# Numerical Simulation Methods in Geophysics, Part 10: 2D Helmholtz equation

1. MGPY+MGIN

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# Recap

- Maxwell equations in time domain
- harmonic approach (or decomposition)
  - $\Rightarrow$  (complex-valued) Helmholtz equation for E and B
- solve 1D Helmholtz equation complex-values
  - compare with analytic solution

#### **Next lectures and exercises**

- LV10: 15.01. exercise on 16.01.
- LV11: 22.01. exercise on 23.01.
- LV12: 29.01. exercise on 30.01.
- VL13: 05.02., exercise on 06.02.
- report on 2D Helmholtz equations

#### Todo

- solve 2D Helmholtz equation
  - use secondary field approach
- use wide range of frequencies
  - combine E and H to yield MT sounding curves
- excurse on 3D vectorial Maxwell solvers
- overview on equation solvers and high-performance computing
- outlook to computational fluid dynamics

#### Electromagnetic fields in the Earth

Maxwell equations lead to diffusion equation

$$rac{\partial^2 \mathbf{B}}{\partial z^2} = \mu_0 \sigma rac{\partial \mathbf{B}}{\partial t}$$

A periodic excitation ( $B_0e^{\imath\omega t}$ ) leads to (cf. temperature problem)

$$B=B_0e^{-z/d}\cos(\omega t-z/d)$$

with the skin depth  $d=\sqrt{2/(\mu_0\sigma\omega)}pprox 503\sqrt{
ho/f}$ 

#### Electromagnetic fields in the Earth

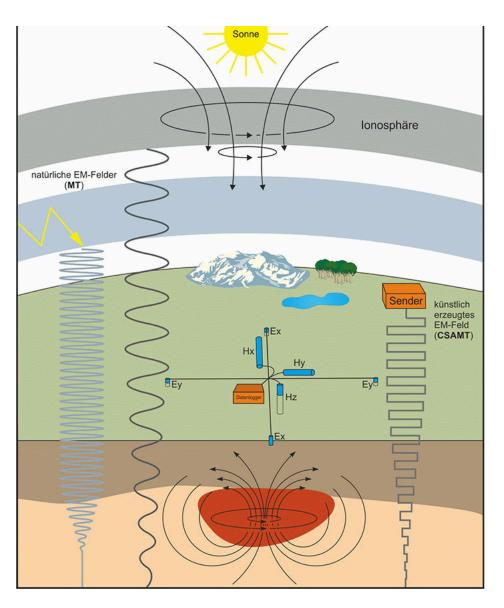
Assume E field in x direction

$$E_x = -rac{1}{\mu_0\sigma}rac{\partial B_y}{\partial z} = rac{B_0}{\mu_0\sigma d}e^{-z/d}\sqrt{2}\cos(\omega t - z/d + \pi/4)$$

