

# Curriculum Vitae

## Jun Zhang, PhD

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### Education

2016.11 – 2021.05	Ph.D. at College of Engineering and Computer Science, Australian National University (ANU)	Canberra
2008.09 - 2015.04	B.Sc. (E.E.) and M.Sc. (Engineering), School of Aeronautics, Northwestern Polytechnical University (NPU)	Xi'an

### Work Experience

2023.12 – Present	Senior Post-doc Researcher, Institute of Visual Computing, TU Graz	Graz
	Advisor: Prof. Friedrich Fraundorfer	
	Projects: Aerial Visual Localization and Mapping (SLAM), Event-based 3D Vision.	
2021.11 – 2023.11	Post-doctoral Researcher, SMaRC & RPL @ EECS, KTH	Stockholm
	Advisors: Prof. John Folkesson, Prof. Patric Jensfelt	
	Projects: AUV Localization and Mapping, Neural Rendering and SLAM.	
2016.11 – 2021.05	Ph.D. Researcher, Australian Centre for Robotic and Vision (ACRV) @ ANU	Canberra
	Advisors: Dr. Viorela Ila, Dr. Laurent Kneip, Prof. Robert Mahony	
	Projects: Visual Odometry/SLAM in Underwater and Dynamic Scenes.	
2014.05 - 2015.09	Research Assistant, Wangxuan Institute of Computer Technology, PKU	Beijing
	Advisor: A/Prof. Zouhui Lian	
	Project: Mesh Segmentation and Non-rigid 3D Shape Retrieval.	

### Awards

2021-2023	Post-Doctoral Fellow Research Funding, RPL, SMaRC, KTH.
2016-2020	PhD Scholarship and University Research Scholarship, ANU.
2012-2015	Second Prize of the National Scholarship, NPU.

### Mentoring

2024-present	Event-based Visual Localization, Kuangyi Chen/Runze Yuan (Ph.D. Project, TU Graz);
2023-present	Neural-based Multi-view Stereo and 3D Reconstruction, Yuxi Hu (Ph.D. Project, TU Graz);
2021-2023	AUV Localization and Bathymetry Reconstruction from Side-scan Sonar and Multi-beam Sensors, Yiping Xie/Li Ling (Ph.D. Project, SMaRC, KTH);
2022-2023	Efficient and Global Consistent Neural Representation for SLAM, Leonard Bruns (Ph.D. Project, RPL, KTH);
2025	Event Image Representation for Visual Localization, Vinayak Lal (Master Seminar Project, TU Graz);
2023	Canonical Image Representation for Side-scan Sonar, Weiqi Xu (Master Thesis, SMaRC, KTH);
2020	Equivariant Visual Odometry, Ryan Pike (Honor Bachelor Project, ANU);

### Publications

- [1] Yuxi Hu, **Jun Zhang**, Kuangyi Chen, Zhe Zhang and Friedrich Fraundorfer, “C<sup>3</sup>-GS: Learning Context-aware, Cross-dimension, Cross-scale Feature for Generalizable Gaussian Splatting”, The 36<sup>th</sup> British Machine Vision Conference (BMVC), 2025.
- [2] Yuxi Hu, **Jun Zhang**, Zhe Zhang, Rafael Weilharter, Yuchen Rao, Kuangyi Chen, Runze Yuan and Friedrich Fraundorfer, “ICG-MVSNET: Learning Intra-view and Cross-view Relationship for Guidance in Multi-View Stereo”, IEEE International Conference on Multimedia and Expo (ICME), 2025.
- [3] Leonard Bruns, **Jun Zhang** and Patric Jensfelt, “Neural Graph Mapping for Dense SLAM with Efficient Loop Closure Integration”, IEEE/CVF Winter Conference on Applications of Computer Vision (WACV), 2025.
- [4] Kuangyi Chen, **Jun Zhang** and Friedrich Fraundorfer, “EVLoc: Event-based Visual Localization in LiDAR Maps via Event-Depth Registration”, IEEE International Conference on Robotics and Automation (ICRA), 2025.
- [5] Jianguo Shi, **Jun Zhang**, Yujing Chen and Jia Ren, “Optimal Fault-tolerant Control for Tugboats Robust Path Following

in Nearshore”, IEEE International Conference on Robotics and Automation (**ICRA**), 2025.

[6] **Jun Zhang**, Yiping Xie, Li Ling and John Folkesson, “A Dense Subframe-based SLAM Framework with Side-scan Sonar”, IEEE Journal of Ocean Engineering (**JOE**), 2024.

