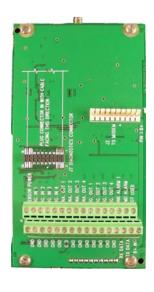
FGRIO System User Manual

Version 1







FGRIO Master FGRIO-M FGRIO Slave FGRIO-S FGR2-IO Slave FGR2-IOS-CE-U

UL Notification:

This equipment is suitable for use in Class I, Division 2, Groups A, B, C, and D or non-hazardous locations only."

Warning—Explosion Hazard—Substitution of components may impair suitability for Class I, Division 2.

The diagnostics port and cable do not have a latching connector and cannot be used in a hazardous location.

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Description

This is an addendum to the Spread Spectrum Wireless Data Transceiver User Manual. It covers details applicable specifically to using the FreeWave FGRIO Master and Slave modems. Please use this addendum in conjunction with the User Manual.

The FreeWave Technologies FGRIO System provides outstanding performance and versatility in wireless transmission of process-control signals. FGRIO offers "transparent" acquisition, transport and reconstruction of analog, digital and power signals, eliminating the need for associated buried wiring. The RTU requires no altered programming. The FGRIO is Class 1 Div 2 approved and is lower-cost and provides better signal integrity than vulnerable wiring.

The FGRIO System is based upon wireless RF Technologies. RF is subject to interference and communication interruptions. It should not be expected, therefore, to provide 100% communication, 100% of the time. The FGRIO System should not be used without proper provisions to ensure safety upon loss of radio communications.

Glossary

FGRIO Master– FreeWave wireless radio transceiver that operates as a Master for up to 4 FGRIO or FGR2-IO Slaves, and can operate as a Slave in a point to multipoint network. The FGRIO Master can receive over air a total of 4 analog input signals and 4 digital input signals from up to 4 FGRIO or FGR2-IO Slaves. It can also transmit up to 4 digital output signals over air to the FGRIO or FGR2-IO Slaves. *The FGRIO Master does not operate as a Slave/Repeater in the SCADA system*.

FGRIO Slave – FreeWave wireless radio transceiver that accepts up to a total of 4 input signals from sensors, then transmits these signals over air to the FGRIO Master. Two of the 4 available input signals can only be transmitted as analog signals and are labeled as Analog Input 1 and Analog Input 2 on the Slave's terminal block. The other two input signals may be either analog or digital inputs, depending on the user's needs. The FGRIO Slave can also receive over air 2 digital output signals and a sensor power control signal from the FGRIO Master.

FGR2-IO Slave – New generation FreeWave wireless radio transceiver that accepts up to a total of 4 input signals from sensors, then transmits these signals over air to the FGRIO Master. Two of the available 4 input signals can only be transmitted as analog signals and are labeled as Analog Input 1 and Analog Input 2 on the Slave's terminal block. The other two input signals may be either analog or digital inputs, depending on the user's needs. The FGR2-IO Slave can also receive over air 2 digital output signals and a sensor power control signal from the FGRIO Master. The FGR2-IO has a line-of-sight range of 60 miles, compared to the 2 mile line-of-sight range of the FGRIO Slave.

A note about terminology: The phrase 'FGRIO System', when used in this manual, will refer to any system that uses an FGRIO Master in conjunction with either FGRIO or FGR2-IO Slaves. IO Slave will refer to either an FGRIO Slave or an FGR2-IO Slave.



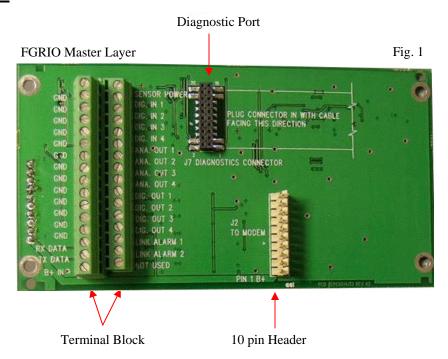
Glossary (cont.)

Analog Circuit— An electronic circuit that operates with currents and voltages that vary continuously with time and have no abrupt transitions between levels. Temperatures, pressures, or flow rates are all represented by analog circuits.

Digital Circuit— An electronic circuit that functions as though currents or voltages exist only at one of a set of discrete levels, all transitions between levels being ignored. The states of a digital circuit are often referred to as on or off, high or low.

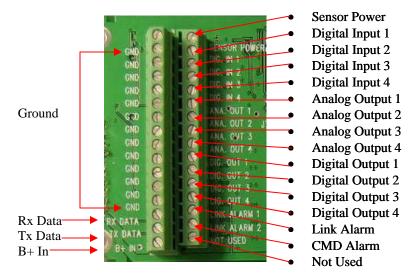
VSNS- This is screw terminal # 7 on the IO Slave. This is an output used to power sensors/ transmitters. The maximum output voltage of this terminal is 20VDC for the FGRIO-S and 30VDC for the FGR2-IOS-C-U and FGR2-IOS-CE-U

Diagrams



FGRIO Master Terminal Block

Fig. 2



Diagrams (cont.)

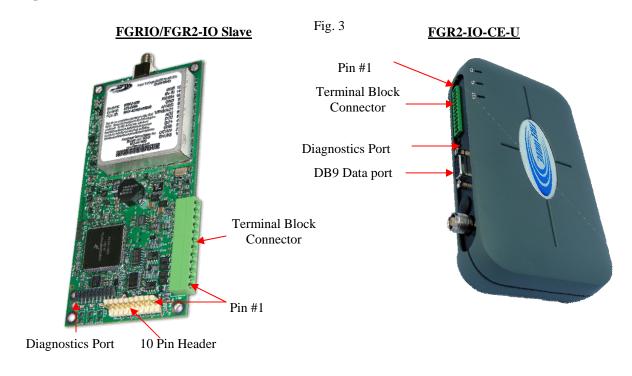


Fig. 4 **FGRIO Slave FGR2-IO Slave Terminal Block Terminal Block** 12-Ground 12-Ground 11-B+ IN 11-B+ IN 10-Analog Input 2 10-Analog Input 2 9-Ground 9-Ground 8-Analog Input 1 8-Analog Input 1 7-VSNS/Analog Out 1 7-VSNS/Analog Out 1 6-Ground 6-Analog Output 2* 5-Digital Output 2 5-Digital Output 2 4-Digital Output 1 4-Digital Output 1 3-Ground 3-Ground 2-Digital Input 2 OR 2-Digital Input 2 OR Analog Input 4* Analog Input 4* 1-Digital Input 1 **OR** 1-Digital Input 1 **OR** Analog Input 3* Analog Input 3*

<u>Note:</u> *Analog Output 2 is not available in the IO Wire Replacement mode. Analog Inputs 3 and 4 are 0-3.3VDC inputs. See wiring diagrams on pages 29-31 for details.

