Digital Image Processing

Image Enhancement (Spatial Filtering 1)

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Contents

In this session we will look at spatial filtering techniques:

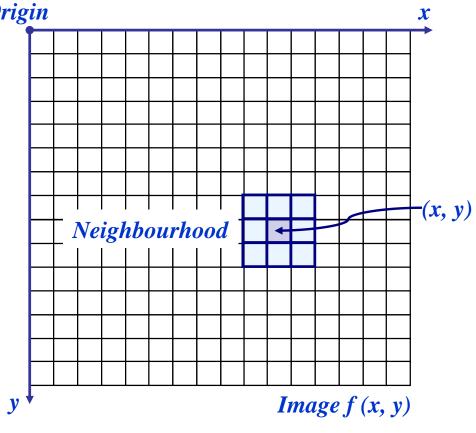
- Neighbourhood operations
- What is spatial filtering?
- Smoothing operations
- What happens at the edges?
- Unsharp Masking

Neighbourhood Operations

Neighbourhood operations simply **operate on a larger neighbourhood** of pixels than point operations *Origin*

Neighbourhoods are mostly a rectangle around a central pixel

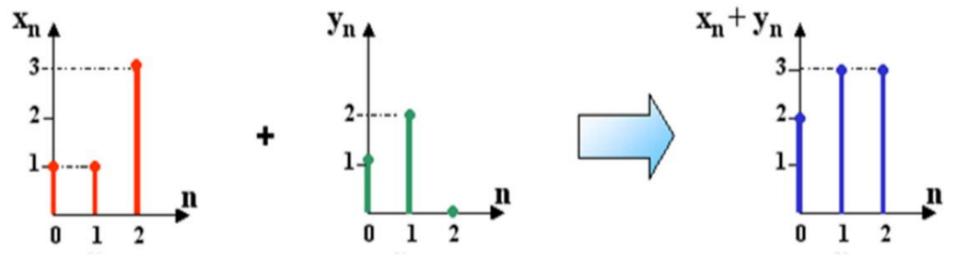
Any size rectangle and any shape filter are possible



Linear vs Non Linear Filters

In mathematics, a linear map or linear function f(x) is a function that satisfies the following two properties:

- Additivity: f(x + y) = f(x) + f(y).
- Homogeneity of degree 1: $f(\alpha x) = \alpha f(x)$ for all α .



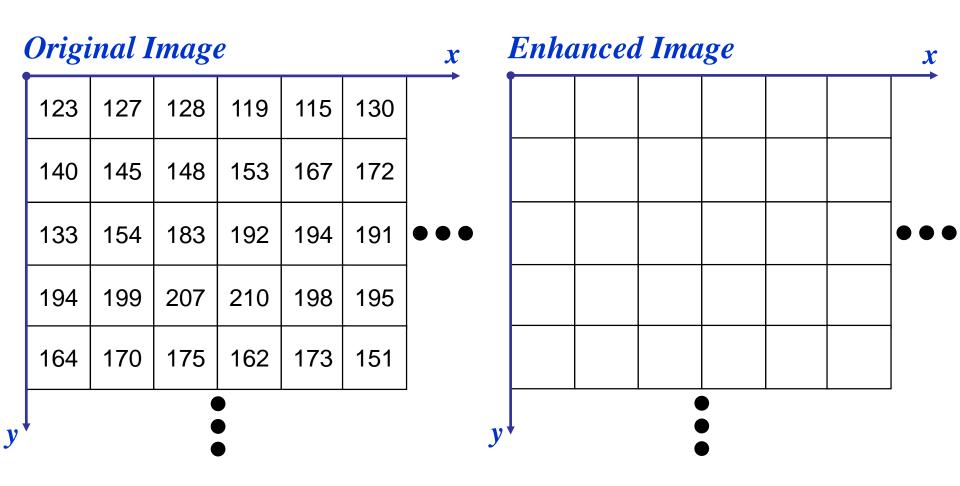
- 1. mean(Xn)+mean(Yn)=mean(Xn+Yn) 8/3=1+5/3 which is OK, so mean is linear function.
- median(Xn)+median(Yn)=median(Xn+Yn),
 1+1=3 which is not true, median is non linear.