 $\Rightarrow$  phase shift of 45° ( $\pi/4$ ) between  $E_x$  und  $B_y$ 

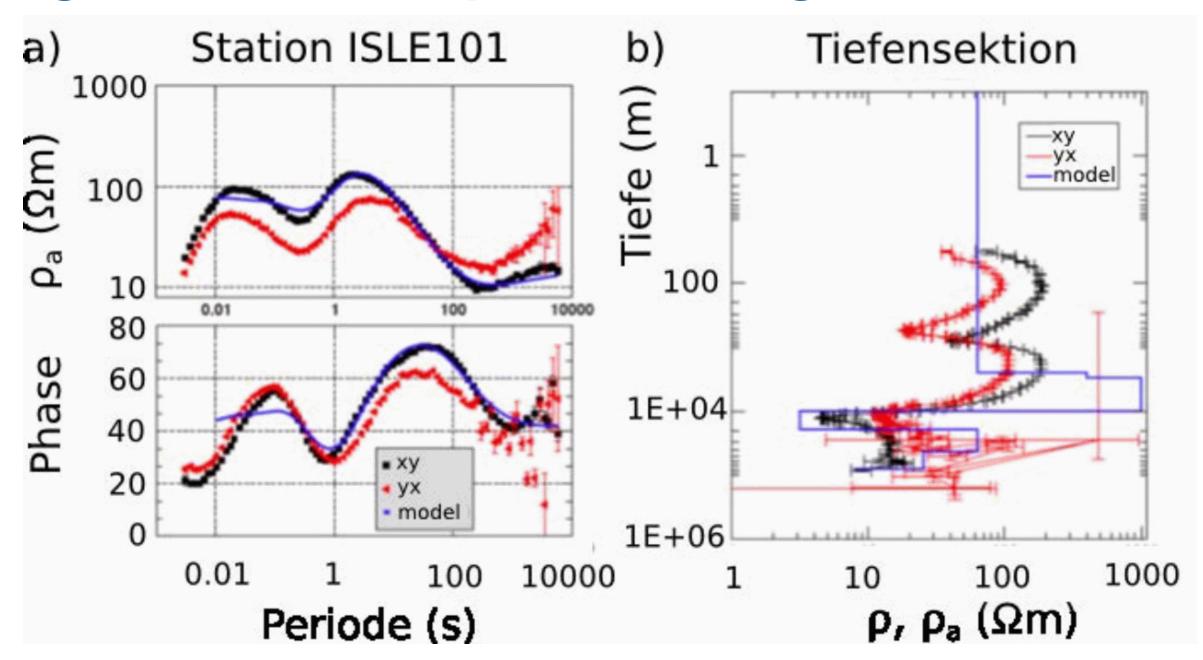
$$rac{|E_x|}{|B_y|} = rac{\sqrt{2}}{\mu_0 \sigma d} \Rightarrow 
ho = rac{\mu_0}{\omega} \left|rac{E_x}{B_y}
ight|^2$$

### The magnetotelluric (MT) method

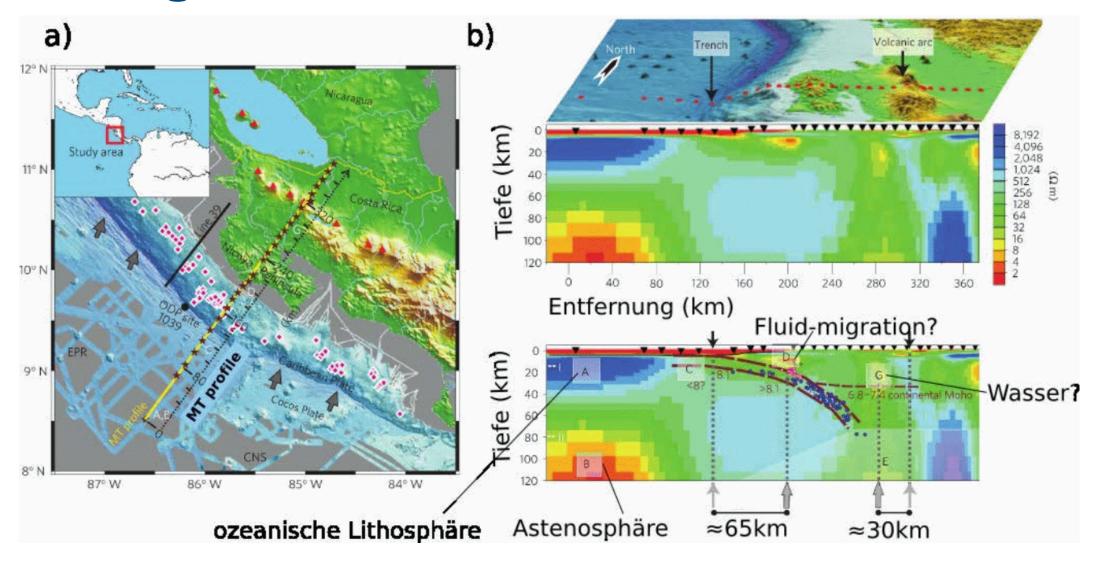


- inductive electromagnetics with f=0.001-100,Hz (T=0.01-1000s)
- source in ionosphere (natural source) or on ground (controlled source)
- measure magnetic and electric fields
- analyse (complex) ratio in frequency domain
- depth sounding ( $ho_a \& \phi$ ) with T
- MT course of Anna Marti (U Barcelona)

