

Numerical Simulation Methods in Geophysics, Exercise 5: Finite Elements

1. MGPY+MGIN

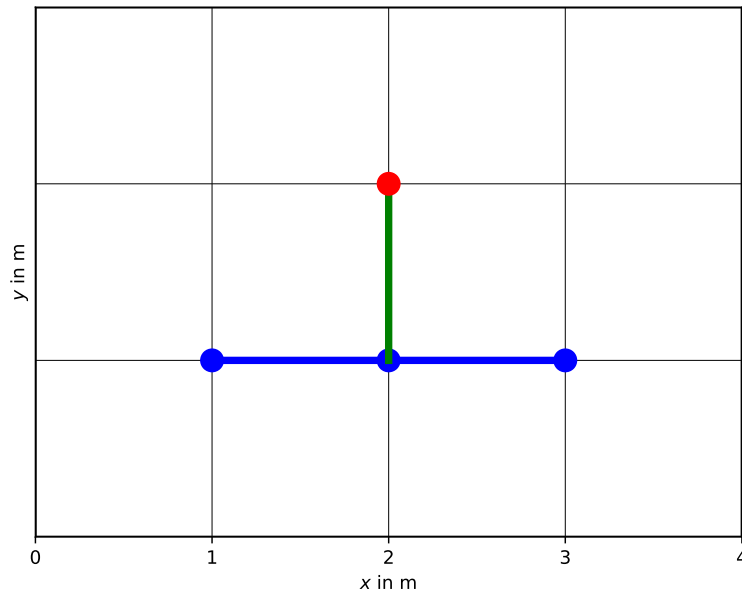
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Recap time-stepping in FD

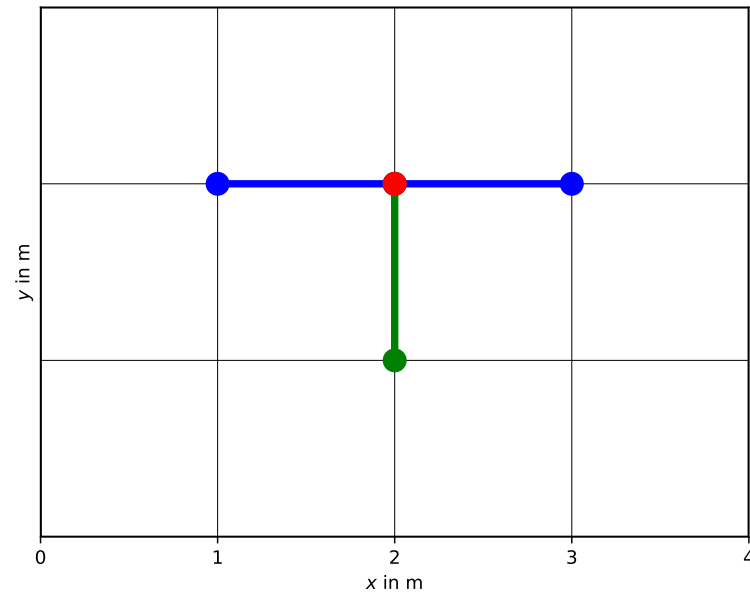
Explicit: $\mathbf{u}^{n+1} = (\mathbf{I} - \Delta t \mathbf{A}) \mathbf{u}^n$

Implicit: $(\mathbf{I} + \Delta t \mathbf{A}) \mathbf{u}^{n+1} = \mathbf{u}^n$

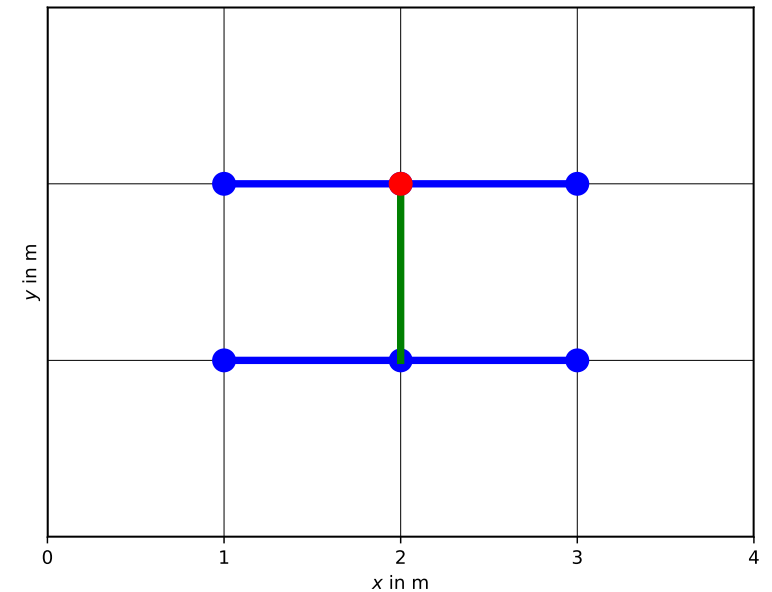
Mixed: $(2\mathbf{I} + \Delta t \mathbf{A}) \mathbf{u}^{n+1} = (2\mathbf{I} - \Delta t \mathbf{A}) \mathbf{u}^n$