Linear vs Non Linear Filters

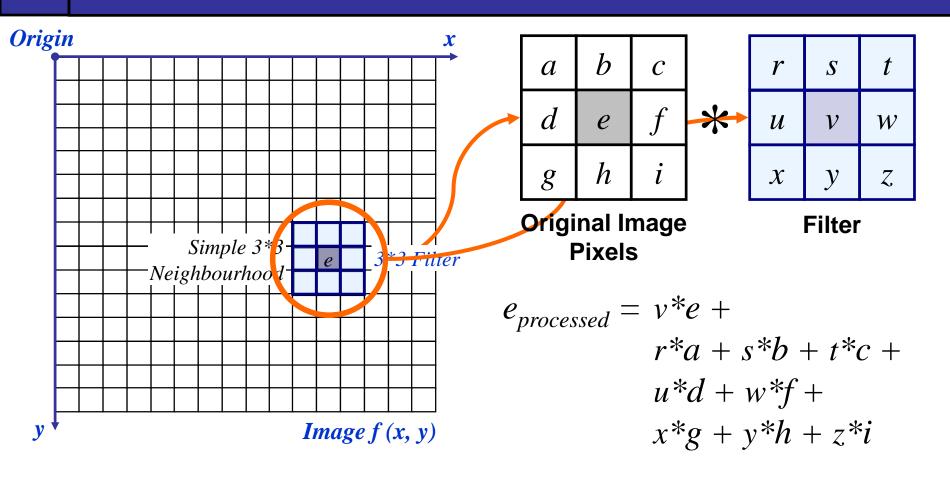
Knowing which type of filter to select depends on the goals and nature of the image data.

- 1. In cases where the input data contains a large amount of noise but the magnitude is low, a linear low-pass filter may suffice.
- 2. Conversely, if an image contains a low amount of noise but with relatively high magnitude, then a non linear (e.g., median filter) may be more appropriate.

Simple Neighbourhood Operations Example

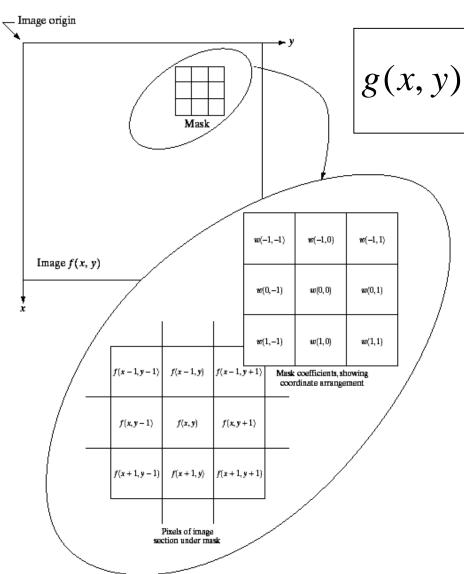


The Spatial Filtering Process



The above is repeated for every pixel in the original image to generate the filtered image