#### Magnetotelluric depth sounding



### 2D/3D Magnetotellurics



Imaging of a subduction zone (Worszewski et al., 2011)

#### Helmholtz equations

$$\mathbf{\nabla} imes \mu^{-1} \mathbf{\nabla} imes \mathbf{E} + \imath \omega \sigma \mathbf{E} - \omega^2 \epsilon \mathbf{E} = -\imath \omega \mathbf{j}_s$$

$$\mathbf{
abla} imes \sigma^{-1} \mathbf{
abla} imes \mathbf{H} + \imath \omega \mu \mathbf{H} - \omega^2 \epsilon \mu / \sigma \mathbf{H} = \mathbf{
abla} imes \sigma^{-1} \mathbf{j}_s$$

PDEs identical  ${f E}$  and  ${f H}$  through exchanging  $\mu$  and  $\sigma$ 

component perpendicular to modelling frame (E/H polarization)

$$\nabla \times a \nabla \times = - \nabla \cdot a \nabla$$

#### Finite element discretization

weak formulation (for E)

$$\int_{\Omega} \mu^{-1} oldsymbol{
abla} v_i \cdot oldsymbol{
abla} v_j \mathrm{d}\Omega + \imath \omega \int_{\Omega} \sigma v_i v_j \mathrm{d}\Omega = \int_{\Omega} v_i f \mathrm{d}\Omega$$

• stiffness = second derivative  $\nabla \cdot \mathbf{v}_i$ , expressed by 2 gradients

$$\mathbf{A}_{i,j} = \int_{\Omega} \mu^{-1} \mathbf{
abla} v_i \cdot \mathbf{
abla} v_j \mathrm{d}\Omega$$

#### Finite element discretization

weak formulation (for E)

$$\int_{\Omega} \mu^{-1} oldsymbol{
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ullet mass matrix resembles functions  ${f v}_i$ 

$$\mathbf{M}_{i,j} = \int_{\Omega} \sigma v_i \cdot v_j \mathrm{d}\Omega$$

#### Complex or real-valued?

Either discretize the complex system

$$(\mathbf{A} + \imath \omega \mathbf{M})(\mathbf{u}_r + \imath \mathbf{u}_i) = \mathbf{b}_r + \imath \mathbf{b}_i$$

by complex shape functions OR transfer into real

$$\mathbf{A}\mathbf{u}_r + \imath \mathbf{A}\mathbf{u}_i + \imath \omega \mathbf{M}\mathbf{u}_i - \omega \mathbf{M}\mathbf{u}_i = \mathbf{b}_r + \imath \mathbf{b}_i$$

$$egin{pmatrix} \mathbf{A} & -\omega \mathbf{M} \ \omega \mathbf{M} & \mathbf{A} \end{pmatrix} egin{pmatrix} \mathbf{u}_r \ \mathbf{u}_i \end{pmatrix} = egin{pmatrix} \mathbf{b}_r \ \mathbf{b}_i \end{pmatrix}$$

### Secondary field approach

Consider the field to consist of a primary (background) and an secondary (anomalous) field  $F=F_0+F_a$  (or  $F_p+F_s$ )

solution for  $F_0$  known, e.g. analytically or 1D (semi-analytically)

- $\Rightarrow$  form equations for  $F_a$ , because
- ullet  $F_a$  is weaker or smoother (e.g.  $F_0 \propto 1/r^n$  at sources)
- boundary conditions easier to set (e.g. homogeneous Dirichlet)

#### **Example DC resistivity**

$$-oldsymbol{
abla} \cdot (\sigma oldsymbol{
abla} u) = oldsymbol{
abla} \cdot j_s = I\delta(\mathbf{r} - \mathbf{r}_s)$$

