Moving Beyond Linearity

The truth is never linear!
Or almost never!

But often the linearity assumption is good enough.

When its not . . .

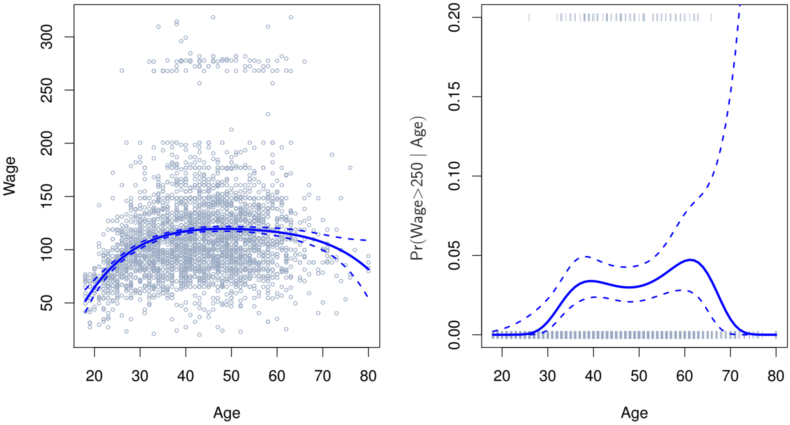
- polynomials,
- step functions,
- splines,
- local regression, and
- generalized additive models

offer a lot of flexibility, without losing the ease and interpretability of linear models.

Polynomial Regression

$$y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \beta_3 x_i^3 + \ldots + \beta_d x_i^d + \epsilon_i$$

Degree−4 Polynomial



Details

- Create new variables $X_1 = X$, $X_2 = X^2$, etc and then treat as multiple linear regression.
- Not really interested in the coefficients; more interested in the fitted function values at any value x_0:

$$\hat{f}(x_0) = \hat{\beta}_0 + \hat{\beta}_1 x_0 + \hat{\beta}_2 x_0^2 + \hat{\beta}_3 x_0^3 + \hat{\beta}_4 x_0^4.$$

- Since $\hat{f}(x_0)$ is a linear function of the $\hat{\beta}_\ell$, can get a simple expression for *pointwise-variances* $\mathrm{Var}[\hat{f}(x_0)]$ at any value x_0. In the figure we have computed the fit and pointwise standard errors on a grid of values for x_0. We show $\hat{f}(x_0) \pm 2 \cdot \mathrm{se}[\hat{f}(x_0)]$.
- We either fix the degree d at some reasonably low value, else use cross-validation to choose d.

Details continued

- Logistic regression follows naturally. For example, in figure we model

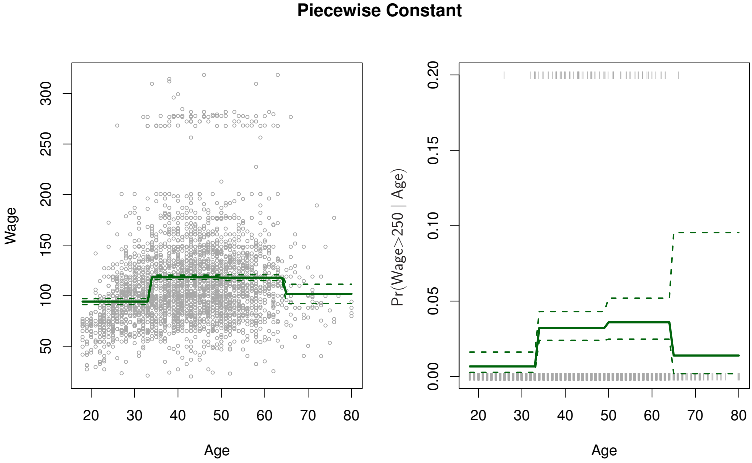
$$\Pr(y_i > 250|x_i) = \frac{\exp(\beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \ldots + \beta_d x_i^d)}{1 + \exp(\beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \ldots + \beta_d x_i^d)}.$$

- To get confidence intervals, compute upper and lower bounds on *on the logit scale*, and then invert to get on probability scale.
- Can do separately on several variables—just stack the variables into one matrix, and separate out the pieces afterwards (see GAMs later).
- Caveat: polynomials have notorious tail behavior — very bad for extrapolation.

