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# Mining Data Streams (Part 2)

Mining of Massive Datasets
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## Today's Lecture

- More algorithms for streams:
  - (1) Filtering a data stream: Bloom filters
    - Select elements with property x from stream
  - (2) Counting distinct elements: Flajolet-Martin
    - Number of distinct elements in the last k elements of the stream
  - (3) Estimating moments: AMS method
    - Estimate std. dev. of last k elements
  - (4) Counting frequent items

# (1) Filtering Data Streams

#### Filtering Data Streams

- Each element of data stream is a tuple
- Given a list of keys S
- Determine which tuples of stream are in S
- Obvious solution: Hash table
  - But suppose we do not have enough memory to store all of S in a hash table
    - E.g., we might be processing millions of filters on the same stream

#### **Applications**

#### Example: Email spam filtering

- We know 1 billion "good" email addresses
- If an email comes from one of these, it is NOT spam

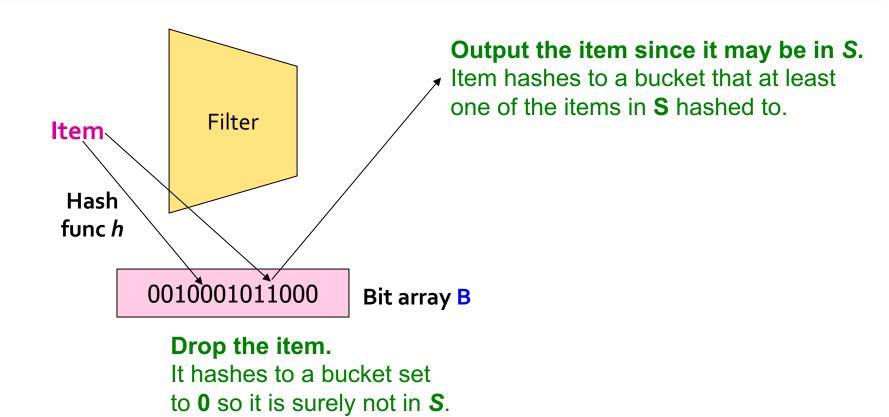
#### Publish-subscribe systems

- You are collecting lots of messages (news articles)
- People express interest in certain sets of keywords
- Determine whether each message matches user's interest

#### First Cut Solution (1)

- Given a set of keys S that we want to filter
- Create a bit array B of n bits, initially all Os
- Choose a hash function h with range [0,n)
- Hash each member of s∈ S to one of n buckets, and set that bit to 1, i.e., B[h(s)]=1
- Hash each element a of the stream and output only those that hash to bit that was set to 1
  - Output a if B[h(a)] == 1

#### First Cut Solution (2)



- Creates false positives but no false negatives
  - If the item is in S we surely output it, if not we may still output it

#### First Cut Solution (3)

- |S| = 1 billion email addresses|B| = 1GB = 8 billion bits
- If the email address is in S, then it surely hashes to a bucket that has the big set to 1, so it always gets through (no false negatives)
- Approximately 1/8 of the bits are set to 1, so about 1/8<sup>th</sup> of the addresses not in S get through to the output (false positives)
  - Actually, less than 1/8<sup>th</sup>, because more than one address might hash to the same bit

#### Example: Bloom Filter

- Use N = 11 bits for our filter
- Stream elements = integers.
- Use two hash functions:
  - $h_1(x) =$ 
    - Take odd-numbered bits from the right in the binary representation of x.
    - Treat it as an integer i.
    - Result is i modulo 11.
  - $h_2(x)$  = same, but take even-numbered bits.

# **Example: Continued**

Stream element	h <sub>1</sub>	h <sub>2</sub>	Filter contents
			0000000000
25 = 1 <mark>1</mark> 001	5	2	00100100000
159 = 10 <mark>0</mark> 11111	7	0	10100101000
585 = <b>1</b> 001001001	9	7	10100101010

#### **Bloom Filter Lookup**

- Suppose element y appears in the stream,
   and we want to know if we have seen y before
- Compute h(y) for each hash function.
- If all the resulting bits positions are 1, say we have seen y before.
- If at least one of these positions is 0, say we have not seen y before.