Problem: point source leads to infinite potential

$$u(\mathbf{r}) = rac{I}{2\pi\sigma} rac{1}{|\mathbf{r} - \mathbf{r}_s|}$$

Approach:  $u=u_p(\sigma_0)+u_s(\sigma-\sigma_0)$ :

$$-oldsymbol{
abla} \cdot (\sigma oldsymbol{
abla} u_s) = oldsymbol{
abla} \cdot ((\sigma - \sigma_0) oldsymbol{
abla} u_p)$$

### **Example DC resistivity**

$$-oldsymbol{
abla} \cdot (\sigma oldsymbol{
abla} u_s) = oldsymbol{
abla} \cdot ((\sigma - \sigma_0) oldsymbol{
abla} u_p)$$

discrete form using unit conductivity  $\sigma_1=1$ S/m

$$\mathbf{A}^{\sigma}\mathbf{u}_{s} = \mathbf{A}^{\delta\sigma}\mathbf{u}_{p} = \mathbf{A}^{\sigma}\mathbf{u}_{p} - \sigma_{0}\mathbf{A}^{1}\mathbf{u}_{p}$$

### Secondary field Helmholtz equation

The equation  $-\nabla^2 F - k^2 F = 0$  is solved by the primary field for  $k_0$ :

 $-oldsymbol{
abla}^2 F_0 - k_0^2 F_0 = 0$  and the total field for  $k_0 + \delta k$ :

$$-oldsymbol{
abla}^2(F_0+F_a)-(k_0^2+\delta k^2)(F_0+F_a)=0$$

$$-oldsymbol{
abla}^2F_a-k^2F_a=\delta k^2F_0$$

(i) Note

Same operator, source terms at anomalies, weighted by the primary field.

### Secondary field for EM

Maxwells equations  $k^2 = -\imath \omega \mu \sigma$ 

$$-\boldsymbol{\nabla}^2\mathbf{E}_0+\imath\omega\mu\sigma\mathbf{E}_0=0$$

leads to

$$-\mathbf{
abla}^2\mathbf{E}_a + \imath\omega\mu\sigma\mathbf{E}_a = -\imath\omega\mu\delta\sigma\mathbf{E}_0$$

(i) Note

Source terms only arise at anomalous conductivities and increase with primary field

### Secondary field for EM

$$-\mathbf{
abla}^2\mathbf{E}_a + \imath\omega\mu\sigma\mathbf{E}_a = -\imath\omega\mu\delta\sigma\mathbf{E}_0$$

leads to the discretized form ( ${f A}$ -stiffness,  ${f M}$ -mass)

$$\mathbf{A}\mathbf{E}_a + \imath \omega \mathbf{M}_{\sigma} E_a = -\imath \omega \mathbf{M}_{\delta \sigma} \mathbf{E}_0$$

```
1 A = stiffnessMatrix1DFE(x=z)
2 M = massMatrix1DFE(x=z, a=w*mu*sigma)
3 dM = massMatrix1DFE(x=z, a=w*mu*(sigma-sigma0))
4 u = uAna + solve(A+M*w*1j, dM@uAna * w*1j)
```

