

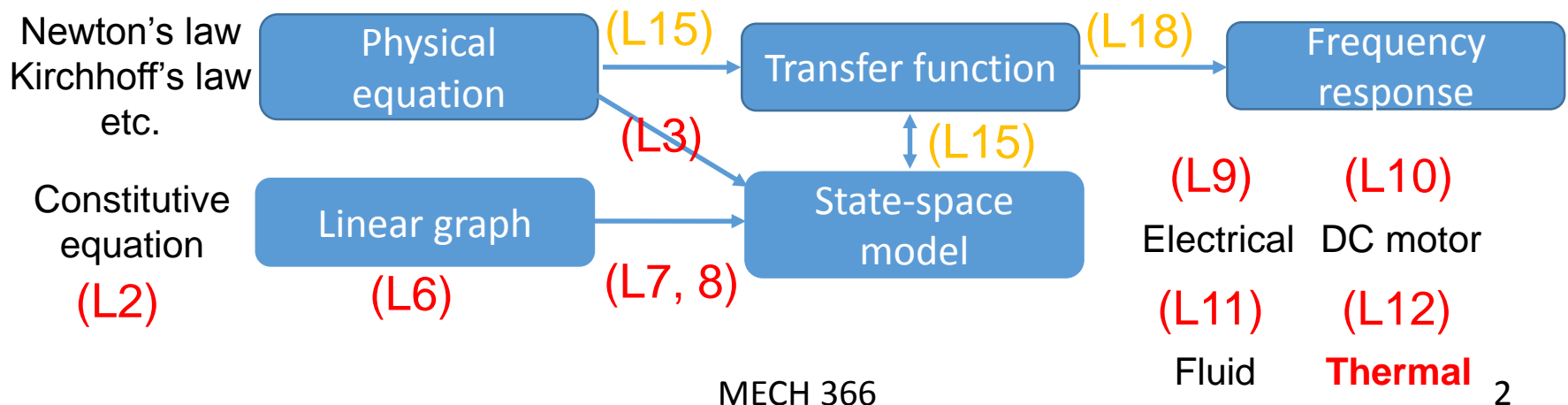
MECH366 : Modeling of Mechatronic Systems

L12 : Modeling of thermal systems

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Review and today's topic

- Up to now, we have studied for mechanical, electrical and fluid systems:
 - How to draw linear graphs & derive state-space models
- Today, we will study modeling of thermal systems.
- Various models and their relations



___ : State variable

Constitutive relation for



System type	Energy storage element		Energy dissipating element
	A-Type	T-Type	D-Type
Mechanical (translational)	Mass	Spring	Viscous Damper
v : velocity across var.	$m\dot{v} = f$	$\dot{f} = kv$	$f = bv$
f : force through var.	m : mass	k : stiffness	b : damping const.
Electrical	Capacitor	Inductor	Resistor
v : voltage across var.	$C\dot{v} = i$	$L\dot{i} = v$	$v = Ri$
i : current through	C : capacitance	L : inductance	R : resistance
Thermal	Thermal capacitor	None	Thermal resistor
T : temperature across $[K]$	$C_t\dot{T} = Q$	"Thermal inductor" does not exist!	$T = R_t Q$
Q : heat transfer rate $[J/s], [W]$ through var.	C_t : thermal capacitance		R_t : thermal resistance
Fluid	Fluid capacitor	Fluid inductor	Fluid resistor
P : pressure difference $[N/m^2]$ across var.	$C_f\dot{P} = Q$	$I_f\dot{Q} = P$	$P = R_f Q$
Q : volume flow rate $[m^3/s]$ through var.	C_f : fluid capacitance	I_f : fluid inertance	R_f : fluid resistance

power
 $\mathcal{P} = fv$

$\mathcal{P} = iv$

$\mathcal{P} = Q$

$\mathcal{P} = QP$

Energy expressions based on across and through variables

	A-type element	T-type element
Mechanical v : Across variable f : Through variable	Kinetic energy $\frac{1}{2}mv^2$	Potential energy $\left(\frac{1}{2}kx^2 =\right) \frac{1}{2}\frac{f^2}{k}$
Electrical v : Across variable i : Through variable	Electrostatic energy $\frac{1}{2}Cv^2$	Electromagnetic energy $\frac{1}{2}Li^2$
Thermal T : Across variable Q : Through variable	Thermal energy $\int Q = C_t T$	N/A
Fluid P : Across variable Q : Through variable	Potential energy $\frac{1}{2}C_f P^2$	Kinetic energy $\frac{1}{2}I_f Q^2$