Explicit



Implicit



Mixed

The FE stiffness matrix

Matrix integrating gradients of base functions for neighbors with a

$$\mathbf{A}_{i,i+1} = -\frac{a_i}{\Delta x_i^2} \cdot \Delta x_i = -\frac{a_i}{\Delta x_i}$$

$$A_{i,i} = \int_{\Omega} a \nabla v_i \cdot \nabla v_i d\Omega = -A_{i,i+1} - A_{i+1,i}$$

\Rightarrow matrix-vector equation $\mathbf{A}\mathbf{u} = \mathbf{b}$ with bending&shear stiffness in \mathbf{A}

Right-hand side vector

The right-hand-side vector $b = \int v_i f d\Omega$ also scales with Δx

e.g. $f = \nabla \cdot \mathbf{j}_s \Rightarrow b = \int v_i \nabla \cdot \mathbf{j}_s d\Omega = \int_{\Gamma} v_i \mathbf{j}_s \cdot \mathbf{n}$

RHS = integrated source function (includes Δx)

(both \mathbf{A} and \mathbf{b} identical to FD for $\Delta x=1$)

Difference of FE to FD

Any source function $f(x)$ can be integrated on the whole space!

Tasks

1. Write a function computing the FE stiffness matrix for 1D discretization
2. Test it by solving the Poisson equation with $f = 1$
3. Compare with analytical solution
4. Compute FD solution and compare with FE
5. Change discretization and check again
6. Change conductivity & compare FD and FE

Analytical solution for $f=1$

$$u(x) = -\frac{1}{2}x^2 + C_1x + C_0 \quad \Rightarrow \quad u'(x) = -x + C_1$$

BC $x=0$	BC $x = X$	C_0	C_1
Dirichlet	Dirichlet	u_0	$X/2 + (u_X - u_0)/X$
Dirichlet	Neumann	u_0	$u'_X + X$
Neumann	Dirichlet	u'_0	$u_X - u'_0X + X^2/2$

Time-stepping in FE

Variational formulation of Diffusion equation

$$\frac{\partial u}{\partial t} - \nabla \cdot a \nabla u = f$$

Finite Difference in Time (NOT in space)

$$\frac{u^{n+1} - u^n}{\Delta t} - \nabla \cdot a \nabla u = f$$

Variational formulation

$$\frac{u^{n+1} - u^n}{\Delta t} - \nabla \cdot a \nabla u = f$$

Multiplication with test function w and integration \Rightarrow weak form

$$1/\Delta t \left(\int_{\Omega} w u^{n+1} d\Omega - \int_{\Omega} w u^n d\Omega \right) - \int_{\Omega} w \nabla \cdot a \nabla u d\Omega = \int_{\Omega} w f d\Omega$$

$$1/\Delta t \left(\int_{\Omega} w u^{n+1} d\Omega - \int_{\Omega} w u^n d\Omega \right) - \int_{\Omega} a \nabla w \cdot \nabla u d\Omega = \int_{\Omega} w f d\Omega$$

Variational formulation of Diffusion equation

u is constructed of shape functions \mathbf{v}_i that are identical to w

The integral over the Poisson term $\int_{\Omega} a \nabla w \cdot \nabla u d\Omega$ is represented using the stiffness matrix $\mathbf{A}\mathbf{v}$

$$\mathbf{A}_{i,j} = \int_{\Omega} \sigma \nabla v_i \cdot \nabla v_j d\Omega$$

Variational formulation of Poisson equation

Weighted integrals over both u are represented by the mass matrix $\mathbf{M}\mathbf{v}$

$$\mathbf{M}_{i,j} = \int_{\Omega} v_i \cdot v_j d\Omega$$

explicit method: $\mathbf{M}\mathbf{u}^{n+1} = (\mathbf{M} - \mathbf{A})\mathbf{u}^n$

implicit method: $(\mathbf{M} + \mathbf{A})\mathbf{u}^{n+1} = \mathbf{M}\mathbf{u}^n$

mixed method: $(\mathbf{M} + \mathbf{A}/2)\mathbf{u}^{n+1} = (\mathbf{M} - \mathbf{A}/2)\mathbf{u}^n$

