

Bayesian Statistics, Monte Carlo Methods (Importance Sampling)

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- Let us introduce the Dirac-delta function δ_{θ_0} for $\theta_0 \in \Theta$ defined for any $f : \Theta \rightarrow \mathbb{R}^{n_f}$ as follows:

$$\int_{\Theta} f(\theta) \delta_{\theta_0}(\theta) d\theta = f(\theta_0)$$

- Note that this implies in particular that for $A \subset \Theta$,

$$\int_{\Theta} \mathcal{I}_A(\theta) \delta_{\theta_0}(\theta) d\theta = \int_A \delta_{\theta_0}(\theta) d\theta = \mathcal{I}_A(\theta_0)$$

- Now, for $\theta^{(i)} \sim \pi, i = 1, 2, \dots, N$, we can introduce the following mixture of Dirac-delta functions

$$\hat{\pi}_N(\theta) = \frac{1}{N} \sum_{i=1}^N \delta_{\theta^{(i)}}(\theta),$$

which is the empirical measure.

- Now consider the problem of estimating $E_\pi(f)$. We simply replace π with its sample representation $\hat{\pi}_N$ and obtain

$$\begin{aligned} E_\pi(f) &\simeq \int_{\Theta} f(\theta) \sum_{i=1}^N \frac{1}{N} \delta_{\theta^{(i)}}(\theta) d\theta \\ &= \sum_{i=1}^N \int_{\Theta} f(\theta) \frac{1}{N} \delta_{\theta^{(i)}}(\theta) d\theta = \frac{1}{N} \sum_{i=1}^N f(\theta^{(i)}) \end{aligned}$$

which is precisely $S_N(f)$, the Monte Carlo estimator suggested earlier.

- Clearly based on $\hat{\pi}_N$, we can easily estimate $E_\pi(f)$ for any f .
- More precisely,

$$E_X[E_{\hat{\pi}_N}(f(X))] = E_\pi(f(X)), \text{ and } \text{var}_X(E_{\hat{\pi}_N}(f(X))) = \frac{\text{var}_\pi(f(X))}{N}.$$

- Direct methods feasible for standard distributions: inverse method, composition, etc.
- In case where $\pi \propto \pi^*$ does not admit any standard form, we can use a proposal distribution q on \mathcal{X} where $q \propto q^*$.
- We need q to demoniate π ,

$$C = \sup_{x \in \mathcal{X}} \frac{\pi^*(x)}{q^*(x)} < +\infty.$$

Generating Continuous Random Variables (The Rejection Method)

Suppose we have a method for generating a random variable Y having density function $\pi(x)$. We can use this as basis for generating a random variable X having density function $q(x)$.

Let C be a constant such that

$$\frac{\pi(y)}{q(y)} \leq C \text{ for all } y$$

The Rejection Method

Step 1: Generate Y having density q .

Step 2: Generate a random number U .

Step 3: If $U \leq \frac{\pi(Y)}{Cq(Y)}$, set $X = Y$. Otherwise, return to Step 1.

Generating Continuous Random Variables (The Rejection Method)

- This is a simple generic algorithm but it requires coming up with a bound C .
- Its performance typically degrades exponentially fast with the dimension of X .
- It seems you are wasting some information by rejecting samples.
- You need to wait a random time to obtain some samples from π .
- Is it possible to “recycle” these samples?

Importance Sampling

- Consider again the target distribution π and the proposal distribution q . We only require $\pi(x) > 0 \Rightarrow q(x) > 0$.
- In this case, the Importance Sampling (IS) identity is

$$E_{\pi}(\phi(X)) = \int_{\mathcal{X}} \phi(x)\pi(x)dx = \int_{\mathcal{X}} \phi(x)\frac{\pi(x)}{q(x)}q(x)dx = E_q(w(X)\phi(X))$$

where the so-called Importance Weight is given by
 $w(x) = \pi(x)/q(x)$

- This is a simple yet very flexible identity.