Main differences of thermal systems from other systems

- No thermal inductor
 - Only one energy storage element
 - No natural oscillatory behaviour
 - Mechanical examples: Pendulum, mass spring system exchanges kinetic and potential energies.
 - Electrical example: LC circuit exchanges electrostatic (in C) and electromagnetic (in L) energies.
- Power is defined by only one variable.
- Resistor does not dissipate energy, but **impedes** heat flow.



Linear graph representation

- Single-port elements
 - Energy storage elements
 - Energy (dissipation) elements
 - Energy sources

Energy storage element

Thermal capacitor

- Constitutive equation

$$C_t \frac{dT}{dt} = Q \quad C_t = \rho V c$$

C_t [J/K] : thermal capacitance

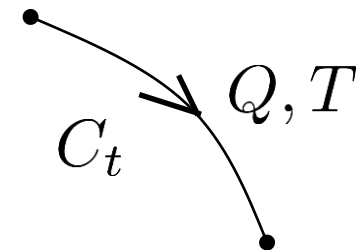
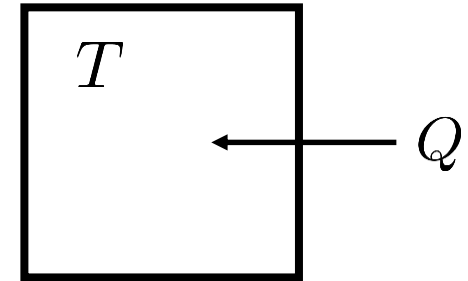
ρ [kg/m³] : mass density of the object

V [m³] : volume of the object

c [J/(K · kg)] : specific heat of the object

Amount of heat per unit mass required
to raise temperature by one degree

- Thermal energy stored $\mathcal{E} = C_t T$





Linear graph representation

- Single-port elements
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Energy dissipation element

Thermal resistor

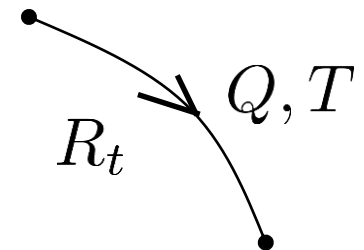
- Constitutive equation

$$R_t Q = T$$

R_t [Ks/J] ([K/W]) : thermal resistance

- No energy dissipation
 - Thermal resistance simply acts to **impede** heat flow.
- Three heat transfer mechanisms
 - Conduction
 - Convection
 - Radiation (nonlinear) $R_t Q = T_1^4 - T_2^4$

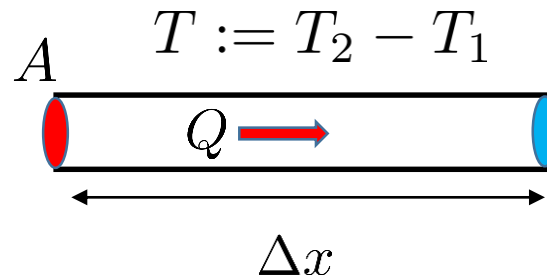
Linear graph



Energy dissipation element

Thermal resistor: Conduction

- Heat transfer through a material (e.g. metal block)
 - For a uniform material below



