Gautami Golani

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EDUCATION –

National University of Singapore (NUS), Singapore

Jan 2019 - Jan 2020

M.Sc. in Electrical Engineering; Specialization in Control & Automation

Manipal Academy of Higher Education (MAHE), Dubai

Sep 2014 - Jun 2018

B.Tech in Mechatronics Engineering; Minor Specialization in Robotics and Automation

Cumulative GPA - 9.82/10.0

EXPERIENCE —

Graduate Student Researcher, National University of Singapore

Mar 2019 - Nov 2019

Guide: Prof. Sam Ge, Control & Simulation Lab

Formulated new path planning schemes and implemented them on an omni-directional mobile robot manipulator.

Aircraft Maintenance Intern, Emirates Aviation Services, L.L.C, Dubai

Jul 2016

- Executed on-job training of the maintenance cycle for various parts within Piper PA-28-161 & Cessna 172S Aircraft.
- Conducted the removal, inspection, and installation of the propeller, main gear oleo strut, landing gear & carburetor.
- Gained an understanding of the overall functioning of an aircraft including the ignition and navigation system.
- Familiarized with the pre-flight inspection procedure to prevent any mishaps.

PROJECTS -

Adaptive Control for Mobile Manipulators

Present

Currently working on the implementation of adaptive control on mobile manipulators.

Path Planning of Mobile Robot Manipulators, National University of Singapore

Mar 2019 - Nov 2019

Guide: Prof. Sam Shuzhi Ge, Control & Simulation Lab

Graduate Project

- Established relevant kinematic equations (mathematical model) of the mobile robot manipulator.
- Formulated new path planning schemes (repetitive and non-repetitive with limits) for the mobile manipulator system to track certain desired paths effectively and attained discretization of both the schemes at a later stage.
- Utilized MATLAB for schemes and their corresponding computer simulation. Generated and analyzed scheme results against certain parameters, with each proposed scheme exhibiting high performance.

Framework of Repetitive Path Planning and Control for UR5 Manipulator, National University of Singapore Mar 2019 - May 2019

 Developed a complete path planning and control framework for the UR5 manipulator; implemented the RPP scheme and computed-torque controller and carried out simulations.

Vision Based Autonomous Assistance Robot using LabVIEW, MAHE, Dubai

Feb 2018 - Jun 2018

Guide: Prof. Royson Dsouza, Manipal Centre of Robotics Excellence (MCORE)

Undergraduate Project

- Led a team of 4 to build a user-driven robot that provides directions to different labs & classes in MAHE, Dubai upon receiving input from the user; used a myRIO as the evaluation board.
- Designed the programs on LabVIEW & developed a face detection algorithm to identify the user.
- Integrated voice commands & motor control for giving directions with features formed and achieved desired results.

Bio mimicking a Pectoral Fin using PID Controller, MAHE, Dubai

Mar 2017 - May 2017

- Studied movements of a Manta Ray to Bio mimic motion of its fin.
- Created one half of Manta Ray's flexible pectoral fins with silicone rubber which was then driven by servo motors to achieve desired oscillation; generated a PID controller program in LabVIEW for this project.

Publications —

Royson Dzouza, Anil Sequeira, Marian Jose & Gautami Golani, "Damage Inspection & Online Monitoring: A Comparative Study between Aluminium & Composite Plate Structures", IOP Conference Series: Materials Science & Engineering, Vol. 22, 2018

TRAINING/CERTIFICATION -

Post Graduate Diploma in Industrial Automation

Prolific Systems & Technologies, Baroda, India

- Gathered knowledge of the hardware components and configuration of PLCs.
- Studied the instructions of 5 PLCs (Allen Bradley, Siemens, GE-Fanuc, Modicon & Mitsubishi); developed and tested several ladder logic programs.
- Explored **SCADA** (Wonderware Intouch); designed and analyzed programs.
- Performed scaling with PLCs and worked towards establishing communication between SCADA and PLC.
- Inspected drives and carried out interfacing of **drives** with **HMI** panels.
- Examined DCS (ABB), panel wiring and wireless/GSM technology in brief

Coursera Certifications

Python Data Representations Dec 2018

Python Programming Essentials Nov 2018 Nov 2018

Autodesk Fusion 360 Integrated CAD/CAM/CAE

TECHNICAL SKILLS -

Programming Languages: Python (Intermediate), MATLAB Computing Software: LabVIEW, Wonderware Intouch

CAD: Pro-E/Creo & SolidWorks **Prototyping: 3D Printing** Others: LaTeX, MS Office & PLCs

ACHIEVEMENTS

Scholarship/Academic Excellence:

Academic Topper in Mechatronics Engineering - MAHE, Dubai for the Academic Years 2015-2018.

Sports:

- Best Player in Women's Cricket MAHE, Dubai for the year 2015-2016.
- Awarded Certificate of Merit for Showing Exemplary Performance in Sports DPS, Dubai from 2010 2012.
- Part of the Winning Team Inter School Cricket Tournaments from 2010-2013.
- Participated in Tennis and Football CBSE Clusters represented DPS, Dubai in 2011.

Competitions (Participation):

- 2nd and 3rd Research Colloquium on Advances in Engineering and IT MAHE, Dubai in 2017 and 2018.
- Symposium on IOT, ROS Workshop MAHE, Dubai in 2017.
- ASME MAQUINA Competition MAHE, Dubai in 2016.
- Gulf Medical University MASE represented DPS, Dubai in 2012.

Professional Associations -

Member, IEEE Graduate Student

Member, IEEE Robotics & Automation Society (RAS)

Aug 2017 - Sep 2017