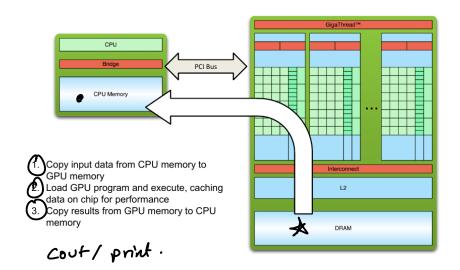


Data Migration (cont.)

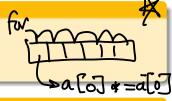


Squaring an Array

Reynel

C Code

```
void squareCPU(float *a, int size) {
   for (int x = 0; x < size; x++)
        a[x] *= a[x];
```



OpenCL Kernel Code

```
__kernel void squareCPU(__global float *a) {
    int x = get_global_id(0);
    a[x] *= a[x];
}
```

CUDA Kerpel Code

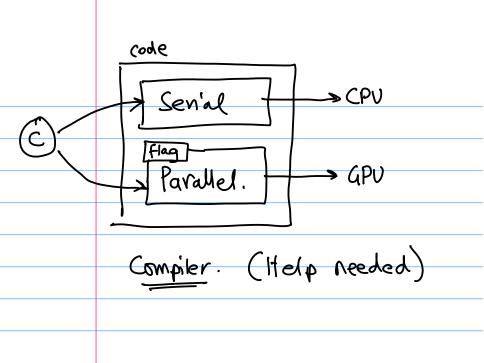
_global void hello(float *a) { int x = threadIdx.x;

a[x] *= a[x];



x = threadid > Object . member;

4 D > 4 A > 4 B > 4



Building up towards Hello World

```
Code

int main()
{
    printf("hello world!\n");
    return 0;
}

GPU
```

Compilation

- nvcc hello_world.cu
- ./a.out

```
global__ void myKernel(void)
 int main()
    myKernel <<<1,1>>>();
80% < <</1 /1 >>>
    printf("hello world!\n");
    return 0:
```

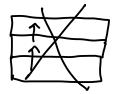
```
tenchion (all
```

```
// indicates function runs or parallel
// device and is called from
// host code
```

fin name ();

```
// like function call, but
// with more information
// 1st digit number of blocks
// 2nd digit threads per block
```

- nvcc will separate source code into host and device components
 - Device functions processed by NVIDIA compiler
 - · Host functions processed by standard host compiler



}

Building up towards Hello World: Inserting GPU Code







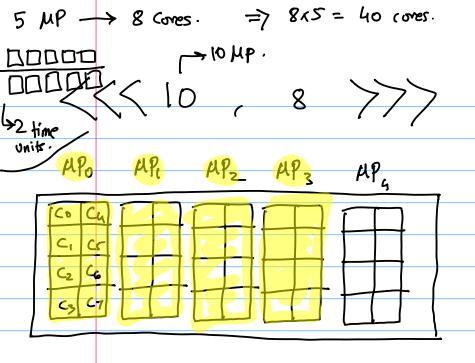
```
global__ void myKernel(void)
int main()
  printf("hello world!\n");
  return 0:
}
```

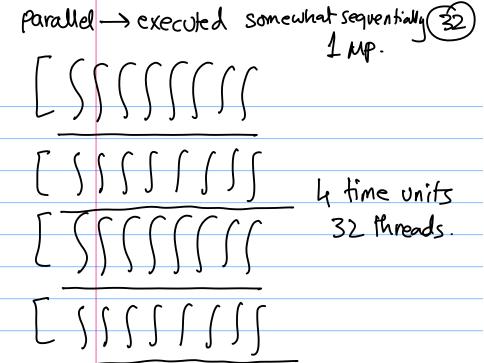
```
// indicates function runs on
// device and is called from
// host code
```

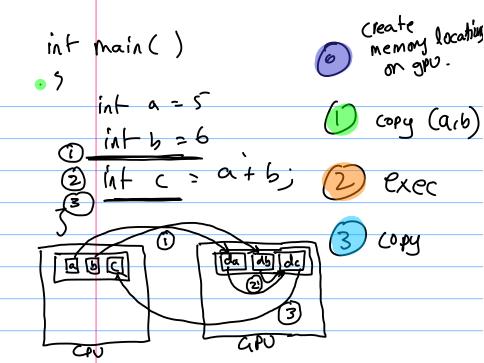
```
// like function call, but
// with more information
// 1st digit number of blocks
// 2nd digit threads per block
```

- nvcc will separate source code into host and device components
 - Device functions processed by NVIDIA compiler
 - · Host functions processed by standard host compiler

Developer H. Ware. 1 thread. 1 block +







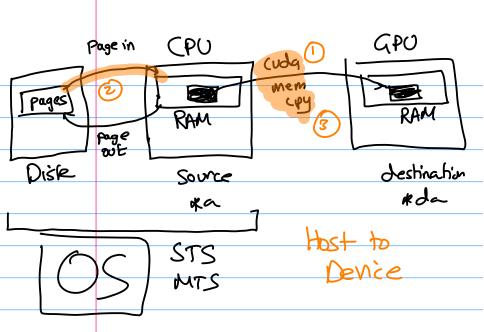
```
/* a, b, c are pointers to memory location on the device */
                                                        C.PU
 _global__ void add(int *a, int *b, int *c)
  *c = *a + *b;
                    int kda = & a;
int main()
  int a=2, b=7, c, *da, *db, *dc;
  cudaMalloc((void **)&da, sizeof(int)); // allocate
  cudaMalloc((void **)&db, sizeof(int)); // on device
  cudaMalloc((void **)&dc, sizeof(int));
  // Copying in blocking mode source
  cudaMemcpy(da, &a sizeof(int), cudaMemcpyHostToDevice);
  add < <<1,1>>> (da, db, dc);
 cudaMemcpy(&c, dc, sizeof(int), cudaMemcpyDeviceToHost);
  printf("a + b = %d\n", c);
                                            *C=*a++b
  cudaFree(da); cudaFree(db); cudaFree(dc);
  return 0:
}
```