- Thermal resistance is

$$R_t = \frac{\Delta x}{kA} \quad k [W/K] : \text{thermal conductivity}$$

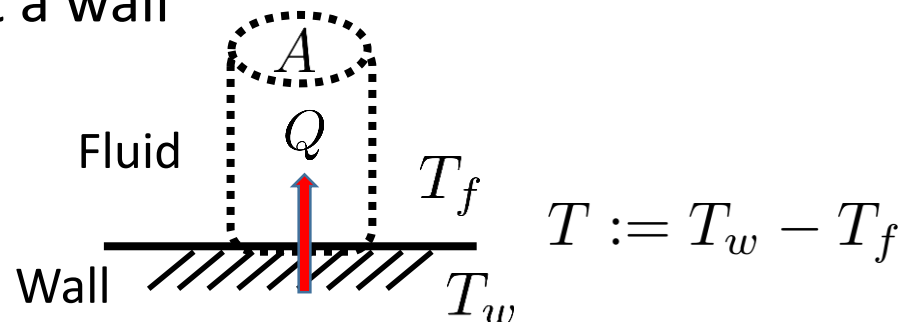
High k -value: Thermal conductor (e.g. metal)

Low k -value: Insulator (e.g. wood, plastic)

Energy dissipation element

Thermal resistor: Convection

- Heat transfer by moving fluids (e.g. air)
 - Ex: Fluid flowing against a wall



- Thermal resistance is

$$R_t = \frac{1}{h_c A}$$

$h_c [W/m^2 K]$: convection heat transfer coefficient
 $A [m^2]$: section area of heat transfer

- Natural convection (e.g. hot air rises)
- Forced convection (e.g. fluid moved by fan or pump)



Linear graph representation

- Single-port elements
 - Energy storage elements
 - Energy dissipation elements
 - Energy sources