Step Functions

Another way of creating transformations of a variable — cut the variable into distinct regions.

$$C_1(X) = I(X < 35), \quad C_2(X) = I(35 \leq X < 50), \ldots, C_3(X) = I(X \geq 65)$$



Step functions continued

- Easy to work with. Creates a series of dummy variables representing each group.
- Useful way of creating interactions that are easy to interpret. For example, interaction effect of `Year` and `Age`:

$$I(\texttt{Year} < 2005) \cdot \texttt{Age}, \quad I(\texttt{Year} \geq 2005) \cdot \texttt{Age}$$

  would allow for different linear functions in each age category.

- Choice of cutpoints or *knots* can be problematic. For creating nonlinearities, smoother alternatives such as *splines* are available.

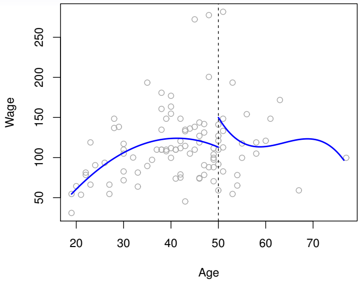
Piecewise Polynomials

- Instead of a single polynomial in X over its whole domain, we can rather use different polynomials in regions defined by knots. E.g. (see figure)

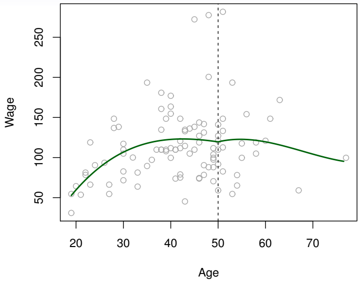
$$y_i = \begin{cases} \beta_{01} + \beta_{11} x_i + \beta_{21} x_i^2 + \beta_{31} x_i^3 + \epsilon_i & \text{if } x_i < c; \\ \beta_{02} + \beta_{12} x_i + \beta_{22} x_i^2 + \beta_{32} x_i^3 + \epsilon_i & \text{if } x_i \geq c. \end{cases}$$

- Better to add constraints to the polynomials, e.g. continuity.
- *Splines* have the "maximum" amount of continuity.

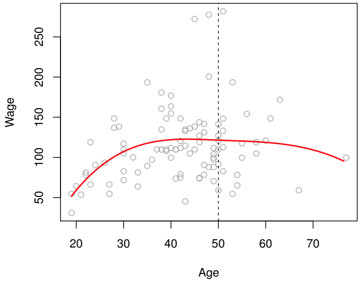
Piecewise Cubic



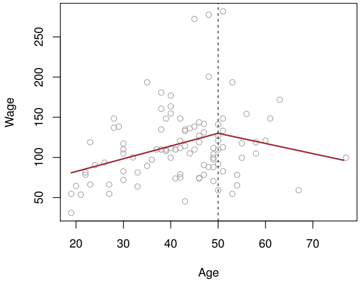
Continuous Piecewise Cubic



Cubic Spline



Linear Spline



Linear Splines

A linear spline with knots at ξ_k, $k = 1, \ldots, K$ is a piecewise linear polynomial continuous at each knot.

We can represent this model as

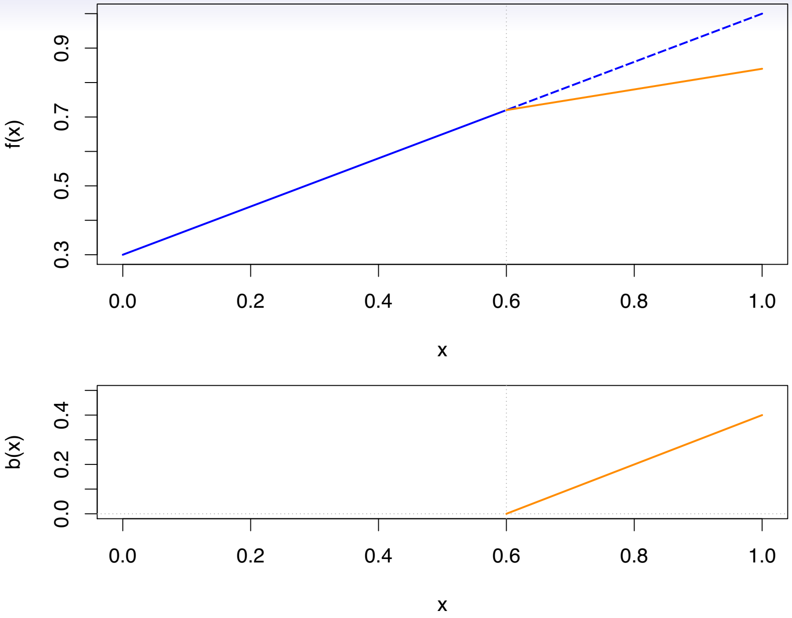
$$y_i = \beta_0 + \beta_1 b_1(x_i) + \beta_2 b_2(x_i) + \cdots + \beta_{K+3} b_{K+3}(x_i) + \epsilon_i,$$