Spatial Filtering: Equation Form



 $g(x, y) = \sum_{s=-at=-b}^{a} \sum_{t=-b}^{b} w(s, t) f(x+s, y+t)$

Filtering can be given in equation form as shown above

Notations are based on the image shown to the left

Smoothing Spatial Filters

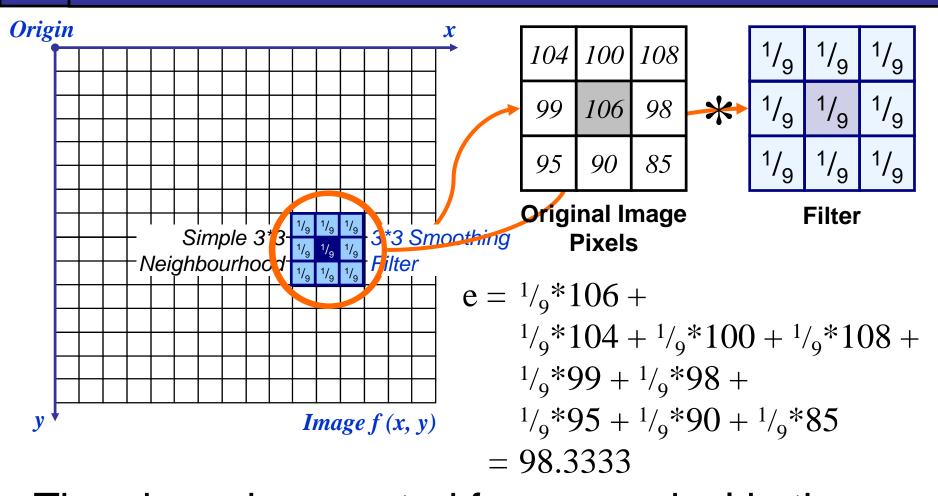
One of the simplest spatial filtering operations we can perform is a smoothing operation

- Simply average all of the pixels in a neighbourhood around a central value
- Especially useful in removing noise from images
- Also useful for highlighting gross detail

1/9	1/9	1/9
1/9	1/9	1/9
1/9	1/9	1/9

Simple averaging filter

Smoothing Spatial Filtering



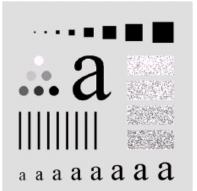
The above is repeated for every pixel in the original image to generate the smoothed image

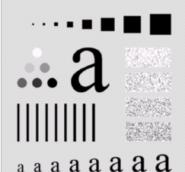
The image at the top left is an original image of size 500*500 pixels

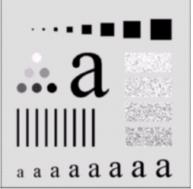
The subsequent images show the image after filtering with an averaging filter of increasing sizes