#### Example: Lookup

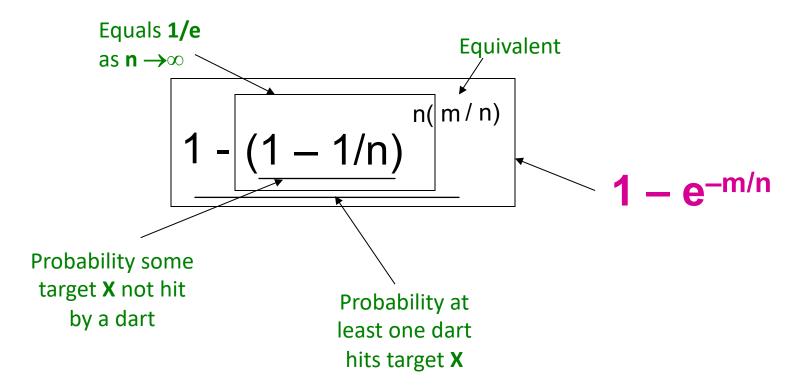
- Suppose we have the same Bloom filter as before, and we have set the filter to 10100101010.
- Lookup element y = 118 = 1110110 (binary).
- $h_1(y) = 14 \mod 11 = 3$
- $-h_2(y) = 5 \mod 11 = 5$
- Bit 5 is 1, but bit 3 is 0, so we are sure y is not in the set.

# **Analysis:** Throwing Darts (1)

- More accurate analysis for the number of false positives
- Consider: If we throw m darts into n equally likely targets, what is the probability that a target gets at least one dart?
- In our case:
  - Targets = bits/buckets
  - Darts = hash values of items

# **Analysis:** Throwing Darts (2)

- We have m darts, n targets
- What is the probability that a target gets at least one dart?



# **Analysis:** Throwing Darts (3)

- Fraction of 1s in the array B =
   probability of false positive = 1 e<sup>-m/n</sup>
- Example: 10<sup>9</sup> darts, 8·10<sup>9</sup> targets
  - Fraction of 1s in  $B = 1 e^{-1/8} = 0.1175$ 
    - Compare with our earlier estimate: 1/8 = 0.125

#### **Bloom Filter**

- Consider: |S| = m, |B| = n
- Use k independent hash functions  $h_1,...,h_k$
- Initialization:
  - Set B to all 0s
  - Hash each element  $s \in S$  using each hash function  $h_i$ , set  $B[h_i(s)] = 1$  (for each i = 1,..., k) (note: we have a single array B!)
- Run-time:
  - When a stream element with key x arrives
    - If  $B[h_i(x)] = 1$  for all i = 1,..., k then declare that x is in S
      - That is, x hashes to a bucket set to 1 for every hash function h<sub>i</sub>(x)
    - Otherwise discard the element x

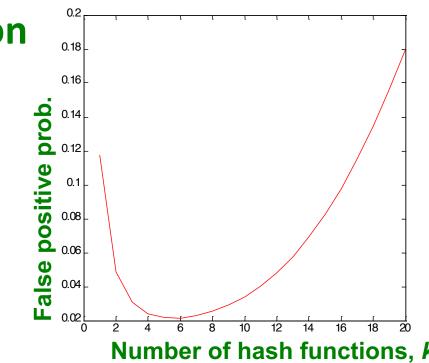
#### **Bloom Filter -- Analysis**

- What fraction of the bit vector B are 1s?
  - Throwing k·m darts at n targets
  - So fraction of 1s is  $(1 e^{-km/n})$
- But we have k independent hash functions and we only let the element x through if all k hash element x to a bucket of value 1
- So, false positive probability =  $(1 e^{-km/n})^k$

#### Bloom Filter – Analysis (2)

- = m = 1 billion, n = 8 billion
  - k = 1:  $(1 e^{-1/8}) = 0.1175$
  - k = 2:  $(1 e^{-1/4})^2 = 0.0493$

What happens as we keep increasing k?



- Number of hash functions, k
- "Optimal" value of k:  $n/m \ln(2)$ 
  - In our case: Optimal  $k = 8 \ln(2) = 5.54 \approx 6$ 
    - **Error at k = 6**:  $(1 e^{-1/6})^2 = 0.0235$

#### Bloom Filter: Wrap-up

- Bloom filters guarantee no false negatives, and use limited memory
  - Great for pre-processing before more expensive checks
- Suitable for hardware implementation
  - Hash function computations can be parallelized

# (2) Counting Distinct Elements

## **Counting Distinct Elements**

#### Problem:

- Data stream consists of a universe of elements chosen from a set of size N
- Maintain a count of the number of distinct elements seen so far
- Obvious approach:
  - Maintain the set of elements seen so far
  - That is, keep a hash table of all the distinct elements seen so far

## Applications

- How many different words are found among the Web pages being crawled at a site?
  - Unusually low or high numbers could indicate artificial pages (spam?)
- How many different Web pages does each customer request in a week?
- How many distinct products have we sold in the last week?