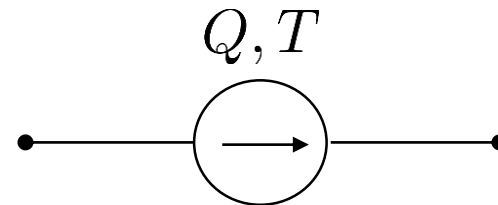
Linear graph representation

Fluid energy sources

- Heat source

- Heater

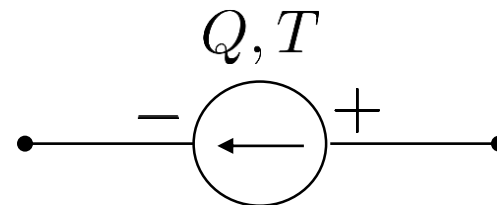
Linear graph



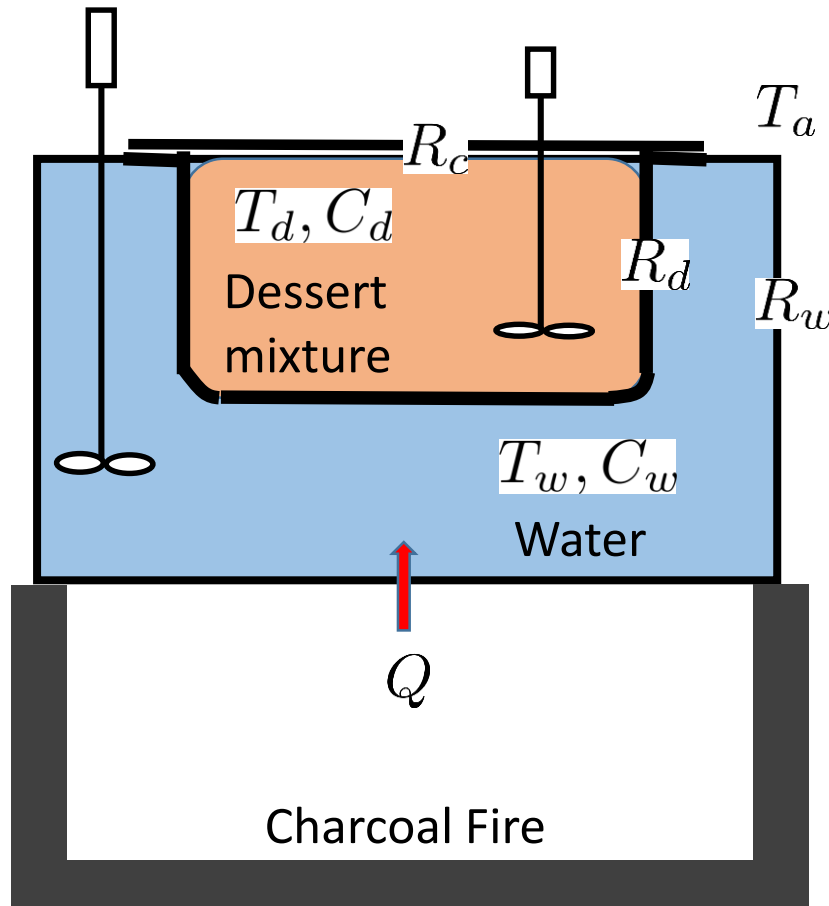
- Temperature source

- Heater
- Large reservoir

Linear graph



Example: “watalappam” making (taken from de Silva’s book)



C : thermal capacitance
 R : thermal resistance
 T : temperature
 Q : heat transfer rate

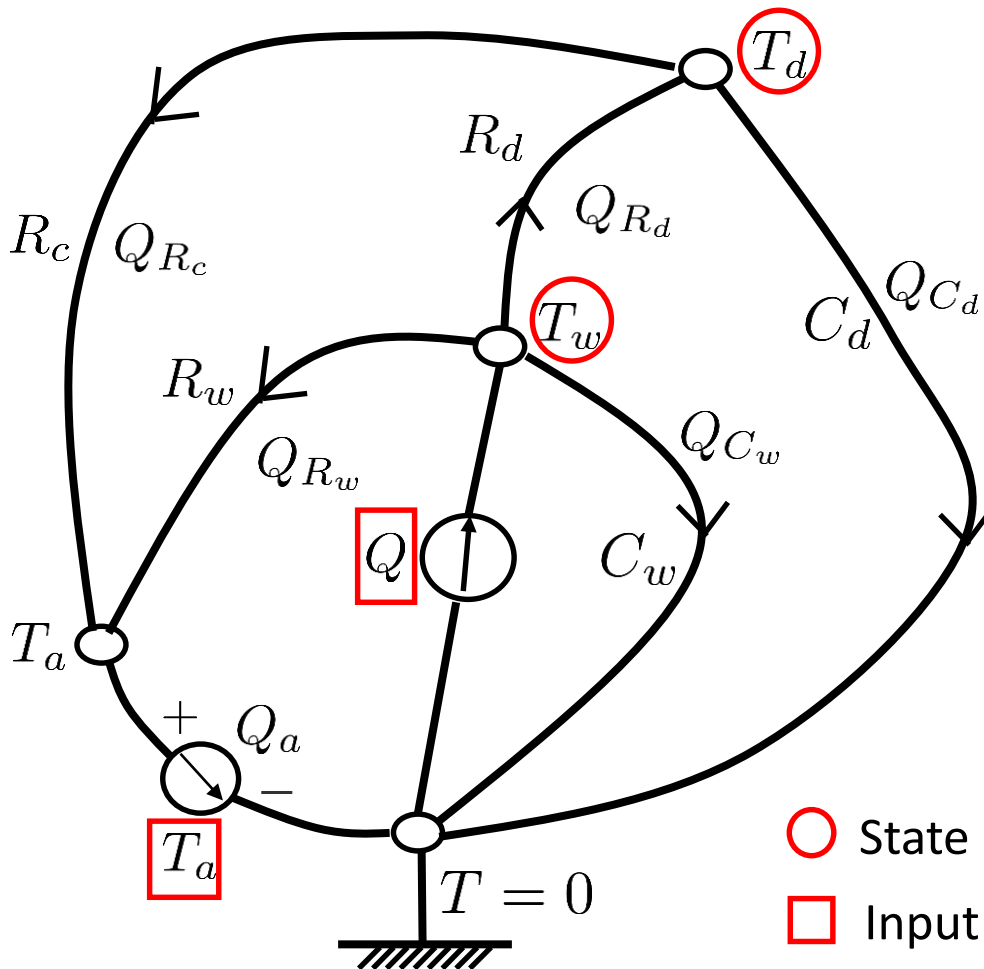
Input: heat transfer rate Q

Disturbance input:
ambient temperature T_a

Output: temperature T_d

Example

Linear graph drawing



- Constitutive eq.

