くなだ。時間発展が計算できる 状態の時間発展が計算できる 〈揺動論の基礎〉 解ける問題は少ない・・・ 理動論 解出問題,+为ずか方変更」を近似的に解く 一般的方意定 H。当年理動いシルトニアン(もとのいミルトニアン) (1) $\frac{1}{1} \hat{H}_{0} | \mathcal{Y}_{n}^{(0)} \rangle = E_{n}^{(0)} | \mathcal{Y}_{n}^{(0)} \rangle \qquad n = 1.2, \dots$ {[90]}}n=1,2,.... は正規直交完全系 ンこのかわか、Z113とする (2) H=H。+及V的固有值、固有状態を近似的一元为3 けない 110519-

多緒足のなり工人は一国有状態への揺動

j=1,2,...をひてつ固定 → $E_j^{(0)}$ は縮化していなりと仮定

(1) H|Y; >= E; |Y; > となる E; と |Y; > を たっトで 未必る

(2) $\lambda \rightarrow 0$ ご $(9;) \rightarrow (9;)$ を要請

p 入につp 2 万 p 3 万 p 5 p 4 p 3 p 5 p 6 p 6 p 6 p 6 p 6 p 6 p 6 p 6 p 6 p 7 p 6 p 7 p 7 p 7 p 8 p 9

(3)
$$E_{j} = E_{j}^{(0)} + \lambda E_{j}^{(1)} + \lambda^{2} E_{j}^{(2)} + \cdots$$

$$(4) |9_{j}\rangle = |9_{j}^{(0)}\rangle + \lambda |9_{j}^{(0)}\rangle + \lambda^{2} |9_{j}^{(2)}\rangle + \cdots$$
##RACIACE(1) = ##RETINZ(1)

(S) $\langle 9_j^{(0)} | 9_j^{(h)} \rangle = 0$ h=1,2,... と仮定 L2 f(1)

(1)
$$E_{j} = E_{j}^{(0)} + \lambda E_{j}^{(1)} + \lambda^{2} E_{j}^{(2)} + \cdots$$

(2) $|\mathcal{G}_{j}\rangle = |\mathcal{G}_{j}^{(0)}\rangle + \lambda |\mathcal{G}_{j}^{(1)}\rangle + \lambda^{2} |\mathcal{G}_{j}^{(2)}\rangle + \cdots$

Schrödinger 方程寸 (3) (Ho+2V)1分= $E_{j}1分$ に代入

$$(4) \left(\widehat{H}_{0} + \lambda \widehat{V} \right) \left(| \mathcal{Y}_{j}^{(0)} \rangle + \lambda | \mathcal{Y}_{j}^{(0)} \rangle + \lambda^{2} | \mathcal{Y}_{j}^{(2)} \rangle + \cdots \right)$$

$$= \left(E_{j}^{(0)} + \lambda E_{j}^{(1)} + \lambda^{2} E_{j}^{(2)} + \cdots \right) \left(| \mathcal{Y}_{j}^{(0)} \rangle + \lambda | \mathcal{Y}_{j}^{(0)} \rangle + \lambda^{2} | \mathcal{Y}_{j}^{(2)} \rangle + \cdots \right)$$

尾角に λ の包ェの次数をみる

0元 (5) $\hat{H}_0(9_i^{(0)}) = E_i^{(0)}(9_i^{(0)}) \longrightarrow \xi_{0,23}$

$$1= \mathcal{R} \quad (6) \ \widehat{H}_{0} \left(\varphi_{j}^{(i)} \right) + \widehat{V} \left(\varphi_{j}^{(o)} \right) = E_{j}^{(o)} \left(\varphi_{j}^{(i)} \right) + E_{j}^{(i)} \left(\varphi_{j}^{(o)} \right)$$

$$\frac{2\pi}{2\pi} (3) \left(\frac{1}{2} \right) \left(\frac{1}{2} \right) \left(\frac{1}{2} \right) + \left(\frac{1}{2} \right) \left(\frac{1}{2} \right$$

$$P_{3}-(6)$$
 (1) $\hat{H}_{0}[9_{j}^{(0)}]+\hat{V}[9_{j}^{(0)}]=E_{j}^{(0)}[9_{j}^{(0)}]+E_{j}^{(0)}[$

$$\hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{E}_{j}^{(0)} \langle \mathcal{P}_{j}^{(0)} | \mathcal{Y}_{j}^{(0)} \rangle = 0 \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{F}_{0} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{I}^{\alpha} \qquad \hat{A}^{\dagger} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} = \hat{A} \, \mathcal{I}^{\alpha} \qquad \qquad \hat{A}^{\dagger} \qquad \qquad \hat{A}^{\dagger} \qquad \hat{A}^{\dagger} \qquad \qquad \hat{A}^{\dagger} \qquad \hat{A}^{\dagger}$$