[7] Yiping Xie, **Jun Zhang**, Nils Bore and John Folkesson, “NeuRSS: Enhancing AUV Localization and Bathymetric Mapping with Neural Rendering for Sidescan SLAM”, IEEE Journal of Ocean Engineering (**JOE**), 2024.

[8] **Jun Zhang**, Yiping Xie, Li Ling and John Folkesson, “A Fully-automatic Side-scan Sonar Simultaneous Localization and Mapping Framework”, IET Radar, Sonar & Navigation (**RSN**), 2024.

[9] Li Ling, **Jun Zhang**, Nils Bore, John Folkesson and Anna W  hlin, “Benchmarking Classical and Learning-based Multibeam Point Cloud Registration”, IEEE International Conference on Robotics and Automation (**ICRA**), 2024.

[10] Weiqi Xu, Li Ling, Yiping Xie, **Jun Zhang** and John Folkesson, “Evaluation of a Canonical Image Representation for Side-scan Sonar”, IEEE **Oceans**-Limerick, 2023.

[11] **Jun Zhang**, Mina Henein, Robert Mahony and Viorela Ila, “VDO-SLAM: A Visual Dynamic Object-aware SLAM System”, Arxiv:2005.11052, 2020.

[12] Robert Mahony, Pieter Van Goor, Mina Henein, Pike Ryan, **Jun Zhang** and Yonhon Ng, “Equivariant Visual Odometry in the Wild”, The 59<sup>th</sup> IEEE Conference on Decision and Control (**CDC**), 2020.

[13] **Jun Zhang**, Mina Henein, Robert Mahony and Viorela Ila, “Robust Ego and Object 6-DoF Motion Estimation and Tracking”, IEEE/RSJ International Conference on Intelligent Robots and Systems (**IROS**), 2020.

[14] Mina Henein, **Jun Zhang**, Robert Mahony and Viorela Ila, “Dynamic SLAM: The Need for Speed”, IEEE International Conference on Robotics and Automation (**ICRA**), 2020.

[15] **Jun Zhang** and Viorela Ila, “Multi-frame Motion Segmentation for Dynamic Scene Modelling”, The 20<sup>th</sup> Australasian Conference on Robotics and Automation (**ACRA**), 2018.

[16] **Jun Zhang**, Viorela Ila and Laurent Kneip, “Robust Visual Odometry in Underwater Environment”, MTS/IEEE **Oceans**-Kobe, 2018.

[17] **Jun Zhang**, Zhouhui Lian, Zhenbao Liu and Jianguo Xiao, “CEFM: A Heuristic Mesh Segmentation Method based on Convexity Estimation and Fast Marching”, Proceedings of the 10<sup>th</sup> International Conference on Computer Graphics Theory and Applications (**CGTA**), 2015.

[18] Zhouhui Lian, **Jun Zhang** and et. al, “SHREC’15 Track: Non-rigid 3D Shape Retrieval”, **EuroGraphics** Workshop on 3D Object Retrieval, 2015.

## Skills

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**Programming Language/Software/tools:** C/C++, Python, Matlab, ROS, Pytorch, Meshlab, 3DMax, Geomagic, OpenCV.

**Experienced Areas:** visual/sonar perception, location and mapping (SLAM), structure from motion, multi-view geometry, 3D vision, image processing, Markov random fields, probabilistic graphic models, back-end optimization, neural rendering.

**Language Skills:** English (proficient), Mandarin (native), Hainanese (native), Swedish (basic) and German (basic).

## Teaching Duty

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Teaching assistant: [Mathematical Principle in Vision and Graphics](#) (2024 Summer Semester, TU Graz).

Partial lecture responsibility in the [Robot Vision](#) (2024-present SS) and [Camera Drones](#) (2024-present WS) (TU Graz).

## Academic Activities

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**Reviewer** for conferences and journals:

- Conference: ICRA (20-26), IROS (20-25), ICCV (25), BMVC (25), CVWW (25);
- Journal: RAL, TRO, IJRR, AURO, TASE, NUECOM;

**Editorial Duty:**

- IEEE Robotics and Automation Letters (as Associate Editor);

**Invited Talk:**

- The 59<sup>th</sup> Photogrammetric, Stuttgart, 04/2025;
- RPL, KTH, Stockholm, 12/2021;
- MIS, UPJV, Amiens, 08/2024;
- ACFR, UniSyd, Sydney, 12/2019;

**Summer School:**

- Robotic Vision, 2017, Kioloa, Australia;
- Computer Graphics, 2013, Hangzhou, China;