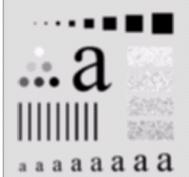
-3, 5, 9, 15 and 35

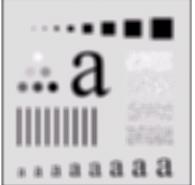
Notice how detail begins to disappear







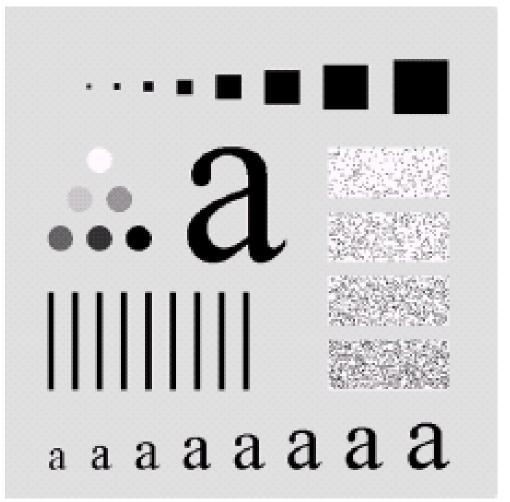






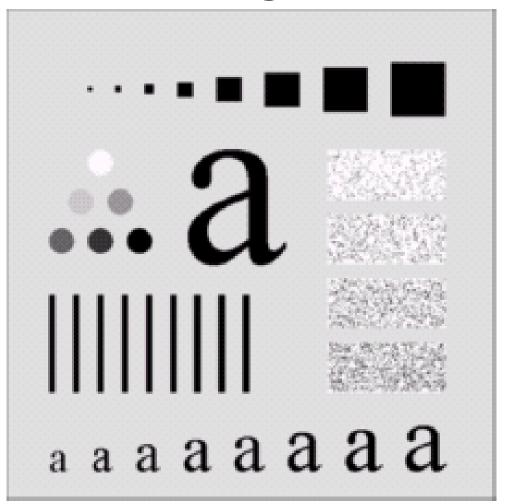


Original Image



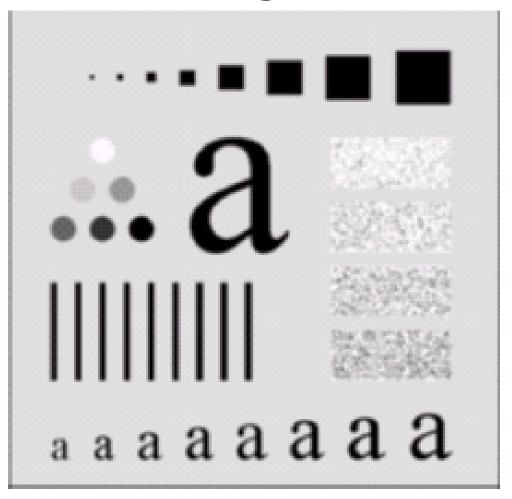


3x3 Average Filter



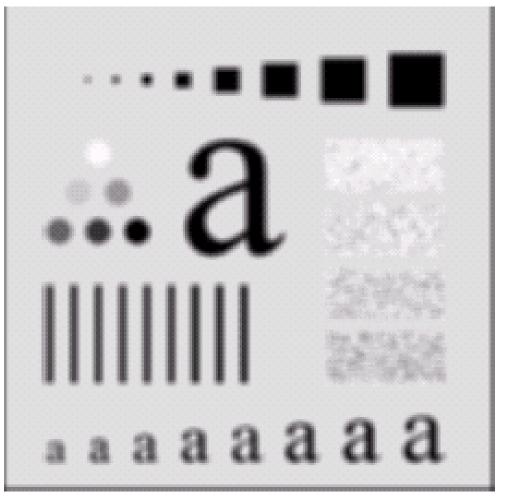


5x5 Average Filter



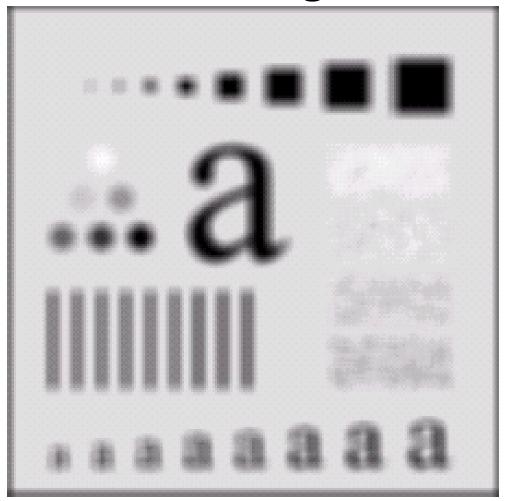


9x9 Average Filter



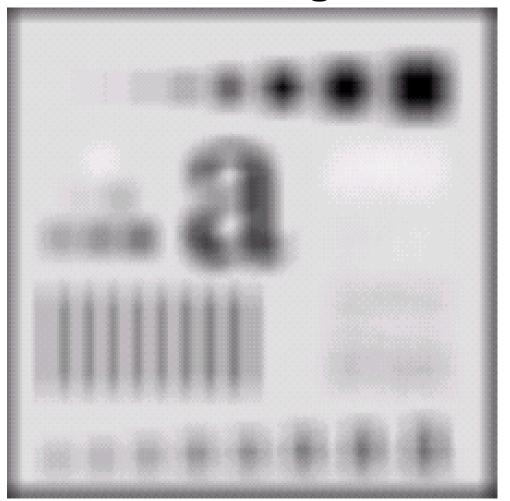


15x15 Average Filter





35x35 Average Filter





Weighted Smoothing Filters

More effective smoothing filters can be generated by allowing different pixels in the neighbourhood different weights in the

averaging function

Pixels closer to the central pixel are more important

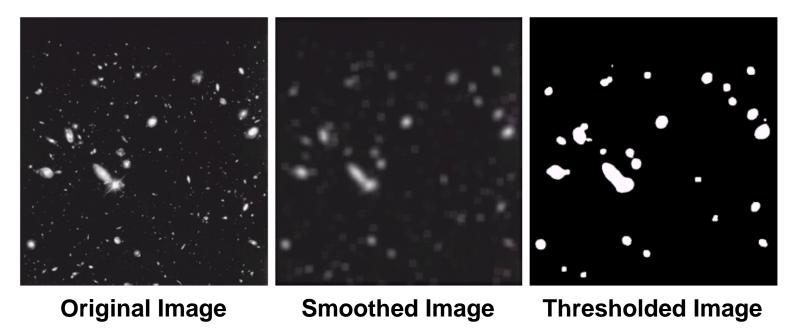
 Often referred to as a weighted averaging