工才(げ)一固有值の神匠

(5)
$$E_j = E_{j0} + \langle g_{j0} | \lambda \sqrt{|g_{j0}\rangle} + O(\lambda^2)$$

 $H = H_0 + \lambda \hat{V}$

 $(7) | \mathcal{G}_{j}^{(0)} \rangle = \sum_{n=1}^{\infty} \frac{\langle \mathcal{G}_{n}^{(0)} | \hat{\mathcal{V}} | \mathcal{G}_{j}^{(0)} \rangle}{E_{j}^{(0)} - E_{n}^{(0)}} | \mathcal{G}_{n}^{(0)} \rangle = \sum_{n=1}^{\infty} \frac{| \mathcal{G}_{n}^{(0)} \rangle \langle \mathcal{G}_{n}^{(0)} | \hat{\mathcal{V}} | \mathcal{G}_{j}^{(0)} \rangle}{E_{j}^{(0)} - E_{n}^{(0)}} | \mathcal{G}_{n}^{(0)} \rangle \langle \mathcal{G}_{n}^{(0)} | \hat{\mathcal{V}} | \mathcal{G}_{n}^{(0)} \rangle \langle \mathcal{G}_{n}^{(0)} | \mathcal{G}_{n}^$

 $(3) \ 20 = E_{(0)} \langle \partial_{(0)} | \partial_{(1)} \rangle + E_{(1)} \langle \partial_{(0)} | \partial_{(0)} \rangle + E_{(2)} \langle \partial_{(0)} | \partial_{(0)} \rangle$

 $(4) \quad E_{i}^{(2)} = \langle \mathcal{G}_{j}^{(0)} | \mathcal{V} | \mathcal{G}_{j}^{(0)} \rangle$ $\frac{\sum_{n=1}^{\infty} \frac{\langle y_{n}^{(0)} | \hat{y}_{n}^{(0)} \rangle \langle y_{n}^{(0)} | \hat{y}_{j}^{(0)} \rangle}{E_{j}^{(0)} - E_{n}^{(0)}} = \sum_{n=1}^{\infty} \frac{|\langle y_{n}^{(0)} | \hat{y}_{j}^{(0)} \rangle|^{2}}{E_{j}^{(0)} - E_{n}^{(0)}}$ $\frac{\sum_{n=1}^{\infty} \frac{|\langle y_{n}^{(0)} | \hat{y}_{j}^{(0)} \rangle|^{2}}{E_{j}^{(0)} - E_{n}^{(0)}}$ $\frac{\sum_{n=1}^{\infty} \frac{|\langle y_{n}^{(0)} | \hat{y}_{j}^{(0)} \rangle|^{2}}{E_{j}^{(0)} - E_{n}^{(0)}}$ $\frac{\sum_{n=1}^{\infty} \frac{|\langle y_{n}^{(0)} | \hat{y}_{j}^{(0)} \rangle|^{2}}{E_{j}^{(0)} - E_{n}^{(0)}}$ En (n+1) (J=1 (基位状態)なら (2次理動で、 からるる、エネルギーハッ

(1)
$$\hat{H}_{0}[9_{n}^{(0)}] = E_{n}^{(0)}[9_{n}^{(0)}] \qquad n=1,2,...$$
 $\hat{J} \in \mathcal{V} \times \mathbb{D}$ $\mathbb{R} \rightarrow E_{j}^{(0)}[g_{j}^{(0)}] \times \mathbb{R}$ \mathbb{R} \mathbb{R}

(5)
$$\hat{H}_{0} - \hat{E}_{j}^{(0)} = \sum_{N=1}^{\infty} (\hat{E}_{N}^{(0)} - \hat{E}_{j}^{(0)}) | \mathcal{Y}_{N}^{(0)} \rangle \langle \mathcal{Y}_{N}^{(0)} | F')$$

