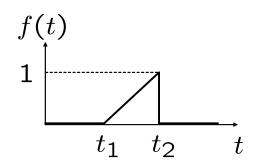
MECH366 Modeling of Mechatronic Systems Exercises for Laplace Transform

Taken from Appendix B of the Phillips and Parr's textbook.

- 1. (B.1, B.2) Use the Laplace transform table to obtain the Laplace transform of the following functions.
 - (a) f(t) = u(t 2.5)
 - (b) $f(t) = e^{-4t}$
 - (c) f(t) = t
 - (d) $f(t) = -3te^{-t}$
 - (e) $f(t) = -5\cos t$
 - (f) $f(t) = t \sin 3t$
 - (g) $f(t) = 7e^{-0.5t} \cos 3t$
 - (h) $f(t) = 5\cos(4t + \pi/6)$
 - (i) $f(t) = 6e^{-2t}\sin(t \pi/4)$
- 2. (B.5.(a)) Find and plot f(t) if its Laplace transform is given by

$$F(s) = \frac{e^{-t_1 s} - e^{-t_2 s}}{s}, \quad t_2 > t_1.$$

3. (B.5.(b)) Find the Laplace transform of the triangular pulse shown below.



- 4. (B.6) For a function $f(t) = 4e^{-2(t-3)}u(t-3)$,
 - (a) Find $\mathcal{L}\{f'(t)\}\$ by differentiating f(t) and then using the Laplace transform table.
 - (b) Find $\mathcal{L}\{f'(t)\}$ using the theorem for differentiation.
- 5. (B.7) For functions $f_1(t) = 5e^{-2(t-1)}$ and $f_2(t) = 5e^{-2(t-1)}u(t-1)$,
 - (a) Sketch the two time functions.
 - (b) Find the Laplace transforms.