## HW4 - Theoretical Part

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## December 1, 2018

1. For an edge e = (x, y), denote the capacity of e as C((i, j)), and denote the weight of e as W((i, j)).

The reduction transformation: Given a directed capacitated weighted graph G = (V, E, C, W), we construct the following flow network G' = (V', E', C', W'):

- (a) Set G' = (V, E, C, W)
- (b) Find all pairs of nodes (i, j) that have multiple directed edges from node i to node j. For each edge  $e_t \in E$  from i to j,
  - i. remove edge  $e_t$
  - ii. add a dummy node  $k_t$
  - iii. add edge  $(i, k_t), (k_t, j)$
  - iv. set  $C'((i, k_t)) = C'((k_t, j)) = C((i, j))$
  - v. set  $W'((i, k_t)) = W'((k_t, j)) = \frac{1}{2}W((i, j))$

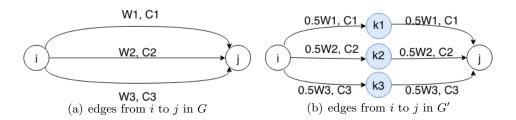


Figure 1: How to construct G'

This transformation takes O(m) time, so it takes polynomial time.

First I'll prove that the constructed graph G' is a standard network without multiedges. Consider any edge (i,j) in G'. If  $i,j \in G$  and there is only one edge between i,j, then in G', there is still one edge between i,j. If  $i,j \in G$  and there are multiply edges between i,j in G, then by our construction, we remove all these edges. So there is no edge between i, j in G'. Otherwise, either i or j or both i and j are the newly added node in G'. By our construction, each node we add only has one in edge and one out edge. So there is at most one edge between i, j in G'. Furthermore G' has all the qualities of a network since it inherits from G. So we know that G' is a standard one without multi-edges.

Then I'll show the equivalence of the instances in min cost flow problem.

Suppose f is the optimal solution to the min-cost flow problem in multi-edges network. Set f' as follows:

$$f'((i,j)) = \begin{cases} f((i,j)) & \text{if } i,j \in G \\ f((i,k)) & \text{if } i \in G, j \notin G, \exists k \in G \text{ s.t. } (i,k) \in E, (i,j), (j,k) \in E' \\ f((k,j)) & \text{if } i \notin G, j \in G, \exists k \in G \text{ s.t. } (k,j) \in E, (k,i), (i,k) \in E' \end{cases}$$

Obviously there is no edge between two newly added nodes.

For flow conservation constraints. We know that for the original node  $v \in G$ ,

$$f'^{out}(v) = \sum_{j \in G, (v,j) \in E'} f'((v,j)) + \sum_{j \notin G, (v,j) \in E'} f'((v,j))$$

$$= \sum_{j: (i,j) \text{has one edge in G}} f((i,j)) + \sum_{j: (i,j) \text{has multiple edges in G } e:e \in E \text{ from } i \text{ to } j} f(e)$$

$$= f^{out}(v)$$

Similarly we can get  $f'^{in}(v) = f^{in}(v)$ . So we have  $f'^{in}(v) = f'^{out}(v)$  for  $v \in G$ . For  $v \notin G$ , it only has one predecessor i and one neighbor j where  $i, j \in G$ . So here  $f'^{in}(v) - f'^{out}(v) = f'((i,v)) - f'((v,j)) = f((i,j)) - f((i,j)) = 0$ . So we know f' satisfies flow constraints.

For capacity constraints, it naturally holds for original edges. For new added edges (i,j), where  $i \in G$ ,  $j \notin G$ ,  $\exists k \in G$  s.t.  $(i,k) \in E$ ,  $(j,k) \in E'$ . We know  $f'((i,j)) = f((i,k)) \leq C((i,k)) = C'((i,j))$ . Similarly it holds for the situation if  $i \notin G$  and  $j \in G$ . So we know that f' satisfies capacity constraints.

Finally I'll prove that f' achieves the optimal.

Claim 1 Given the construction of flow as above, the total cost of the flow f' in G' is the same as the total cost of f in G.