LEDs

The LEDs should have the following appearance when the IO Slave is linked to the FGRIO Master in a FGRIO Stand Alone Network:

F	GRIO Master			FGRIO Slave	
Carrier Detect (CD)	Transmit (TX)	Clear to Send (CTS)	Carrier De- tect (CD)	Transmit (TX)	Clear to Send (CTS)
Solid green bright	Solid red dim	BLINKING red	Blinking green	Blinking red	Blinking red

The LEDs on the FGRIO Master and IO Slave should have the following appearance when the FGRIO Master is linked to the FGR Network Master and the IO Slave is linked to the FGRIO Master:

F	GRIO Master	r		FGRIO Slave	
Carrier Detect (CD)	Transmit (TX)	Clear to Send (CTS)	Carrier De- tect (CD)	Transmit (TX)	Clear to Send (CTS)
Solid green bright	Solid red dim	FLICKERING red	Blinking green 🚔	Blinking red	Blinking red

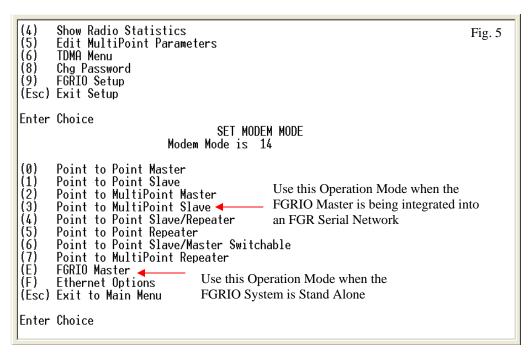
Set Up with HyperTerminal

FGRIO Master– In order for the FGRIO System to function properly, the following settings must be programmed. For all other settings not listed below, please refer to the User Manual.

(0) Operation Mode

(3) **Point to MultiPoint Slave**— Choose this setting when the FGRIO System is being integrated into an FGR Serial Network. The IO functionality is turned on in Menu 9— FGRIO Set Up, in HyperTerminal.

Note: Setting **(E), FGRIO Master**, should only be selected when the FGRIO System is operating independently of an FGR FreeWave Network.



FGRIO Master

(2) Call Book— IO Slaves' serial numbers must be programmed in the FGRIO Master's Call Book. In addition, the Network ID must be set to the same ID as the rest of the network. Programming both the Call Book and Network ID settings is unique to the FGRIO System and must be done for both integrated and stand alone applications.

(3) Radio Transmission Characteristics

(1) Max Packet Size and (2) Min Packet Size—The FGRIO System requires a minimum combined packet size of 48 Bytes. The following is a list of the available packet sizes that can be used.

Fig. 6

	Combined Packet Size Definition with RF Date Rate of 3									
					Max S	Setting				
Min Setting	0	1	2	3	4	5	6	7	8	9
0				56	72	88	104	120	136	152
1				60	76	92	108	124	140	156
2			48	64	80	96	112	128	144	160
3			52	68	84	100	116	132	148	164
4			56	72	88	104	120	136	152	168
5			60	76	92	108	124	140	156	172
6		48	64	80	96	112	128	144	160	176
7		52	68	84	100	116	132	148	164	180
8		56	72	88	104	120	136	152	168	184
9		60	76	92	108	124	140	156	172	188

(4) **RF Data Rate**— The RF Data Rate must be set to 3 when using the FGRIO System. This is for applications that are stand alone or when integrated into an existing FGR network.

MultiPoint Parameters-

- **(0) Number Repeaters** This setting must be set to 1 for all FGR and IO radios in the Network.
- (6) **Network ID** In addition to entering the IO Slaves' serial numbers in the Call Book, the Network ID being used for the Network must be set from 1-4095. (Do NOT use 255). Programming both the Call Book and Network ID settings is unique to the FGRIO System and must be done for both integrated and stand alone applications.

Note: The FGRIO Master does not function as a Slave/Repeater in the SCADA network.



FGRIO Master

(9) FGRIO Setup—Outputs on the FGRIO Master are mapped to inputs on the IO Slave.

Fig. 7 🤏 Comm 1 - HyperTerminal <u>File Edit View Call Transfer Help</u> FGRIO Setup (0) FGRIO (1) Digital Out1 (2) Digital Out2 1234128 (3) Digital Out3 (4) Digital Out4 Analog Out1 (5) (6) Analog Out2 (7) Analog Out3 ў 255 (8) Analog Out4 TimeOut (9) (A) Sensor Pwr SCROLL CAPS NUM Capture Connected 0:03:47 **ANSIW** 19200 8-N-1

FGRIO Master

(9) FGRIO Setup (cont.)

- (0) FGRIO Must be set to 1 to enable I/O functions.
- (1) to (8) To map the FGRIO Master outputs to the correct IO Slave inputs, use the following steps:
 - 1) Select which IO Slave you are mapping to the FGRIO Master. Note the Master's Call Book Entry # that lists this IO Slave's serial number.
 - 2) Next, determine which analog or digital input from the IO Slave radio you wish to map to the FGRIO Master. This could be Analog Input(AI)#1, AI#2, AI#3, AI#4, or Digital Input(DI)#1, or DI#2, depending on which sensor(s) the Slave will be connected to.
 - 3) Using the following table, find the intersection between the Master's Call Book Entry # (found in step 1) and the selected input from the Slave (found in step 2). Note the number listed at this intersection.
 - 4) Go to Menu 9, FGRIO Setup (Figure 7). Select which Master's output you would like to "connect" to the input from the Slave. At the flashing curser, enter the number to the left of the selected output. Next enter the number found in step 3. This number should be displayed to the right of the selected output.

Fig. 8

	AI#1	AI#2	AI#3	AI#4	DI#1	DI#2
FRGIO-M Call Book Entry #0	1	2	9	10	1	2
FRGIO-M Call Book Entry #1	3	4	11	12	3	4
FRGIO-M Call Book Entry #2	5	6	13	14	5	6
FRGIO-M Call Book Entry #3	7	8	15	16	7	8

EXAMPLE

To map Analog Output 1 of the FGRIO Master to Analog Input 2 of the IO Slave (serial #930-0004), entry (5) in the FGRIO Setup menu will have a value of 2. This is calculated by first checking the Call Book entry # of IO Slave #930-0004 (See Figure 9, next page). The entry # is 0. Next, go to the table above, find call book entry # 0, then go to the column for IO Slave Analog Input #2. The value listed is 2. A 2 will be entered for Analog Output #1 of the FGRIO Master.



FGRIO Master

Fig. 9

```
Enter Choice
                                    MODEM CALL BOOK
                                    Entry to Call is (ALL)
                      Repeater1
                                     Repeater2
Entry
          Number
         930-0004
(0)
(1)
(2)
(3)
(4)
(5)
(6)
         000-0000
         000-0000
         000-0000
         000-0000
         000-0000
         000-0000
         000-0000
         000-0000
         000-0000
         Change Entry to Use (0-9) or A(ALL)
         Exit to Main Menu
Enter all zeros (000-0000) as your last number in list
```

(9) FGRIO Setup (cont.)

(9) TimeOut– 0-255. This setting determines the amount of time to wait before issuing a Link Alarm due to loss of communication between the FGRIO Master and IO Slave. A setting of 1 = 1/6 second

6 = 1 second 42 = 7 seconds 252 = 42 seconds

(A) Sensor Power—0 or 1. A setting of 0 supplies continuous power to the sensor at the IO Slave. A setting of 1, "Gated", is used when the RTU provides a switched power output to control powering the sensors at the IO Slave and analog outputs of the FGRIO Master on and off.



IO Slave- In order for the FGRIO System to function properly, the following settings must be programmed. For all other settings not listed below, please refer to the User Manual.