where the b_k are *basis functions*.

$$\begin{aligned} b_1(x_i) &= x_i \\ b_{k+1}(x_i) &= (x_i - \xi_k)_+, \quad k = 1, \ldots, K \end{aligned}$$

Here the $()_+$ means *positive part*; i.e.

$$(x_i - \xi_k)_+ = \begin{cases} x_i - \xi_k & \text{if } x_i > \xi_k \\ 0 & \text{otherwise} \end{cases}$$



f(x)
0.3
0.5
0.7
0.9
0.0
0.2
0.4
0.6
0.8
1.0
x
b(x)
0.0
0.2
0.4
0.0
0.2
0.4
0.6
0.8
1.0
x

Cubic Splines

A cubic spline with knots at ξ_k, $k = 1, \ldots, K$ is a piecewise cubic polynomial with continuous derivatives up to order 2 at each knot.

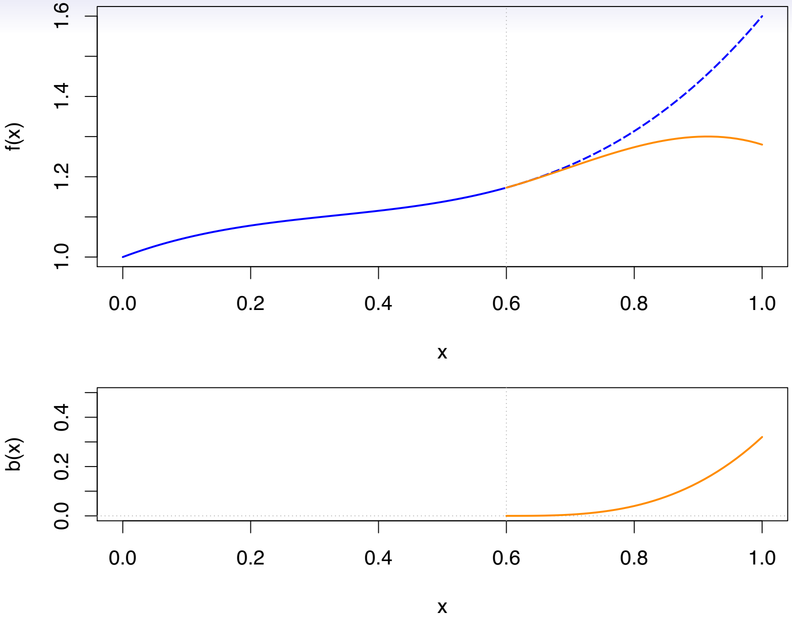
Again we can represent this model with truncated power basis functions

$$y_i = \beta_0 + \beta_1 b_1(x_i) + \beta_2 b_2(x_i) + \cdots + \beta_{K+3} b_{K+3}(x_i) + \epsilon_i,$$

$$\begin{aligned}
b_1(x_i) &= x_i \\
b_2(x_i) &= x_i^2 \\
b_3(x_i) &= x_i^3 \\
b_{k+3}(x_i) &= (x_i - \xi_k)_+^3, \quad k = 1, \ldots, K
\end{aligned}$$

where

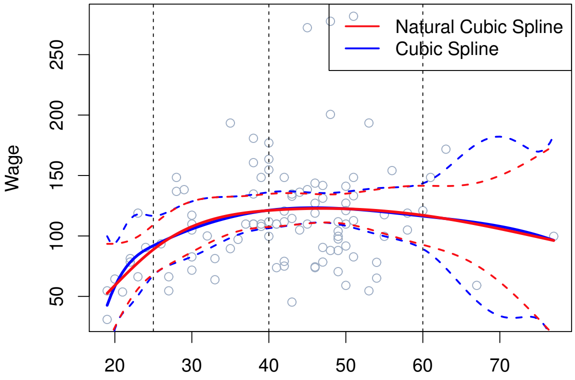
$$(x_i - \xi_k)_+^3 = \begin{cases} (x_i - \xi_k)^3 & \text{if } x_i > \xi_k \\ 0 & \text{otherwise} \end{cases}$$



f(x)
1.0
1.2
1.4
1.6
0.0
0.2
0.4
0.6
0.8
1.0
x
b(x)
0.0
0.2
0.4
0.0
0.2
0.4
0.6
0.8
1.0
x