**Proof** 

$$TotalCost(f') = \sum_{e \in E'} W'(e)f'(e)$$

$$= \sum_{e \in E \text{ has one edge}} W(e)f(e) + \sum_{(i,j) \in E \text{ has multiple edges } e_t} \sum_{t} W'((i,k_t))f'((i,k_t))$$

$$+ W'((k_t,j))f'((k_t,j))$$

$$= \sum_{e \in E \text{ has one edge}} W(e)f(e) + \sum_{(i,j) \in E \text{ has multiple edges } e_t} \sum_{t} \frac{1}{2}W((i,j))f(i,j))$$

$$+ \frac{1}{2}W((i,j))f(i,j))$$

$$= \sum_{e \in E \text{ has one edge}} W(e)f(e) + \sum_{(i,j) \in E \text{ has multiple edges } e_t} \sum_{t} W((i,j))f((i,j))$$

$$= \sum_{e \in E \text{ has one edge}} W(e)f(e)$$

$$= \sum_{e \in E} W(e)f(e)$$

$$= TotalCost(f)$$

From claim 1 and the fact that f is the optimal solution. We can conclude that f' is an optimal solution. (Otherwise, if  $f'_1$  has smaller cost in G', we can construct another flow  $f_1$  in G with smaller total cost, which causes a contradiction to the fact that f is optimal.)

On the other hand, suppose f' is the optimal solution of G. Then construct flow f as follows: For  $e = (i, j) \in E'$ , let f(e) = f'(e). For  $e = (i, j)_t \notin E'$ , then exists  $k_t \in G'$  s.t.  $(i, k_t), (k_t, j) \in E'$ . Then let  $f((i, j)_t) = f'((i, k_t))$ . Here t means the  $t_{th}$  edge from i to j. It's straightforward to show that f satisfies capacity and supply constraints in G.

Claim 2 Given the construction of flow as above, the total cost of the flow f in G is the same as the total cost of f' in G'.

Proof

$$TotalCost(f) = \sum_{e \in E} W(e)f(e)$$

$$= \sum_{e \in E \text{ has one edge}} W(e)f(e) + \sum_{(i,j) \in E \text{ has multiple edges } e_t} \sum_{t} W((i,j))f((i,j))$$

$$= \sum_{e \in E \text{ has one edge}} W(e)f(e) + \sum_{(i,j) \in E \text{ has multiple edges } e_t} \sum_{t} \frac{1}{2}W((i,j))f(i,j))$$

$$+ \frac{1}{2}W((i,j))f(i,j))$$

$$= \sum_{e \in E \text{ has one edge}} W(e)f(e) + \sum_{(i,j) \in E \text{ has multiple edges } e_t} \sum_{t} W'((i,k_t))f'((i,k_t))$$

$$+ W'((k_t,j))f'((k_t,j))$$

$$= \sum_{e \in E'} W'(e)f'(e)$$

$$= TotalCost(f')$$

From claim2, and the fact that f' is optimal, we have f is also optimal in the multiedge min-cost flow problem. (Otherwise, if  $f_1$  has smaller cost in G, we can construct another flow  $f'_1$  in G' with smaller total cost, which causes a contradiction to the fact that f' is optimal.)

So we know that we can reduce the multi-edge min-cost problem to a standard one. #

2. The decision version of this problem: Given a monotone instance  $\phi$ , and an integer k, can we set k variables to 1 so that  $\phi$  evaluates to 1?

Next I'll prove that  $VC(D) \leq_P$  The Decision Version of this Problem.

The reduction transformation: Consider an arbitrary instance of the decision version of vertex cover: (G,k). G=(V,E), |V|=n, |E|=m. Denote  $V=\{v_1,\cdots,v_n\}$ ,  $E=\{e_1,\cdots,e_m\}$ . Introduce variables  $x_1,\cdots,x_n$  to  $\phi$ . For every edge  $e=(v_i,v_j)\in E$ , introduce the clause  $(x_i\vee x_j)$  to  $\phi$ . So we can get a monotone instance with n variables and m clauses. (Because it does not contain negation, and it is in CNF.) Clearly the transformation takes O(m+n) time, which is polynomial time.

Equivalence of the instances: Then I'll show that the instance (G, k) is a yes instance of  $VC(D) \Leftrightarrow (\phi, k)$  is a yes instance of the decision version of this problem.

 $[\Rightarrow]$  Suppose that G has a vertex cover C of size k. Set the literal corresponding to the nodes in C to 1, and the remains to 0. That is, denote  $C = \{v_{t_1}, \dots, v_{t_k}\}$ . Then set  $x_{t_1}, \dots, x_{t_k}$  to be 1, and all other variables to be 0.