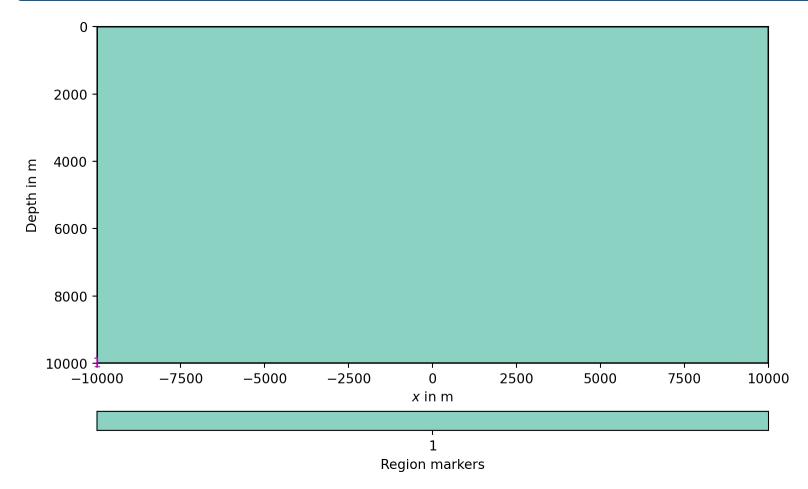
# 2D problems

Make use of pyGIMLi

See documentation on pyGIMLi.org

#### The meshtools module

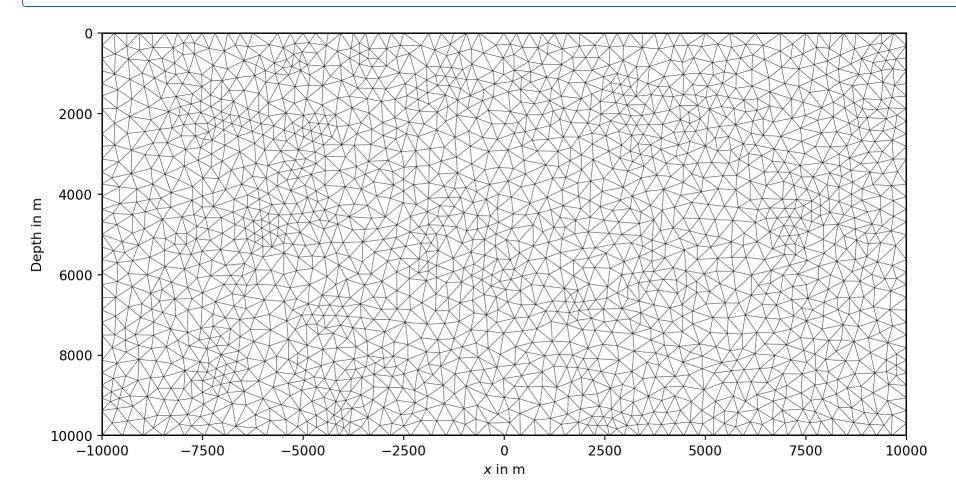
```
import pygimli as pg
import pygimli.meshtools as mt
world = mt.createWorld(start=[-10000, -10000], end=[10000, 0])
pg.show(world)
```



#### The meshtools module

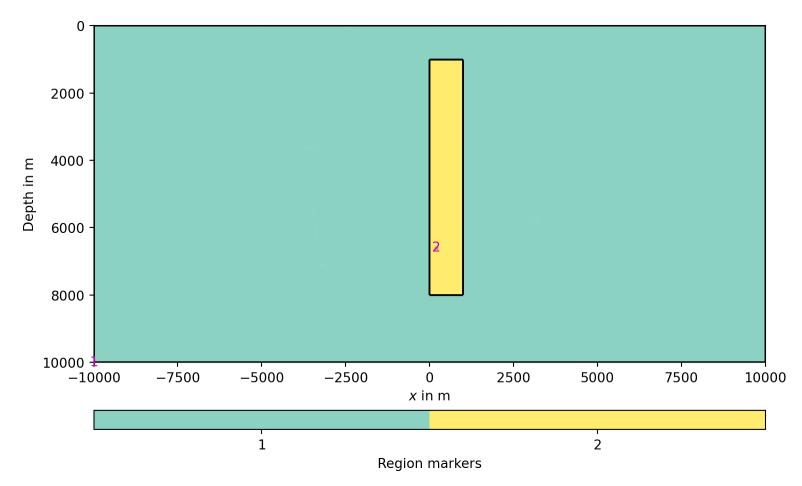
```
1 mesh = mt.createMesh(world, quality=34, area=1e5)
```

2 pg.show(mesh)