- Monte Carlo approximation of q is

$$\hat{q}_N(x) = \frac{1}{N} \sum_{i=1}^N \delta_{X^{(i)}}(x), \text{ where } X^{(i)} \sim q, i.i.d$$

- It follows that an estimate of $E\pi(\phi(X)) = E_q(w(X)\phi(X))$ is

$$E_{\hat{q}_N}(w(X)\phi(X)) = \frac{1}{N} \sum_{i=1}^N w(X^{(i)})\phi(X^{(i)}), , X^{(i)} \sim q, i.i.d$$

- It corresponds to the following approximation

$$\hat{\pi}_N(x) = \frac{1}{N} \sum_{i=1}^N w(X^{(i)})\delta_{X^{(i)}}(x), \text{ where } X^{(i)} \sim q, i.i.d$$

- We have

$$E_X[E_{\hat{q}_N}(w(X)\phi(X))] = E_\pi(\phi(X)),$$

and

$$\begin{aligned} \text{var}_X(E_{\hat{q}_N}(w(X)\phi(X))) &= \frac{\text{var}_q(w(X)\phi(X))}{N} \\ &= \frac{E_\pi(w(X)\phi^2(X)) - E_\pi^2(\phi(X))}{N}. \end{aligned}$$

- In practice, it is recommended to ensure

$$E_\pi(w(X)) = \int \frac{\pi^2(x)}{q(x)} dx < \infty$$

- Even if it is not necessary, it is actually even better to ensure that:

$$\sup w(x) < \infty, x \in X$$

Example

- Consider the function $h(x) = 10\exp(-2|x - 5|)$. Suppose that we want to calculate $E(h(X))$, where $X \sim \text{Uniform}(0, 1)$. That is, we want to calculate the integral

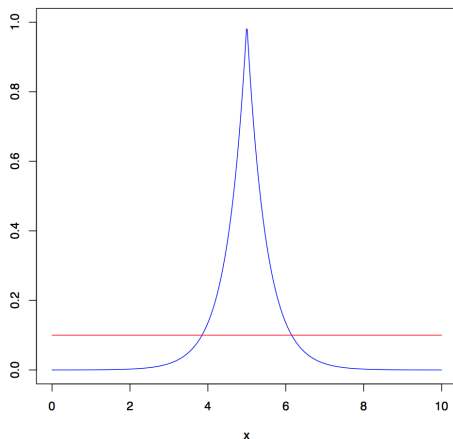
$$\int_0^{10} \exp(-2|x - 5|) dx.$$

```
X <- runif(100000,0,10)
Y <- 10*exp(-2*abs(X-5))
c( mean(Y), var(Y) )
[1] 0.9919611 3.9529963
```

- The function h in this case is peaked at 5, and decays quickly elsewhere, therefore, under the uniform distribution, many of the points are contributing very little to this expectation.

Example

Figure : The integrand (blue) and the density being integrated against (red) approach 1



- Rewrite the integral as:

$$\int_0^{10} 10 \exp(-2|x-5|) \frac{1/10}{\frac{1}{\sqrt{2\pi}} e^{-(x-5)^2/2}} \frac{1}{\sqrt{2\pi}} e^{-(x-5)^2/2} dx$$

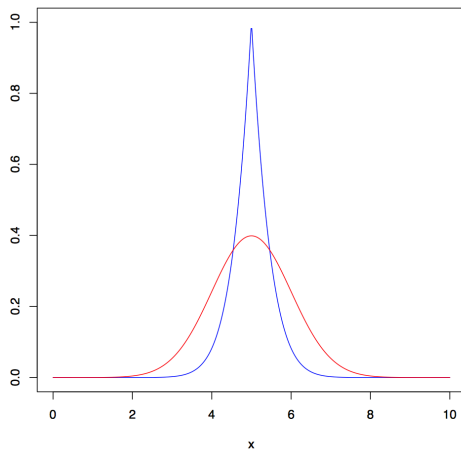
- That is, $E(h(X)w(X))$, where $X \sim N(5, 1)$.
- The integral is:

$$\int_0^{10} \exp(-2|x-5|) \sqrt{2\pi} e^{(x-5)^2/2} \frac{1}{\sqrt{2\pi}} e^{-(x-5)^2/2} dx$$

```
w <- function(x) dunif(x, 0, 10)/dnorm(x, mean=5, sd=1)
f <- function(x) 10*exp(-2*abs(x-5))
X=rnorm(1e5,mean=5,sd=1)
Y=w(X)*f(X)
c( mean(Y), var(Y) )
[1] 0.9999271 0.3577506
```

