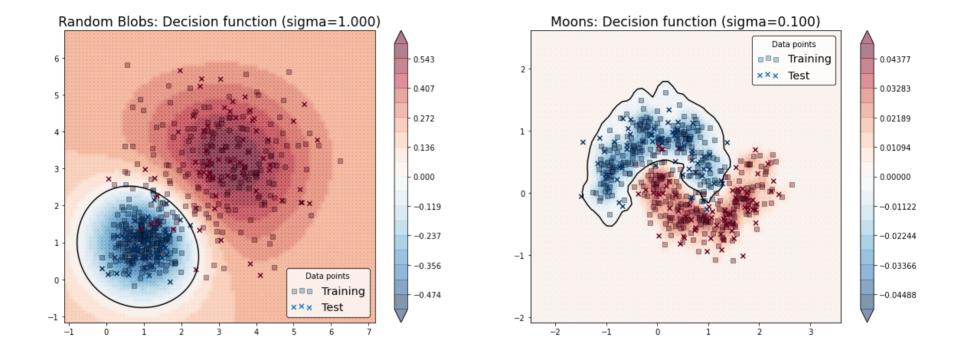
Bonus task: Here we inspect the decision function and how it separates the two classes in the feature space. For that we will evaluate $g(\mathbf{X})$ for \mathbf{X} 's on a regular grid. 1. Set up interval to plot decision function, e.g. min. and max. value of our synthetic datasets. 2. Create grid-points \mathbf{X} covering the intervall. 3. Evaluate $z = g(\mathbf{X})$ for all points. 4. Plot the z's for different points and color them according to their sign.

Decision Function for Gaussian Kernel (Model of previous tasks)

```
In [17]: XX_blobs_grid, YY_blobs_grid = get_gridpoints(X_blobs)
Z_blobs_grid = est_blobs.decision_function(np.c_[XX_blobs_grid.ravel(), YY_blobs_grid.ravel()])
Z_blobs_grid = Z_blobs_grid.reshape(XX_blobs_grid.shape)

XX_moons_grid, YY_moons_grid = get_gridpoints(X_moons)
Z_moons_grid = est_moons.decision_function(np.c_[XX_moons_grid.ravel(), YY_moons_grid.ravel()])
Z_moons_grid = Z_moons_grid.reshape(XX_moons_grid.shape)
```

```
In [18]: fig, axrr = plt.subplots(1, 2, figsize=(20, 7))
         # plot contours, levels, ...
         pcm = axrr[0].pcolormesh(XX blobs grid, YY blobs grid, Z blobs grid, alpha=0.5, shading="gouraud",
                            norm=get color normalizer(Z blobs grid))
         fig.colorbar(pcm, ax=axrr[0], extend="both", orientation="vertical")
         axrr[0].contour(XX blobs grid, YY blobs grid, Z blobs grid, colors=['k'], linestyles=['-'], levels=[0])
         # plot points
         axrr[0].scatter(X blobs train[:, 0], X blobs train[:, 1], c=y blobs train, marker="s", edgecolors="k", a
         lpha=0.35)
         axrr[0].scatter(X blobs test[:, 0], X blobs test[:, 1], c=y blobs test, marker="x", edgecolors="k")
         # plot labels, titles, ...
         axrr[0].legend(["Training", "Test"], title="Data points", fontsize="x-large", scatterpoints=3, edgecolor
         ="k")
         axrr[0].set title("Random Blobs: Decision function (sigma=%.3f)" % best param blobs["sigma"],
                          fontsize="xx-large")
         pcm = axrr[1].pcolormesh(XX moons grid, YY moons grid, Z moons grid, alpha=0.5, shading="gouraud",
                            norm=get color normalizer(Z moons grid))
         fig.colorbar(pcm, ax=axrr[1], extend="both", orientation="vertical")
         axrr[1].scatter(X moons train[:, 0], X moons train[:, 1], c=y moons train, marker="s", edgecolors="k", a
         lpha=0.35)
         axrr[1].scatter(X moons test[:, 0], X moons test[:, 1], c=y moons test, edgecolors="k", marker="x")
         axrr[1].legend(["Training", "Test"], title="Data points", fontsize="x-large", scatterpoints=3, edgecolor
         ="k")
         axrr[1].set title("Moons: Decision function (sigma=%.3f)" % best param moons["sigma"],
                          fontsize="xx-large")
         axrr[1].contour(XX moons grid, YY moons grid, Z moons grid, colors=['k'], linestyles=['-'], levels=[0])
         plt.show()
```