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```
/* a, b, c are pointers to memory location on the device */
__global__ void add(int *a, int *b, int *c)
{ *c = *a + *b; }
int main()
 int a=2, b=7, c, *da, *db, *dc;
   cudaMalloc((void **)&da, sizeof(int)); // allocate
   cudaMalloc((void **)&db, sizeof(int)); // on device
   cudaMalloc((void **)&dc, sizeof(int));
   // Copying in blocking-mode
   cudaMemcpy(da, &a, sizeof(int), cudaMemcpyHostToDevice);
   cudaMemcpy(da, &a, sizeof(int), cudaMemcpyHostToDevice);
   add < < 1,1>>> (da, db, dc);
   cudaMemcpy(&c, dc, sizeof(int), cudaMemcpyDeviceToHost);
  printf(a + b = dn, c):
   cudaFree(da); cudaFree(db); cudaFree(dc);
  return 0:
}
```

```
/* a, b, c are pointers to memory location on the device */
 global__ void add(int *a, int *b, int *c)
                                             c[x]=a[x]+b[x
  *c = *a + *b:
int main()
  int a=2, b=7, c, *da, *db, *dc;
   cudaMalloc((void **)&da, sizeof(int)); // allocate
   cudaMalloc((void **)&db, sizeof(int)); // on device
   cudaMalloc((void **)&dc, sizeof(int));
   // Copying in blocking-mode
   cudaMemcpy(da, &a, sizeof(int), cudaMemcpyHostToDevice);
   cudaMemcpy(da, &a, sizeof(int), cudaMemcpyHostToDevice);
   add <<<1,1>>> (da, db, dc);
   cudaMemcpy(&c, dc, sizeof(int), cudaMemcpyDeviceToHost);
   printf("a + b = d\n, c);
   cudaFree(da); cudaFree(db); cudaFree(dc);
   return 0:
}
```

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```
^{\prime *} a, b, c are pointers to memory location on the device */
 global void add int *a, int *b, int *c)
int main()
   int a=2, b=7, c, *da, *db
   cudaMalloc((void **)&da, sizeof(int)); // allocate
   cudaMalloc((void **)&db, sizeof(int)); // on device
   cudaMalloc((void **)&dc, stzeof(int));
   // Copying in blocking-mode
   cudaMemcpy(da, &a, sizeof(int), cudaMemcpyHostToDevice);
   cudaMemcpy(da, /&a, &ize f(int), cudaMemcpyHostToDevice);
  add <<1,1>>> (da, db, dc);
   cudaMemcpy(&c, dc, sizeof(int), cudaMemcpyDeviceToHost);
   printf("a + b = %d\n", c);
   cudaFree(da); cudaFree(db); cudaFree(dc);
   return 0:
```

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Running in Parallel

- so far; pointing parameters to GPU, and running single thread on GPU.
- Time to look at how to run things in parallel.

Code Change

```
// add <<<1. 1>>> (da. db. dc):
   add < < N, 1>>> (da, db, dc);
```

Instead of running add() once, execute it N times in parallel

Changes in Kernel Code



```
__global__ void add(int *a, int *b, int *c)
    c[blockIdx.x] = a[blockIdx.x] + b[blockIdx.x];
```

```
int main()
 int *a, *b, *c, *da, *db, *dc, N=5, i;
```

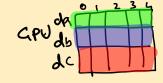
```
(int*)malloc(sizeof(int)*N); // allocate host mem
b = (int*)malloc(sizeof(int)*N); // and assign random
```

c = (int*)malloc(sizeof(int)*N); // memory

cudaMalloc((void **)&da, sizeof(int)*N);

cudaMalloc((void **)&db, sizeof(int)*N);

cudaMalloc((void **)&dc, sizeof(int)*N);



cudaMemcpy(da, &a, sizeof(int)*N, cudaMemcpyHostToDevice); cudaMemcpy(da, &a, sizeof(int)*N, cudaMemcpyHostToDevice);

add < < N, 1>>> (da, db, dc);

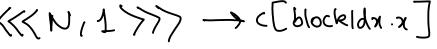
cudaMemcpy(&c, dc, sizeof(int)*N, cudaMemcpyDeviceToHost);

for (i = 0; i < N; i++)

printf("a[\%d] + b[\%d] = \%d\n", i, i, c[i]);

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That was Blocks in Parallel. What about Threads in Parallel



Function Call Change

```
// add<<<1, 1>>>(da, db, dc); // single thread GPU
// add <<< N, 1>>> (da, db, dc); // N blocks on GPU
   add<<<1, N>>>(da, db, dc); // N threads on GPU
```

Changes in Kernel Code

```
__global__ void add(int *a, int *b, int *c)
    c[threadIdx.x] = a[threadIdx.x] + b[threadIdx.x];
```

• Rest of Host code would be the same (x) = (x) + b(x)