Example

Figure : The integrand (blue) and the density being integrated against (red) approach 2



Example

- Double exponential density: $\pi(x) = \frac{1}{2}e^{-|x|}$. The CDF is

$$F(x) = \frac{1}{2}e^x I(x \leq 0) + (1 - e^{-x}/2)I(x > 0)$$

- Estimate $E(X^2)$. That is, calculate the integral $\int_{-\infty}^{\infty} x^2 \frac{1}{2}e^{-|x|} dx$
- Rewrite the integral as:

$$\int_{-\infty}^{\infty} x^2 \frac{\frac{1}{2}e^{-|x|^2}}{\frac{1}{\sqrt{8\pi}}e^{-\frac{x^2}{8}}} \frac{1}{\sqrt{8\pi}}e^{-\frac{x^2}{8}} dx$$

```
X <- rnorm(1e5, sd=2)
Y <- (X^2) * .5 * exp(-abs(X))/dnorm(X, sd=2)
mean(Y)
[1] 1.998898
```

Optimal IS Distribution

- For a given test function, one can minimize the IS variance using:

$$q^{opt}(x) = \frac{|\phi(x)|\pi(x)}{\int_{\mathcal{X}} |\phi(x)|\pi(x)dx}$$

- Proof.

$$\text{Var}_q(w(x)\phi(x)) = \int q(x) \frac{\pi^2(x)}{q^2(x)} \phi^2(x) dx - \left(\int q(x) \frac{\pi(x)}{q(x)} \phi(x) dx \right)^2$$

$$\text{and } \int q(x) \frac{\pi^2(x)}{q^2(x)} \phi^2(x) dx \geq \left(\int q(x) \frac{\pi(x)}{q(x)} |\phi(x)| dx \right)^2 = \left(\int q(x) \frac{\pi(x)}{q(x)} |\phi(x)| dx \right)^2.$$

This lower bound is attained for $q^{opt}(x)$.

Normalized Importance Sampling

- In most if not all applications we are interested in, standard IS cannot be used as the importance weights $w(x) = \pi(x)/q(x)$ cannot be evaluated in closed-form. In practice, we typically only know $\pi(x) \propto \pi^*(x)$ and $q(x) \propto q^*(x)$.
- Normalized IS identity is based on

$$\pi(x) = \frac{\pi^*(x)}{\int \pi^*(x) dx} = \frac{w^*(x)q^*(x)}{\int w^*(x)q^*(x) dx} = \frac{w^*(x)q(x)}{\int w^*(x)q(x) dx}$$

Normalized Importance Sampling

- For any test function $\phi(x)$, we can also write

$$E_{\pi}(\phi(x)) = \frac{E_q(w^*(X)\phi(X))}{E_q(w^*(X))} = \frac{E_q(w(X)\phi(X))}{E_q(w(X))}$$

- Given a Monte Carlo approximation of q :

$$\hat{q}_N(x) = \frac{1}{N} \sum_{i=1}^N \delta_{X^{(i)}}(x), \text{ where } X^{(i)} \sim q, i.i.d$$

- Then,

$$\hat{\pi}_N(x) = \frac{1}{N} \sum_{i=1}^N W(X^{(i)}) \delta_{X^{(i)}}(x),$$

$$\text{where } W(X^{(i)}) = \frac{w^*(X^{(i)})}{\sum_{j=1}^N w^*(X^{(j)})}$$

$$E_{\hat{\pi}_N}(\phi(X)) = \frac{1}{N} \sum_{i=1}^N W(X^{(i)}) \phi(X^{(i)}), \text{ , } X^{(i)} \sim q, i.i.d$$

- The estimates are a ratio of estimates.