(6) $\hat{W}_{j}(\hat{H}_{0} - \hat{E}_{j}^{(0)}) = -\sum_{N=1}^{\infty} |\mathcal{Y}_{N}^{(0)} \rangle \langle \mathcal{Y}_{N}^{(0)} | = |\mathcal{Y}_{j}^{(0)} \rangle \langle \mathcal{Y}_{j}^{(0)} | - \hat{1}$

(7) $\hat{W}_{j}(\hat{H}_{0} - \hat{E}_{j}^{(0)}) | \mathcal{Y}_{j}^{(m)} \rangle + \hat{W}_{j} \hat{V} | \mathcal{Y}_{j}^{(m-1)} \rangle = \sum_{N=1}^{\infty} \hat{E}_{j}^{(m-k)} \hat{W}_{j} | \mathcal{Y}_{j}^{(k)} \rangle$

(8) $|9^{(m)}\rangle = W_{j}V(9^{(m-1)}) - \sum_{k=1}^{m-1} E_{j}^{(m-k)}W_{j}(9^{(k)})$

(3) $\hat{W}_{j} = \sum_{n=1}^{\infty} \frac{|\mathcal{Y}_{n}^{(0)}\rangle\langle\mathcal{Y}_{n}^{(0)}|}{|\mathcal{Y}_{n}^{(0)}\rangle\langle\mathcal{Y}_{n}^{(0)}|}$ 文定素 由 $\frac{1}{2}$ 日 $\frac{1}{$

P8-(2) (2) $E_{j}^{(m)} = \langle \mathcal{G}_{j}^{(0)} | \hat{\mathcal{V}} | \mathcal{G}_{j}^{(m-1)} \rangle$ (1),[2]の石辺には M-1 以下の量のみが現める 一二山を次で角に12()けばよい、 (3) $|\mathcal{G}_{j}^{(2)}\rangle = \hat{W}_{j}\hat{V}|\mathcal{G}_{j}^{(0)}\rangle - E_{j}^{(0)}\hat{W}_{j}|\mathcal{G}_{j}^{(0)}\rangle$

$$= \sum_{\substack{(N,N'=1)\\ (N+N')}} \frac{|\varphi_{(0)}\rangle \langle \varphi_{(0)}| \sqrt{|\varphi_{(0)}\rangle \langle \varphi_{(0)}\rangle \langle \varphi_{(0)}| \sqrt{|\varphi_{(0)}\rangle \langle \varphi_{(0)}| \sqrt{|\varphi_{$$

P8-(8) (1) $|9|(m) > = W_j \hat{V}(9,(m-1)) > - \sum_{k=1}^{m-1} E_j(m-k) \hat{W}_j(9,(k))$

 $(4)^{n} \stackrel{\text{\tiny [3)}}{\vdash} \stackrel{\text{\tiny [3)}}{\vdash} = \langle \mathcal{G}_{j}^{(n)} \rangle \sqrt{\langle \mathcal{G}_{j}^{(n)} \rangle}$ $=\sum_{n=0}^{\infty}\langle 9_{i}^{(0)}|\hat{\mathcal{V}}|9_{n}^{(0)}\rangle\langle 9_{n}^{(0)}|\hat{\mathcal{V}}|9_{n}^{(0)}\rangle\langle 9_{n}^{(0)}|\hat{\mathcal{V}}|9_{i}^{(0)}\rangle$ $(E_{j}^{(0)} - E_{n}^{(0)})(E_{j}^{(0)} - E_{n}^{(0)})$ $-(9;0)/\hat{V}(9;0)>\sum_{n=1}^{\infty}(9;0)\hat{V}(9;0)<9;0)\hat{V}(9;0)>$ $(E_{i}^{(0)}-E_{i}^{(0)})^{2}$

などなど

多缩退(21)3工术(书)固有低、固有优整力的理動 10 $P[-(1) (1) \hat{H}_{o} | \hat{y}_{n}^{(0)}) = E_{(0)}^{(0)} | \hat{y}_{n}^{(0)} \rangle$ 2重緒足 ある jについと Ejo) = Ejt (neの Eno) は要を3) とある 医最低次の理動 H=Ho+XVの回轴 (2) $|\Psi_{l}\rangle = |\mathcal{Y}_{j}^{(0)}\rangle$ $|\Psi_{2}\rangle = |\mathcal{Y}_{j+1}^{(0)}\rangle \times \mathbb{E}\langle \longrightarrow (3)\langle \Psi_{k}|\Psi_{k}\rangle = S_{k,k}(k,l=1,2)$ 2017 (6) Holy (0) + a VIV, 7+ B VIV2) = E; (9) (900) + E a (4) 7+ EB (4)