1/16	² / ₁₆	¹ / ₁₆
² / ₁₆	⁴ / ₁₆	² / ₁₆
¹ / ₁₆	² / ₁₆	¹ / ₁₆

Weighted averaging filter

Another Smoothing Example

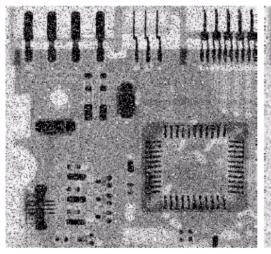
By smoothing the original image we get rid of lots of the finer detail which leaves only the gross features for thresholding

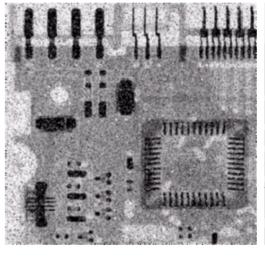


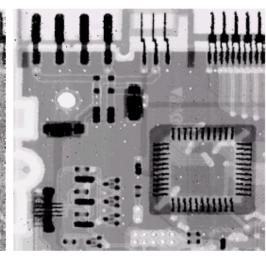
Simple Neighbourhood Operations

Some simple **non linear** neighbourhood operations include:

- Min (dilation): Set the pixel value to the minimum in the neighbourhood
- Max (erosion): Set the pixel value to the maximum in the neighbourhood
- Median: The median value of a set of numbers is the midpoint value in that set (e.g. from the set [1, 7, 15, 18, 24] 15 is the median). Sometimes the median works better than the average