$$R_d Q_{R_d} = T_w - T_d$$

$$R_c Q_{R_c} = T_d - T_a$$

$$R_w Q_{R_w} = T_w - T_a$$

$$C_w \dot{T}_w = Q_{C_w} \quad C_d \dot{T}_d = Q_{C_d}$$

- Node eq.

$$Q_{R_d} = Q_{R_c} + Q_{C_d}$$

$$Q_{R_d} + Q_{R_w} + Q_{C_w} = Q$$

$$Q_{R_c} + Q_{R_w} + Q_a = 0$$



Example

State-space model derivation

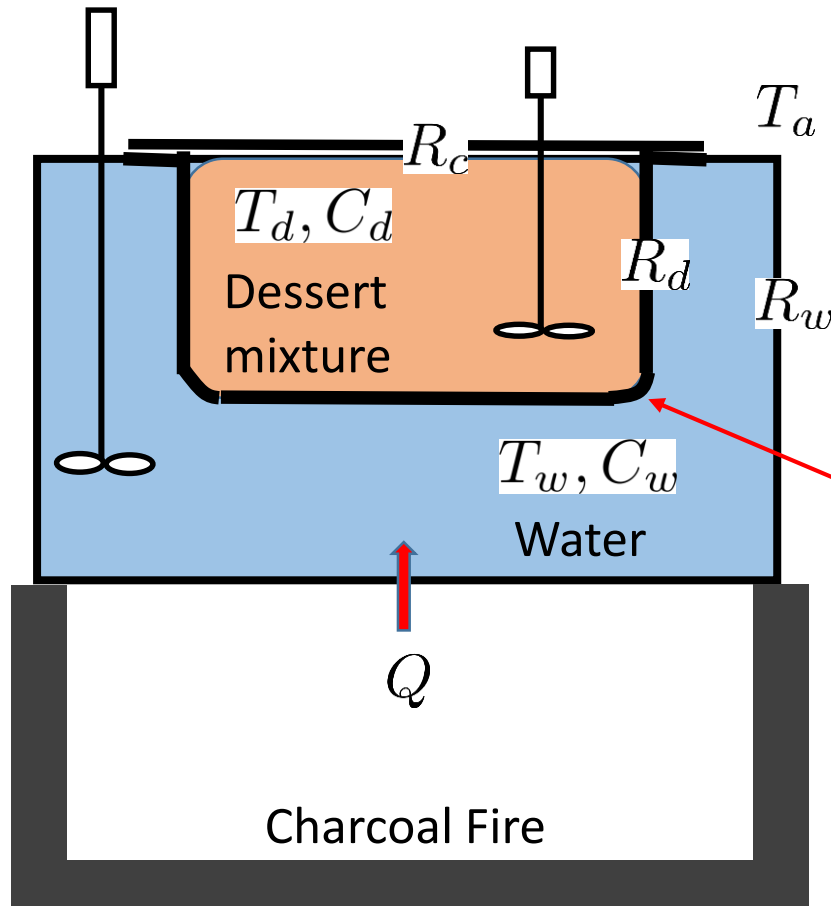
$$\dot{T}_w = \frac{1}{C_w} Q_{C_w} = \frac{1}{C_w} \left\{ Q - \underbrace{\frac{1}{R_w} (T_w - T_a)}_{Q_{R_w}} - \underbrace{\frac{1}{R_d} (T_w - T_d)}_{Q_{R_d}} \right\}$$

$$\dot{T}_d = \frac{1}{C_d} Q_{C_d} = \frac{1}{C_d} \left\{ \underbrace{\frac{1}{R_d} (T_w - T_d)}_{Q_{R_d}} - \underbrace{\frac{1}{R_c} (T_d - T_a)}_{Q_{R_c}} \right\}$$