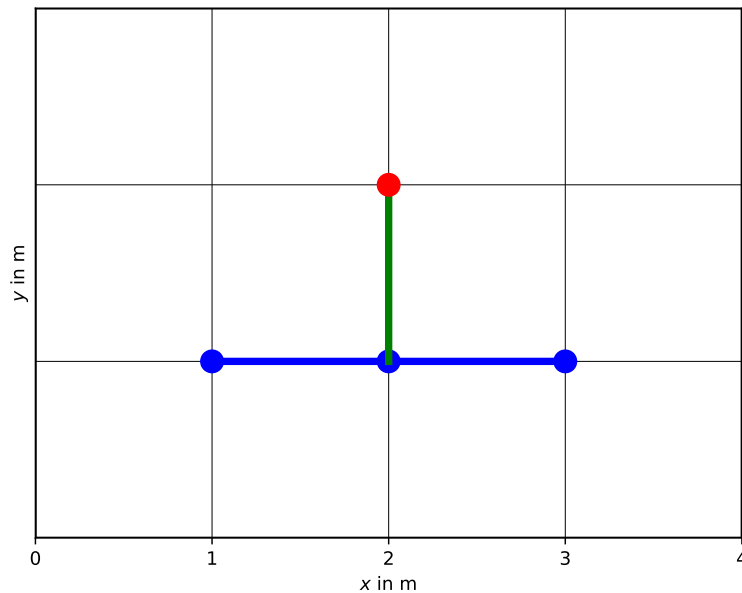
same as in FD but with FE mass matrix

Time-stepping in FE

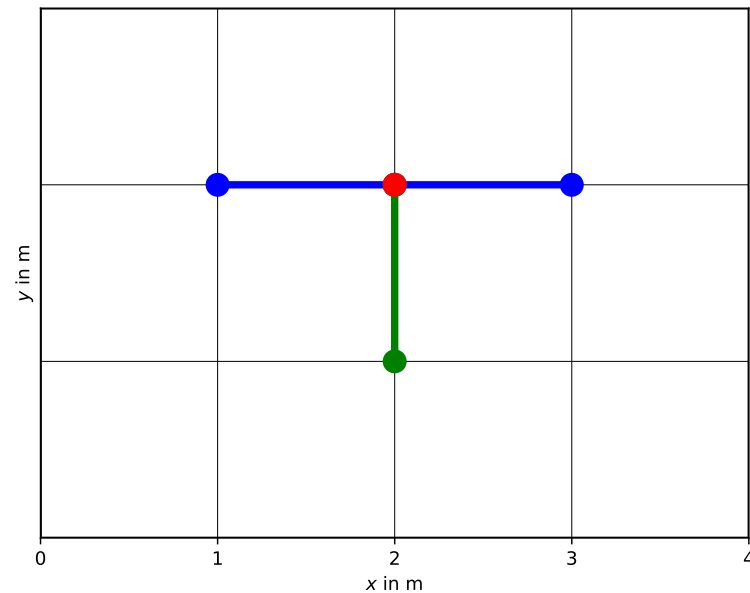
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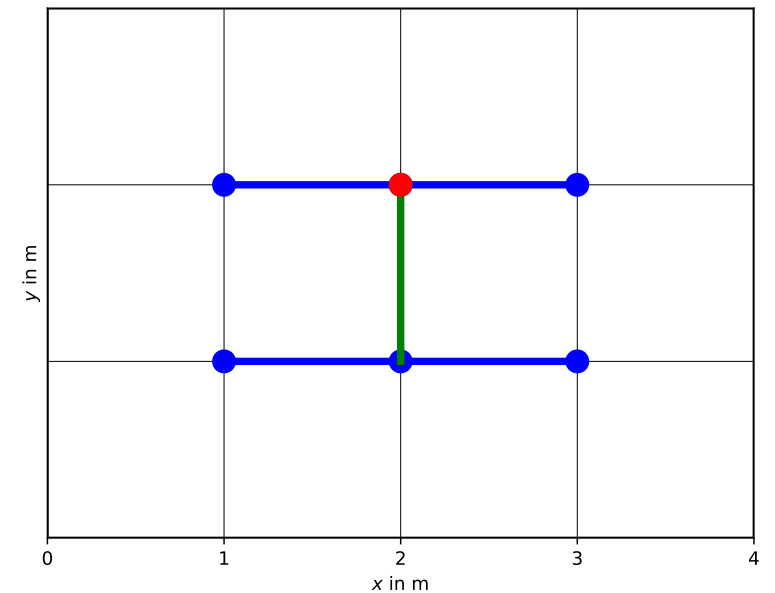
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Explicit



Implicit



Mixed

Tasks

1. Write a function computing the FE stiffness matrix for 1D discretization
2. Test it by solving the Poisson equation with $f = 1$ (analytical solution)
3. Compare with analytical and FD solutions
4. Write a function computing the FE mass matrix for 1D discretization
5. Repeat the time-stepping tasks from FD with FE