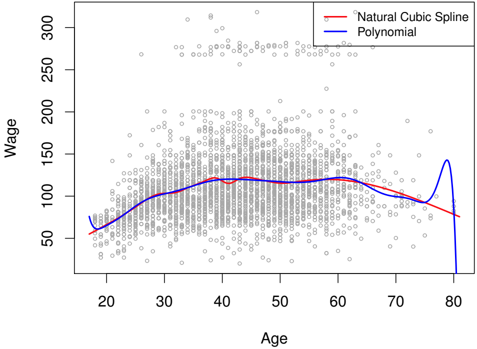
Natural Cubic Splines

A natural cubic spline extrapolates linearly beyond the boundary knots. This adds $4 = 2 \times 2$ extra constraints, and allows us to put more internal knots for the same degrees of freedom as a regular cubic spline.



Knot placement

- One strategy is to decide K, the number of knots, and then place them at appropriate quantiles of the observed X.
- A cubic spline with K knots has $K + 4$ parameters or degrees of freedom.
- A natural spline with K knots has K degrees of freedom.



Comparison of a degree-14 polynomial and a natural cubic spline, each with 15df.

Smoothing Splines

This section is a little bit mathematical 

Consider this criterion for fitting a smooth function $g(x)$ to some data:

$$\underset{g \in \mathcal{S}}{\text{minimize}} \sum_{i=1}^{n} (y_i - g(x_i))^2 + \lambda \int g''(t)^2 dt$$

- The first term is RSS, and tries to make $g(x)$ match the data at each x_i.
- The second term is a *roughness penalty* and controls how wiggly $g(x)$ is. It is modulated by the *tuning parameter* $\lambda \geq 0$.
  - The smaller λ, the more wiggly the function, eventually interpolating y_i when $\lambda = 0$.
  - As $\lambda \to \infty$, the function $g(x)$ becomes linear.

Smoothing Splines continued

The solution is a natural cubic spline, with a knot at every unique value of x_i. The roughness penalty still controls the roughness via λ.

Some details

- Smoothing splines avoid the knot-selection issue, leaving a single λ to be chosen.

- The vector of n fitted values can be written as $\hat{\mathbf{g}}_\lambda = \mathbf{S}_\lambda \mathbf{y}$, where $\mathbf{S}_\lambda$ is a $n \times n$ matrix (determined by the x_i and λ).
- The *effective degrees of freedom* are given by

$$df_\lambda = \sum_{i=1}^{n} \{\mathbf{S}_\lambda\}_{ii}.$$

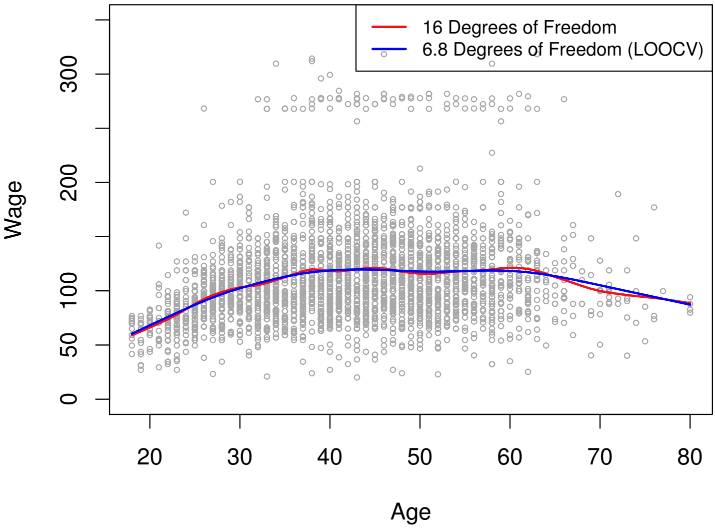
Smoothing Splines continued — choosing λ

- We can specify *df* rather than λ!