#### **Using Small Storage**

- Real problem: What if we do not have space to maintain the set of elements seen so far?
- Estimate the count in an unbiased way
- Accept that the count may have a little error,
   but limit the probability that the error is large

#### Flajolet-Martin Approach

- Pick a hash function h that maps each of the
   N elements to at least log<sub>2</sub> N bits
- For each stream element a, let r(a) be the number of trailing 0s in h(a)
  - r(a) = position of first 1 counting from the right
    - E.g., say h(a) = 12, then 12 is 1100 in binary, so r(a) = 2
- Record R = the maximum r(a) seen
  - $\mathbf{R} = \mathbf{max}_{\mathbf{a}} \mathbf{r(a)}$ , over all the items  $\mathbf{a}$  seen so far
- Estimated number of distinct elements = 2<sup>R</sup>

#### Why It Works: Intuition

- Very very rough and heuristic intuition why Flajolet-Martin works:
  - h(a) hashes a with equal prob. to any of N values
  - Then h(a) is a sequence of log<sub>2</sub> N bits, where 2<sup>-r</sup> fraction of all as have a tail of r zeros
    - About 50% of as hash to \*\*\*0
    - About 25% of as hash to \*\*00
    - So, if we saw the longest tail of r=2 (i.e., item hash ending \*100) then we have probably seen about 4 distinct items so far
  - So, it takes to hash about 2<sup>r</sup> items before we see one with zero-suffix of length r

## Why It Works: More formally

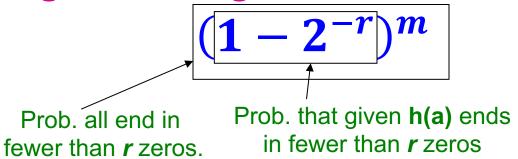
- Now we show why Flajolet-Martin works
- Formally, we will show that probability of finding a tail of r zeros:
  - Goes to 1 if  $m \gg 2^r$
  - Goes to 0 if  $m \ll 2^r$

where m is the number of distinct elements seen so far in the stream

Thus, 2<sup>R</sup> will almost always be around m!

# Why It Works: More formally

- What is the probability that a given h(a) ends in at least r zeros is 2<sup>-r</sup>
  - h(a) hashes elements uniformly at random
  - Probability that a random number ends in at least r zeros is 2-r
- Then, the probability of NOT seeing a tail of length r among m elements:



# Why It Works: More formally

- Note:  $(1-2^{-r})^m = (1-2^{-r})^{2^r(m2^{-r})} \approx e^{-m2^{-r}}$
- Prob. of NOT finding a tail of length r is:
  - If  $m \ll 2^r$ , then prob. tends to 1
    - $(1-2^{-r})^m \approx e^{-m2^{-r}} = 1$  as  $m/2^r \rightarrow 0$
    - So, the probability of finding a tail of length r tends to 0
  - If *m* >> **2**<sup>r</sup>, then prob. tends to **0** 
    - $(1-2^{-r})^m \approx e^{-m2^{-r}} = 0$  as  $m/2^r \to \infty$
    - So, the probability of finding a tail of length r tends to 1
- Thus, 2<sup>R</sup> will almost always be around m!

#### Why It Doesn't Work

- E[2<sup>R</sup>] is actually infinite
  - Probability halves when  $R \rightarrow R+1$ , but value doubles
- Workaround involves using many hash functions h<sub>i</sub> and getting many samples of R<sub>i</sub>
- How are samples R<sub>i</sub> combined?
  - Average? What if one very large value  $2^{R_i}$ ?
  - Median? All estimates are a power of 2
  - Solution:
    - Partition your samples into small groups
    - Take the median of groups
    - Then take the average of the medians

# (3) Computing Moments

#### Generalization: Moments

- Suppose a stream has elements chosen from a set A of N values
- Let m<sub>i</sub> be the number of times value i occurs in the stream
- The k<sup>th</sup> moment is

$$\sum_{i\in A} (m_i)^k$$

## **Special Cases**

$$\sum_{i\in A} (m_i)^k$$

- Othmoment = number of distinct elements
  - The problem just considered
- 1<sup>st</sup> moment = count of the numbers of elements = length of the stream
  - Easy to compute
- 2<sup>nd</sup> moment = surprise number S = a measure of how uneven the distribution is

#### **Example: Surprise Number**

- Stream of length 100
- 11 distinct values
- Item counts: 10, 9, 9, 9, 9, 9, 9, 9, 9, 9, 9, 9
  Surprise S = 910
- Item counts: 90, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1
  Surprise S = 8,110