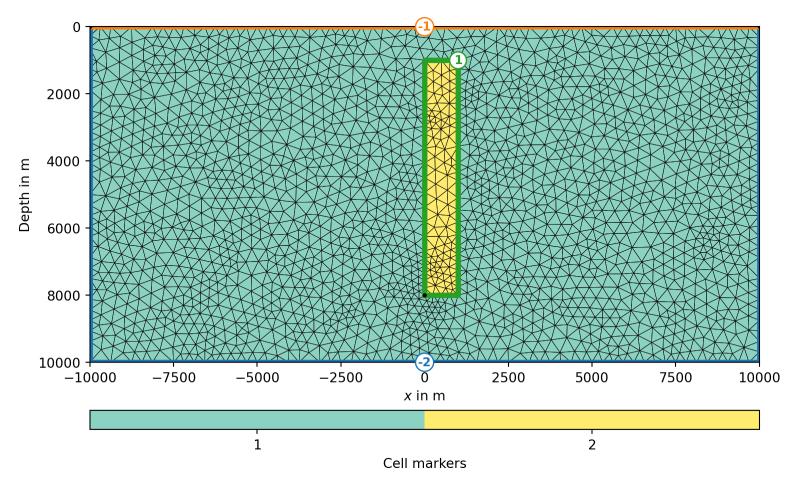
### **Creating a 2D geometry**

```
1 anomaly = mt.createRectangle(start=[0, -8000], end=[1000, -1000], marker=2)
2 pg.show(world+anomaly)
```



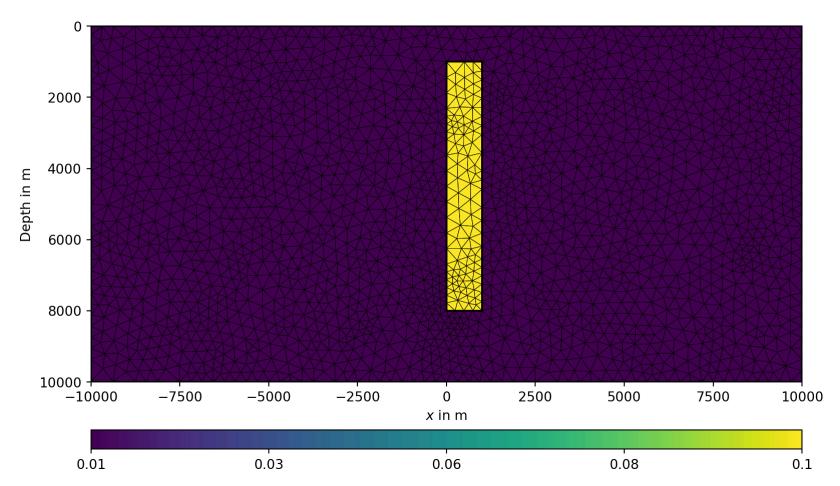
# Creating a 2D mesh

```
1 mesh = mt.createMesh(world+anomaly, quality=34, smooth=True, area=1e5)
2 pg.show(mesh, markers=True, showMesh=True);
```



### Creating a 2D conductivity model

```
1 sigma0 = 1 / 100 # 100 Ohmm
2 sigma = mesh.populate("sigma", {1: sigma0, 2: sigma0*10})
3 pg.show(mesh, "sigma", showMesh=True);
```



#### The solver module

```
import pygimli.solver as ps
mesh["my"] = 4 * np.pi * 1e-7

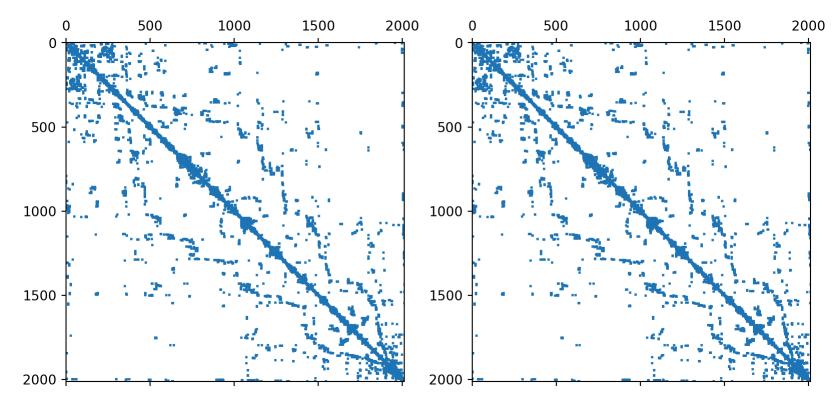
A = ps.createStiffnessMatrix(mesh, a=1/mesh["my"])

M = ps.createMassMatrix(mesh, mesh["sigma"])

fig, ax = plt.subplots(ncols=2)

ax[0].spy(pg.utils.toCSR(A), markersize=1)

ax[1].spy(pg.utils.toCSR(M).todense(), markersize=1)
```