(0) Operation Mode (E) FGRIO Slave

Fig. 10

```
MAIN MENU
                               Short Range 900MHz 2.50c 06-06-2005
                              Modem Serial Number 930-0019
       Set Operation Mode
       Set Baud Rate
       Edit Call Book
       Edit Radio Transmission Characteristics
       Show Radio Statistics
Edit MultiPoint Parameters
       Chg Password
FGRIO Setup
(Esc) Exit Setup
Enter Choice
                                        SET MODEM MODE
                              Modem Mode is 14
       Point to Point Master
Point to Point Slave
Point to MultiPoint Master
       Point to MultiPoint Slave
       Point to Point Slave/Repeater
Point to Point Repeater
       Point to Point Slave/Master Switchable
       Point to MultiPoint Repeater
FGRIO Slave ←
(Esc) Exit to Main Menu
Enter Choice _
```

- (2) Call Book—The FGRIO Master's serial number must be programmed as entry #0 in the IO Slave's Call Book. Set "Entry to Call" to 0. In addition, the Network ID must be set to the same ID as the rest of the network. Programming both the Call Book and Network ID settings is unique only to the FGRIO System and must be done for both integrated and stand alone applications.
- (3) Radio Transmission Characteristics
 - (1) Max Packet Size and (2) Min Packet Size—The FGRIO System requires a minimum combined packet size of 48 Bytes. The following is a list of the available packet sizes that can be used (Figure 11, next page).



IO Slave

(3) Radio Transmission Characteristics (cont.)

Fig. 11

	Combined Packet Size Definition with RF Date Rate of 3									
					Max	Setting				
Min Setting	0	1	2	3	4	5	6	7	8	9
0				56	72	88	104	120	136	152
1				60	76	92	108	124	140	156
2			48	64	80	96	112	128	144	160
3			52	68	84	100	116	132	148	164
4			56	72	88	104	120	136	152	168
5			60	76	92	108	124	140	156	172
6		48	64	80	96	112	128	144	160	176
7		52	68	84	100	116	132	148	164	180
8		56	72	88	104	120	136	152	168	184
9		60	76	92	108	124	140	156	172	188

- (4) **RF Data Rate** The RF Data Rate must be set to 3 when using the FGRIO System. This is for applications that are stand alone or when integrated into an existing FGR network.
- (8) Retry Timeout—By lowering the Retry Timeout, the inactive link time between the FGRIO Master and IO Slave can be reduced when going from autonomous mode to connecting back to the FGR Network. If the Network Master goes down, the FGRIO Master and Slave will continue to operate in autonomous mode. When the Network Master comes back up, the FGRIO Master will break the link with the IO Slave to reestablish a link with the Network Master. Once the FGRIO Master is linked to the Network Master, then the IO Slave will be able to link back to the FGRIO Master. With a lower Retry Timeout setting, it will take less time for the IO Slave to link to the FGRIO Maser.

(5) MultiPoint Parameters-

- (0) Number Repeaters- This setting must be set to 1 for all FGR and IO radios in the Network.
- (6) Network ID- In addition to entering the FGRIO Master's serial number in the Call Book, the Network ID being used for the Network must be set from 1-4095 (Do NOT use 255). Use the same Network ID for the IO Slave as was used for the FGRIO Master. Programming both the Call Book and Network ID settings is unique to the FGRIO System and must be done for both integrated and stand alone applications.



IO Slave

(9) FGRIO Setup

- (0) Default Delay, the value set is in .28 second units. This sets the time duration that will pass, after a loss of communication, before the radio enters default condition. e.g. A value of 36 = 36*0.28 seconds = 10.08 seconds.
- (1) Digital Out1– Select the desired FGRIO Master Digital Input # (1-4) to control the IO Slave Digital Output # 1.
- (2) Digital Out2– Select the desired FGRIO Master Digital Input # (1-4) to control the IO Slave Digital Output # 2.
- (3) Digital Def 1 Select the desired IO Slave Output Default at power-on and link failure.
 - 0= Open Drain output ON (Conducting to GND, 2 Amps max)
 - 1= Open Drain output OFF (Non-Conducting)
 - 2= Make no change in state.
- (4) Digital Def2- Select the desired IO Slave Output Default at power-on and link failure.
 - 0= Open Drain output ON (Conducting to GND, 2 Amps max)
 - 1= Open Drain output OFF (Non-Conducting)
 - 2= Make no change in state.

Note: If programming a DO to turn on after loss of link, ensure that the energized device can sustain the state undamaged in case the loss in lengthy.

- (5) IO Modbus—This menu option must be set to "Disabled" when using a FGRIO network configuration.
- (**E and F**) DI1 Pull Up/Down- Options E and F control power-up states of the internal resistor (10Kohms) connected to the DIs. They can pull up, such as when using a closed-contact-to-GND switch input, pull down so that unused inputs read "0" as DIs or ~0 as auxiliary analogs, or float to not load analog inputs.
- (**I and J**) AI(DI1) and AI(DI2) Filter do not apply in the FGRIO network.

Note: Both of the IO Slave Digital Outputs may be driven by the same FGRIO Master Input.



(9) FGRIO Setup (cont.)

Fig. 12

(0) (1) (2) (3) (4) (5) (6) (7) (8) (9) (A) (B)	Default Delay Digital Out1 Digital Out2 Digital Def1 Digital Def2 IO MODBus	255 1 2 On Off Disabled
(D) (E) (F) (G) (H) (I) (J)	DI1 Pull Up/Down DI2 Pull Up/Down AI(DI1) Filter AI(DI2) Filter	Up Down No Filter No Filter
(Esc)	Exit to Main Menu Choice	



Set Up with Tool Suite

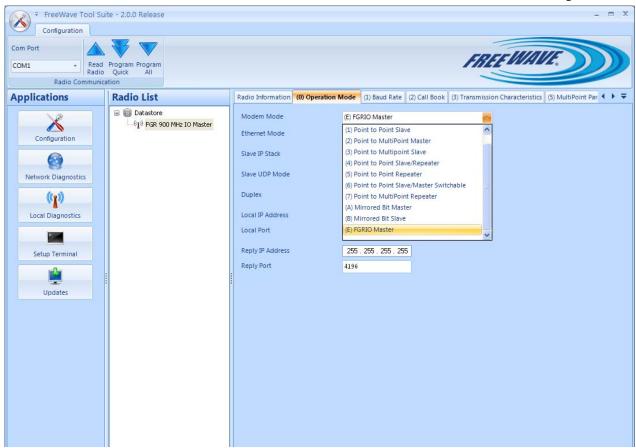
FGRIO Master—In order for the FGRIO System to function properly, the following settings must be programmed. For all other settings not listed below, please refer to the User Manual.

0) Set Operation Mode Tab-(Figure 13)

Point to MultiPoint Slave— Choose this setting when the FGRIO System is being integrated into an FGR FreeWave Network. The IO functionality is turned on under the IO Settings tab.

Note: Setting **(E), FGRIO Master**, should only be selected when the FGRIO System is operating independently of an FGR FreeWave Network.





