Address: #115 North Rd Acton, Canberra, Australia

Jun Zhang

Mobile: (+61)431698396 Email: jun.zhang2@anu.edu.au

Homepage: https://halajun.github.io/

**Education** 

2016.11 - present	Ph.D. Candidate at College of Engineering and Computer Science,	Canberra
	Australian National University (ANU)	
2012.09 - 2015.04	M.Sc.Eng. of Vehicle Operation Engineering, School of Aeronautics,	Xi'an
	Northwestern Polytechnical University (NPU)	
2008.09 - 2012.06	B.Eng. of Electrical Engineering and Automation, School of Aeronautics,	Xi'an
	Northwestern Polytechnical University (NPU)	

Research Experience		
2016.11 - present	PhD Candidate, ANU & ACRV	Canberra
	Supervisors: Dr. Viorela Ila, Dr. Laurent Kneip, Prof. Robert Mahony.	
	Visual Odometry/SLAM in Underwater and Dynamic Scenes.	
2015.10 - 2016.01	Research Assistant, Multimedia Lab, SIAT	Shenzhen
	Supervisors: Dr. Yu Qiao	
	Building 3D/2D Face Database for Recognition and Reconstruction.	
2014.05 - 2015.09	Research Assistant, Institute of Computer Science and Technology, PKU	Beijing
	Supervisors: Dr. Zouhui Lian	
	Non-rigid 3D Shape Retrieval.	
2015.01 - 2015.04	Master Thesis, School of Aeronautics, NPU	Xi'an

### **Publications**

- [1] Jun Zhang\*, Mina Henein\*, Robert Mahony and Viorela Ila, "VDO-SLAM: A Visual Dynamic Object-aware SLAM System", submitted to International Journal of Robotics Research (IJRR), under review. [\*equally contributed]
- [2] Jun Zhang, Mina Henein, Robert Mahony and Viorela Ila, "Robust Ego and Object 6-DoF Motion Estimation and Tracking", IROS 2020.
- [3] Mina Henein, Jun Zhang, Robert Mahony and Viorela Ila, "Dynamic SLAM: The Need for Speed", ICRA 2020.
- [4] Jun Zhang and Viorela Ila, "Multi-frame Motion Segmentation for Dynamic Scene Modelling", ACRA 2018.
- [5] Jun Zhang, Viorela Ila and Laurent Kneip, "Robust Visual Odometry in Underwater Environment", OCEANS 2018.
- [6] Zhouhui Lian, Jun Zhang and et. al, "SHREC'15 Track: Non-rigid 3D Shape Retrieval", Eurographics 3DOR 2015.
- [7] Jun Zhang, Zhouhui Lian, Zhenbao Liu and Jianguo Xiao, "CEFM: A Heuristic Mesh Segmentation Method based on Convexity Estimation and Fast Marching", VISIGRAPP 2015.

# **Awards**

2019-2020 Award of ACRV HDR Scholarship Top-up, ACRV, ANU.

2016-2020 Award of PhD Scholarship and University Research Scholarship, ANU.

Supervisors: Dr. Zhenbao Liu, Dr. Shuhui Bu. Mesh Segmentation and 3D Object Retrieval.

2012-2015 Award of the Second Prize of the National Scholarship, NPU.

2009 Award of the Third Prize of the Mathematical Contest in Modeling, NPU.

# **Skills**

**Programming Skills**: C/C++, Matlab, Python. Specialized Software: Meshlab, 3DMax, Geomagic.

Language Skills: Mandarin, English.

## **Academic Services**

Reviewer for academic conferences and journals: ICRA 2020, IROS 2020, TASE;

#### **Personalities & Hobbies**

I am energetic, confident, open-minded, and a man of wide interests: soccer, photography, travel, auto, digital products, etc.