(1) Holy(1)+ aV/14/2+BV(42) = E(0)(900) + Ea(4)+ EB(42)

| Ψ_1 > Ψ_2 (いの内積 → (2) Ψ_2 (1) Ψ_1 > Ψ_2 (1) Ψ_2 > Ψ_3 (2) Ψ_4 (1) Ψ_4 > Ψ_4

多担動計算の何り 一人工的な何題 血縮退のなり場合

• 当年理動系 ハミルトニアン (2) $H_0 = \frac{\beta^2}{2m} = -\frac{\hbar^2}{2m} \frac{d^2}{dx^2}$ Schrödinger 万程寸 (3) $-\frac{t^2}{zm}9''(x) = E9(x)$

Schrödinger 万程立 (3)
$$-\frac{h}{2m}$$
 $\mathcal{G}''(x) = E \mathcal{G}(x)$

$$M = 1, 2, \dots (= >1) Z$$

$$(4) \mathcal{G}_{n}^{(0)}(x) = \int_{L}^{Z} \sin\left(\frac{n\pi}{L}x\right) \qquad (5) E_{n}^{(0)} = E_{0} n^{2} \qquad (6) E_{0} = \frac{\pi c^{2} h^{2}}{2mL^{2}}$$

・人工意の揺動む。テンシャレ Vの)

$$f(x) = \int_{-L}^{2} \sin\left(\frac{n\pi}{L}x\right)$$

(7)
$$H = \hat{H}_{s} + V(\hat{\chi})$$
 (Sch.eq. (8) $-\frac{\hat{h}^{2}}{2m} P''(x) + V(x) P(x) = E P(x)$)

エネルギーの 1次補正 (8) $E_j = E_j^{(0)} + E_j^{(1)} + \cdots$ ($\lambda = (と C =)$

$$(9) E_{j}^{(1)} = \langle \mathcal{G}_{j}^{(0)} | V(\hat{\alpha}) | \mathcal{G}_{j}^{(0)} \rangle = \int_{0}^{L} dx \left\{ \mathcal{G}_{j}^{(0)}(\alpha) \right\}^{*} V(\alpha) \mathcal{G}_{j}(\alpha) = \frac{2}{L} \int_{0}^{L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V(\alpha)$$

(1)
$$E_{j}^{(l)} = \frac{2}{L} \int_{0}^{L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V(\alpha)$$

(2) $V(\alpha) = V_{o} L$

(3) $E_{j}^{(l)} = \frac{2}{L} \int_{0}^{L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{o} L$

(4) $S(x - \frac{L}{2})$

(5) $S(x - \frac{L}{2})$

(6) $S(x - \frac{L}{2})$

(7) $S(x - \frac{L}{2})$

(8) $S(x - \frac{L}{2})$

(9) $S(x - \frac{L}{2})$

(1) $S(x - \frac{L}{2})$

(1) $S(x - \frac{L}{2})$

(2) $V_{o} = \frac{2}{L} \int_{0}^{L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{o} L$

(1) $S(x - \frac{L}{2})$

(2) $V_{o} = \frac{2}{L} \int_{0}^{L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{o} L$

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(2) $V_{o} = \frac{2}{L} \int_{0}^{L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{o} L$

 $(3) E_{j}^{(1)} = \frac{2}{L} \int_{0}^{L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \delta(x - \frac{L}{2}) \int_{0}^{-L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_$ • $\pi \sqrt{2}$ (4) $\sqrt{\alpha} = \sqrt{5(x - \frac{1}{4})} - 5(x - \frac{3}{4}L)$

(5)
$$E_{j}^{(1)} = \frac{2}{L} \int_{0}^{L} dx \left(\sin \frac{j\pi}{L} x \right)^{2} V_{0} L \left(S(x - \frac{L}{4}) - S(x - \frac{3}{4}L) \right)$$

 $= 2V_0 \left(\left(\sin \frac{j\pi}{4} \right)^2 - \left(\sin \frac{3j\pi}{4} \right)^2 \right) = 0$ $sin(j\pi - \frac{j\pi}{4}) = 1sin(\frac{j\pi}{4})$ |少程動ではエネにギーハの花面正なし一つ2次程動、