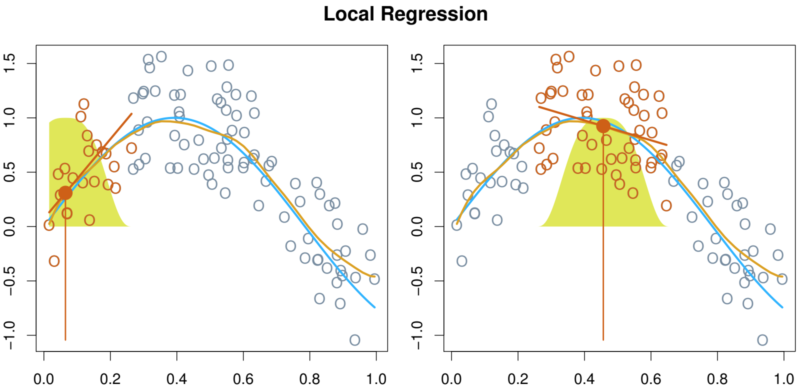
- The leave-one-out (LOO) cross-validated error is given by

$$\mathrm{RSS}_{cv}(\lambda) = \sum_{i=1}^{n} (y_i - \hat{g}_\lambda^{(-i)}(x_i))^2 = \sum_{i=1}^{n} \left[\frac{y_i - \hat{g}_\lambda(x_i)}{1 - \{\mathbf{S}_\lambda\}_{ii}} \right]^2 .$$

Smoothing Spline



Local Regression

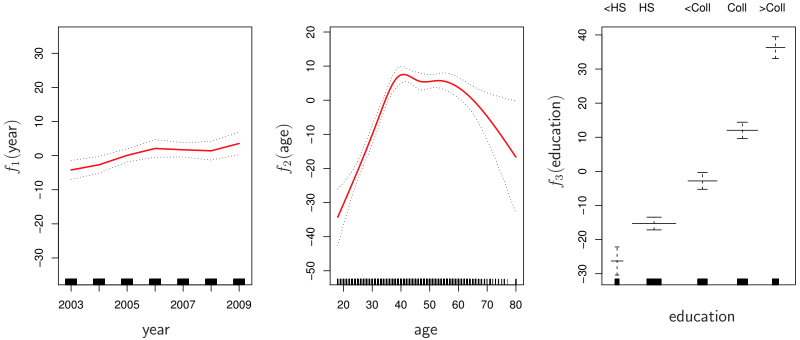


With a sliding weight function, we fit separate linear fits over the range of X by weighted least squares.
See text for more details, and `loess()` function in R.

Generalized Additive Models

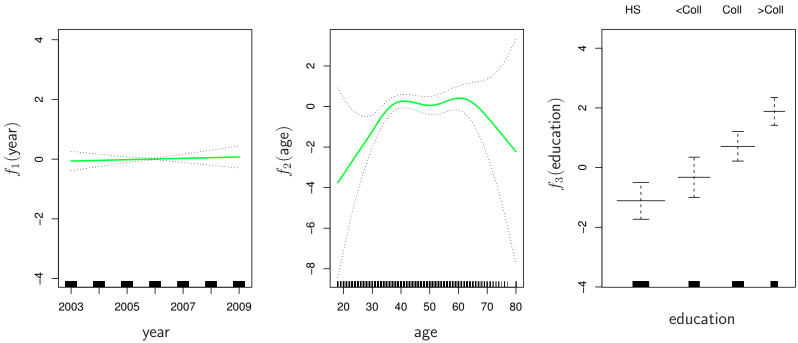
Allows for flexible nonlinearities in several variables, but retains the additive structure of linear models.

$$y_i = \beta_0 + f_1(x_{i1}) + f_2(x_{i2}) + \cdots + f_p(x_{ip}) + \epsilon_i.$$



GAMs for classification

$$\log\left(\frac{p(X)}{1-p(X)}\right) = \beta_0 + f_1(X_1) + f_2(X_2) + \cdots + f_p(X_p).$$



$\texttt{gam(I(wage} > \texttt{250)} \sim \texttt{year} + \texttt{s(age, df} = \texttt{5)} + \texttt{education, family} = \texttt{binomial)}$