2) Call Book Tab-

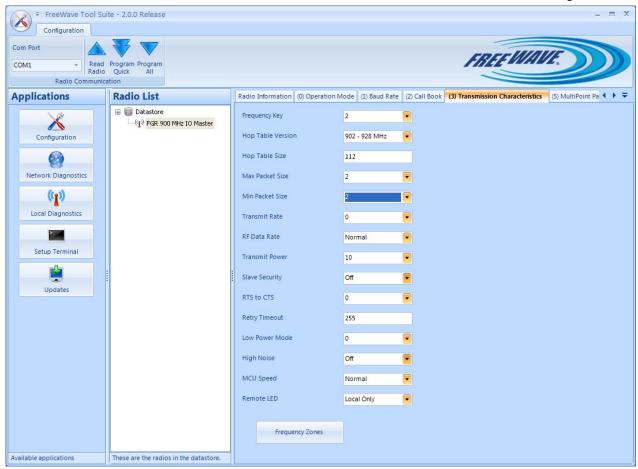
Enter the serial number for each IO Slave, for a maximum of up to four (4) IO-Slave Radios.

3) Radio Transmission Characteristics Tab-(Figure 14)

Max Packet Size and Min Packet Size—The FGRIO System requires a minimum combined packet size of 48 Bytes. See Figure 6 (pg. 10) for a list of available packet sizes.

RF Data Rate— The RF Data Rate must be set to "Normal" (3) when using the FGRIO System. This is for applications that are stand alone or when integrated into an existing FGR network.

Figure 14



5) MultiPoint Parameters Tab— (Figure 15)

Number Repeaters— This setting must be set to 1 for all FGR and FGRIO radios in the Network.

Network ID– In addition to entering the serial numbers of the IO Slaves in the Call Book, the Network ID being used for the Network must be set from 1-4095 (Do NOT use 255). Programming both the Call Book and Network ID settings is unique to the FGRIO System and must be done for both integrated and stand alone applications.

Note: The FGRIO Master does not function as a Slave/Repeater in the SCADA network.

5) MultiPoint Parameters Tab (cont.)

₹ FreeWave Tool Suite - 2.0.0 Release Configuration FRFFWAVE **Applications Radio List** ion (0) Operation Mode (1) Baud Rate (2) Call Book (3) Transmission Characteristics (5) MultiPoint Parameters Master Packet Repeat (1) FGR 900 MHz IO Slave (1) FGR 900 MHz IO Master Max Slave Retry Retry Odds Configuration (1) 931-0180 - FGR2 900 MHz IO Slav DTR Connect Repeater Frequency Network Diagnostics Network ID 25 Multi-Master Sync Off ((1)) 1 PPS Enable Delay 255 Slave/Repeater Off Local Diagnostics Diagnostics Radio ID Local Mode Radio Name IO Master Setup Terminal Subnet Updates Available applications These are the radios in the datastore

Figure 15

FGRIO Master

(9) IO Settings Tab- (Figure 16). This tab allows the user to map the inputs of the IO-Slave to the outputs of the FGRIO-Master.

Enable FGRIO– To turn on the IO functionality in the FGRIO-M, the "Enable FGRIO" drop down box must be set to enabled.

Mapping—In the IO Settings tab of the FGRIO-M, the FGRIO-M outputs are mapped to the IO-Slave inputs. To map, select the appropriate Slave input from the drop down box next to the master's output.

Note: The slaves are labeled by their position in the masters Call Book. E.g. Slave 0 refers to the serial number in entry to call 0.

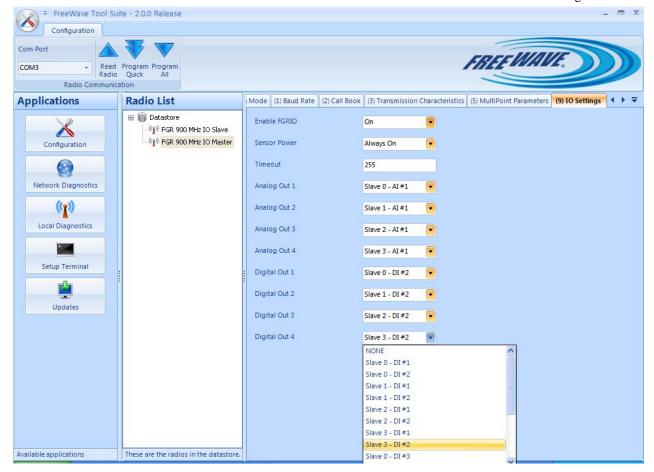
FGRIO Master (9)IO Settings Tab- (cont.)

Time Out– 0-255. This setting determines the amount of time to wait before issuing a Link Alarm due to loss of communication between the FGRIO Master and IO Slave.

A setting of 1 = 1/6 second 6 = 1 second 42 = 7 seconds 252 = 42 seconds

Sensor Power— Always On or Gated. A setting of Always On supplies continuous power to the sensor at the IO Slave. A setting of Gated, is used when the RTU provides a switched power output to control powering the sensors at the IO Slave and analog outputs of the FGRIO Master on and off.

Figure 16

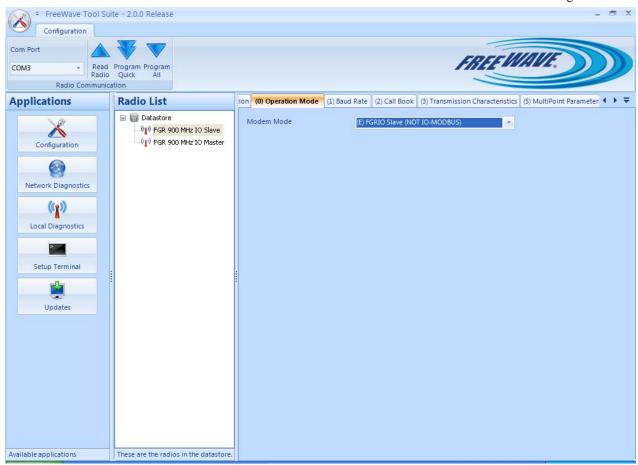


IO Slave- In order for the FGRIO System to function properly, the following settings must be programmed. For all other settings not listed below, please refer to the User Manual.

Set Operation Mode Tab- (Figure 17)

(E) FGRIO Slave— The modem mode of (E) IO-Slave (NOT IO-MODBUS) must be used in the FGRIO System.





(2) Call Book—The FGRIO Master's serial number must be programmed as entry #0 in the IO Slave's Call Book. Set "Entry to Call" to 0. In addition, the Network ID must be set to the same ID as the rest of the network. Programming both the Call Book and Network ID settings is unique to the FGRIO System and must be done for both integrated and stand alone applications.

IO Slave

Transmission Characteristics-(Figure 18)

Max Packet Size and Min Packet Size– The FGRIO System requires a minimum combined packet size of 48 Bytes. See Figure 6 (pg. 10) for a list of available packet sizes that can be used.

RF Data Rate - The RF Data Rate must be set to "Normal" (3) when using the FGRIO System. This is for applications that are stand alone or when integrated into an existing FGR network.

Retry Timeout– By lowering the Retry Timeout, the inactive link time between the FGRIO Master and IO Slave can be reduced when going from autonomous mode to connecting back to the FGR Network. If the Network Master goes down, the IO Master and Slave will continue to operate in autonomous mode. When the Network Master comes back up, the FRGIO Master will break the link with the IO Slave to reestablish a link with the Network Master. Once the FGRIO Master is linked to the Network Master, then the IO Slave will be able to link back to the FGRIO Master. With a lower Retry Timeout setting, it will take less time for the IO Slave to link to the FGRIO Master.