This assignment is valid because the number of the variables set to 1 is equal to the size of vertex cover, which is k. It also satisfies  $\phi$  because for each clause in  $\phi$ , denote as  $(x_i, x_j)$ . From transformation we know that  $e = (x_i, x_j) \in E$ . By definition of the vertex cover, either  $v_i$  or  $v_j$  or both  $v_i$  and  $v_j$  are in C. So either  $x_i$  or  $x_j$  or both  $x_i$  and  $x_j$  are set to 1. So we have  $x_i \vee x_j = 1$ . Hence each clause in  $\phi$  is satisfiable. And therefore we know that  $\phi$  evaluates to 1.

[ $\Leftarrow$ ] Now suppose that there is a satisfying truth assignment of  $\phi$  with k variables set to 1. Denote these k variables as  $x_{t_1}, \dots, x_{t_k}$ . Construct a set  $C = \{v_{t_1}, \dots, v_{t_k}\}$ . Clearly |C| = k. Then I'll prove C is a vertex cover of G. Because  $x_1, \dots, x_n$  are a satisfying truth assignment of  $\phi$ , so each clause of  $\phi$  is satisfiable.  $\forall e = (v_i, v_j) \in E$ , consider the clause  $(x_i \vee x_j)$  in  $\phi$ . (This clause exists because of our reduction transformation.) So we know that this clause evaluates 1, so either  $x_i$  or  $x_j$  or both  $x_i$  and  $x_j$  are set to 1. So either  $v_i$  or  $v_j$  or both  $v_i$  and  $v_j$  are in C. Therefore we have proved that every edge in E has at least one end point in C, so C is a vertex cover of G in size k.

Since VC(D) is NP-complete, we know the decision version of this problem is NP-complete. Because of the rough equivalence of decision and original problems, we conclude that this problem is NP-complete. #

3. The decision version of this problem: Given a large store with m customers and n products and maintains an  $m \times n$  matrix A such that  $A_{ij} = 1$  if customer i has purchased product j; otherwise,  $A_{ij} = 0$ . Is there a subset of orthogonal customers of size k?

Then I'll show that  $IS(D) \leq_P$  The Decision Version of this Problem.

The reduction transformation: Consider an arbitrary instance of the decision version of independent set (G,k). G=(V,E), |V|=m, |E|=n. Denote  $V=\{v_1,\cdots,v_m\}$ ,  $E=\{e_1,\cdots,e_n\}$ . Denote  $e_j=(v_{j_1},v_{j_2})$ . Then for this problem, denote the customers as  $\{x_1,\cdots,x_m\}$ . Denote the products as  $\{p_1,\cdots,p_n\}$ . Initialize the matrix A=0. Then for each edge  $e_j=(v_{j_1},v_{j_2})\in G$ , let  $A_{j_1,j}=A_{j_2,j}=1$ .

Clearly the transformation takes O(m+n) time, which is polynomial time.

Equivalence of the instances: Then I'll show that the instance (G, k) is a yes instance of IS(D)  $\Leftrightarrow (\phi, k)$  is a yes instance of the decision version of this problem.

 $[\Rightarrow]$  Suppose that G has an independent set S of size k.  $S = \{v_{t_1}, \cdots, v_{t_k}\}$ . Then I'll show that the subset of customers  $Q = \{x_{t_1}, \cdots, x_{t_k}\}$  are orthogonal customers by contradiction. For  $\forall 1 \leq i < j \leq k$ , assume that  $x_{t_i}$  and  $x_{t_j}$  purchased the product  $p_q$  in common. Then by definition of the matrix A we will have  $A_{t_i,q} = A_{t_j,q} = 1$ . From our reduction transformation we know that  $A_{i,j} = 1$  if and only if the edge  $e_j$  connects  $v_i$ . So we get the edge  $e_q$  connects  $v_{t_i}$  and  $v_{t_j}$ . This leads to a contradiction to  $v_{t_i}$  and  $v_{t_j}$  are from an independent set S. Therefore we know that customers  $x_{t_i}$  and  $x_{t_j}$  did not buy any products in common, which means they are orthogonal. So we know that the customers in subset Q are orthogonal customers. And |Q| = k.