Original Image With Noise

Image After Averaging Filter

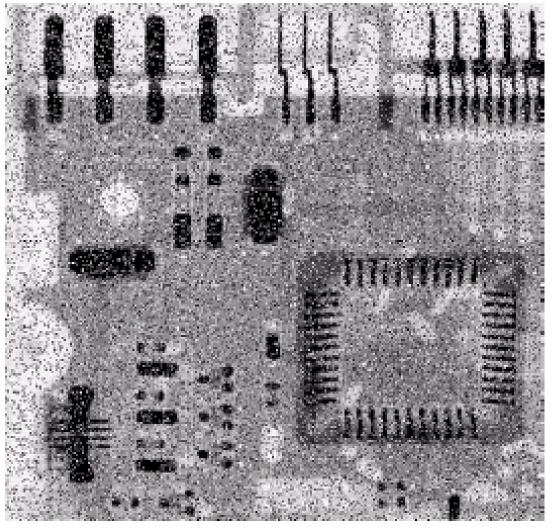
Image After Median Filter

Filtering is often used to remove noise from images

Sometimes a median filter works better than an averaging filter

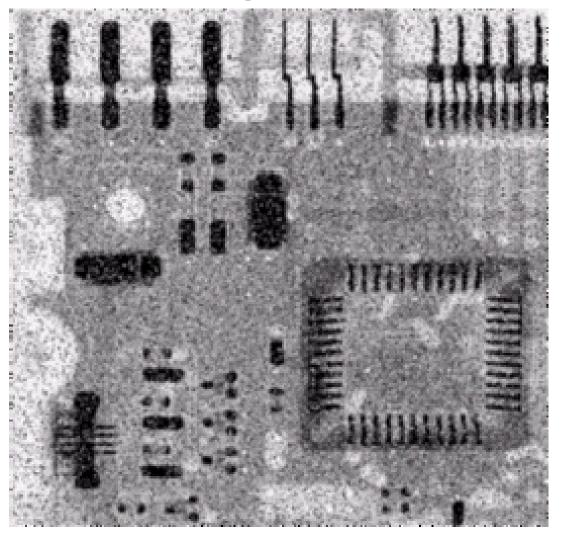


Original Image



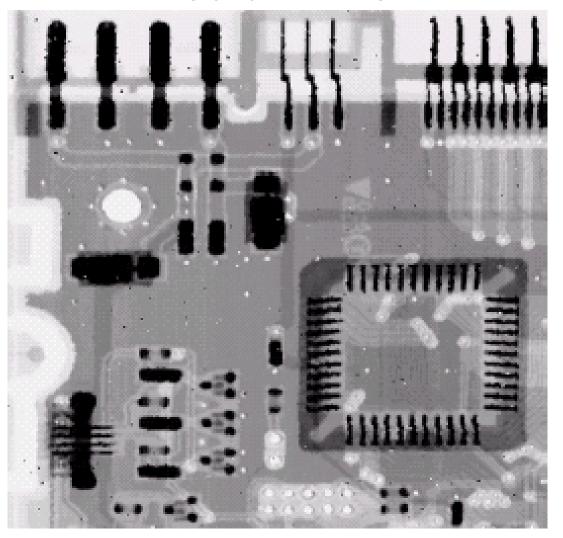


Average Filter





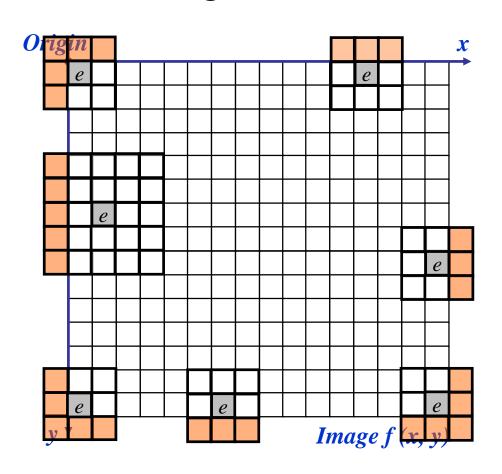
Median Filter





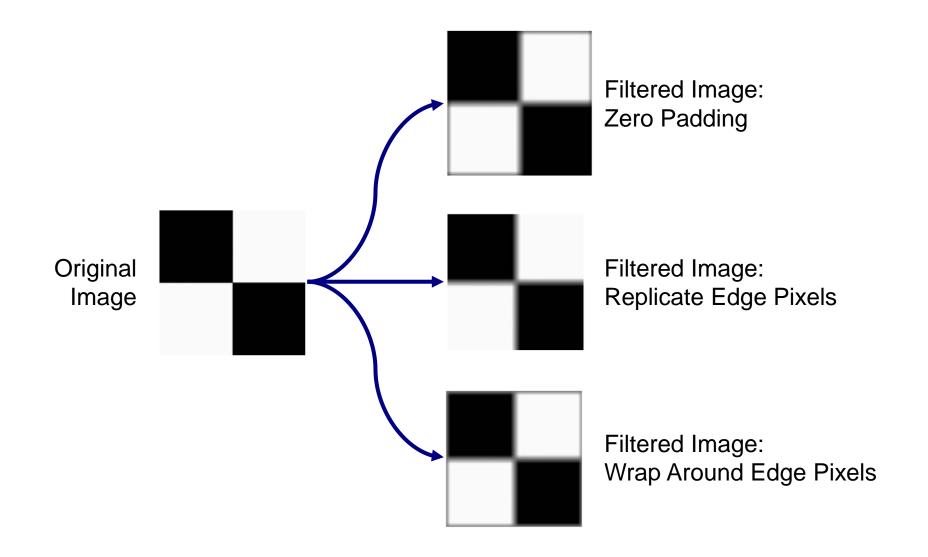
Strange Things Happen At The Edges!