₹ FreeWave Tool Suite - 2.0.0 Release - 0 X Configuration Com Port FRFFWAVI **Applications** ion (0) Operation Mode (1) Baud Rate (2) Call Book (3) Transmission Characteristics (5) MultiPoint Parameters (9) M 🔸 🔻 **Radio List** Datastore Frequency Key (1) FGR 900 MHz IO Slave (1) FGR 900 MHz IO Master Hop Table Version Configuration (1) 931-0180 - FGR2 900 MHz IO Slav Hop Table Size Network Diagnostics Max Packet Size ((P)) Min Packet Size Local Diagnostics Transmit Rate 0 Transmit Power Slave Security Off RTS to CTS Updates Retry Timeout 64 High Noise Off MCU Speed Normal Frequency Zones These are the radios in the datastore Available applications

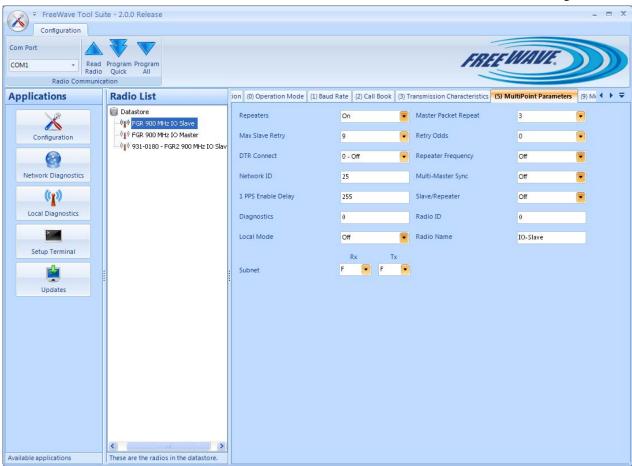
Figure 18

MultiPoint Parameters Tab-(Figure 19)

Number Repeaters- This setting must be set to "On" for all FGR and IO radios in the Network.

Network ID– In addition to entering the FGRIO Master's serial number in the Call Book, the Network ID being used for the Network must be set from 1-4095. (Do NOT use 255). Programming both the Call Book and Network ID settings is unique to the FGRIO System and must be done for both integrated and stand alone applications.





IO Slave

(9) Wire Replacement Tab (Figure 20)

Digital Out 1 – Select the desired FGRIO Master Digital Input # (1-4) to control the IO Slave Digital Output # 1.

Digital Out 2– Select the desired FGRIO Master Digital Input # (1-4) to control the IO Slave Digital Output # 2.

Digital Out 1 Default – Select the desired IO Slave Output Default at power-on and link failure.

Open Drain output ON (Conducting to GND, 2 Amps max)

Open Drain output OFF (Non-Conducting)

Make no change in state.

Digital Out 2 Default - Select the desired IO Slave Output Default at power-on and link failure.

Open Drain output ON (Conducting to GND, 2 Amps max)

Open Drain output OFF (Non-Conducting)

Make no change in state.

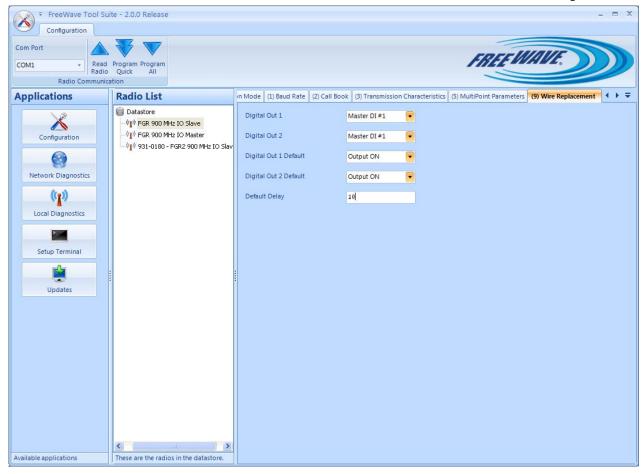
Note: If programming a DO to turn on after loss of link, ensure that the energized device can sustain the state undamaged in case the loss in lengthy.

Default Delay - This value is set in .28 second units. This sets the time duration that will pass, after a loss of communication, before the radio enters default condition. E.g. A value of 36 = 36*0.28 seconds = 10.08 seconds.

DI1 Pull Up/Down— These options control power-up states of the internal resistor (10Kohms) connected to the DIs. They can pull up, such as when using a closed-contact-to-GND switch input, pull down so that unused inputs read "0" as DIs or ~0 as auxiliary analogs, or float to not load analog inputs.

Note: Both of the IO Slave Digital Outputs may be driven by the same FGRIO Master Input.

Figure 20



Installation

IO Slave

(1) B+ IN

Screw Terminal #11 (B+ In) on the terminal block of the IO Slave is the raw power for the radio. This terminal is directly connected to Pin # 1 on the 10 pin white header of the IO Slave. Either one can be used to power the radio.

(2) 1-5 Volt Sensor

- For connection to either Analog Input 1 or Analog Input 2, the 1-5 volt sensor can be wired to the IO Slave with a 3 wire connection.
- The Sensor Ground Wire can be connected to Ground Screw Terminal #3, 9, or 12 on the terminal block of the IO Slave.
- •The Sensor Power Wire is connected to the VSNS screw terminal #7 on the terminal block of the IO Slave. Rated total current draw from VSNS is 40 mA or less.
- •Sensor Output Wire is connected to Analog Input 1 screw terminal #8 or Analog Input 2 screw terminal #10 on the terminal block of the IO Slave.



Installation

IO Slave

(2) 1-5 Volt Sensor (cont.)

• Sensor Output Wire is connected to Analog Input 1 screw terminal # 8 or Analog Input 2 screw terminal # 10 on the terminal block of the IO Slave.

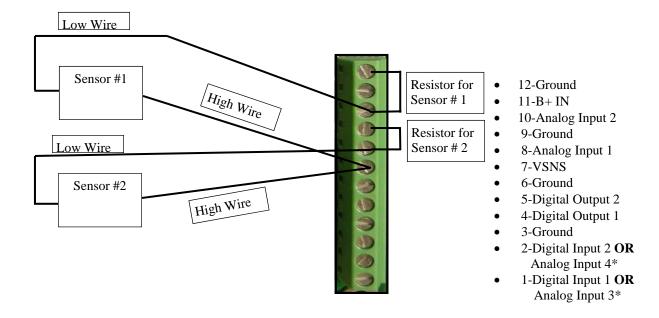
(3) 4-20 Milliamp Sensor (Figures 21-22)

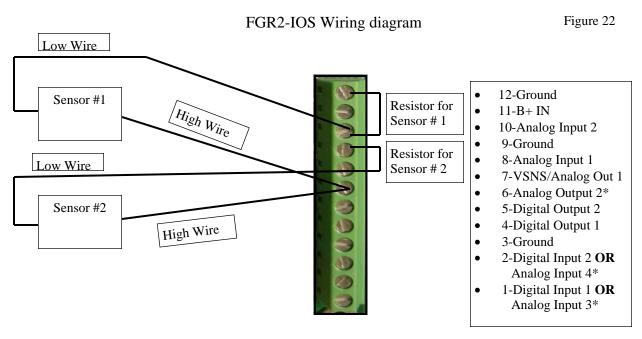
- Consists of a 2 wire connection from the Sensor to the IO Slave.
- An external resistor (typically 249 Ohms) is required to convert 4-20 milliamps to 1-5 volts. The resistor goes from the desired Analog Input to Ground screw terminals on the terminal block of the IO Slave.
- Sensor Power Supply (High) Wire is connected to VSNS screw terminal #7 on the terminal block of the IO Slave.
- Sensor Output (Low) Wire is connected to the same Analog Input as the resistor on the terminal block of the IO Slave.