二の何(2) 基底工术(H'- E_{I} 人の 2次程動がの神圧をなるよう公式) $E_{I}^{(2)} = \sum_{n \neq I} \frac{|\langle \mathcal{Y}_{I}^{(n)} | \hat{\mathcal{V}} | \mathcal{Y}_{I}^{(n)} \rangle|^{2}}{|E_{I}^{(n)} - E_{I}^{(n)}|}$

$$(2) (9_{n}^{(0)}) (19_{n}^{(0)}) = \int_{0}^{L} dx (9_{n}^{(0)}(x))^{*} v_{0} L \{8(x-\frac{L}{4})-8(x-\frac{3}{4}L)\} 9_{n}^{(0)}(x)$$

$$= 2V_0 \left\{ \int_0^L dx \sin\left(\frac{n\pi}{L}x\right) \sin\left(\frac{\pi}{L}x\right) \left\{ \delta(x - \frac{L}{4}) - \delta(x - \frac{3}{4}L) \right\} \right\}$$

$$= 2V_0 \left\{ \sin\frac{n\pi}{4} \sin\frac{\pi}{4} - \sin\frac{3n\pi}{4} \sin\frac{3\pi}{4} \right\} = \sqrt{2}V_0 \left\{ \sin\frac{n\pi}{4} - \sin\frac{3\pi}{4} \sin\frac{3\pi}{4} \right\} = \sqrt{2}V_0 \left\{ \sin\frac{n\pi}{4} - \sin\frac{3\pi}{4} \cos\frac{3\pi}{4} \right\} = \sqrt{2}V_0 \left\{ \sin\frac{n\pi}{4} - \sin\frac{n\pi}{4} \cos\frac{n\pi}{4} \right\} = \sqrt{2}V_0 \left\{ \sin\frac{n\pi}{4} - \sin\frac{n\pi}{4} \right\} = \sqrt{2}V_0 \left\{ \sin\frac{n\pi}{4} - \sin\frac{n\pi}$$

$$\frac{NR}{4}$$
 Sin $\frac{R}{4}$ - Sin

$$\frac{\partial \mathcal{R}}{\partial x} = \sin(n\mathcal{R} - \frac{1}{2})$$

い個のとき(3) SIN(NR) = (1)

$$\left(-\frac{n\pi}{L}\right) = 5$$

$$\left(\sin\frac{3n\pi}{4} - \sin(n\pi - \frac{n\pi}{4}) - \sin(n\pi)\cos(\frac{n\pi}{4}) - \cos(n\pi)\sin(\frac{n\pi}{4})\right)$$

$$\begin{array}{c}
\sin 4 = \sin(n\pi - 4) = \sin(n\pi$$

$$\left(-\frac{4}{4}\right) = 5$$

$$-\frac{4}{4}$$
) = si

$$=2V_{o}\left\{ \sin\frac{n\pi}{4}\sin\frac{\pi}{4}-\sin\frac{3n\pi}{4}\sin\frac{3\pi}{4}\right\} =\sqrt{2}V_{o}\left\{ \sin\frac{n\pi}{4}-\sin\frac{3n\pi}{4}\right\}$$

$$\frac{\sqrt{2}}{\sqrt{1}}$$
 - so



$$\int_{0}^{2} \left| \left(\left(\frac{1}{2} \right) \left| \left(\frac{1}{2} \right) \right| \right| \right| \right)}{\left(\left(\frac{1}{2} \right) \left| \left(\frac{1}{2} \right) \right| \right| \right| \right|}{\left(\frac{1}{2} \right) \left| \left(\frac{1}{2} \right) \right| \right| \right|}{\left(\frac{1}{2} \right) \left| \left(\frac{1}{2} \right) \right| \right| \right|}{\left(\frac{1}{2} \right) \left| \left($$

$$\frac{n}{2} = 2k + 1 \quad (k = 0, 1, 2, \dots) \rightarrow n = 4k + 2$$

$$(2)$$
 (2) $(3)^2$ $(3)^2$ $(4)^2$

$$E_{1}^{(2)} = \sum_{i=1}^{\infty} \frac{8(v_{i})^{2}}{5(v_{i})^{2}} = \frac{8(v_{i})^{2}}{5(v_{i})^{2}} = \frac{8(v_{i})^{2}}{5(v_{i})^{2}}$$

$$E_{1}^{(2)} = \sum_{k=0}^{\infty} \frac{8(v_{k})^{2}}{\sum_{k=0}^{\infty} \frac{8(v_{k})^{2}}{\sum_{k=0}^{\infty} \frac{1}{1-(v_{k}+2)^{2}}} = \frac{8(v_{k})^{2}}{\sum_{k=0}^{\infty} \frac{1}{1-(v_{k}+2)^{2}}}$$