#### The complex problem matrix

$$\mathbf{B} = egin{pmatrix} \mathbf{A} & -\omega \mathbf{M} \ \omega \mathbf{M} & \mathbf{A} \end{pmatrix}$$

#### **Sparse matrices**

Up to now: regular (dense) array: save every element including 0

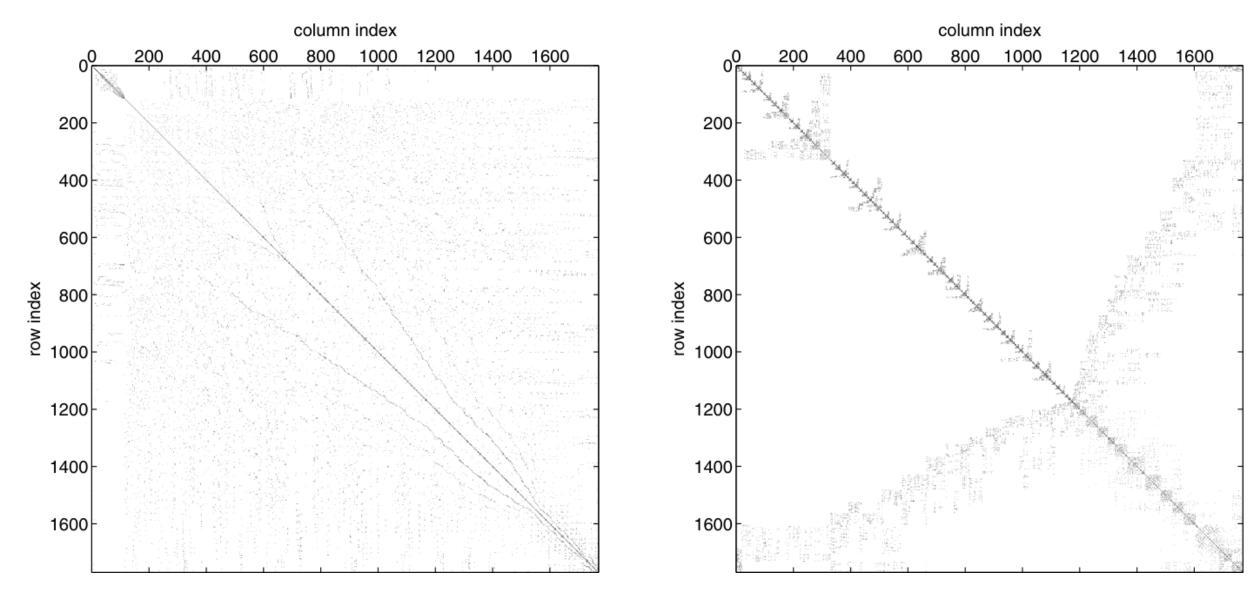
Save only non-zero components (e.g. using scipy.sparse)

- COO coordinate format
- CSC/CRS compressed sparse column/row
- BSR block sparse row format, ...

#### Solve systems of equations

- Gauss elimination (expensive and dense)
- Cholesky (or ILU) decomposition
- Iterative solvers (conjugate gradients)
- incomplete factorizations or factorization of submatrices

## Reordering



original (left) & reordered (right) matrix (Rücker et al. 2006)