Example of one 4-20 milliamp sensors connecting to the terminal block of the IO Slave: (Figures 21-22)

FGRIO-S Wiring diagram

Figure 21





Note: *Analog Output 2 is not available in the IO Wire Replacement mode. Analog inputs 3 and 4 are 0-3.3VDC inputs. See wiring diagrams on pages 29-31 for details.

(3) 1-5 Volt Sensor, Analog Input 3 or Analog Input 4

With FGRIO-S firmware 2.65IO or FGR2-IOS firmware 9.7, and FGRIO-M firmware 2.65, the Digital Inputs (DIs) of the FGRIO-S or FGR2-IOS may be digitized to 10 bit resolution and mapped to Analog Outputs (AOs) on the FRGIO-M. This allows up to 4 analog transducers to be connected to a single remote FGRIO-S or FGR2-IOS radio.

A. Signal Levels and Accuracy.

The existing AIs at screw terminal #8 and screw terminal #10 are usable with .1V to 5.625V input voltages (compatible with most 1-5V and 4-20mA transmitters) and load the input with about 100Kohm to GND. They also offer accuracy of +/-.1% with 16 bit resolution and are therefore recommended for the most critical variables in a system.

In comparison, the new AIs formed from the DIs at screw terminal #1 and screw terminal #2 are directly usable with signals only from .1V to 2.812V in wire replacement mode. Input loading can be selected as 10Kohm to GND or unloaded (>1Megohm). Accuracy is within +/-.25% and resolution is 10 bits. The next section describes methods to best apply inputs to them.

B. Signal Coupling for Analog Input 3 and Analog Input 4.

1) Input Resistor

The IO Slave DIs have always provided an internal 10Kohm resistor pull-up to the radio's 3.3V logic supply. With new firmware 2.65IO in the FGRIO-S, or 9.7 in the FGR2-IOS, the resistor can also be commanded (in the FGRIO Setup menu) to pull down to GND or "float" unconnected. As will be shown, these options are useful for connection of analog inputs.

2) Signal Level Reduction.

As stated above, the DI does not have sufficient voltage range for direct connection to typical transducer outputs, so the input must be restricted. For signal replication, it is assumed the input signal level will be halved, and the measured value sent to the FGRIO-M doubled, to achieve an overall 1:1 signal reproduction.

3) VSNS Sensor Power

The switched voltage source at screw terminal #7 is designed to drive only two 4-20mA transmitters to full scale. Voltage output (1-5V) transmitters usually consume less current and may allow up to 4 to be switched.

Below are two diagrams showing the connection of a 1-5V sensor to Analog Input 3: (Figures 23 and 24)

Figure 23

Connection for 1-5V Transmitter

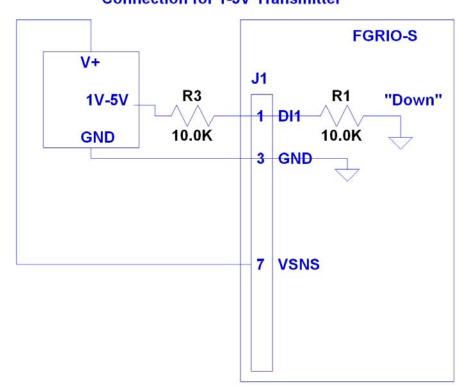
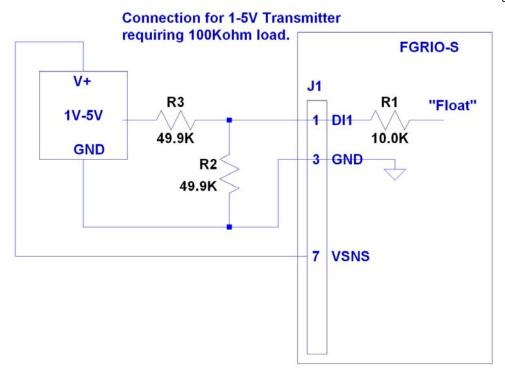


Figure 24



(4) 4-20 Milliamp Sensor, Analog Input 3 or Analog Input 4

The same accuracy and signal level reduction considerations stated under section (3) 1-5 Volt Sensor, Analog Input 3 or Analog Input 4, apply when using a 4-20 milliamp sensor. The switched voltage source at screw terminal #7 is designed to drive only two 4-20mA transmitters to full scale. If a system will use more than two, the additional transmitters must be powered from a separate supply, such as directly from the battery or another DC supply.

On the next page are two diagrams showing the connection of a 4-20 milliamp sensor to Analog Input 3 (Figures 25 and 26):



(4) 4-20 Milliamp Sensor, Analog Input 3 or Analog Input 4

Figure 25

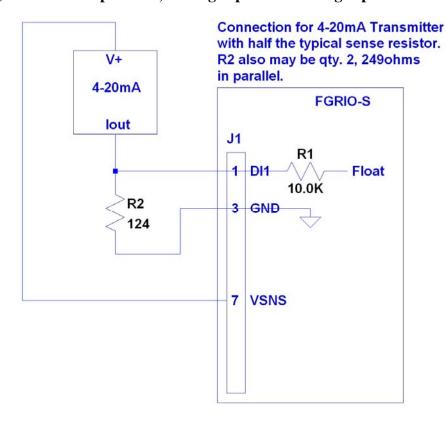
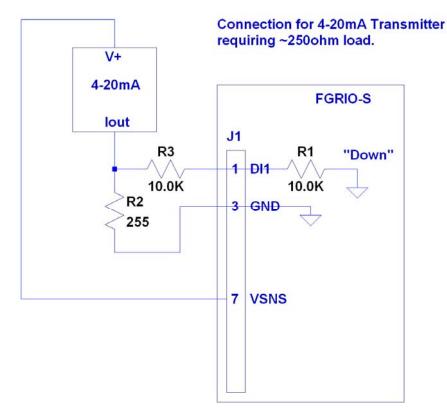


Figure 26



IO Slave

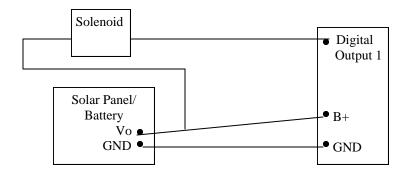
(5) Digital Input

- Switch Output Wire is connected to Digital Input 1 screw terminal # 1 or Digital Input 2 screw terminal # 2 on the terminal block of the IO Slave.
- Switch Ground Wire is connected to Ground screw terminal # 3, 9 or 12 on the terminal block of the IO Slave.
 If the Switch Ground Wire is not returned to the IO Slave, the potential difference
 - between the IO Slave Ground and the Dry Contact Closure (Switch) Ground should not exceed 1 Volt.
- In the case of a 3 wire digital transducer, set up similarly to the 1-5V analog sensor, except with the signal wire connected to a Digital Input.