Decision Function for Linear Kernel

We have seen that the Gaussian kernel leads to a non-linear decision boundary, i.e. $g(\mathbf{x}) = 0$ (black line in plots). Now we take a look on the linear Parzen Window Classifier, buy using a linear kernel.

```
In [19]: est_blobs = ParzenWindowClassifier(kernel="linear")
    est_blobs.fit(X_blobs_train, y_blobs_train)

est_moons = ParzenWindowClassifier(kernel="linear")
    est_moons.fit(X_moons_train, y_moons_train)
```

```
In [20]: XX_blobs_grid, YY_blobs_grid = get_gridpoints(X_blobs)
Z_blobs_grid = est_blobs.decision_function(np.c_[XX_blobs_grid.ravel(), YY_blobs_grid.ravel()])
Z_blobs_grid = Z_blobs_grid.reshape(XX_blobs_grid.shape)

XX_moons_grid, YY_moons_grid = get_gridpoints(X_moons)
Z_moons_grid = est_moons.decision_function(np.c_[XX_moons_grid.ravel(), YY_moons_grid.ravel()])
Z_moons_grid = Z_moons_grid.reshape(XX_moons_grid.shape)
```

```
In [21]: fig, axrr = plt.subplots(1, 2, figsize=(20, 7))
         # plot contours, levels, ...
         pcm = axrr[0].pcolormesh(XX blobs grid, YY blobs grid, Z blobs_grid, alpha=0.5, shading="gouraud",
                            norm=get color normalizer(Z blobs grid))
         fig.colorbar(pcm, ax=axrr[0], extend="both", orientation="vertical")
         axrr[0].contour(XX blobs grid, YY blobs grid, Z blobs grid, colors=['k'], linestyles=['-'], levels=[0])
         # plot points
         axrr[0].scatter(X blobs train[:, 0], X blobs train[:, 1], c=y blobs train, marker="s", edgecolors="k", a
         lpha=0.35)
         axrr[0].scatter(X blobs test[:, 0], X blobs test[:, 1], c=y blobs test, edgecolors="k", marker="x")
         # plot labels, titles, ...
         axrr[0].legend(["Training", "Test"], title="Data points", fontsize="x-large", scatterpoints=3, edgecolor
         ="k")
         axrr[0].set title("Random Blobs: Decision function (linear kernel)", fontsize="xx-large")
         pcm = axrr[1].pcolormesh(XX moons grid, YY moons grid, Z moons grid, alpha=0.5, shading="gouraud",
                            norm=get color normalizer(Z moons grid))
         fig.colorbar(pcm, ax=axrr[1], extend="both", orientation="vertical")
         axrr[1].scatter(X moons train[:, 0], X moons train[:, 1], c=y moons train, marker="s", edgecolors="k", a
         lpha=0.35)
         axrr[1].scatter(X moons test[:, 0], X moons test[:, 1], c=y moons test, edgecolors="k", marker="x")
         axrr[1].legend(["Training", "Test"], title="Data points", fontsize="x-large", scatterpoints=3, edgecolor
         ="k")
         axrr[1].set title("Moons: Decision function (linear kernel)", fontsize="xx-large")
         axrr[1].contour(XX moons grid, YY moons grid, Z moons grid, colors=['k'], linestyles=['-'], levels=[0])
         plt.show()
```

