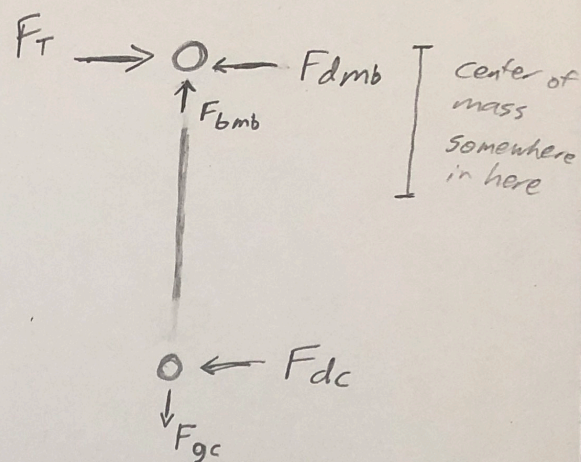
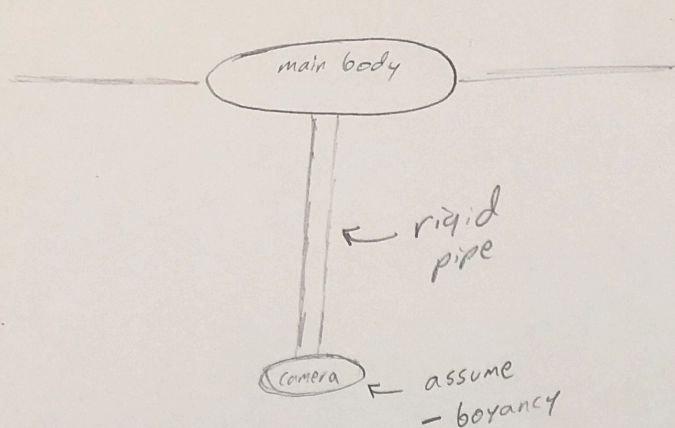
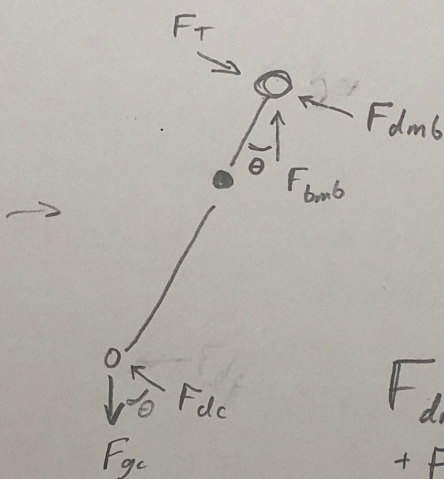
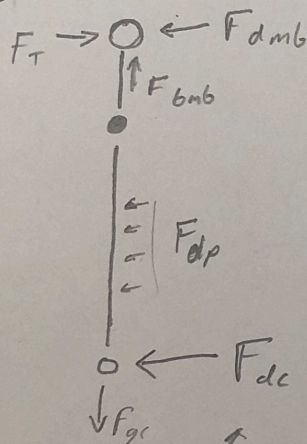


# FDs of Robotics Project



e.g.  
 $w_{mb} = 3w_c$



either

$$F_{dmb} = 3F_{dc} + F_T$$

or

$$F_{dmb} + F_{bmb} \sin \theta = 3F_{dc} + F_T + F_{gc} \cos \theta$$

This is troublesome..

addition of wings to redirect drag from causing moment