(2)
$$E_1^{(2)} = \sum_{k=0}^{\infty} \frac{8(v_0)^2}{E_0 - E_0(4k+2)^2} = \frac{8(v_0)^2}{E_0} \frac{\sqrt{1 - (4k+2)^2}}{|_{k=0}}$$

$$\frac{1}{k=0} = \frac{1-(4k+2)^2}{1-(4k+2)^2} = \frac{1-(4k+2)}{1-(4k+2)}$$

$$= \frac{1}{2} \left(\frac{1}{2} \left(\frac{1}{2} \right)^2 + \frac{1}{2} \left(\frac{1}{2$$

$$= -\frac{\pi(V_0)^2}{E_0}$$

$$= -\frac{\pi(V_0)^2}{E_0}$$

$$= -\frac{\pi(V_0)^2}{E_0}$$

$$= -\frac{\pi(V_0)^2}{E_0}$$

$$= -\frac{\pi(V_0)^2}{E_0}$$

回緒里のおる場合 2次元の自由和子八の程重力

非理事 Schwidinger 另程立

境界ではタロックニの

(x,9) $0 \le x \le L$, $0 \le 9 \le L$

 $(1) - \frac{t^2}{2m} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \mathcal{G}(x, y) = E \mathcal{G}(x, y)$ 工术(共)一团有状態 (2) $y_{nx,ny}(x,y) = \frac{2}{L} sin(\frac{n_x \pi x}{L}x) sin(\frac{n_y \pi y}{L}y)$ 工产化书一因有值 (3) $E_{nx,ny} = E_0 \{ n_x^2 + n_y^2 \}$ (4) $E_0 = \frac{\pi^2 + n_y^2}{2mL^2}$ $(5) N_{x}, N_{y} = 1, 2, 3, \cdots$

• 第1励起状態 (8) $Y_{1,2}^{(0)}(\alpha,9) = \frac{2}{L} \sin(\frac{\pi}{L}x) \sin(\frac{2\pi}{L}y) = \frac{2}{L} (\alpha,9)$ (9) 92,1 (x,y) = = = sin(= x) sin(= y) =: 42(x,9) - (42) (D) E(s) = Eo(22+12) = 5E。 2重縮建!

2重縮退(下工术(井)因有状態(火),(火)八の規動の影響

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(2) WRE = (42/014e) 1= IU 9754 WE TO WE.

(3)
$$\langle \Psi_1 | \hat{V} | \Psi_2 \rangle = \int dx \int dy \ \Psi_1(x,y) \ V(x,y) \ \Psi_2(x,y)$$

$$= 4V_0 \int dx \int_0^L dy \sin(\frac{\pi}{L}x) \sin(\frac{2\pi}{L}y) \ \delta(x - \frac{L}{4}) \ \delta(y - \frac{L}{4}) \sin(\frac{2\pi}{L}x) \sin(\frac{\pi}{L}y)$$

$$=4V_0\left(\sin\frac{\pi}{4}\right)^2\left(\sin\frac{\pi}{2}\right)^2=2V_0$$

(60 b, l=1,2 1= >112+ (6767) (4) < 4/V/4 >= 200

$$f_{3}$$
 (5) $W = \begin{pmatrix} 2v_{0} & 2v_{0} \\ 2v_{0} & 2v_{0} \end{pmatrix} = 2v_{0} \begin{pmatrix} l & 1 \\ 1 & 1 \end{pmatrix}$

$$(1) W = 2V_0 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$(2) \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\delta = 2 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\delta = 2 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\delta = 2 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\delta = 0 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Wの面有值は4V。, O 固有バクトには同じ 近似的な工术は一固有软態·固有值

(3)
$$|\Psi_{-}\rangle \simeq \frac{1}{12} \{|\Psi_{+}\rangle - |\Psi_{2}\rangle \}$$
, $E_{-}\simeq SE_{0}$ 编建就解决正的 $|\Psi_{+}\rangle \simeq \frac{1}{12} \{|\Psi_{+}\rangle + |\Psi_{2}\rangle \}$, $E_{+}\simeq SE_{0} + 4\%$