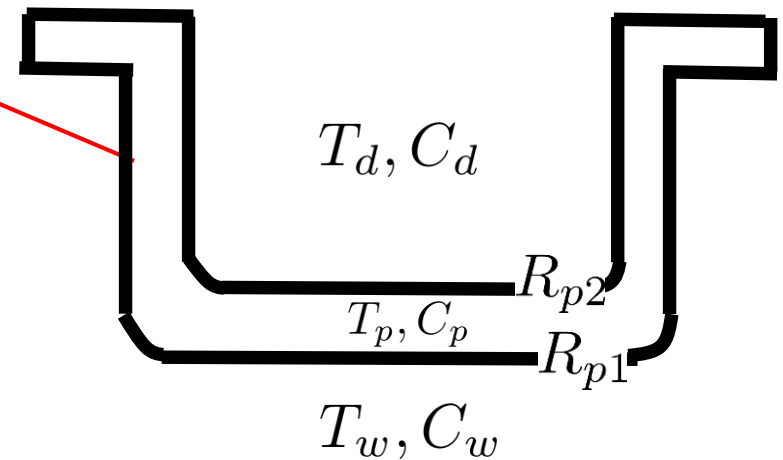
$$\rightarrow \begin{cases} \begin{bmatrix} \dot{T}_w \\ \dot{T}_d \end{bmatrix} = \begin{bmatrix} -\frac{1}{C_w} \left(\frac{1}{R_w} + \frac{1}{R_d} \right) & \frac{1}{C_w R_d} \\ \frac{1}{C_d R_d} & -\frac{1}{C_d} \left(\frac{1}{R_d} + \frac{1}{R_c} \right) \end{bmatrix} \begin{bmatrix} T_w \\ T_d \end{bmatrix} + \begin{bmatrix} \frac{1}{C_w} & \frac{1}{C_w R_w} \\ 0 & \frac{1}{C_d R_c} \end{bmatrix} \begin{bmatrix} Q \\ T_a \end{bmatrix} \\ T_d = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} T_w \\ T_d \end{bmatrix} \end{cases}$$