At the edges of an image we are missing pixels to form a neighbourhood

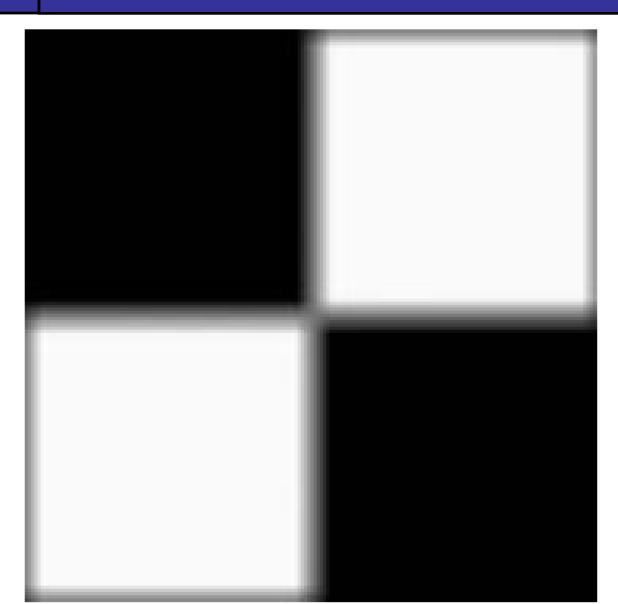


There are a few approaches to dealing with missing edge pixels:

- Omit missing pixels
 - Only works with some filters
 - Can add extra code and slow down processing
- Pad the image
 - Typically with either all white or all black pixels
- Replicate border pixels
- Truncate the image
- Allow pixels wrap around the image
 - Can cause some strange image artefacts