(6) Digital Output

- Digital Output is an open drain field effect transistor connected to Ground. It connects to Ground when zero volts is connected to the controlling Master Digital Input.
- The current rating for Digital Output is 2 amps or less. The Digital Output will self-protect if a current of more than 2 1/2 amps is drawn and automatically retry at .16 second intervals.
- If power on the Solenoid (end device) is not driven from the same power supply as the IO Slave, that source must be equal to or less than the IO Slave power supply voltage. Within the IO Slave, a 3 amp rated Schottky Diode is connected from each Digital Output to the radio power supply terminal for clamping the Solenoid fly back current. If the relay supply voltage exceeded the radio supply voltage, then current would flow through that diode back to the radio, preventing coil current from shutting off and potentially causing an overvoltage condition.

Typical set up of Digital Output wiring between Solenoid and IO Slave:



Terminal Block of IO Slave

FGRIO Master

(1) Rx, Tx, B+

• Receive, Transmit, and Power are available on screw terminals of the FGRIO Master terminal block as well as the 10 pin header.

(2) Analog Output

- The Analog Output wire is connected from the Analog Output 1,2,3 or 4 screw terminal on the FGRIO Master terminal block to the Analog Input of the RTU (destination device).
- Common Ground is required. It is recommended to run a Ground wire from an FGRIO Master Ground screw terminal to Ground on the RTU.

NOTE: Analog Output is 1-5 V at low current, so any 4-20 mA current sensing resistor on the RTU MUST BE REMOVED. If in doubt as to whether RTU-internal resistors are active, test the link with a full scale input.

(3) Digital Output

- The Digital Output wire is connected from the Digital Output 1,2,3 or 4 screw terminal on the FGRIO Master terminal block to the Digital Input of the RTU (destination device).
- Common Ground is required. It is recommended to run a Ground wire from the FGRIO Master Ground screw terminal to Ground on the RTU.

NOTE: The Digital Output actively drives Low (.4V) and High (4.0V). Remove any RTU input pull-up resistor, if less than 10 K ohms. Verify that signal levels meet the RTU input requirements after connection to the RTU.

(4) Digital Input

- The RTU Digital Output Wire is connected to Digital Input 1,2,3 or 4 screw terminal on the terminal block of the FGRIO Master. An internal 10Kohm pullup to +5V is provided.
- The RTU Ground Wire is connected to any of the Ground screw terminals on the terminal block of the FGRIO Master. Some RTUs use isolated I/O and may require a ground connection for each input and output.

(5) Sensor Power

- To minimize power drain of the IO Slave Solar/Battery System, an input terminal called Sensor Power is provided on the FGRIO Master terminal block. Sensor Power has an internal 10 Kohm pull-down to Ground.
- If the RTU provides a switched sensor power output, connect it to this terminal. Verify that the level at Sensor Power falls to < 1.0 V when de-asserted to ensure the slaves will mirror. If not, connect additional pull-down resistance externally.



FGRIO Master

- (5) Sensor Power (cont.)
 - The state of that sensor power will be mirrored at the IO Slave, powering the sensors at the IO Slave on and off. It is necessary to change FGRIO Setup sub menu (A) to "1" (Gated).

NOTE: The sensor power terminal both activates sensor power at the controlled IO Slaves, and activates Analog Outputs at the FGRIO Master interface board, when in Sensor Power "Gated" mode.

(6) Link Alarms

- Link Alarm 1 is an alarm reflecting loss of communication on any path. A wire is run from the Link Alarm 1 screw terminal to the Link Alarm screw terminal on the RTU.
- Link Alarm 2 (CMD Alarm) indicates that a Digital Output or Sensor Power command was not carried out due to an over-current fault. A wire is run from the Link Alarm 2 screw terminal to the Link Alarm screw terminal on the RTU.

NOTE: The terminal block of the FGRIO Master and Slave can accept a single wire up to 16 gauge. Smaller wire is required for 2 wires, or wire + resistor into the same screw terminal.

Frequently Asked Questions

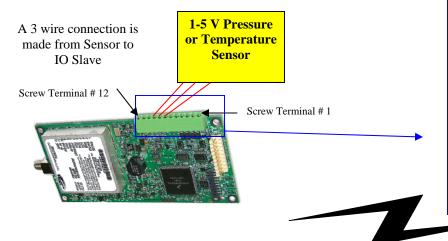
- **Q:** Can IO be used with a 1 watt radio?
- **A:** The FGRIO Master operates as a standard FGR 1 watt radio with a 60 mile line of sight range. The FGRIO Slave functions as an FGR radio with a 2 mile line of sight range. The FGR2-IO Slave functions as an FGR radio with a 60 mile line of sight.
- **Q:** Can the IO radios be repeated through our other radios to extend the range?
- **A:** From the IO Slave to the FGRIO Master, repeaters cannot be used. From the FGRIO Master to the rest of the existing network, repeaters can be used as they already are in existing FreeWave networks. The FGRIO Master will not function as a Slave/Repeater
- **Q:** Can the FGRIO Master operate as Slave/Repeater in the overall network?
- **A:** The FGRIO Master currently does not have the capability to operate as a Slave/Repeater. It does function as the Master to the IO Slave, and as a Slave to the rest of the network.

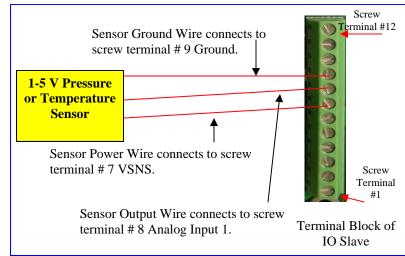


Frequently Asked Questions

- **Q:** Can data be sent directly from the IO Slave to the Master of the FreeWave network?
- **A:** No. The FGRIO system functions as wire replacement only. The IO Slave does not have the capability of transmitting data directly to the Master of the network.
- **Q:** What are the sizes of the FGRIO Master and Slave?
- **A:** The board level IO Slave has the same footprint as the FGRO9 family. The board level IO Slave dimensions are 127 mm (L) x 61 mm (W) x 15.5 mm (H). The FGRIO Master is a standard footprint FGRO9 plus an IO Interface board on top, differing only in width at 2.75 inches. The dimensions of the FGRIO Master are 140 mm (L) x 70 mm (W) x 34 mm (H).
- **Q:** What timing issues does IO introduce?
- **A:** Although IO mimics a wired connection, the electronics and communication heartbeat do cause some signal delay. The worst case delay for digital signals in either direction and the Sensor Power command from FGRIO Master to IO Slave is 167 msec, assuming a robust link. Worst case delay from FGRIO Master Sensor Power assertion to FGRIO Master Analog Output refresh is 700 msec.