Example

- Suppose $X_1, \dots, X_n \sim \text{Binomial}(10, \theta)$ where $\theta \in (0, 1)$ has a $\text{Beta}(5, 3)$ prior density: $p(\theta) = \frac{\Gamma(8)}{\Gamma(5)\Gamma(3)}\theta^4(1 - \theta)^2$. We want to estimate the mean of the posterior distribution:
 $\int_0^1 \theta p(\theta | x_1, \dots, x_n) d\theta$.
- Take q to be the $\text{Beta}(\alpha, \beta)$ density, where $\alpha = c\bar{X}$, $\beta = c(10 - \bar{X})$, where \bar{X} is the sample mean. This will ensure that q is peaked near $\bar{X}/10$, which is where the posterior distribution should have a lot of mass.

Example

- The joint distribution of the data, given θ :

$$\begin{aligned}p(x_1, x_2, \dots, x_n | \theta) &= \prod_{i=1}^n p(x_i | \theta) \\&\propto \theta^{\sum_{i=1}^n x_i} (1 - \theta)^{10n - \sum_{i=1}^n x_i} \\&= \theta^{n\bar{X}} (1 - \theta)^{n(10 - \bar{X})}\end{aligned}$$

- The posterior density:

$$\begin{aligned}p(\theta | x_1, x_2, \dots, x_n) &\propto p(x_1, x_2, \dots, x_n | \theta) p(\theta) \\&\propto \theta^{n\bar{X}} (1 - \theta)^{n(10 - \bar{X})} p(\theta) \\&\propto \theta^{n\bar{X}} (1 - \theta)^{n(10 - \bar{X})} \theta^4 (1 - \theta)^2 \\&= \theta^{n\bar{X} + 4} (1 - \theta)^{n(10 - \bar{X}) + 2}\end{aligned}$$

- The log of this quantity is:

$$(n\bar{X} + 4) \log \theta + (n(10 - \bar{X}) + 2) \log(1 - \theta)$$

Example

- Suppose $X_1, \dots, X_n \sim N(0, \theta)$ and we specify a *Gamma*(3, .5) distribution for the prior of θ . We will use a trial density q which is Gamma distributed with $\alpha = cs^2$, and $\beta = c$, where c is a positive constant, and s^2 is the sample variance. So the mean of the trial distribution will be s^2 . Choose c to optimize estimation precision.

- The joint distribution of the data, given θ ,

$$\begin{aligned}
 & p(x_1, x_2, \dots, x_n | \theta) \\
 &= \prod_{i=1}^n \sqrt{\frac{1}{2\pi\theta}} e^{-x_i^2/2\theta} \\
 &\propto \theta^{-n/2} \exp\left(-\frac{1}{2\theta} \sum_{i=1}^n x_i^2\right)
 \end{aligned}$$

- The posterior distribution is proportional to

$$\begin{aligned}
 p(\theta | x_1, \dots, x_n) &= p(x_1, \dots, x_n | \theta) p(\theta) \\
 &\propto \theta^{-n/2} \exp\left(-\frac{1}{2\theta} \sum_{i=1}^n x_i^2\right) 2^{-3} \Gamma(3)^{-1} \theta^2 e^{-\theta/2} \\
 &\propto \theta^{-n/2} \exp\left(-\frac{1}{2\theta} \sum_{i=1}^n x_i^2\right) \theta^2 e^{-\theta/2} \\
 &= \theta^{(4-n)/2} \exp\left(-\frac{1}{2\theta} \sum_{i=1}^n (\theta^2 + x_i^2)\right)
 \end{aligned}$$

Normalized Importance Sampling

- Contrary to standard IS, this estimate is biased but asymptotically unbiased by the LLN it is asymptotically consistent.
- Derivation of the asymptotic bias and variance based on the delta method.