Example

A detailed model

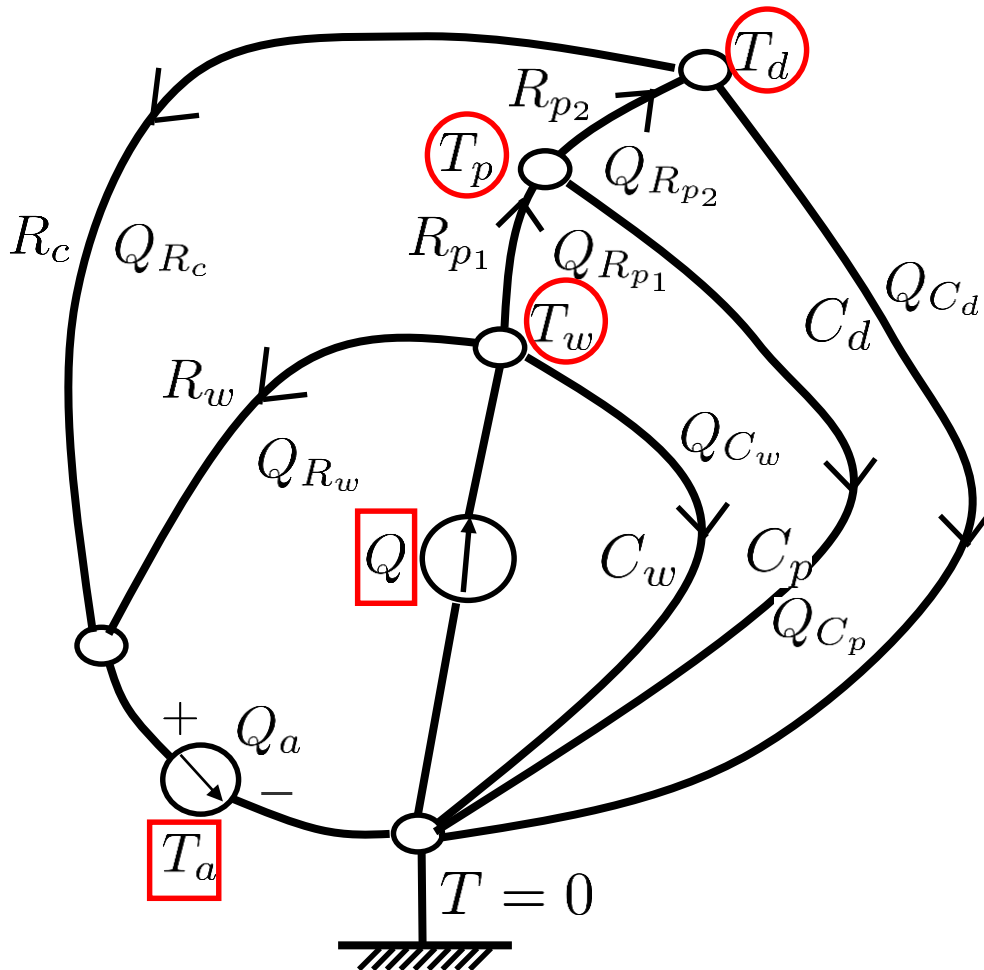


Add thermal resistances for the pot



Example

Linear graph drawing



- Constitutive eq.

$$R_{p1} Q_{R_{p1}} = T_w - T_p$$

$$R_{p2} Q_{R_{p2}} = T_p - T_d$$

$$R_c Q_{R_c} = T_d - T_a$$

$$R_w Q_{R_w} = T_w - T_a$$

$$C_w \dot{T}_w = Q_{C_w} \quad C_d \dot{T}_d = Q_{C_d}$$

- Node eq. $C_p \dot{T}_p = Q_{C_p}$

$$Q_{R_{p2}} = Q_{R_c} + Q_{C_d}$$

$$Q_{R_{p1}} = Q_{R_{p2}} + Q_{C_p}$$

$$Q_{R_{p1}} + Q_{R_w} + Q_{C_w} = Q$$

$$Q_{R_c} + Q_{R_w} + Q_a = 0$$



Example

State-space model derivation

$$\dot{T}_w = \frac{1}{C_w} Q_{C_w} = \frac{1}{C_w} \left\{ Q - \underbrace{\frac{1}{R_w} (T_w - T_a)}_{Q_{R_w}} - \underbrace{\frac{1}{R_{p1}} (T_w - T_p)}_{Q_{R_{p1}}} \right\}$$

$$\dot{T}_d = \frac{1}{C_d} Q_{C_d} = \frac{1}{C_d} \left\{ \underbrace{\frac{1}{R_{p2}} (T_p - T_d)}_{Q_{R_{p2}}} - \underbrace{\frac{1}{R_c} (T_d - T_a)}_{Q_{R_c}} \right\}$$

$$\dot{T}_p = \frac{1}{C_p} Q_{C_p} = \frac{1}{C_p} \left\{ \underbrace{\frac{1}{R_{p1}} (T_w - T_p)}_{Q_{R_{p1}}} - \underbrace{\frac{1}{R_{p2}} (T_p - T_d)}_{Q_{R_{p2}}} \right\}$$

$$\rightarrow \begin{cases} \begin{bmatrix} \dot{T}_w \\ \dot{T}_d \\ \dot{T}_p \end{bmatrix} = A \begin{bmatrix} T_w \\ T_d \\ T_p \end{bmatrix} + B \begin{bmatrix} Q \\ T_a \end{bmatrix} \\ T_d = \begin{bmatrix} 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} T_w \\ T_d \\ T_p \end{bmatrix}$$

Simscape in Matlab/Simulink

- Physical system modeling tool in Matlab/Simulink
- Software which utilizes linear graph concept
- Read/watch
 - www.mathworks.com/products/simscape.html
 - www.mathworks.com/help/physmod/simscape/getting-started-with-simscape.html
 - Essential Steps for Constructing a Physical Model
 - Evaluating Performance of a DC Motor

Summary

- Linear graph for thermal systems
 - Single-port elements
 - Energy storage elements
 - Energy (dissipation) elements
 - Energy sources
- We are done with linear graph!
- Next, Laplace transform and transfer function
- Homework 4: Due Oct 28 (Monday), 3pm
- Lab 3 report: Due Nov 1 (Friday), 6pm