#### **AMS** Method

- AMS method works for all moments
- Gives an unbiased estimate
- We will just concentrate on the 2<sup>nd</sup> moment S
- We pick and keep track of many variables X:
  - For each variable X we store X.el and X.val
    - X.el corresponds to the item i
    - X.val corresponds to the count of item i
  - Note this requires a count in main memory,
     so number of Xs is limited
- Our goal is to compute  $S = \sum_i m_i^2$

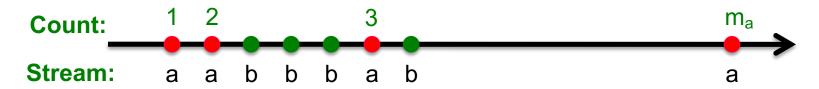
#### One Random Variable (X)

- How to set X.val and X.el?
  - Assume stream has length n (we relax this later)
  - Pick some random time t (t<n) to start, so that any time is equally likely
  - Let at time t the stream have item i. We set X.el = i
  - Then we maintain count c (X.val = c) of the number of is in the stream starting from the chosen time t
- Then the estimate of the 2<sup>nd</sup> moment  $(\sum_i m_i^2)$  is:

$$S = f(X) = n (2 \cdot c - 1)$$

• Note, we will keep track of multiple Xs,  $(X_1, X_2, ..., X_k)$  and our final estimate will be  $S = 1/k \sum_{i}^{k} f(X_i)$ 

#### **Expectation Analysis**



- lacksquare 2<sup>nd</sup> moment is  $S = \sum_i m_i^2$
- $c_t$  ... number of times item at time t appears from time t onwards ( $c_1 = m_a$ ,  $c_2 = m_a 1$ ,  $c_3 = m_b$ )
- $E[f(X)] = \frac{1}{n} \sum_{t=1}^{n} n(2c_t 1)$   $= \frac{1}{n} \sum_{i} n (1 + 3 + 5 + \dots + 2m_i 1)$

*m<sub>i</sub>* ... total count of item *i* in the stream (we are assuming stream has length *n*)

Group times by the value seen

Time t when the last i is seen  $(c_t=1)$ 

Time t when the penultimate i is seen ( $c_t=2$ )

Time t when the first i is seen ( $c_t = m_i$ )

#### **Expectation Analysis**

- $E[f(X)] = \frac{1}{n} \sum_{i} n (1 + 3 + 5 + \dots + 2m_i 1)$ 
  - Little side calculation:  $(1+3+5+\cdots+2m_i-1)=\sum_{i=1}^{m_i}(2i-1)=2\frac{m_i(m_i+1)}{2}-m_i=(m_i)^2$
- Then  $E[f(X)] = \frac{1}{n} \sum_i n (m_i)^2$
- So,  $E[f(X)] = \sum_{i} (m_i)^2 = S$
- We have the second moment (in expectation)!

#### **Higher-Order Moments**

- For estimating k<sup>th</sup> moment we essentially use the same algorithm but change the estimate:
  - For k=2 we used  $n(2\cdot c-1)$
  - For k=3 we use:  $n(3\cdot c^2 3c + 1)$  (where c=X.val)
- Why?
  - For k=2: Remember we had  $(1+3+5+\cdots+2m_i-1)$  and we showed terms **2c-1** (for c=1,...,m) sum to  $m^2$ 
    - $\sum_{c=1}^{m} 2c 1 = \sum_{c=1}^{m} c^2 \sum_{c=1}^{m} (c-1)^2 = m^2$
    - So:  $2c 1 = c^2 (c 1)^2$
  - For k=3:  $c^3 (c-1)^3 = 3c^2 3c + 1$
- Generally: Estimate =  $n(c^k (c-1)^k)$

## **Combining Samples**

#### In practice:

- Compute f(X) = n(2c-1) for as many variables X as you can fit in memory
- Average them in groups
- Take median of averages

#### Problem: Streams never end

- We assumed there was a number n, the number of positions in the stream
- But real streams go on forever, so n is a variable – the number of inputs seen so far

#### Streams Never End: Fixups

- (1) The variables X have n as a factor keep n separately; just hold the count in X
- (2) Suppose we can only store k counts.
  We must throw some Xs out as time goes on:
  - Objective: Each starting time t is selected with probability k/n
  - Solution: (fixed-size sampling!)
    - Choose the first k times for k variables
    - When the  $n^{th}$  element arrives (n > k), choose it with probability k/n
    - If you choose it, throw one of the previously stored variables X out, with equal probability