 $[\Leftarrow]$  Now suppose that we have a subset of orthogonal customers  $Q = \{x_{t_1}, \dots, x_{t_k}\}$ . We claim that  $S = \{v_{t_1}, \dots, v_{t_k}\}$  is an independent set of G. We also prove this by contradiction. Assume that  $\exists 1 \leq i < j \leq n$  s.t. there is an edge  $e_q = (v_{t_i}, v_{t_j}) \in E$ . Then from transformation we have  $A_{t_i,q} = A_{t_j,q} = 1$ . That means customer  $x_{t_i}$  and customer  $x_{t_j}$  both purchased the product q, which results in the contradiction to  $x_{t_i}$  and  $x_{t_j}$  are orthogonal customers. Therefore we know that for each two nodes in S, there is no edge between them. So S is an independent set of G, with size k.

Since IS(D) is NP-complete, we know the decision version of this problem is NP-complete. Because of the rough equivalence of decision and original problems, we conclude that this problem is NP-complete. #

4. I'll reduce this problem to a max-flow problem. We want to construct a graph G. First add n nodes  $\{x_1, \dots, x_n\}$ , where  $x_i$  is corresponding to the  $i_{th}$  person. Then add another k nodes  $\{y_1, \dots, y_k\}$ , where  $y_j$  is corresponding to the  $j_{th}$  hospital. For  $\forall 1 \leq i \leq n, 1 \leq j \leq k$ , if the  $j_{th}$  hospital is within a half-hour's driving time of the  $i_{th}$  person, then add an edge  $(x_i, y_j)$ , the capacity  $c((x_i, y_j)) = 1$ . Then add a source node s. For every  $x_i$ , add an edge  $(s, x_i)$ , the capacity  $c((s, x_i)) = 1$ . Then add a sink node t. For every  $y_j$ , add an edge  $(y_j, t)$ , the capacity  $c((y_j, t)) = \lceil \frac{n}{k} \rceil$ .

Then I'll prove the equivalence. We claim that there is a feasible assignment of injured people that meets all demands if and only if there is a max flow of value n.

 $[\Rightarrow]$  Given a feasible assignment, we'll define a flow in G. Initialize the flow f(e)=0 for every edge e. For each injured person, if the  $i_{th}$  person is assigned to the  $j_{th}$  hospital, then let  $f((x_i,y_j))=1$ . For  $1 \le i \le n$ , set  $f((s,x_i))=1$ . For  $1 \le j \le k$ , set  $f((y_j,t))$  is the number of people the  $j_{th}$  hospital receives. Then we consider the  $y_j$ ,  $\forall 1 \le j \le k$ . We know

$$f^{in}(y_j) = \sum_{i:i_{th} \text{ person goes to } j_{th} \text{ hospital}} f(x_i, y_j))$$

$$= \sum_{i:i_{th} \text{ person goes to } j_{th} \text{ hospital}} 1$$

$$= \# \text{ people that go to the } i_{th} \text{ hospital}$$

$$= f((y_j, t))$$

$$= f^{out}(y_j)$$

So we know that f satisfies the flow conservation constraints.

Since the assignment meets all the demand, we know that  $\forall 1 \leq i \leq n$ ,  $f((s, x_i)) = 1 = c((s, x_i))$ .  $\forall 1 \leq j \leq k$ ,  $f((y_j, t))$  =the number of people the  $j_{th}$  hospital receives  $\leq \lceil \frac{n}{k} \rceil = c((y_j, t))$ .  $\forall 1 \leq i \leq n$ ,  $\forall 1 \leq j \leq k$ ,  $f((x_i, y_j)) \leq 1 = c((x_i, y_j))$ . So f also satisfies the capacity constraints.

 $|f| = \sum_{1 \le i \le n} f((s, x_i)) = n$ . This is the max flow because the capacity of the cut  $(\{s\}, V - \{s\})$  is n. So we prove that there is a max flow of value n.

