ELECTROSPEED
INTEGRATED CONTROL SYSTEM
2060 VT DRIVE ID

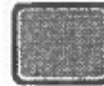POWER ON   RUN   FAULT   UNDERLOAD   OVERLOAD

Left margin notes (box A):

```
w meter
Jog        A
rt. Type   PNP
ing        Direct
nal        4-20 mA
ts         GPm
e          ⊙
in         match Flow meter
p Gain     2.0%
Gain       2.0%
riv Gain   00.0%
w Alrm     00.0
gh Alrm
rm Del     000 At bypass
```

Left margin notes (box B):

```
alog       B
rt. Type
ting
gnal
its
re
en
rp Gain
t Gain
eriv Gain
ow Alrm
igh Alrm
rm Del
```

START	Don't Change. MODEL — Name Plate SF. OVERLOAD — 8 sec. TRIP TIME	Namplate Volts VOLTS AT 60 HZ — 10 START FREQUENCY	00.5 SYNC DELAY — HIGH SPEED CLAMP	LOW SPEED CLAMP — 000 V00Hz V BOOST
OFF	Motor SF. Amp. I LIMIT — 10% over I limit I LIMIT SYNC	000V @ 0 Hz V BOOST SYNC — 480 V CLAMP	ACCEL TIME — DECEL TIME	70 % REGULATOR GAIN — .2 SLIP COMP
MODE 1	FAULT — ⟳ RESTARTS — 2 sec MIN RESTART — 5 min MIN RESET	Running Amps x8 ULNDERLOAD AMPS — 02 min reset MIN RESTART — 000 UL reset RESTARTS — 20 sec UL SEC UL TRIP	SET FREQUENCY — Manual SP. KEYPAD — 43.6 Hz A cnt rL SPEED POT	SET POINT Flow meter Pace ANALOG A — ANALOG B — 10.0 Hz JOG FREQUENCY
MODE 2 Power from Flow meter To Pace	ANALOG CONTROL SETUP	CLOCK DRIVE HISTORY	FREQUENCY AVOIDANCE OUTPUT ROTATION	↑
ENTER	DISPLAY OUTPUT AMPS/VOLTS	DISPLAY ANALOG INPUTS	DISPLAY STATUS	↓

CENTRILIFT

ICS OPERATOR INTERFACE KEYPAD