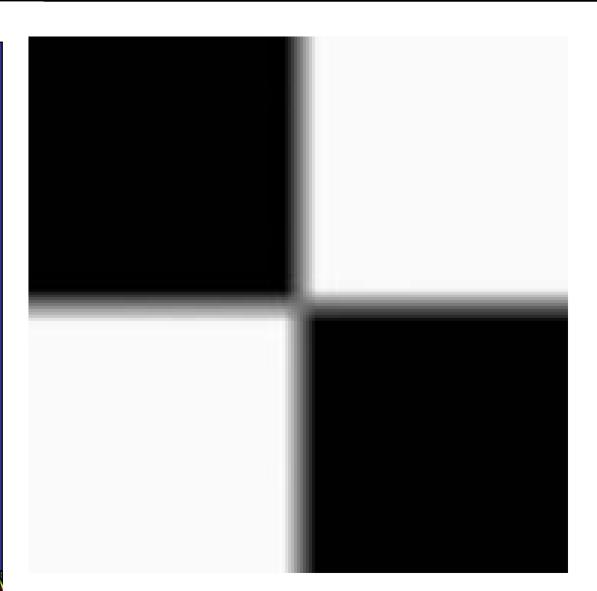




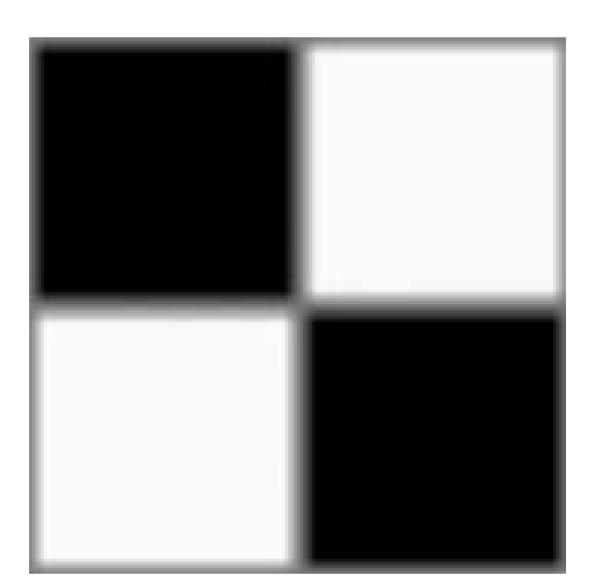


Zero Padding



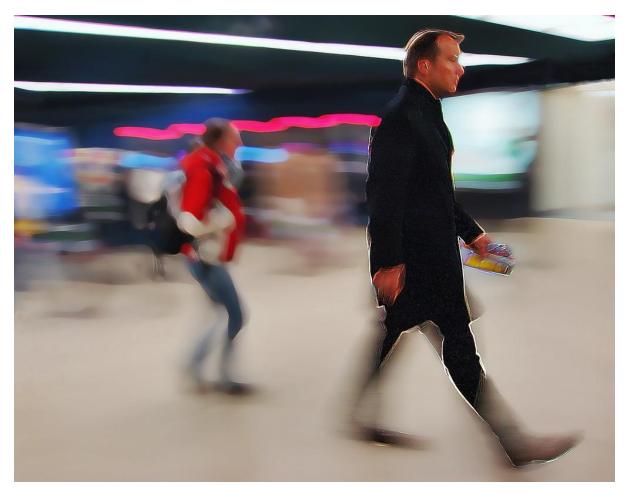


Replicate Edge Pixels



Wrap Around Edge Pixels

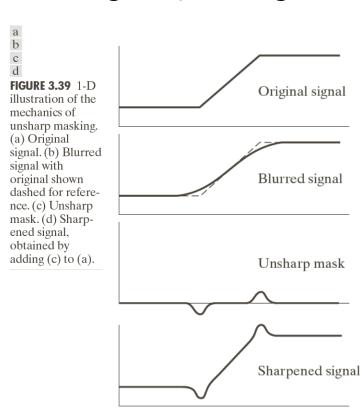
sharpen!



Unlike smoothing the principal objective of **sharpening** is to **highlight transition in intensity**.

unsharp masking

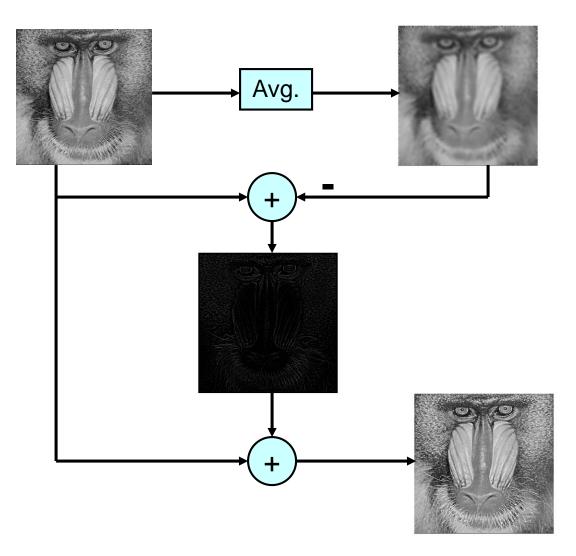
- Unsharp masking is an image manipulation technique for increasing the apparent sharpness of photographic images.
- The "unsharp" of the name derives from the fact that the technique uses a blurred, or "unsharp", positive to create a "mask" of the original image. The unsharped mask is then combined with the negative, creating a resulting image sharper than the original.



Steps

- 1. Blur the image
- 2. Subtract the blurred version from the original (this is called the *mask*)
- 3. Add the "mask" to the original

high-boost filtering



Let f'(x) is the blurred image.

$$g_{mask}(x, y) = f(x, y) - f'(x, y)$$

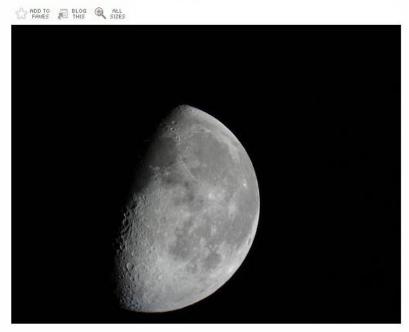
$$g(x, y) = f(x, y) + A * g_{mask}(x, y)$$

Unsharp mask:

high-boost with A=1

unsharp mask example

The Moon 25th August 2005 1:19 GMT



Waning Gibbous Moon, 1:19 GMT Location Edinburgh, Scotland, UK 20.6 days old. Mirror Image!

The Moon with unsharp mask applied



Similar to last nights picture but with some unsharp masking and turned into a greyscale picture. Do you think it helps?

Waning Gibbous Moon, 1:19 GMT Location Edinburgh, Scotland, UK 20.6 days old. Mirror Image! 25th August 2005 1:19 GMT

Summary

In this lecture we have looked at the idea of spatial filtering and in particular:

- Neighbourhood operations
- The filtering process
- Smoothing filters
- Dealing with problems at image edges when using filtering
- Unsharp Masking

Next time we will look at sharpening filters using image derivatives as well as more on filtering and image enhancement