

ELECTROSPEED

INTEGRATED CONTROL SYSTEM

2060 VT DRIVE ID

POWER
ON



RUN



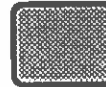
FAULT



UNDERLOAD



OVERLOAD



Analog A
 Cntrl. Type _____
 Acting _____
 Signal _____
 Units _____
 Zero _____
 Span _____
 Prop Gain _____
 Int Gain _____
 Deriv Gain _____
 Low Alarm _____
 High Alarm _____
 Alarm Del _____

START	MODEL OVERLOAD TRIP TIME	VOLTS AT 60 HZ START FREQUENCY	SYNC DELAY HIGH SPEED CLAMP	LOW SPEED CLAMP V BOOST
OFF	I LIMIT I LIMIT SYNC	V BOOST SYNC V CLAMP	ACCEL TIME DECEL TIME	REGULATOR GAIN SLIP COMP
MODE 1	FAULT RESTARTS MIN RESTART MIN RESET	UNDERLOAD AMPS MIN RESTART RESTARTS SEC UL TRIP	SET FREQUENCY KEYPAD SPEED POT	SET POINT ANALOG A ANALOG B JOG FREQUENCY
MODE 2	ANALOG CONTROL SETUP	CLOCK DRIVE HISTORY	FREQUENCY AVOIDANCE OUTPUT ROTATION	
ENTER	DISPLAY OUTPUT AMPS/VOLTS	DISPLAY ANALOG INPUTS	DISPLAY STATUS	

Analog B
 Cntrl. Type _____
 Acting _____
 Signal _____
 Units _____
 Zero _____
 Span _____
 Prop Gain _____
 Int Gain _____
 Deriv Gain _____
 Low Alarm _____
 High Alarm _____
 Alarm Del _____



ICS OPERATOR INTERFACE KEYPAD