[ $\Leftarrow$ ] Given a max flow f of value n inn G. Since the capacity are integer, the max flow we get is also integer. Then we construct a feasible assignment that satisfies all the requirements: for each edge  $(x_i, y_j)$ , if  $f((x_i, y_j)) = 1$ , then we assign the  $i_{th}$  people to the  $j_{th}$  hospital. (Since  $c((x_i, y_j)) = 1$ , we know that  $f((x_i, y_j))$  can only be 0 or 1.) The value of the flow equals flow out of s and the capacity of the cut  $(\{s\}, V - \{s\})$  is n. So every edge out of s is saturated. From the flow conservation constraint we know that  $\forall 1 \leq i \leq n$ ,  $f^{out}(x_i) = f^{out}(x_i) = 1$ . So we ensure every injured person is assigned to exactly one hospital. Then for each hospital, by flow conservation constraint and capacity constraints we know that  $\forall 1 \leq j \leq k$ ,  $f^{in}(x_i) = f^{out}(x_i) \leq \lceil \frac{n}{k} \rceil$ . Here  $f^{in}(x_i) = the$  number of people that go to the  $i_{th}$  hospital. So we know that this

assignment meets the requirement that every hospital receives at most  $\lceil \frac{n}{k} \rceil$  people. So we get a feasible assignment.

So we have successfully reduce the original problem to a max flow problem. We can solve the max flow problem using Ford-Fulkerson Algorithm with input (G, s, t). If the max flow value is equal to n, then we know that there is a feasible assignment: for each edge  $(x_i, y_j)$ , if  $f((x_i, y_j)) = 1$ , then we assign the  $i_{th}$  people to the  $j_{th}$  hospital. If the max flow value is less than n, then we have no feasible assignment.

This reduction needs polynomial time O(nk). And we know that max-flow problem is efficient, so the original problem can be solved in polynomial time  $O(n^2(n+k))$ . So this algorithm is efficient. #

5. (i) Denote  $a_{ij}$  as the indicator whether the employee i is assigned the position j. That is, if the manager assign the position j to the employee i, then  $a_{ij} = 1$ , otherwise  $a_{ij} = 0$ . Then we formulate an integer program as follow.

$$\max \sum_{1 \le i \le m, 1 \le j \le n} s_{ij} a_{ij}$$
s.t. 
$$\sum_{1 \le i \le m} a_{ij} \le 1 \qquad \forall 1 \le j \le n$$

$$\sum_{1 \le j \le n} a_{ij} \le 1 \qquad \forall 1 \le i \le m$$

$$a_{ij} \in \{0, 1\} \qquad \forall 1 \le i \le m, 1 \le j \le n$$

- (ii) We can reduce this problem to a min-cost flow problem. We need to construct a graph G. Add nodes  $x_i$ ,  $1 \le i \le m$ . Add nodes  $y_j$ ,  $1 \le j \le n$ . Add a source node s, and a sink node t. For  $1 \le i \le m$ , add an edge  $(s, x_i)$ , with capacity  $c((s, x_i)) = 1$ , cost  $w((s, x_i)) = 0$ . For  $1 \le j \le n$ , add an edge  $(y_j, t)$ , with capacity  $c((y_j, t)) = 1$ , cost  $w((y_j, t)) = 0$ . For  $1 \le i \le m$ ,  $1 \le j \le n$ , add an edge  $(x_i, y_j)$ , with capacity  $c((x_i, y_j)) = 1$ , weight  $w((x_i, y_j)) = -s_{ij}$ . So we get a network G = (V, E, c, w), source s and sink t. The formulation takes polynomial time. We want to minimize the total cost of the flow. (min-cost flow)

  So the above IP will find the the min-cost flow f. More detailedly, if  $a_{ij} = 1$ , then the  $f((s, x_i)) = f((x_i, y_j)) = f((y_j, t)) = 1$ , and there is no flow on other edges. So in IP we want to maximize the sum of  $s_{ij}a_{ij}$ , that is to minimize the cost of the flow. (Since  $w_{ij} = -s_{ij}$ ). So the solution of the IP is the min-cost flow, where  $a_{ij} = f(x_i, y_j)$ . And the corresponding objective function will be negative the min-cost.
- (iii) If  $s_{ij} = 1$ , then the resulting IP finds the max bipartite matching. We construct a bipartite graph  $G = (X \cup Y, E)$ .  $X = \{x_1, \dots, x_m\}$ ,  $Y = \{y_1, \dots, y_n\}$ . For  $\forall q \leq i \leq m, 1 \leq j \leq n$ , add an edge  $(x_i, y_j)$ . The result of the IP will give us the max bipartite matching of G. If  $s_{ij} = 1$ , then add the pair  $(x_i, y_j)$  to the pair. Since we have the constraints, so we will get a valid matching. Also because we want to maximize the objective function, we will get the maximum bipartite matching.