FGRIO Wiring Diagram



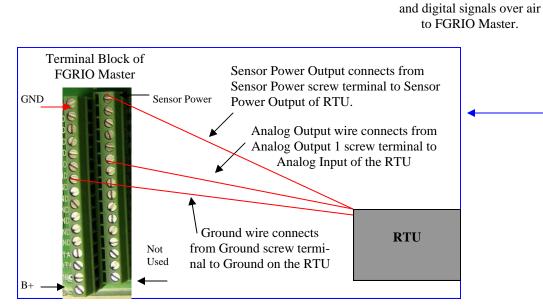


Sensor

Power

GND

IO Slave transmits analog



Not B+Used A 2 wire connection for analog output is made from FGRIO Master to the RTU. Sensor Power should also **RTU**

be connected if available.

Technical Specifications 900 MHz Transceiver Specifications

n	
902	o 928 MHz
ver FGR	IO-M: 5 mW to 1 W (+30 dBm) FGRIO-S: 100 mW (+20 dBm).
FRO	2-IOS: 5mW to 1W (+30 dBm)
2 mi	les Line Of Sight for FGRIO-S to FGRIO-M
60 n	illes Line of Sight for FGRIO-M to Network or FGRIO-M to FGR2-IOS
Spre	ad spectrum GFSK, 120 Kbps
method Freq	uency hopping
andwidth @ 60dB 230	kHz
pacing 230	kHz
FGR	IO-M or FGR2-IOS: -110 dBm at 10-4 bit error rate; FGRIO-S: -100 dBm
FGR	IO-M or FGR2-IOS: -108 dBm at 10-6 bit error rate; FGRIO-S: -98 dBm
	IB at f _c ± 115 kHz
	IB at $f_c \pm 145$ kHz
n FGR	IO-M or FGR2-IOS: 140 dB FGRIO-S: 130 dB
nission	
80 k	pps sustained throughput*
32 B	it CRC, retransmit on error
ption Subs	titution, dynamic key
aroughput 80 K	Baud
RS-2	232/RS485 1200 Baud to 230.4 KBaud, async, full duplex
irements	
tage FGR	IO-M or FGR2-IOS: 6 to 30 VDC; FGRIO-S: 6-20 VDC
urrent at full power 6 VI	OC: FGRIO-M: 1000mA FGRIO-S: 125 mA FGR2-IOS: 800 mA
-	DC: FGRIO-M: 500 mA FGRIO-S: 70 mA FGR2-IOS: 380 mA
30 V	DC: FGRIO-M: 200 mA FGR2-IOS: 170 mA
	OC: FGRIO-M: 140 mA FGRIO-S: 64mA FGR2-IOS: 90 mA
	DC: FGRIO-M: 75 mA FGRIO-S: 38 mA FGR2-IOS: 50 mA FGR2-IOS: 26 mA
	DC: FGRIO-M: 37 mA FGRIO-S: 24 mA FGR2-IOS: 24 mA
	DC: FGRIO-M: 21 mA FGRIO-S: 14 mA FGR2-IOS: 15 mA
	DC: FGRIO-M: 16 mA FGR2-IOS: 8 mA
nt 6 VI	OC: FGRIO-M: 12 mA
12 V	DC: FGRIO-M: 6 mA
30 V	DC: FGRIO-M: 5 mA
	t-to-Point
30 V modes Poin Poin FGR	DC: FGRIO-M: 5 mA

^{*} At 100% receive success rate.



	FGRIO-M	FGRIO-S	FGR2-IOS
Data Port	10-pin PCB connector	10-pin PCB connector	10-pin PCB connector
Enclosure	Bare board	Bare board	Bare board
Dimensions	140 mm (L) x 70 mm (W) x 34 mm (H)	127 mm (L) x 61 mm (W) x 15.5 mm (H)	127 mm (L) x 62 mm (w) x 16 mm (H)
Weight	140.85 g	47.0 g	58.0 g
Power requirements	§ 6-30 VDC	§ 6-20 VDC	§ 6-30 VDC
	§ May be powered through pin "B+ IN" of terminal block, or pin 1 of Data Port.	§ May be powered through pin 11 of termi- nal block, or pin 1 of Data Port.	§ May be powered through pin 11 of terminal block, or pin 1 of Data Port.
Antenna	SMA female connector. External antenna required.	SMA female connector. External antenna required.	SMA female connector. External antenna required.
FCC Identifier	KNY-6231812519	KNY-6231812519	KNY-6231812519
DOC Identifier	2329B-DGR09RAS	2329B-DGR09RAS	2329B-DGR09RAS

Analog Signals	
Number of Signals	FGRIO-S or FGR2-IOS: up to 4 Inputs; FGRIO-M: 4 Outputs; 1 to 4 -S per -M
Analog Input Range, Resistance, Bandwidth	Analog Input 1 and 2:0-5.625V, 94Kohms, 67Hz Lowpass filter and 50/60Hz Notch Analog Inputs 3 and 4: 0-3.3V
Master + Slave System Resolution	Analog Inputs 1 and 2:16 Bits; .0015% of FS Analog Inputs 3 and 4: 10 Bits
Master + Slave System Initial Accuracy @ +25°C	.1% of FS
Master + Slave System Temperature Drift	.14% of FS change from +25°C at -40°C or +75°C
Master + Slave System Aging Drift	.05% of FS at 6 mos., .1% at 2yrs.
Digital Signals: FGRIO-M	
Number of Inputs, Outputs	4 Inputs, 4 Outputs
Input Structure Input Threshold Low Input Threshold High Slave Input to Master Output Delay Input Applied Voltage Range ESD Immunity: Human Body Model ESD Immunity: Machine Model	9.4Kohm pull-up to 5V with in-line 8kHz Lowpass filter 1.75V Max. 3.25V Min .16 sec. Max. +/- 30V 15 KV 8 KV
Output Voltage High (lout < 10 uA) Output Voltage Low (lout < 10 uA) Output Voltage High (lout = 2 mA) Output Voltage Low (lout = 2.4 mA)	4.7V 0.2V 3.75V 0.4V
Digital Signals: FGRIO-S or FGR2-IOS	
Number of Inputs, Outputs	2 Inputs, 2 Outputs
Input Structure Input Threshold Low Input Threshold High Slave Input to Master Output Delay Input Applied Voltage Range ESD Immunity: Human Body Model ESD Immunity: Machine Model	10Kohm pull-up to 3.3V with 10nF Debounce capacitor 1.2V Min. 2.3V Max16 sec. Max. +/- 30V 15 KV 8 KV
Output Structure Output Voltage range Output Current Sinking Output Default	Non-arcing Open-Drain FET to GND with flyback diodes 0V to Supply Voltage > 2.0 Amps; shutdown at < 2.5 Amps; 166 msec retry Programmable link-loss timeout and default state

Sensor Power: FGRIO-M	
Input Structure Input Threshold Low Input Threshold High Master Input to Slave Output Delay Input Applied Voltage Range ESD Immunity: Human Body Model ESD Immunity: Machine Model	10Kohm and 4.7uF pull-down to GND 1.75V Max. 3.25V Min .16 sec. Max. +/- 30V 15 KV 8 KV
Sensor Power: FGRIO-S or FGR2-IOS	
Output Structure Output Current ESD Immunity: Human Body Model ESD Immunity: Machine Model	Open-Drain FET to B+ In, with 10nf and flyback diodes > 40mA; shutdown at < 50mA; 166 msec retry. 15 KV 8 KV

For questions or Technical Support pleas contact FreeWave technical support at: 303 381 9200 or moreinfo@freewave.com