(iv) (i) The integer program for this instance is:

$$\begin{array}{ll} \max & a_{11} + a_{12} + a_{13} + a_{21} + a_{22} + a_{23} \\ \text{s.t.} & a_{11} + a_{12} + a_{13} \leq 1 \\ & a_{21} + a_{22} + a_{23} \leq 1 \\ & a_{11} + a_{21} \leq 1 \\ & a_{12} + a_{22} \leq 1 \\ & a_{13} + a_{23} \leq 1 \\ & a_{ij} \in \{0,1\}, \quad \forall 1 \leq i \leq 2, 1 \leq j \leq 3 \end{array}$$

Its relaxed LP is:

$$\max_{a_{ij} \geq 0} \quad a_{11} + a_{12} + a_{13} + a_{21} + a_{22} + a_{23}$$
 s.t. 
$$a_{11} + a_{12} + a_{13} \leq 1$$
 
$$a_{21} + a_{22} + a_{23} \leq 1$$
 
$$a_{11} + a_{21} \leq 1$$
 
$$a_{12} + a_{22} \leq 1$$
 
$$a_{13} + a_{23} \leq 1$$

It is suffice to constrain all variables to be non-negative, and is free to omit the upper bound 1 of  $a_{ij}$  because the constraints that sum of variables are no greater 1, and that all variables are non-negative ensure that all the variables are definitely no greater than 1. So we only constrain  $a_{ij} \geq 0$ . Then I'll take the dual of the relaxed LP. I'll rewrite the relaxed LP as follows. Let  $x = (a_{11}, a_{12}, a_{13}, a_{21}, a_{22}, a_{23})^T$ ,  $b = c = (1, 1, 1, 1, 1, 1)^T$ . Define

$$A = \begin{pmatrix} 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix}$$

So the relaxed LP can be written as

$$\max_{x \ge 0} c^T x$$
  
s.t.  $Ax \le b$ 

Then we can give the dual:

$$\min_{y \ge 0} \quad b^T y$$
s.t.  $A^T y \ge c$ 

That is:

$$\min_{\substack{y_i \geq 0, 1 \leq i \leq 5}} y_1 + y_2 + y_3 + y_4 + y_5$$
s.t. 
$$y_1 + y_3 \geq 1$$

$$y_1 + y_4 \geq 1$$

$$y_1 + y_5 \geq 1$$

$$y_2 + y_3 \geq 1$$

$$y_2 + y_4 \geq 1$$

$$y_2 + y_5 \geq 1$$

Assume the dual LP has integer solution. Then it could solve the minimum vertex cover.

First I'll prove that the integer solution  $\{y_i\}$  can only be 0 or 1. From the constraints we know that  $y_i \geq 0$ . Assume that for the optimal solution  $\{y_i\}_{i=1}^5$ ,  $\exists t$  s.t.  $y_t \geq 2$ . Then we consider the solution  $\{y_i'\}_{i=1}^5$  so that  $y_i' = y_i$  if  $i \neq t$ , and  $y_t' = 1$ . Clearly  $\{y_i'\}_{i=1}^5$  also meets all the constraints, and can achieve a smaller objective function than  $\{y_i\}_{i=1}^5$ . This causes a contradiction to  $\{y_i\}_{i=1}^5$  is the optimal solution. Therefore we know that  $\{y_i\} \leq 1$ . So the integer solution  $\{y_i\}$  can only be 0 or 1.

Let 
$$G = (V, E)$$
.  $V = \{v_1, \dots, v_5\}$ ,  $E = \{(v_1, v_3), (v_1, v_4), (v_1, v_5), (v_2, v_3), (v_2, v_4), (v_2, v_5)\}$ . Consider a subset  $S \subset V$ . Let  $y_i = \begin{cases} 1 & \text{if } v_i \in S \\ 0 & \text{o.w.} \end{cases}$ 

For a vertex cover S we need that for each edge  $(v_i, v_j)$ , we have  $y_i + y_j \ge 1$  so that it has an end point in S. So we know that this dual LP is solving the minimum vertex cover problem. #